



30 JULY – 3 AUGUST *Los Angeles*
SIGGRAPH2017

Modeling Surface Appearance from a Single Photograph using Self-Augmented Convolutional Neural Networks

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Appearance Modeling from Single Image



Input Image



Albedo Map



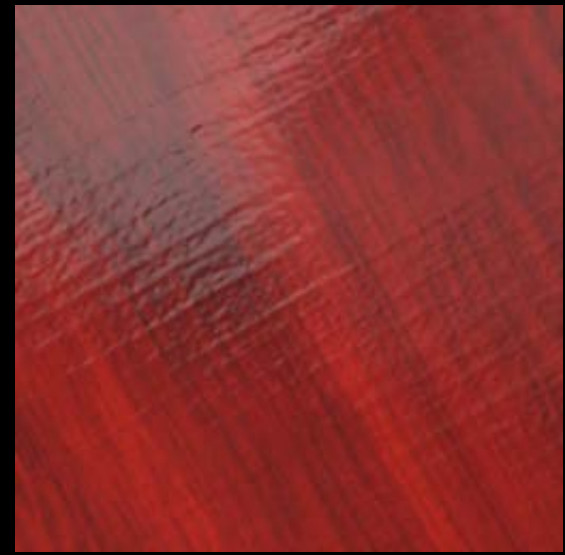
Bump Map



Specular



Artists' Solution



Input Image

Professional software



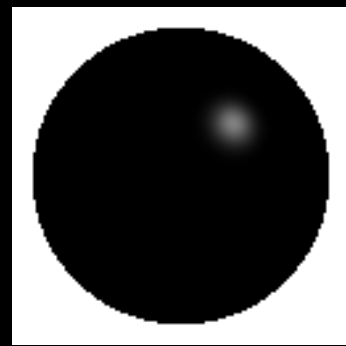
Experienced artist



Albedo Map



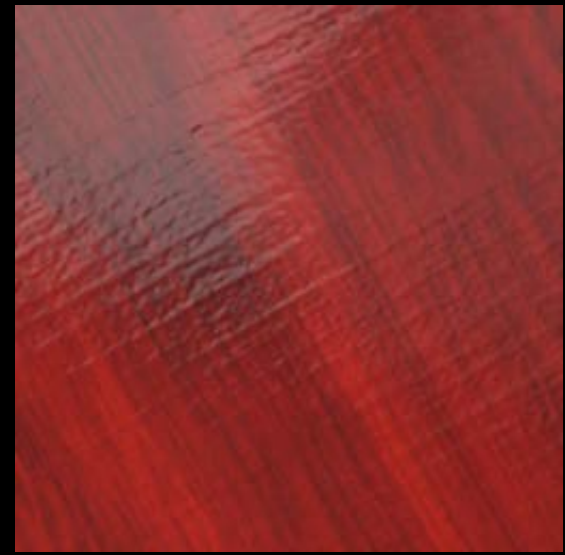
Bump Map



Specular

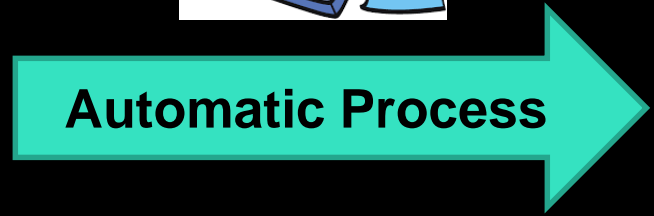


Our Goal



Input Image

End to End System



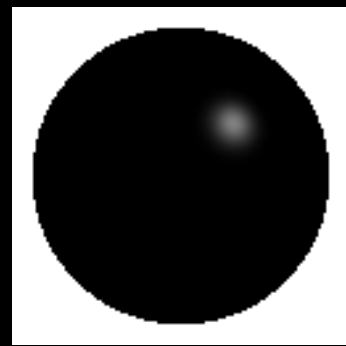
Non-expert Users



Albedo Map



Bump Map



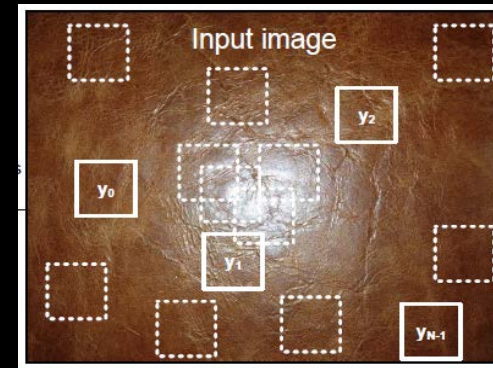
Specular

Related Work

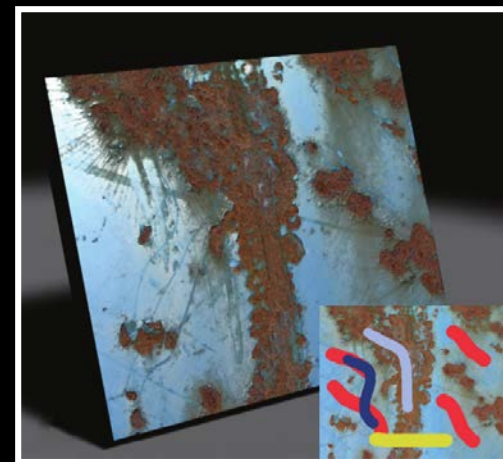
Single image appearance modeling



- Active illumination / Known lighting
 - [Wang 2016]; [Xu 2016]
- Stationary / Stochastic Textures
 - [Wang 2011]; [Aittala 2016]
- Diffuse / homogeneous BRDF
 - [Barron 2015]; [Shi 2017]
- Manual interaction
 - [Dong 2011]



[Aittala 2016]



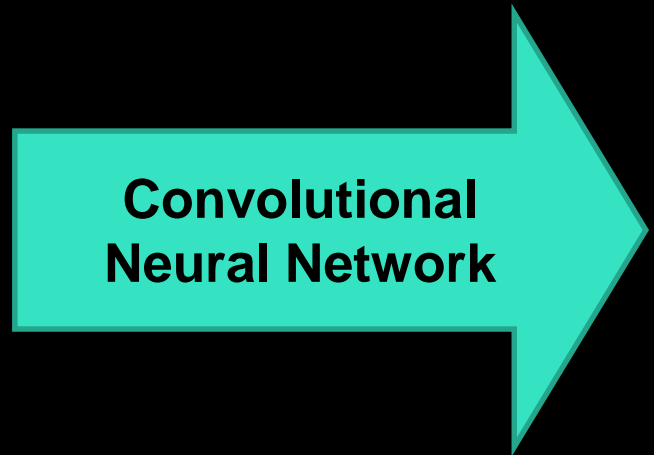
[Dong 2011]



Modeling Appearance by CNN



Input Image



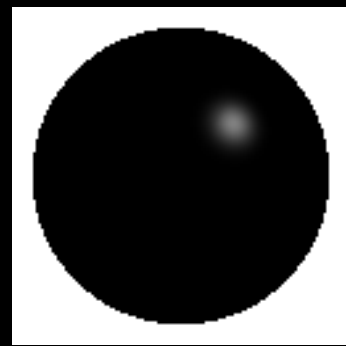
Convolutional
Neural Network



Albedo Map



Bump Map



Homogeneous Specular
(Ward Model)



Obtaining Labeled Data is HARD!



Albedo Map

Bump Map

Homogeneous Specular
(Ward Model)

Obtaining Labeled Data is HARD!



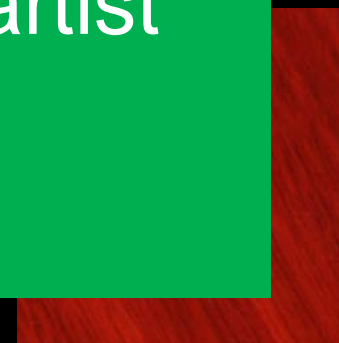
✗ Capture / Modeling by artist

- Complex device
- Long time
- Manual work

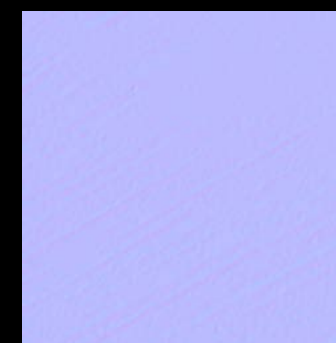


Input Image

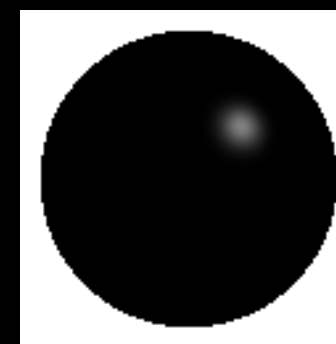
Labeled data pair



Albedo Map



Bump Map



Homogeneous Specular
(Ward Model)

Obtaining Labeled Data is HARD!

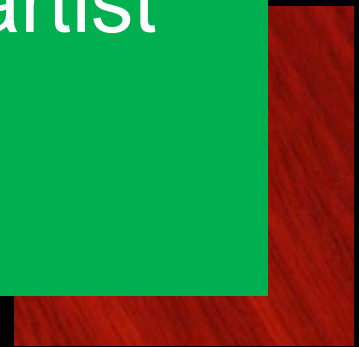


✗ Capture / Modeling by artist

- Complex device
- Long time
- Manual work



Input Image



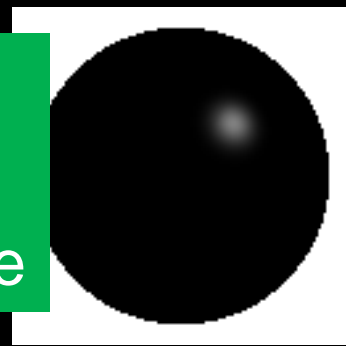
Albedo Map



Bump Map

✗ Analysis by Synthesis

- Few SVBRDF data available
- Non-trivial to sample SVBRDF space

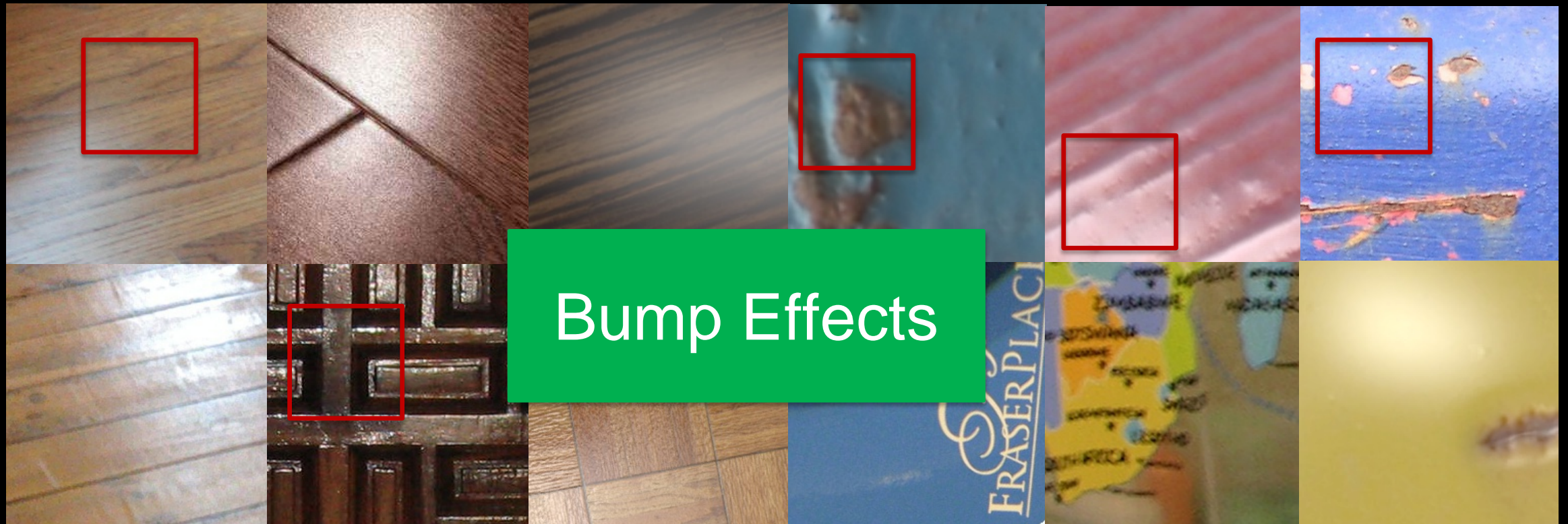


Homogeneous Specular
(Ward Model)

Unlabeled Image Contains Information



Unlabeled Image Contains Information



Key Observation



Forward Mapping: Appearance Modeling

$$A = f(I)$$

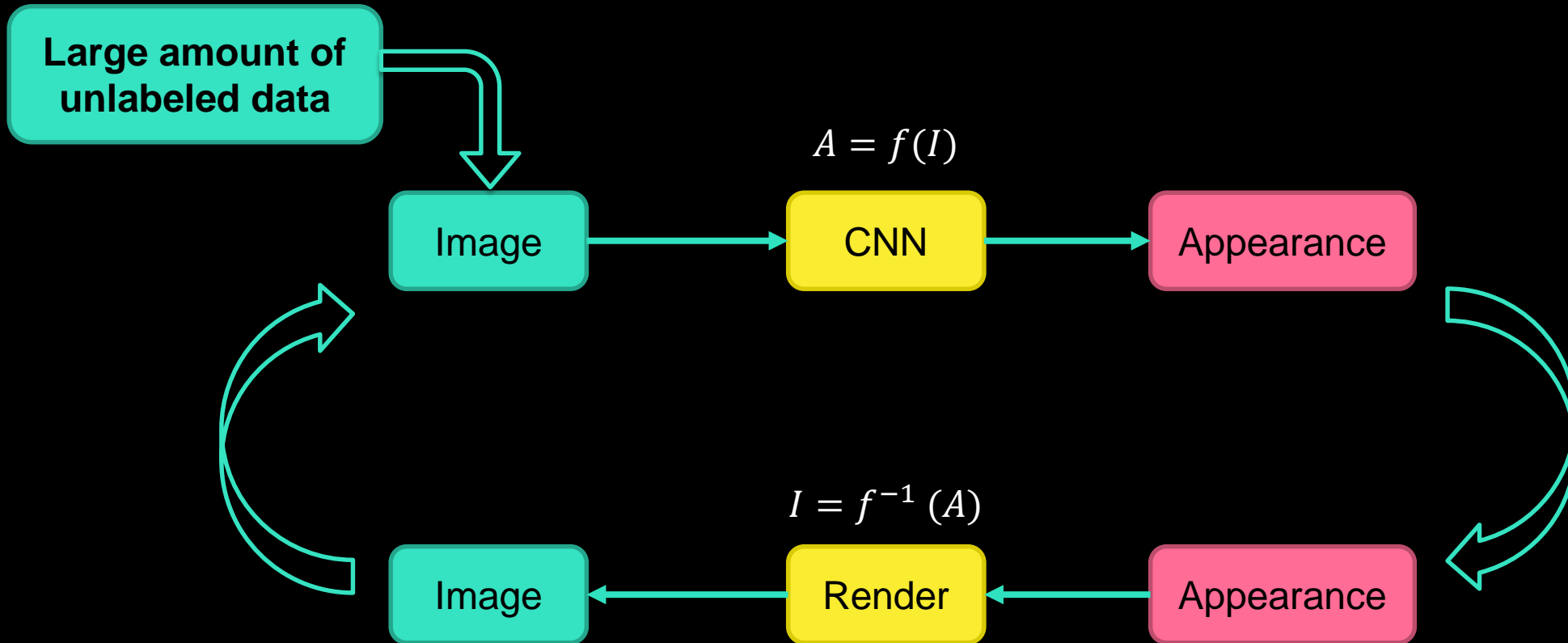


Inverse Mapping: Render

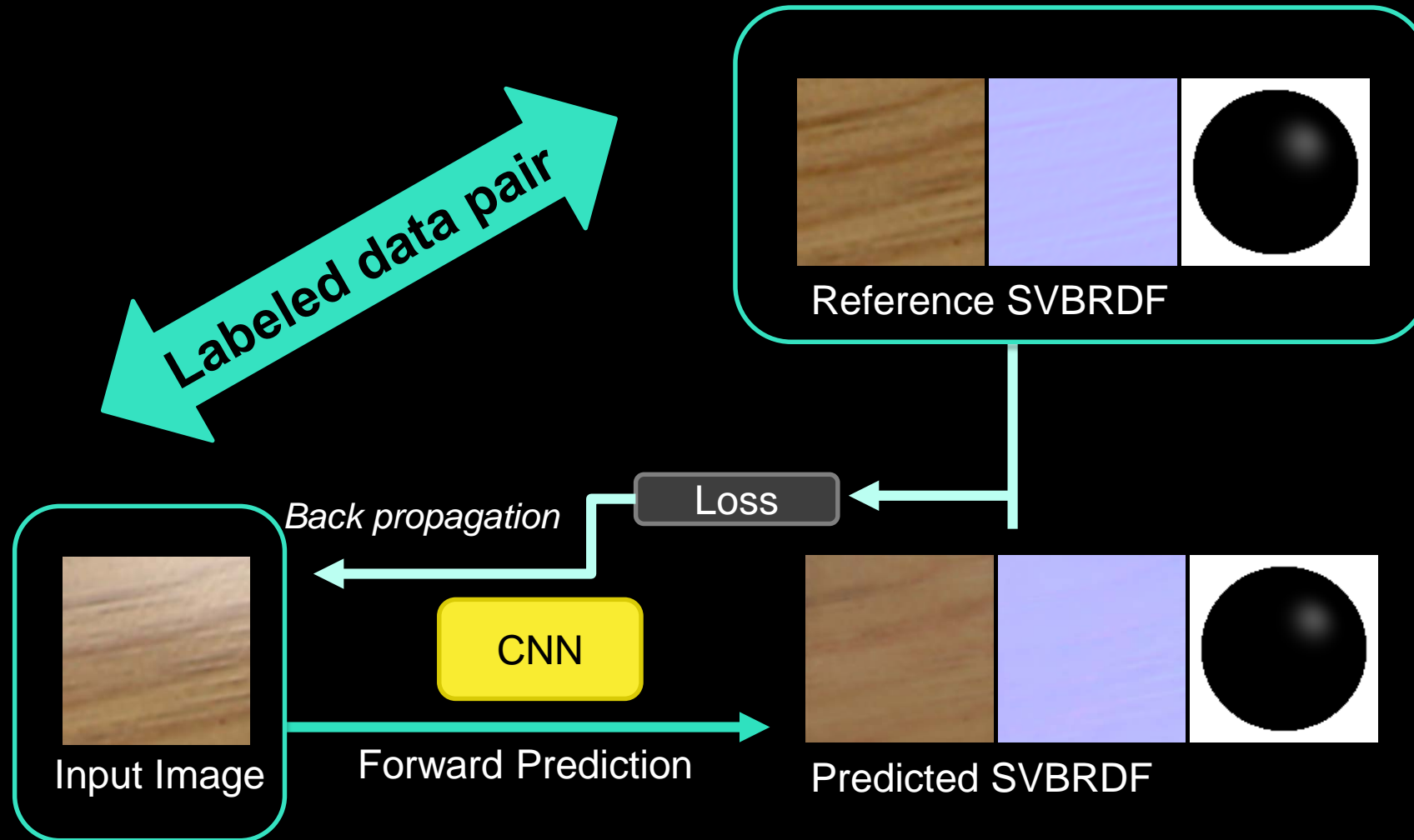
$$I = f^{-1}(A)$$



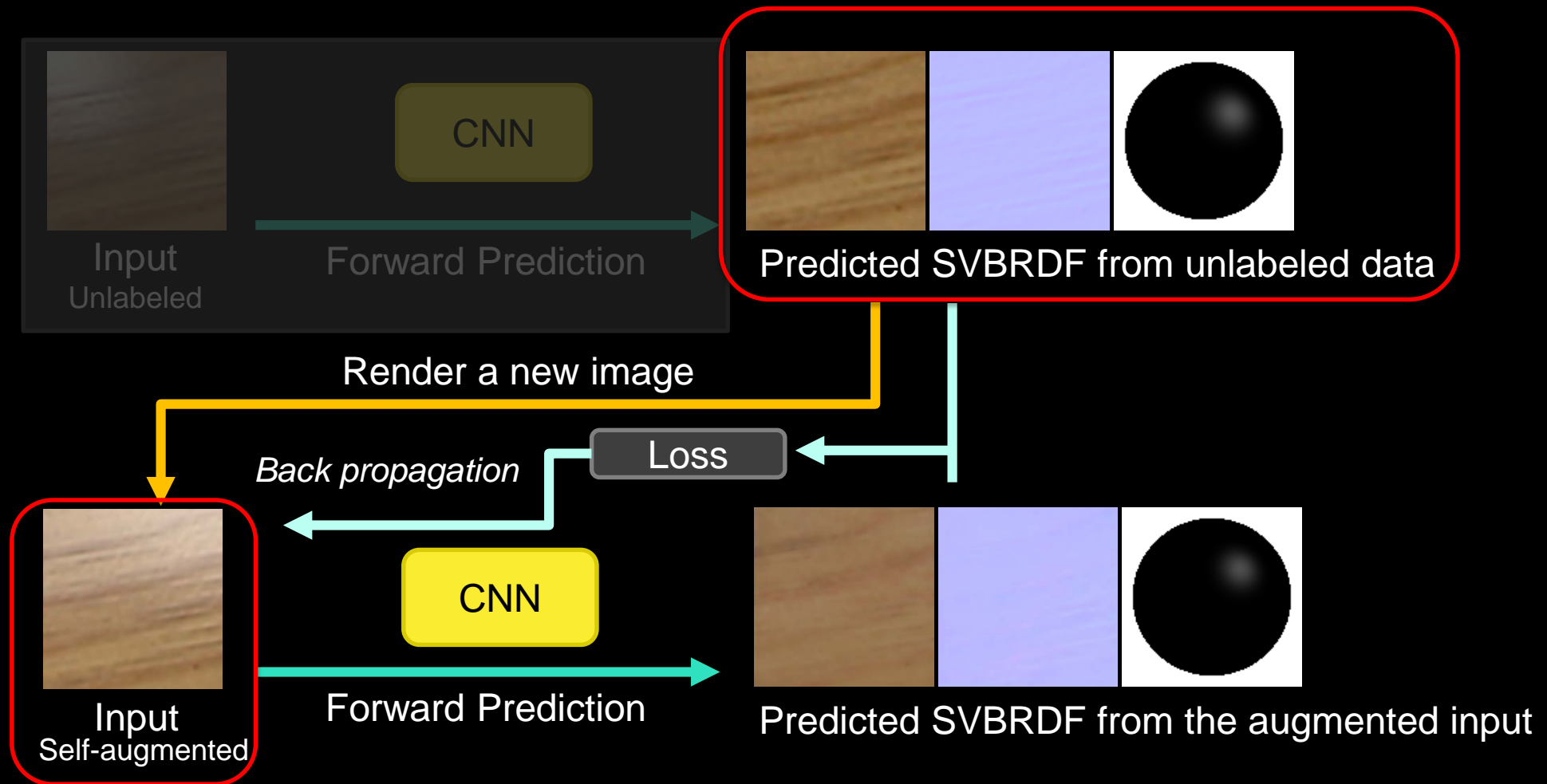
Key Observation



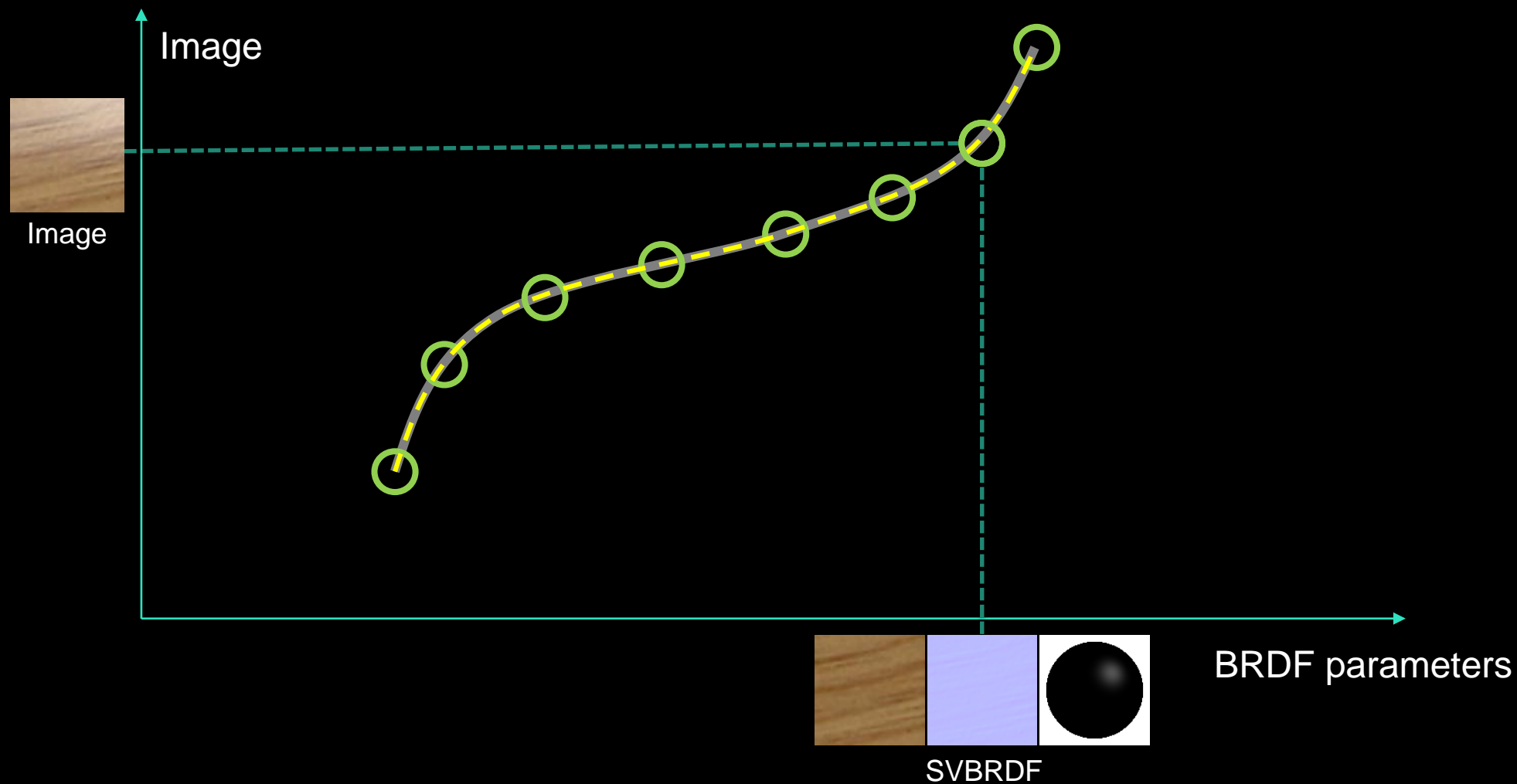
Self-Augmented Training



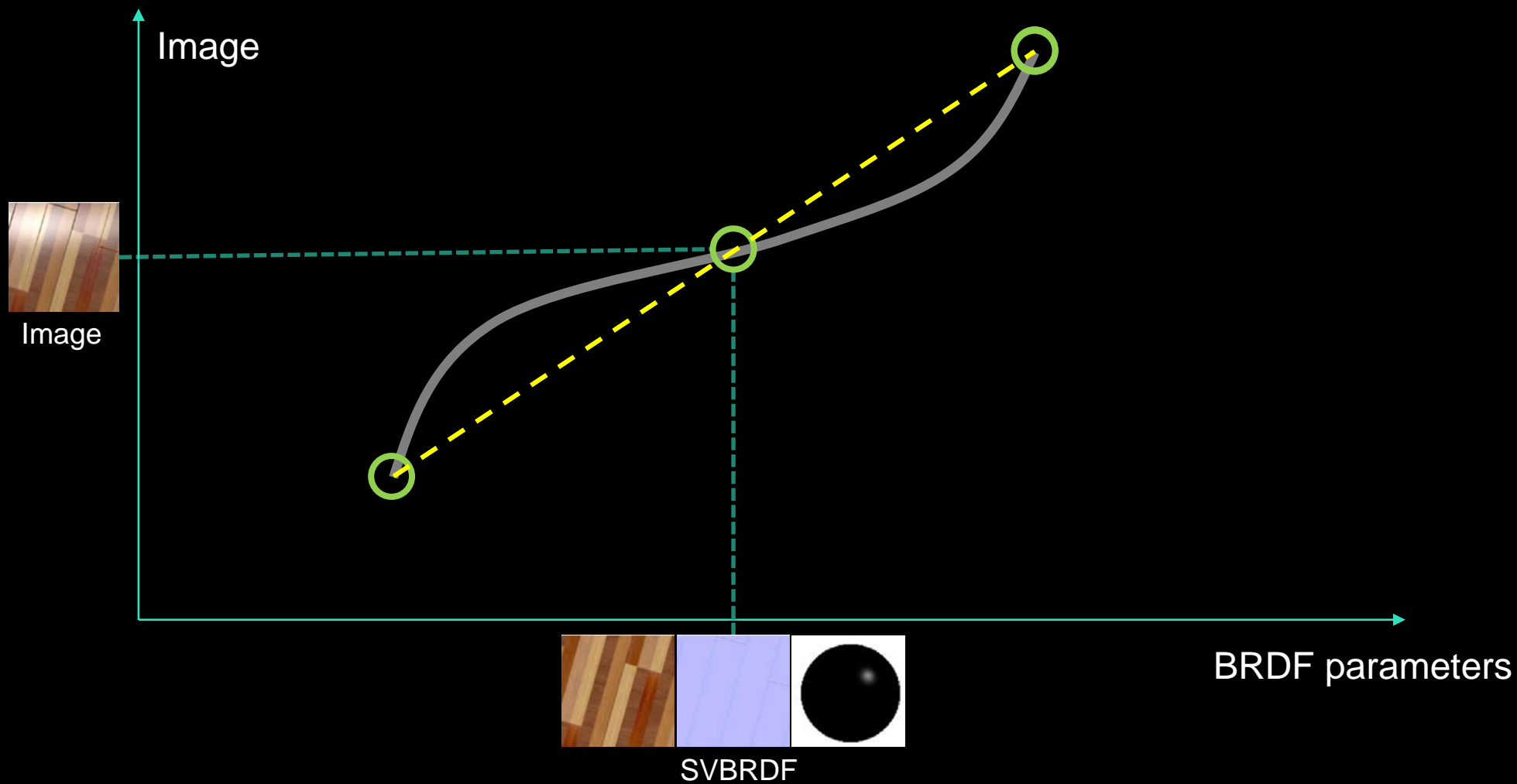
Self-Augmented Training



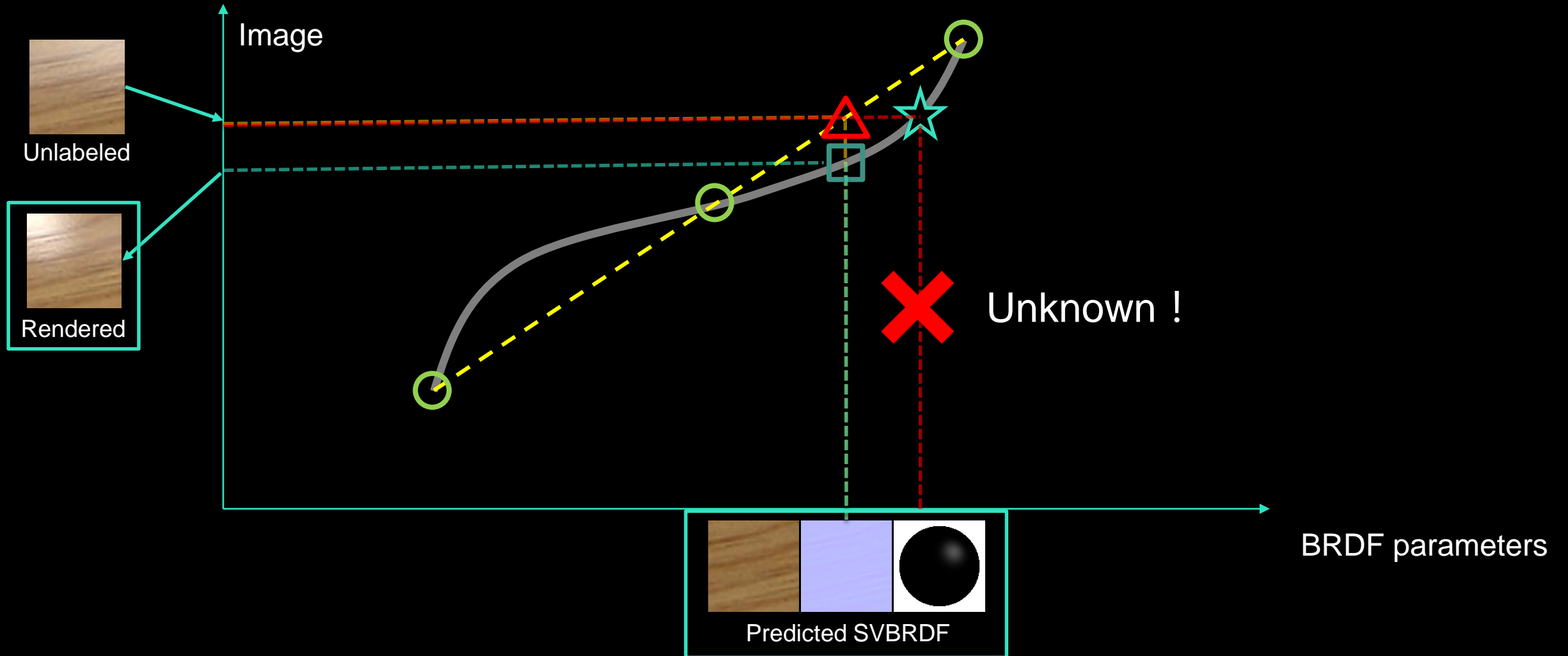
1D illustration of Self-Augmentation



1D illustration of Self-Augmentation

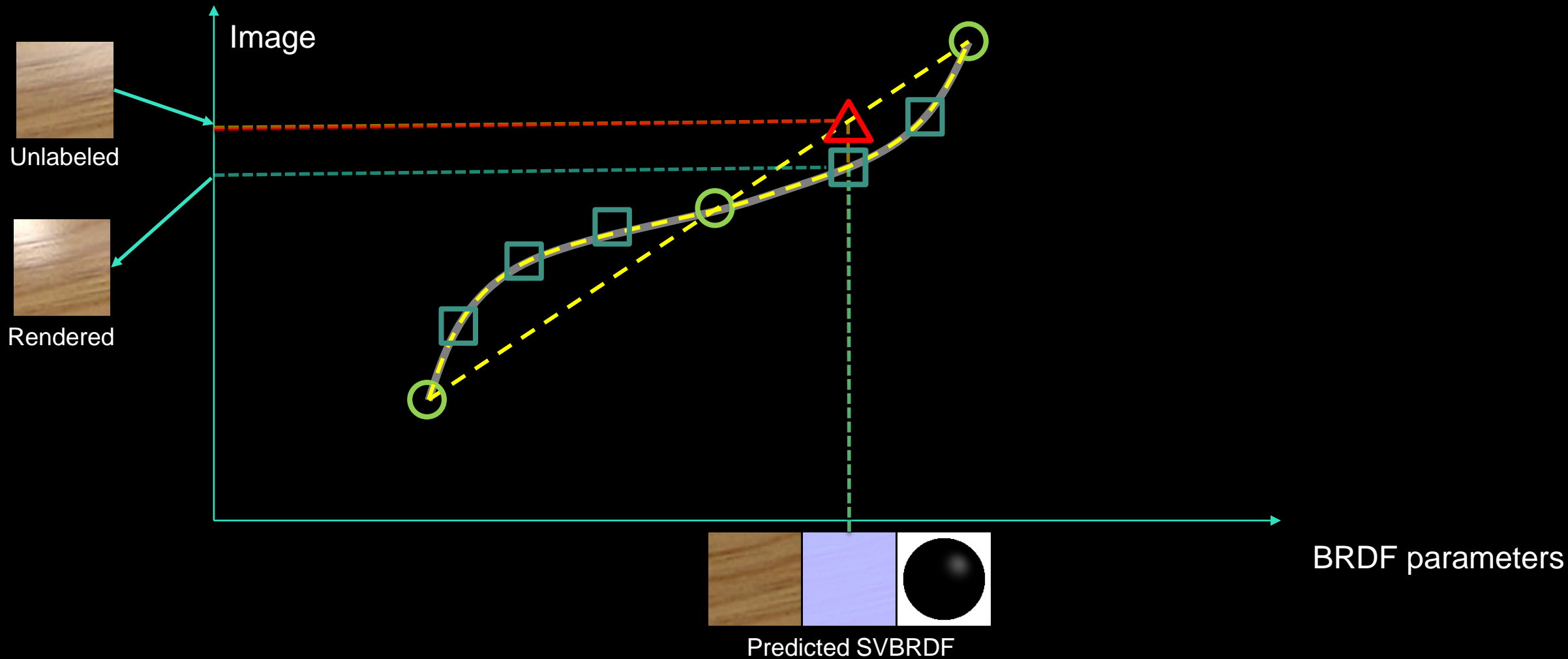


1D illustration of Self-Augmentation





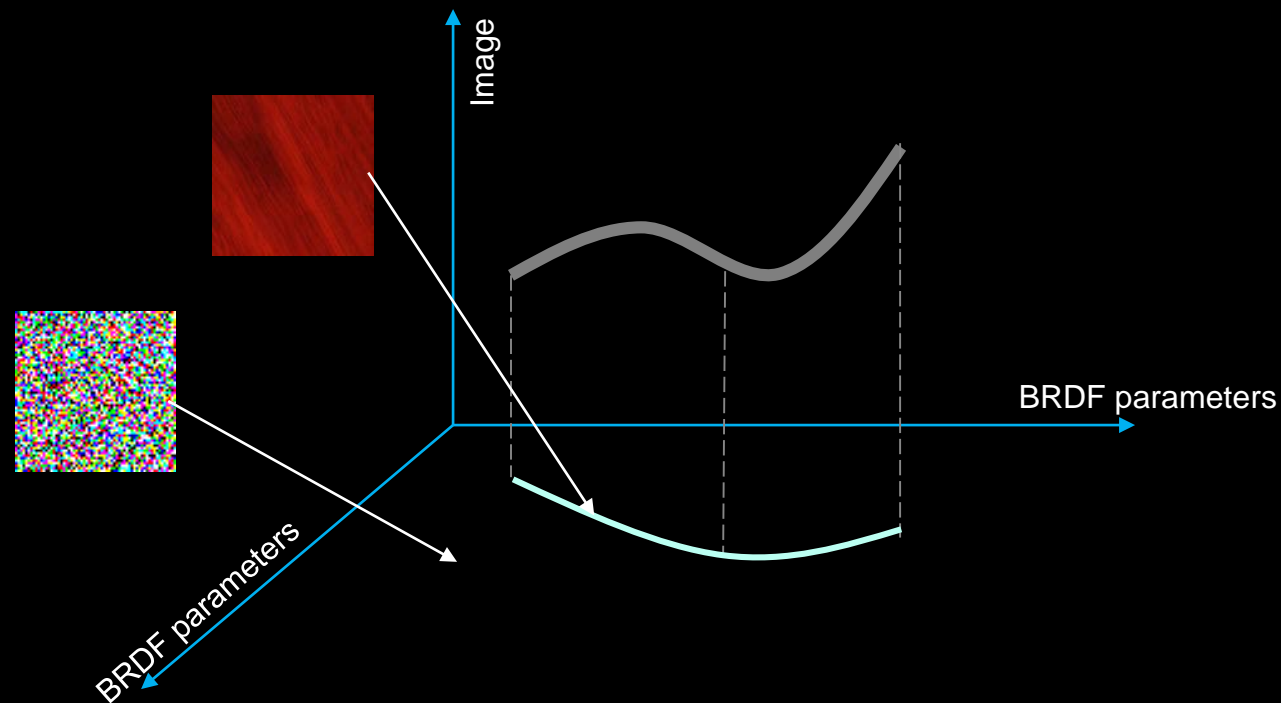
1D illustration of Self-Augmentation



Why SA scheme works



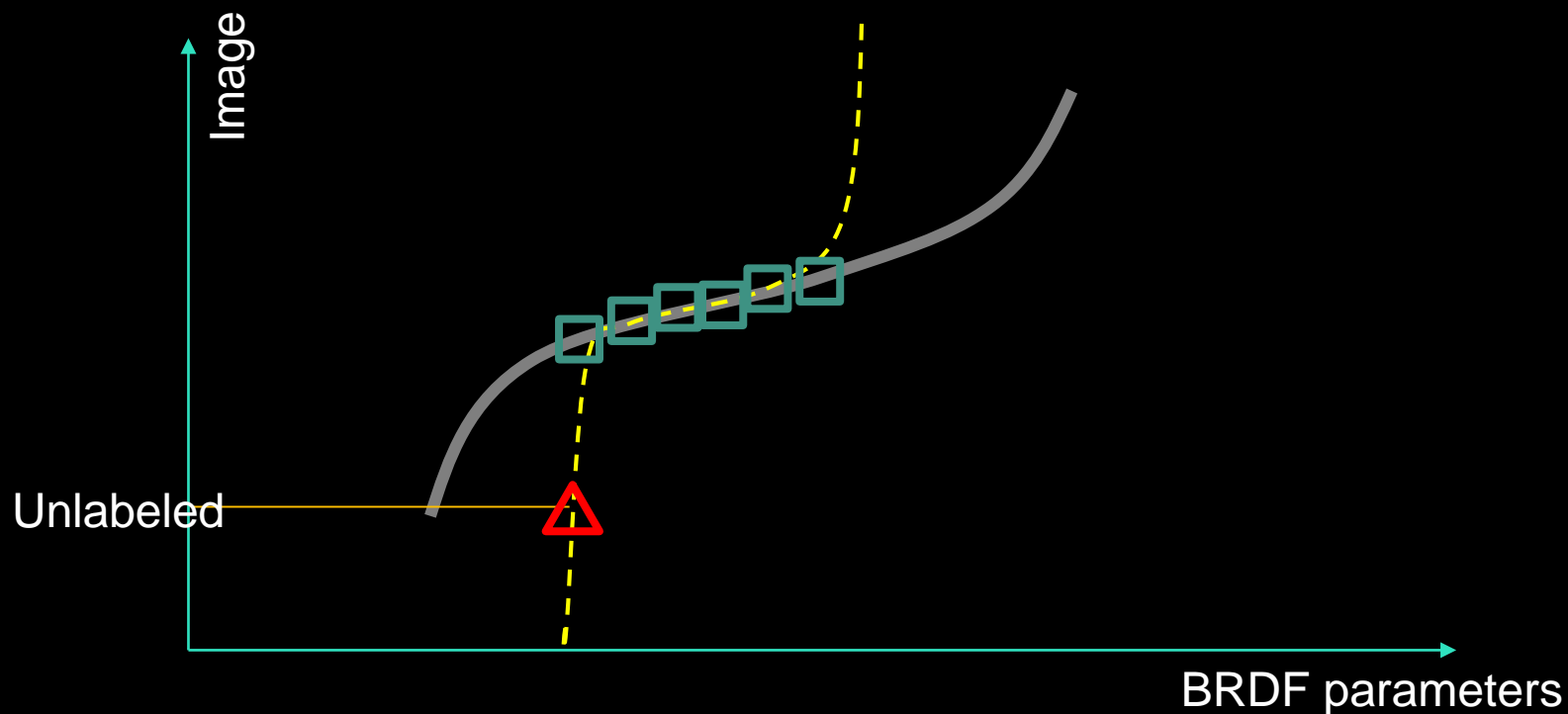
- Exploring the **meaningful domain**
- Defined in **high dimensional space**



The pitfall

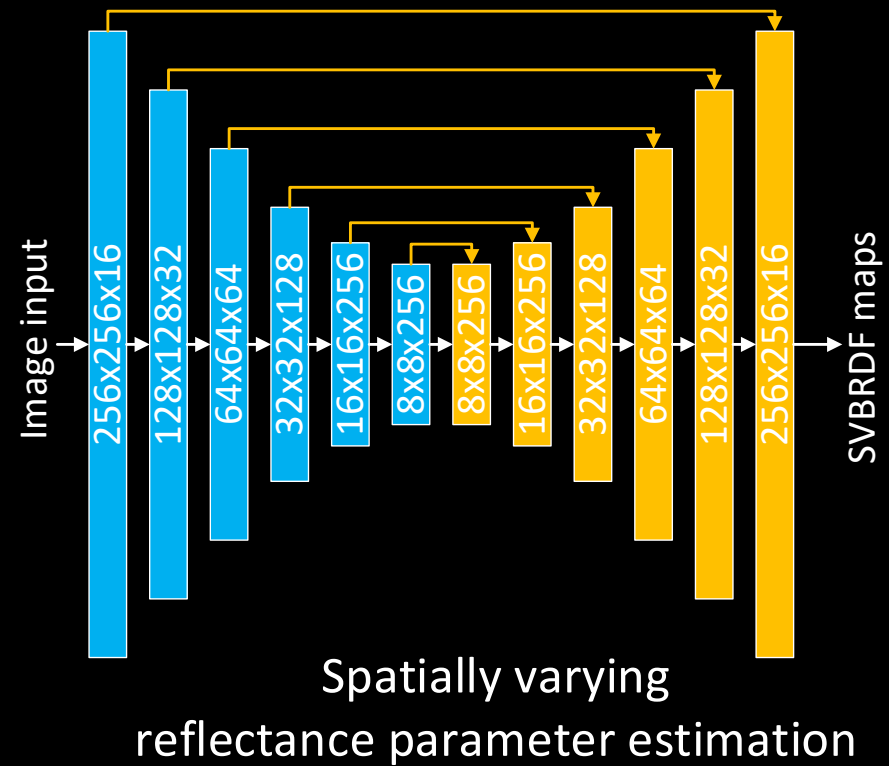
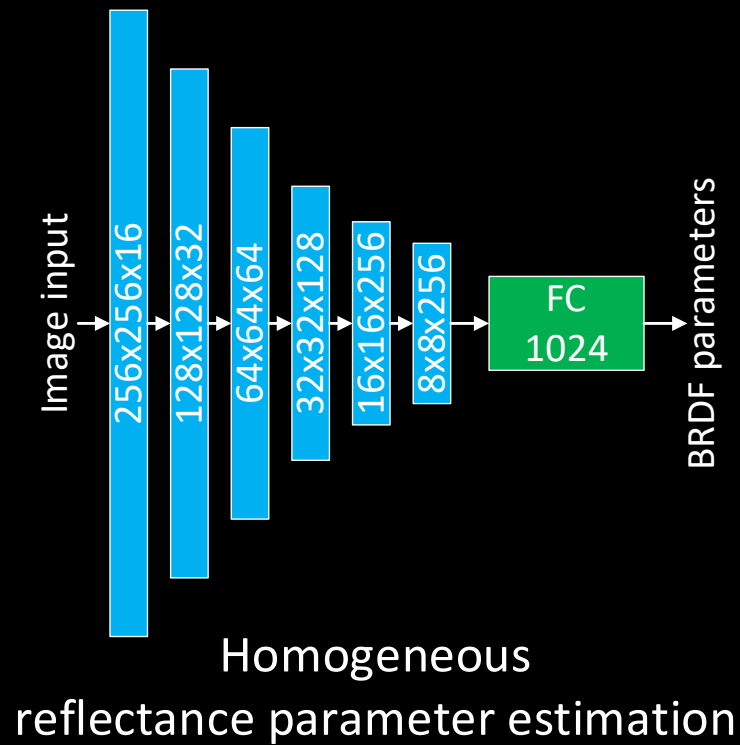


- Local minimal / model collapsing
 - Interleave labeled & SA training minibatches



Network Structure

Fully Convolutional, U-Net



Legend	Width x Height x Channel	Operation
	Width x Height x Channel	Convolution (3x3 kernel, stride 2) + BN + ReLU
	Width x Height x Channel	Bi-linear upsample + Convolution (3x3 kernel) + BN + ReLU
	Hidden unit	Fully connection layer

Training Details

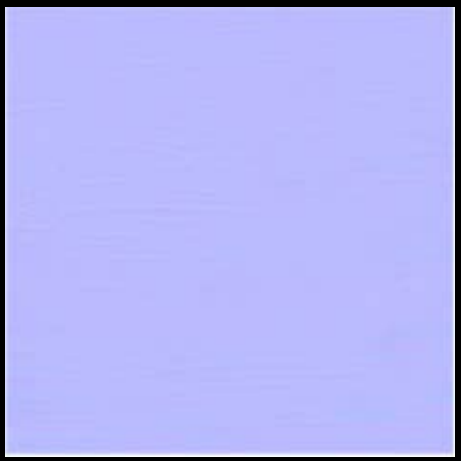
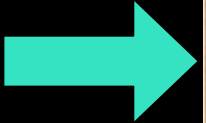


- Training data
 - Wood / Metal / Plastic
 - 60 labeled SVBRDFs
 - 1000+ unlabeled photos
 - 256*256 patch
- Performance (Titan X)
 - Training: ~40 hours
 - Inference: ~0.3 sec.

Data and Source Code:
<http://msraig.info/~sanet/sanet.htm>



Results - WOOD



Input

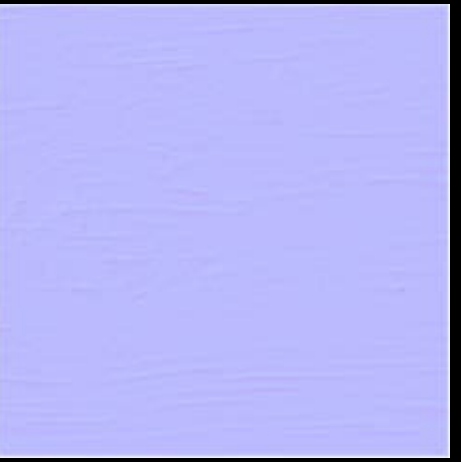
Albedo

Normal

Specular

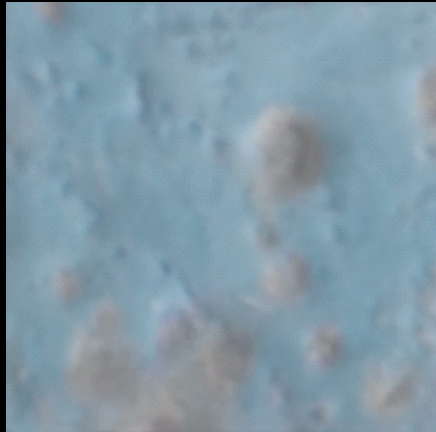
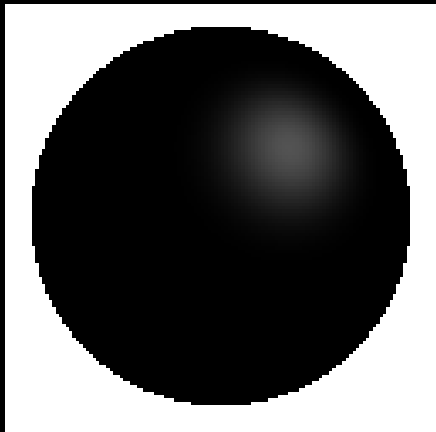
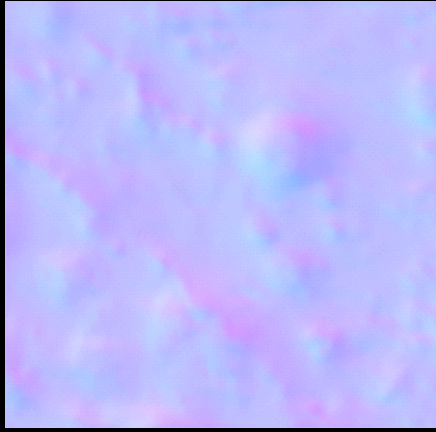
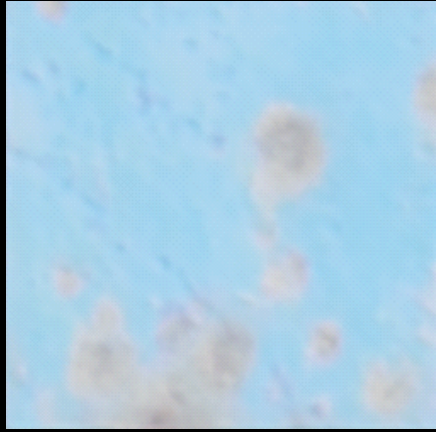
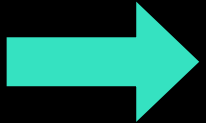
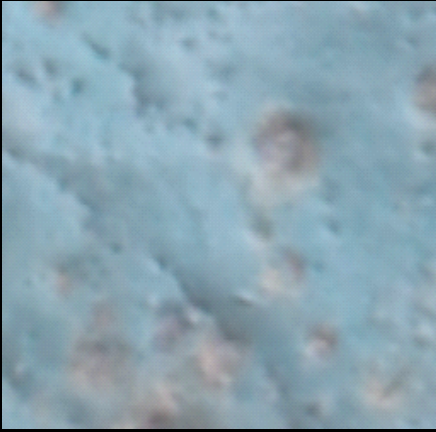
Novel lighting

Reference
(Modeled by Artist)





Results - METAL



Input

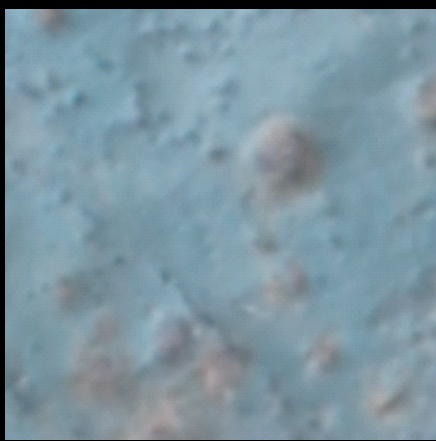
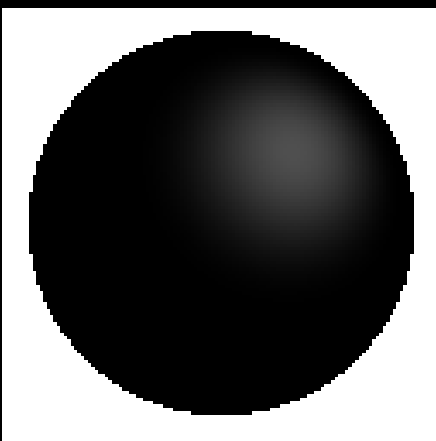
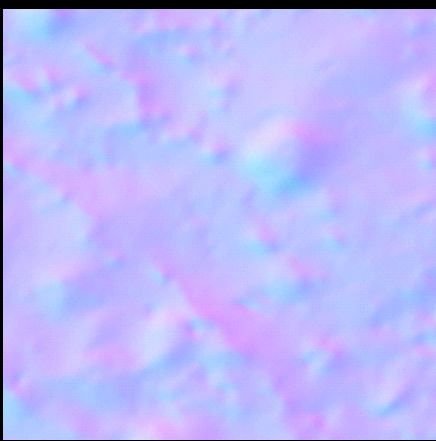
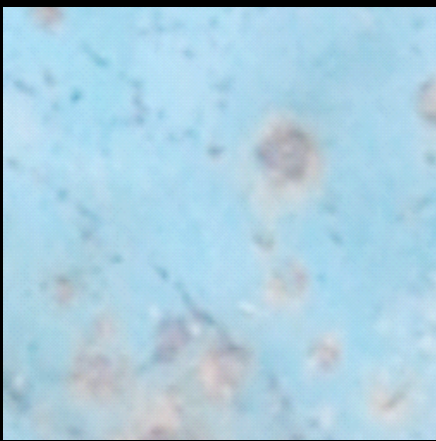
Albedo

Normal

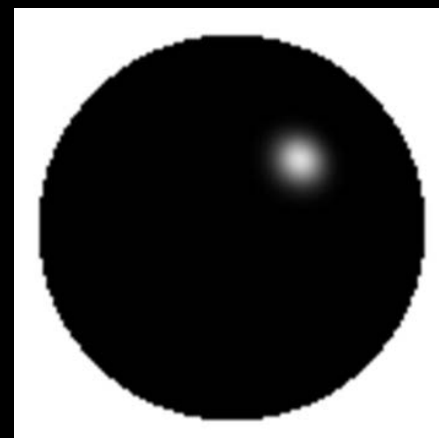
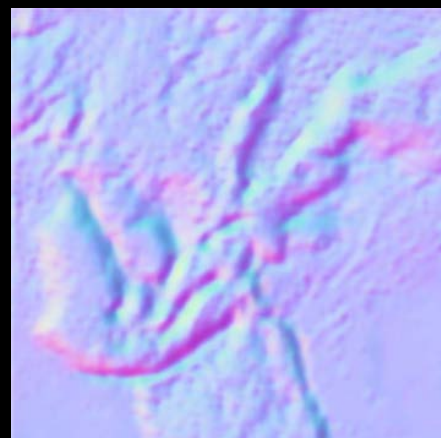
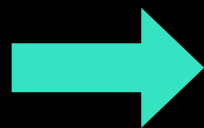
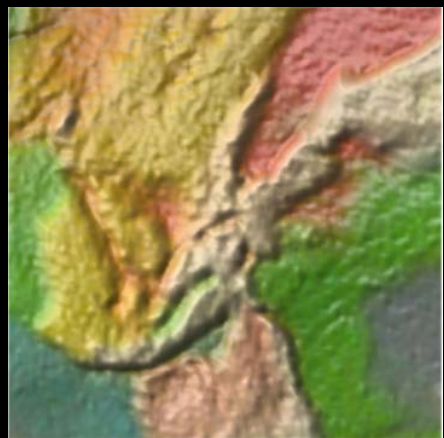
Specular

Novel lighting

Reference
(Modeled by Artist)



Results - PLASTIC



Input

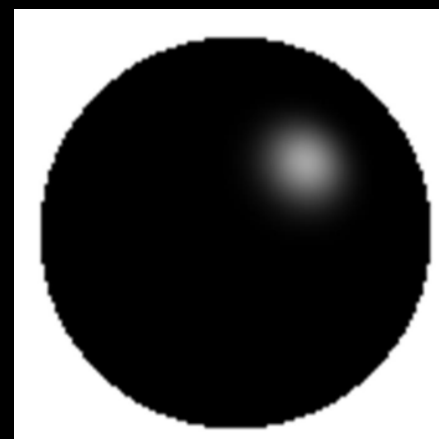
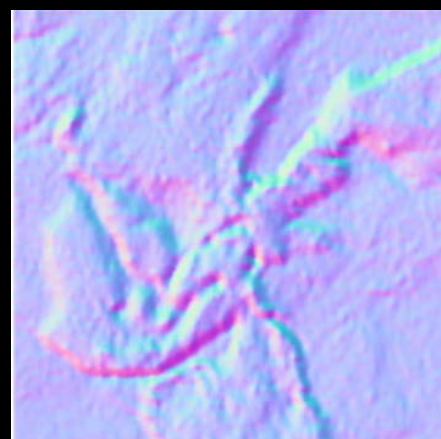
Albedo

Normal

Specular

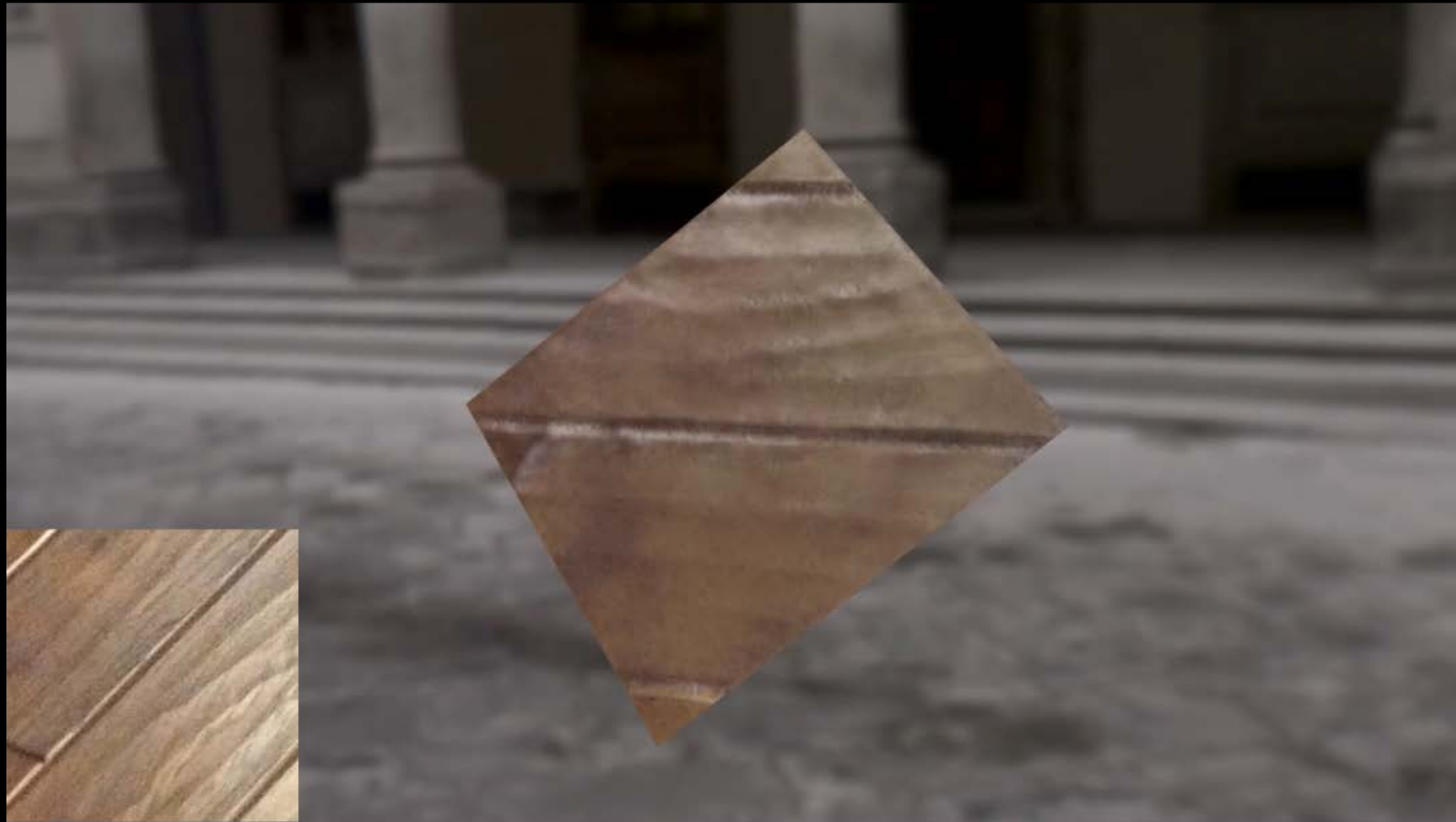
Novel lighting

Reference
(Modeled by Artist)





Relighting Video





Benefit of Self-Augmentation



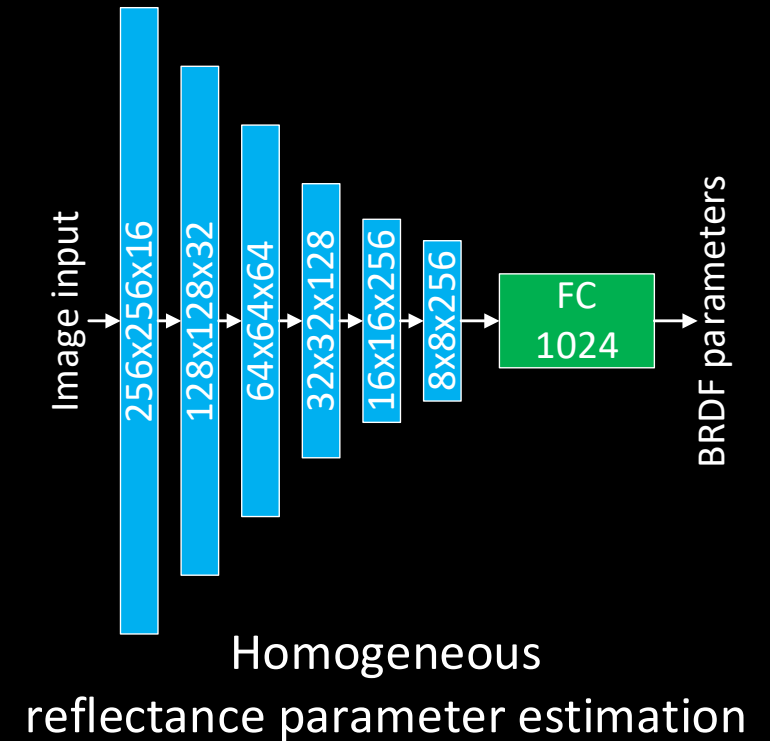
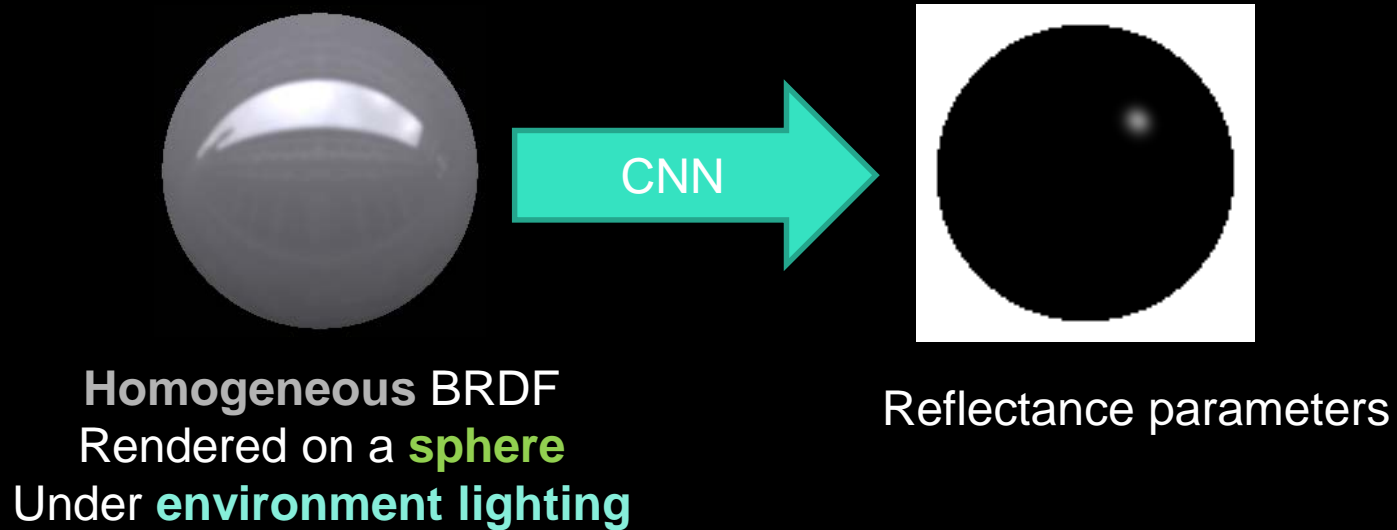
Input

SA-SVRDF-net					With Self-Augmented Training
SVRDF-net					Without Self-Augmented Training

BRDF-Net



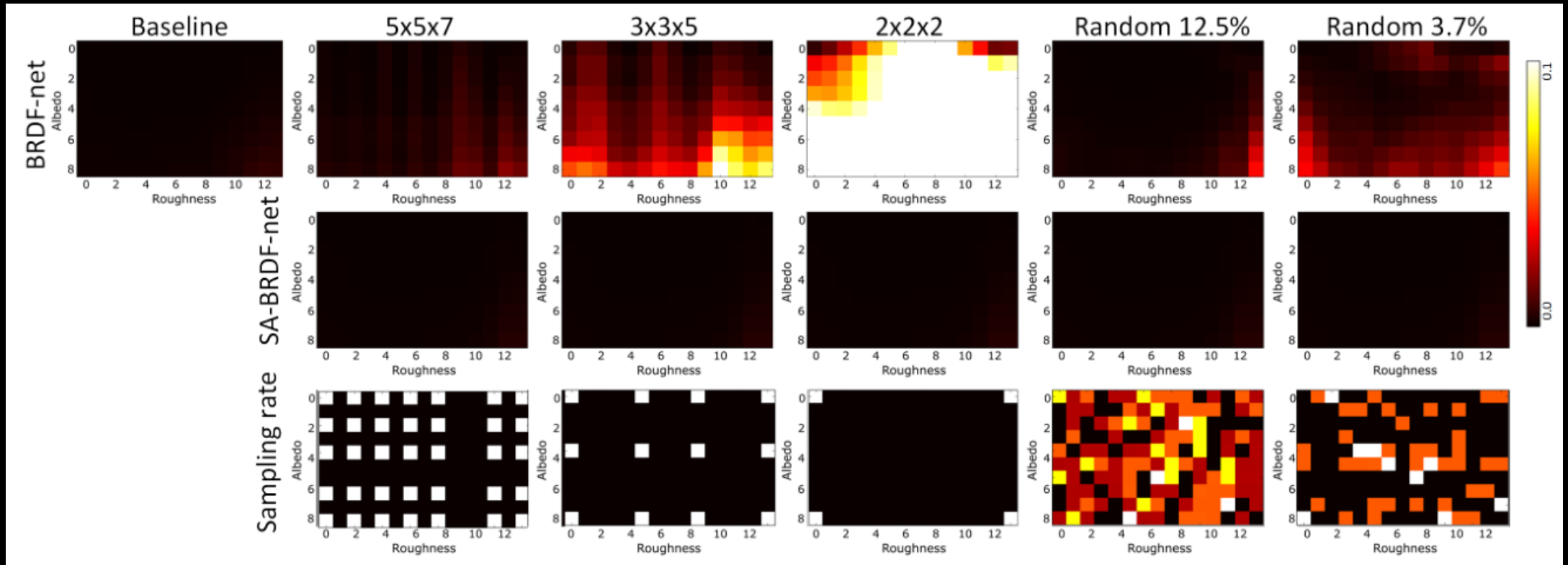
- Manageable scale problem for better understanding



BRDF-Net



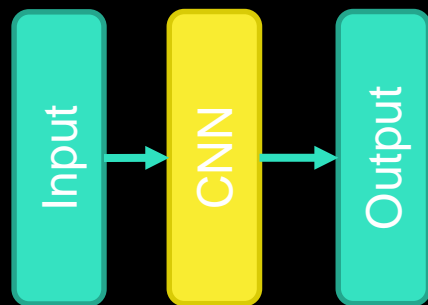
- Effects of self-augmentation
- Full labeled data vs Sparse labeled + unlabeled (rest)



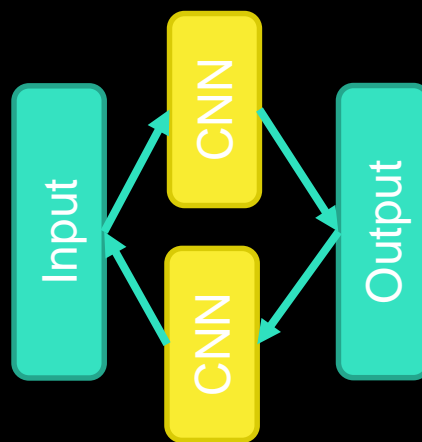
Self-augmentation vs dual learning



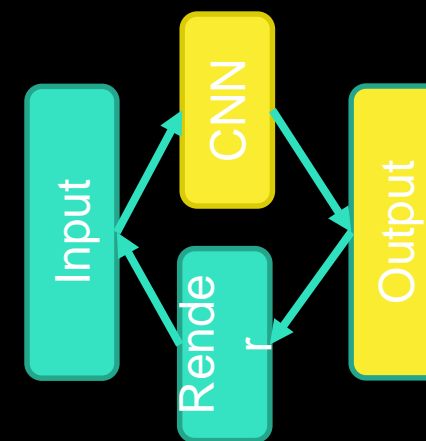
- Parallel scheme
 - With different known components



Traditional training



Dual learning



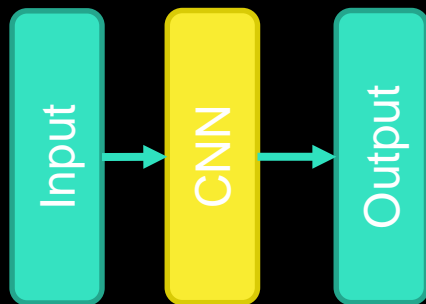
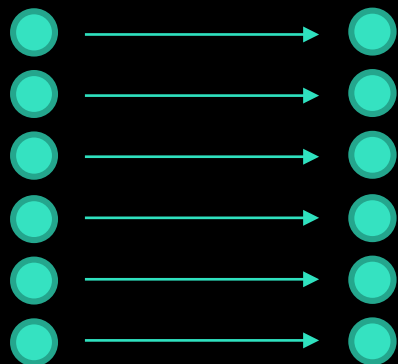
Self-augmentation

Self-augmentation vs dual learning



Rich data in both input and output

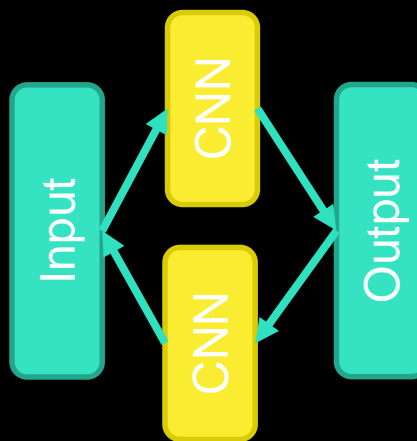
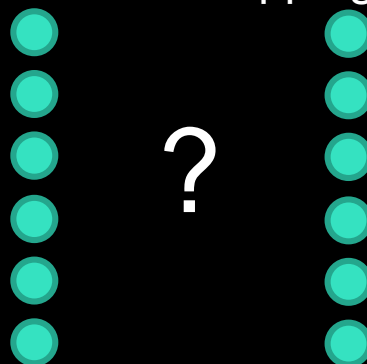
With known mapping



Traditional training

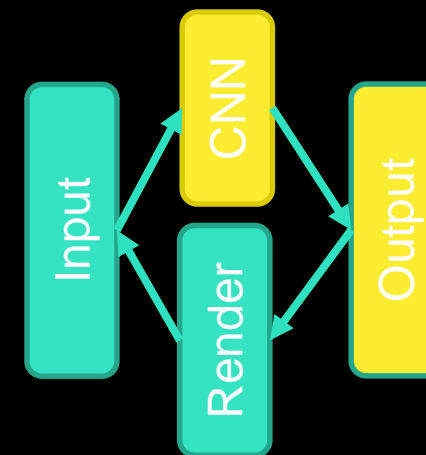
Rich data in both input and output

Learn the mapping



Dual learning

Rich data only for input



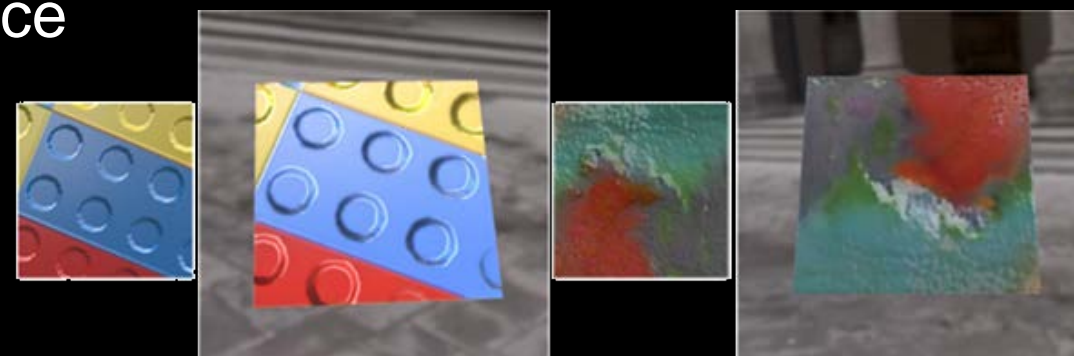
Self-augmentation



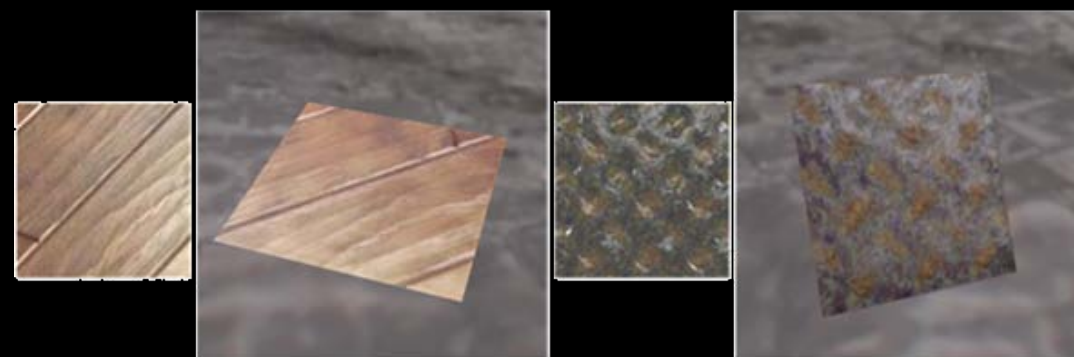
Conclusion



- Self-augmented training
 - Single image => Plausible appearance
 - Labeled + Unlabeled training



- Future Work
 - More complex surface appearance
 - Self-augmentation for other tasks





Acknowledgements



- Anonymous Reviewers
- Beijing Film Academy
- NSF grant: IIS-1350323



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THANKS!



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SIGGRAPH2017

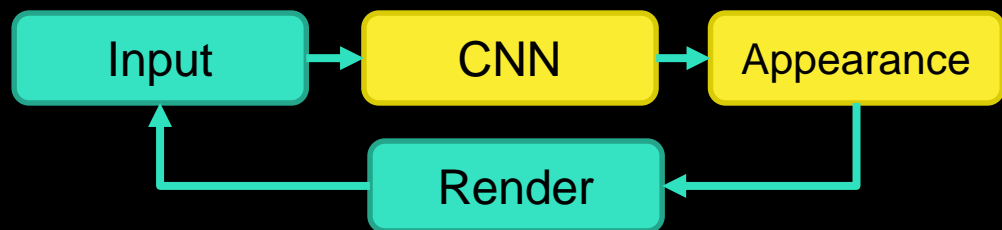
BACKUP SLIDES

Self-augmentation vs dual learning



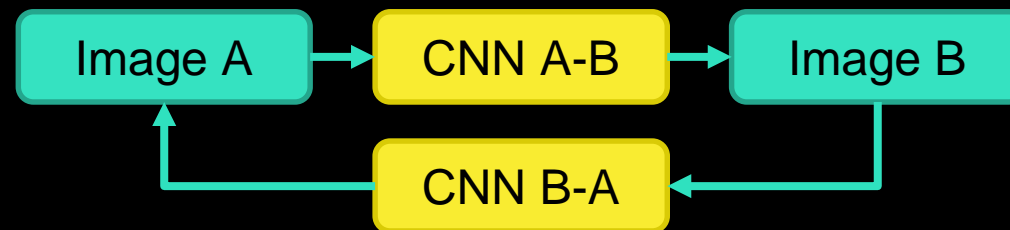
Self-augmentation

- Unlabeled Input
- Known Inverse Mapping



Dual learning

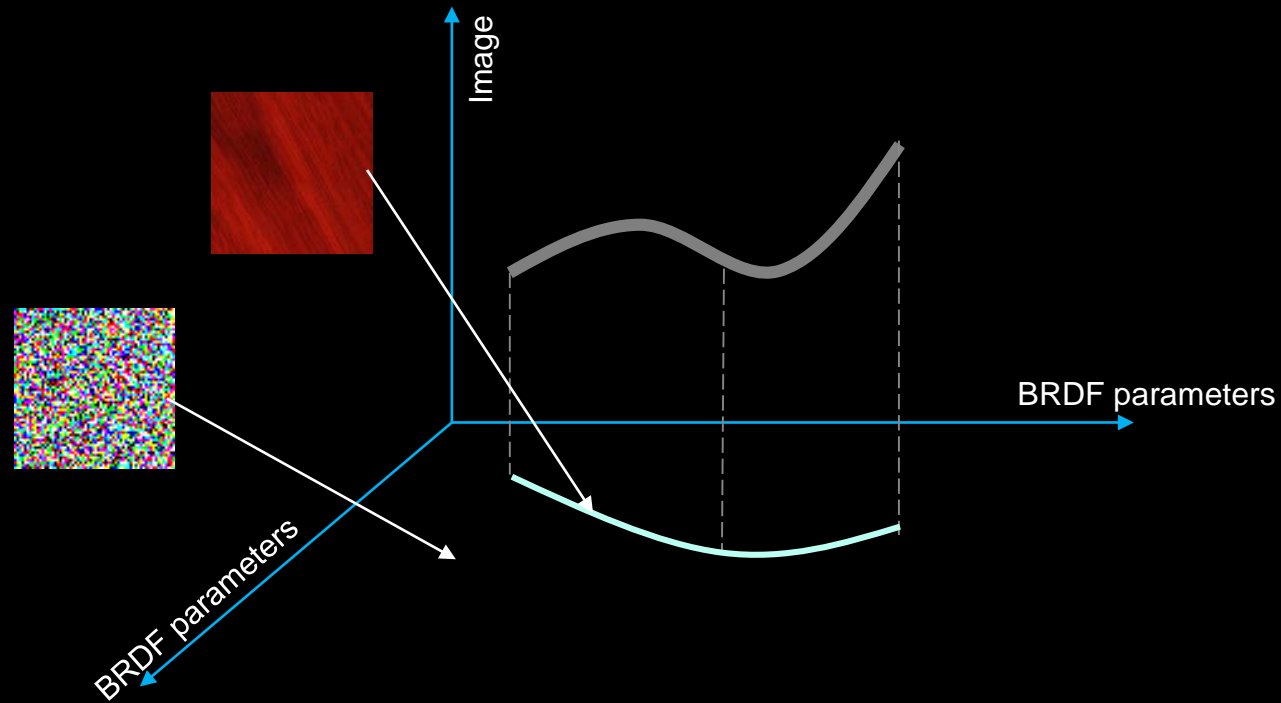
- Unlabeled on two tasks
- Trained dual tasks



Discussion



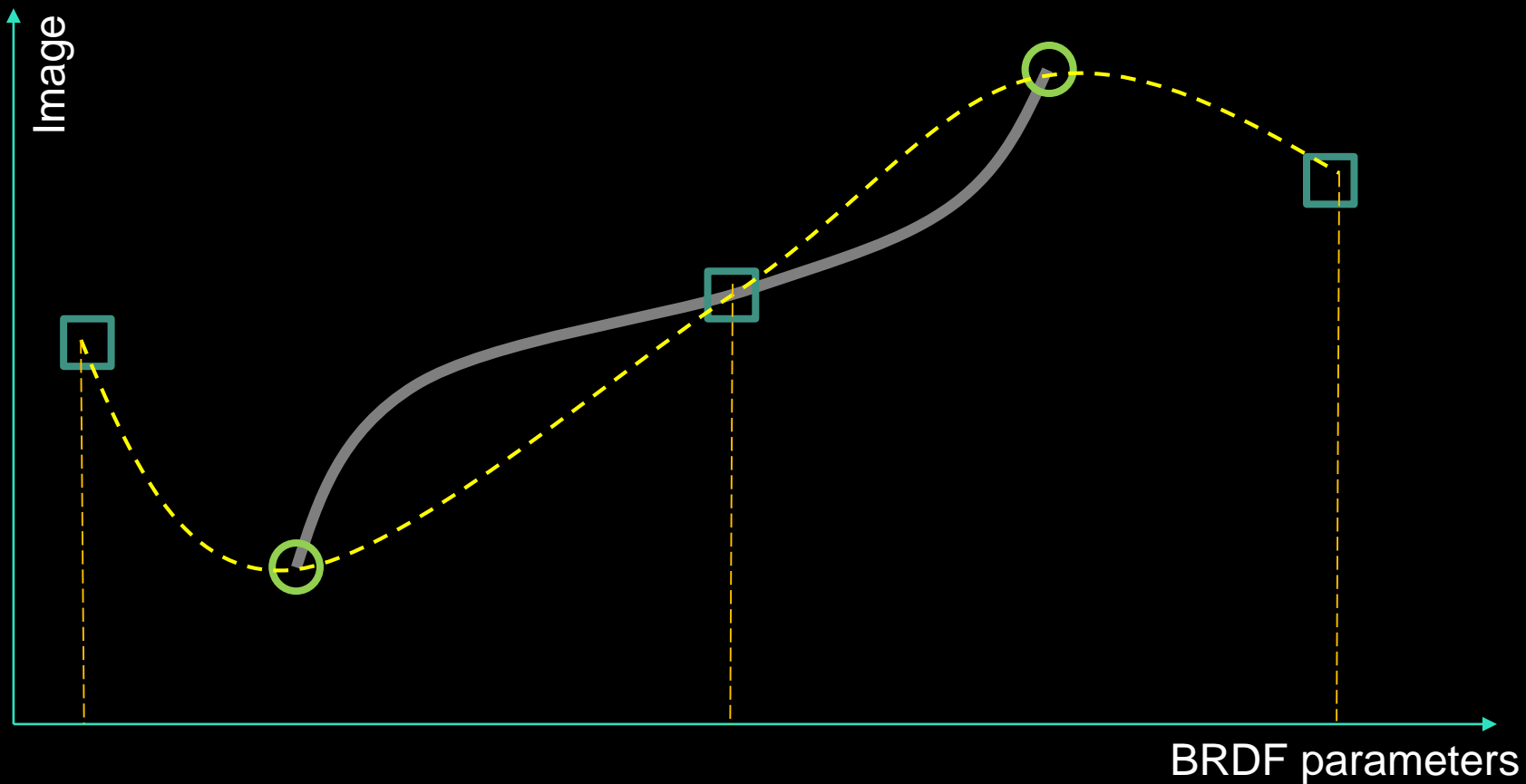
- Exploring the **meaningful domain** defined in **high dimensional** space



SOLUTION: Self-Augment Training



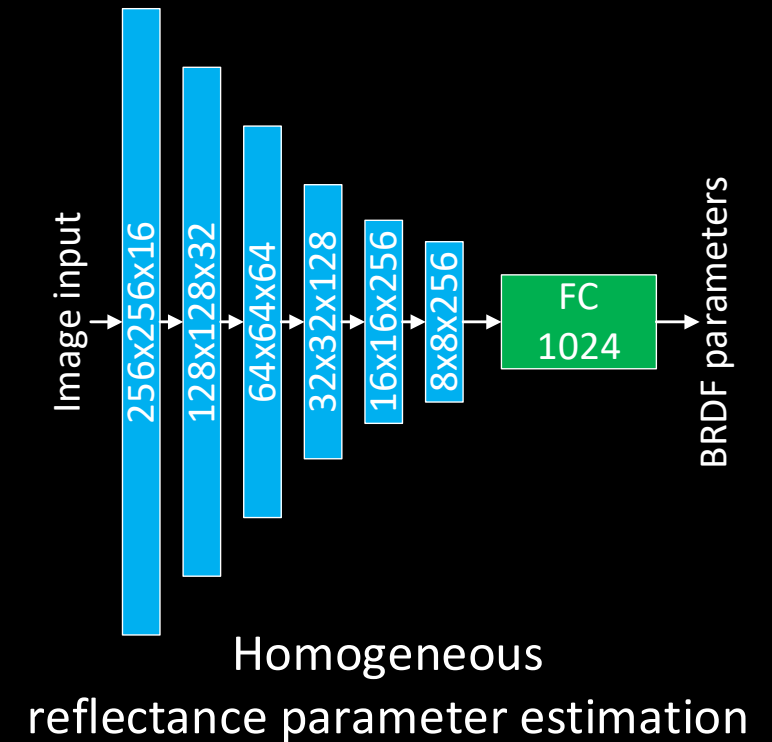
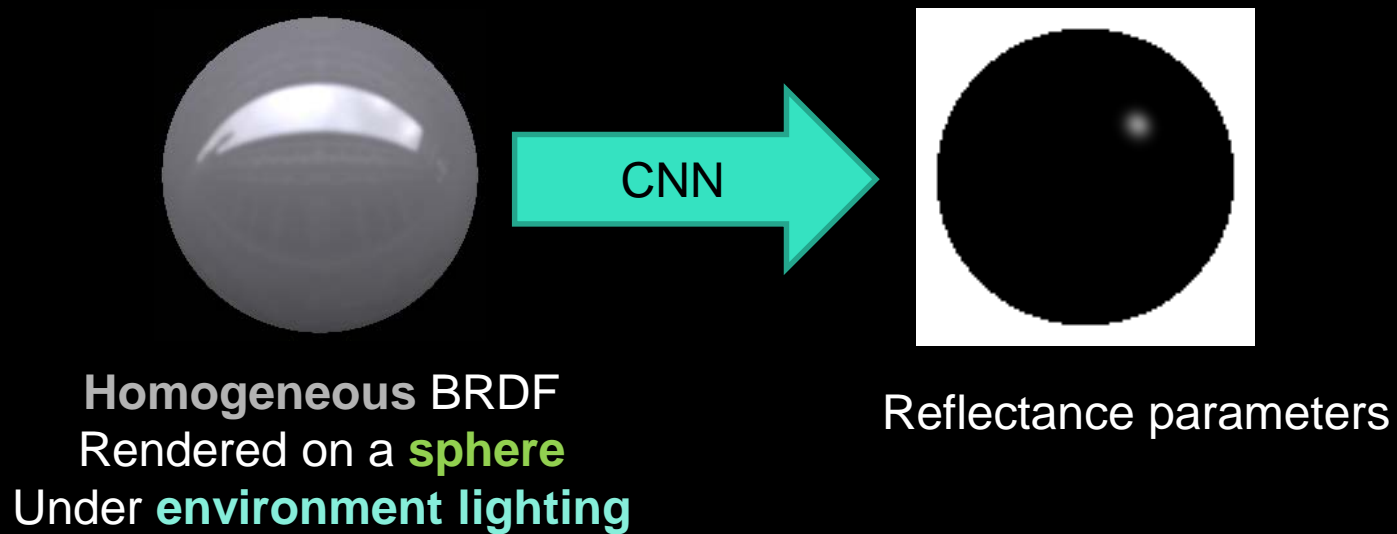
- An 1D illustration



Validation: BRDF-NET



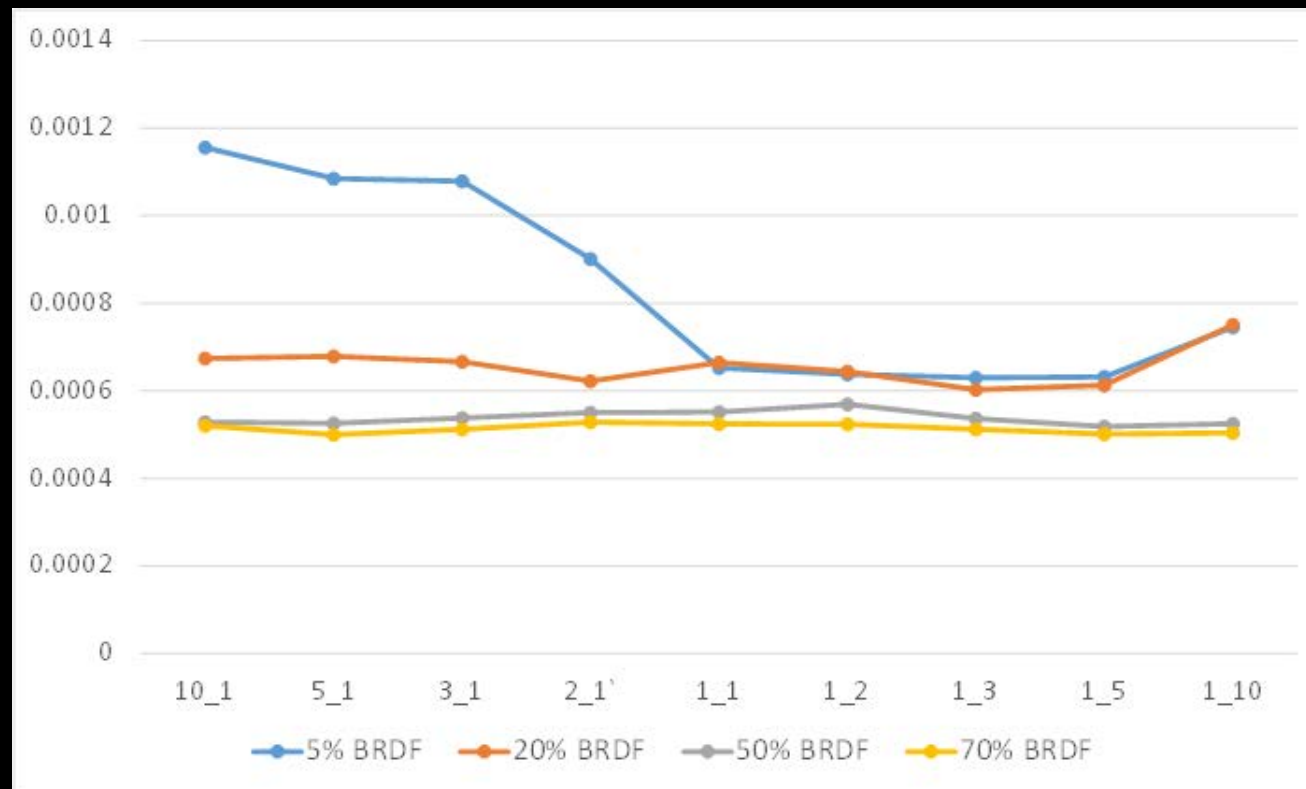
- Manageable scale problem for better understanding



Validation: BRDF-NET



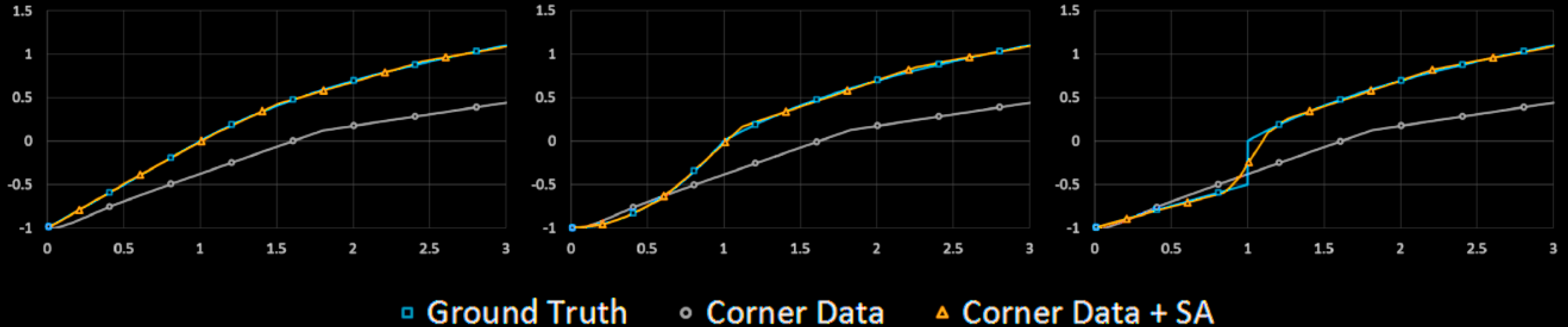
- Interleave training ratio between unlabeled / labeled data



SOLUTION: Self-Augment Training



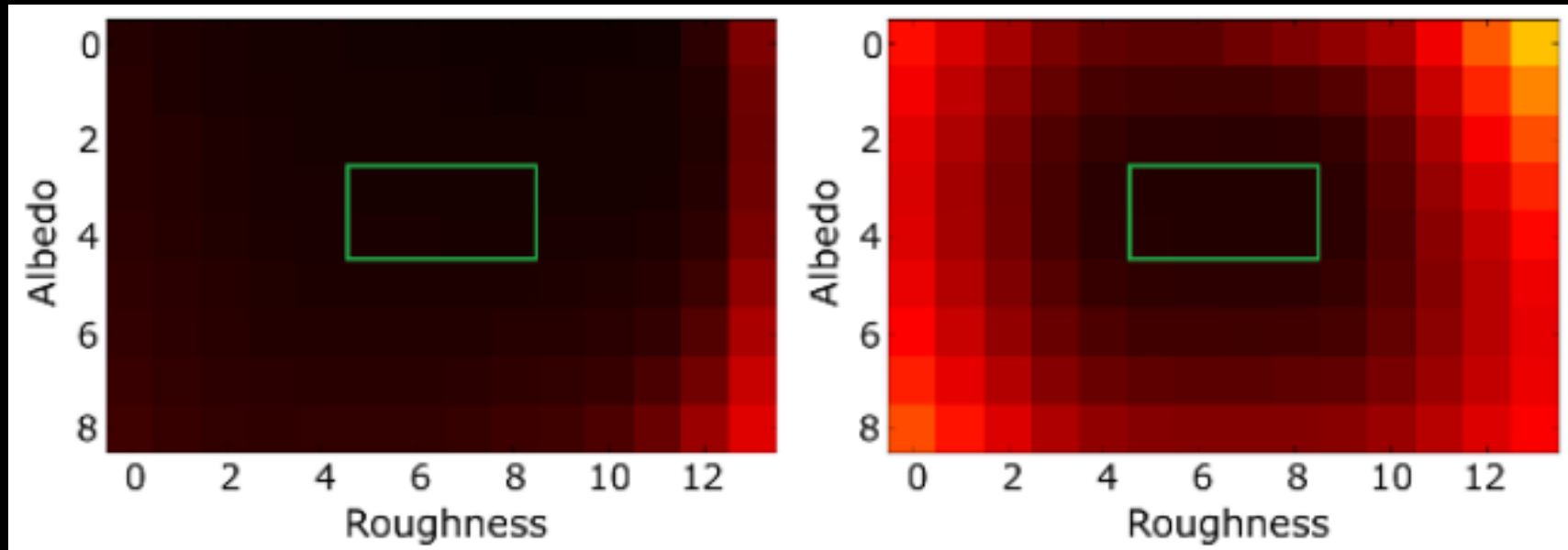
- An 1D training illustration
 - Regression with 2 layer MLP
 - Only 2 labeled data at the ends / unlabeled data for full range



Vaildation: BRDF-NET



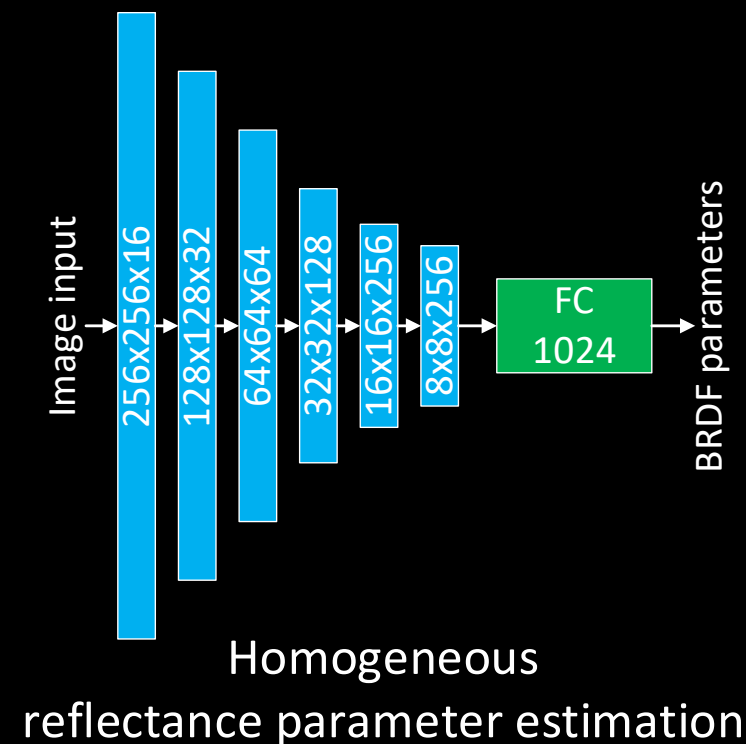
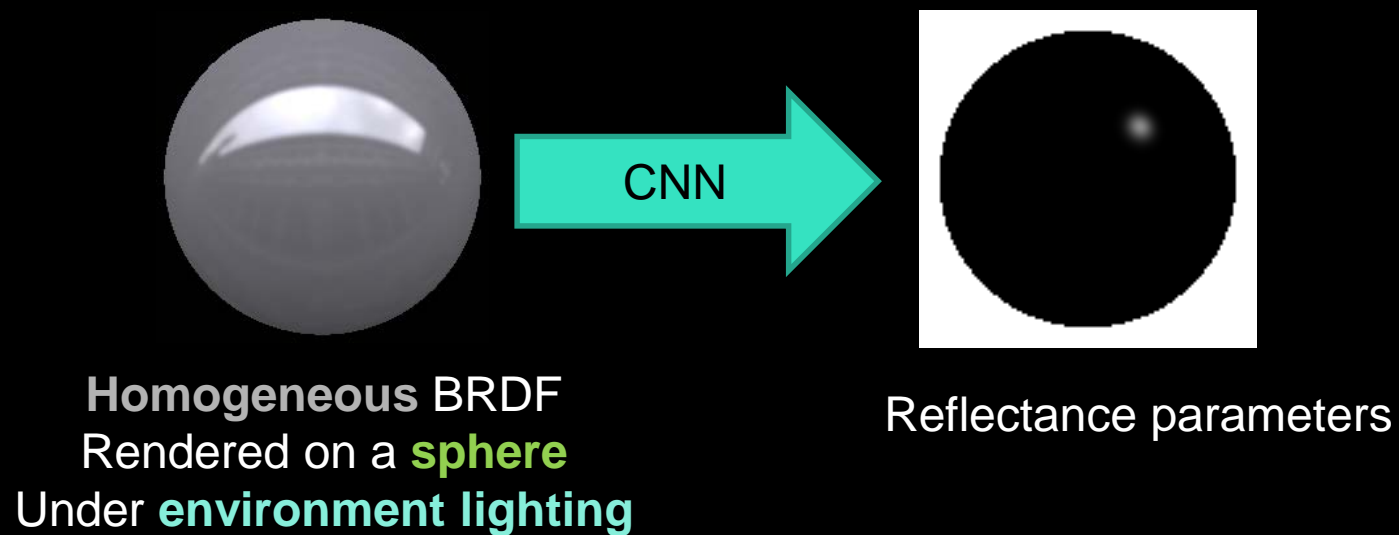
- Vaildation on convex hull assumption



In-Depth Validation of SA scheme



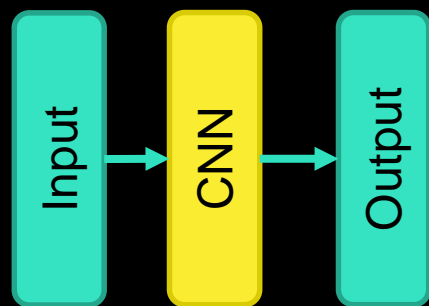
- Convex Hull
 - labeled data should cover whole space
- Interleave ratio
 - 1 : 1



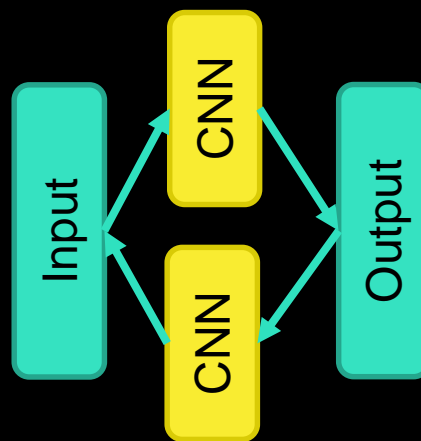
Self-augmentation vs dual learning



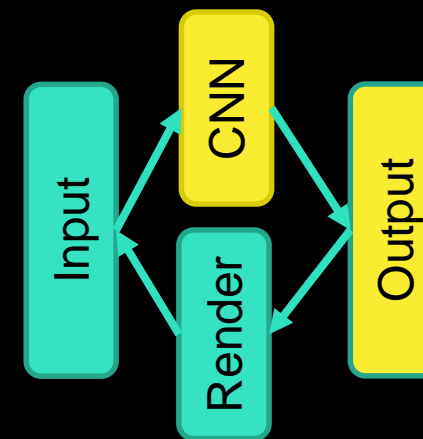
- Unlabeled Input
- Known Inverse Mapping
- Unlabeled on two tasks
- Trained dual tasks



Traditional training



Dual learning



Self-augmentation

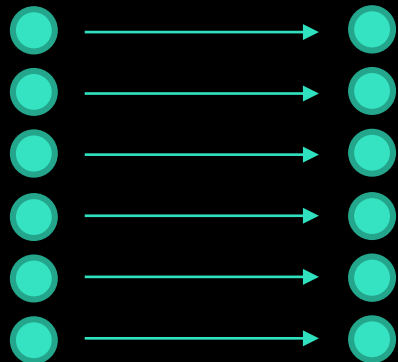
Discussion



- Self-augmentation vs dual learning

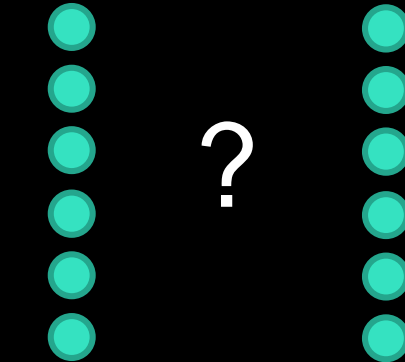
Traditional training

Rich data in both input and output
With known mapping



Dual learning

Rich data in both input and output
Learn the mapping



Self-augmentation

Rich data only for input

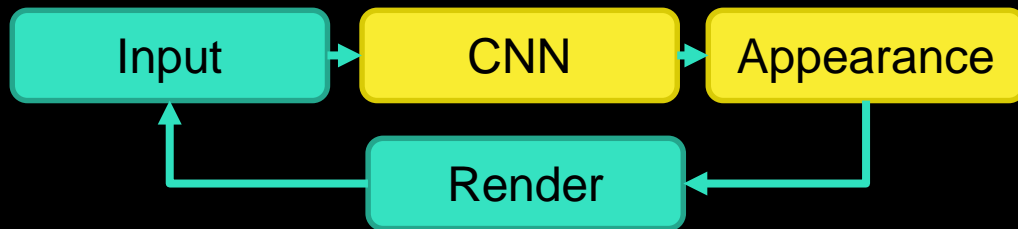


Discussion



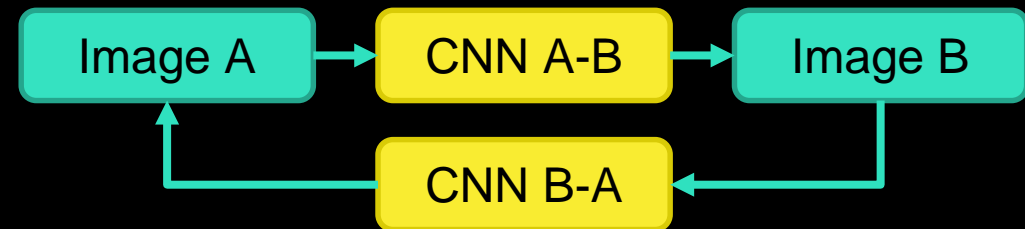
Self-augmented training

- Unlabeled input
- Known inverse mapping

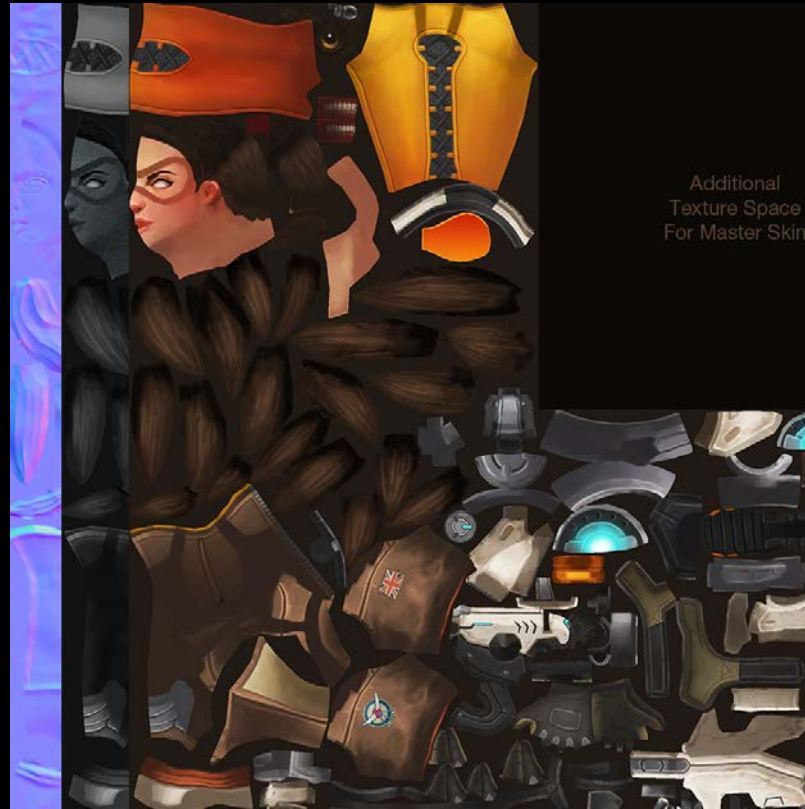


Dual learning

- Unlabeled on two sets
- Trained dual tasks

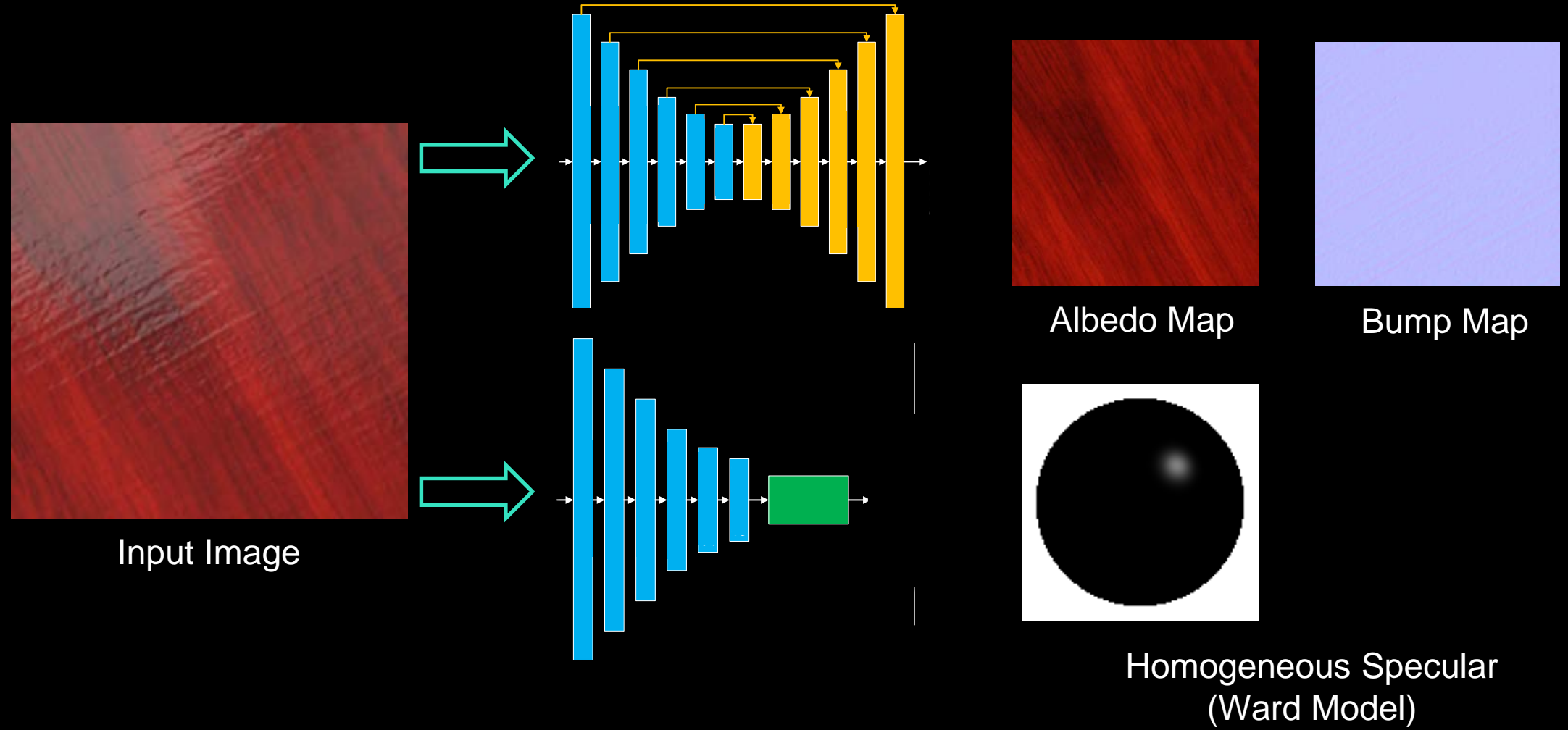


Motivation – Appearance Modeling





Modeling Appearance by CNN





BENEFIT of Self-Augmentation



Input	Diffuse albedo	Normal map	Specular	Novel lighting	
					Reference
					With Self-Augmented Training
					Without Self-Augmented Training