

# Video Based Reconstruction of 3D People Models

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# Motivation

## Applications of 3D Human Model



© Fitnect via youtube.com

VR/AR



© Mario Botsch et al

Medicine and self-perception



© Oculus VR

Telepresence

# Previous works

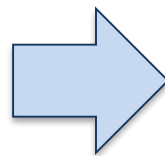
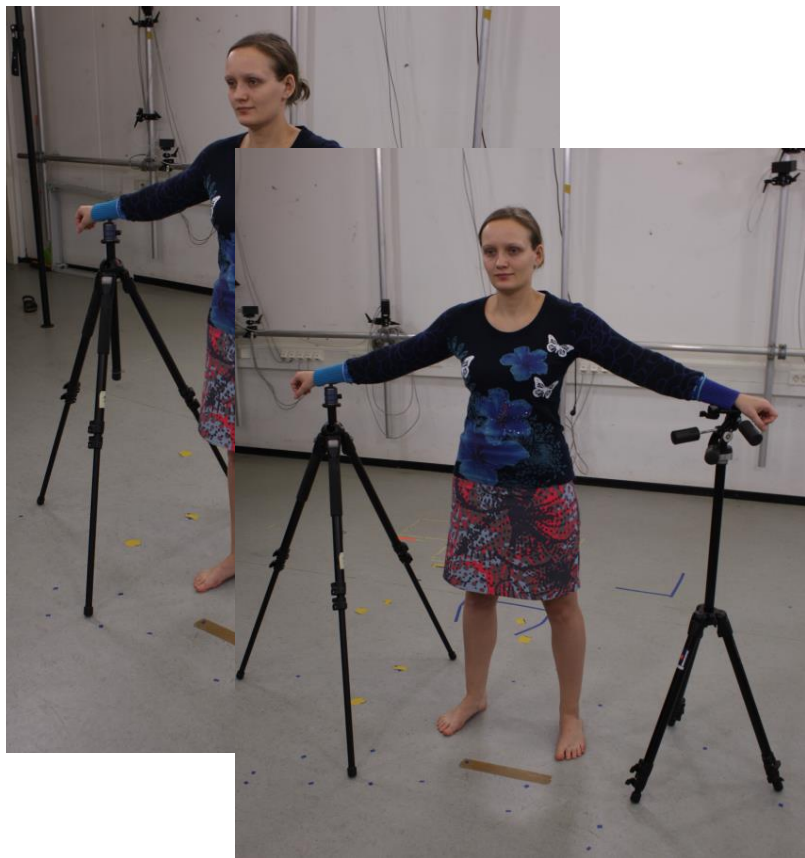
- 3D body scanner



© Twindom

# Previous works

- Monocular 3D reconstruction



Human body is not rigid!

# Previous works

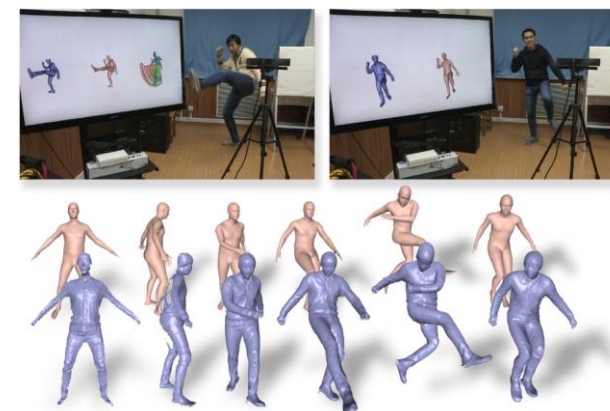
- Depth based



© 3D Self-Portraits, Li et al



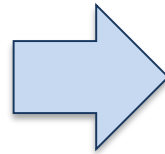
© DynamicFusion, Newcombe et al



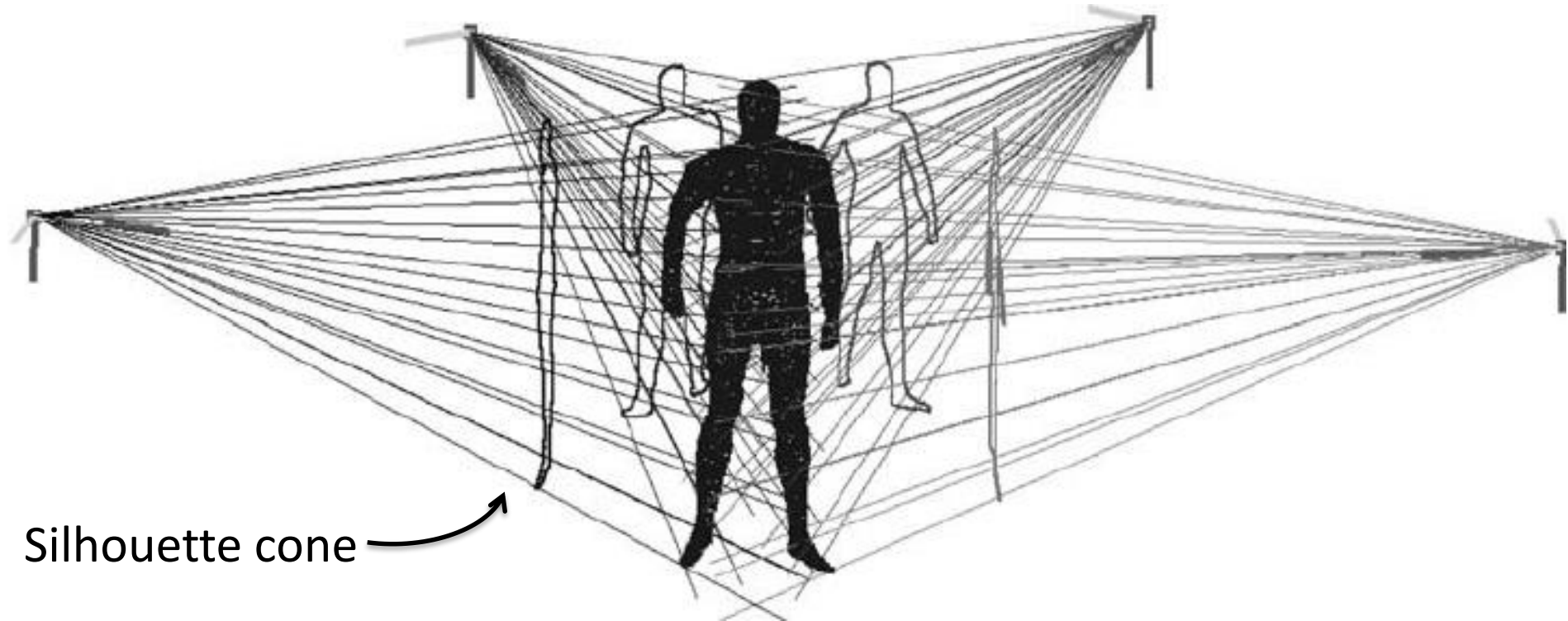
© DoubleFusion, Yu et al

Goal:

3D Reconstruction from a **Single RGB Video of Moving People in Clothes**



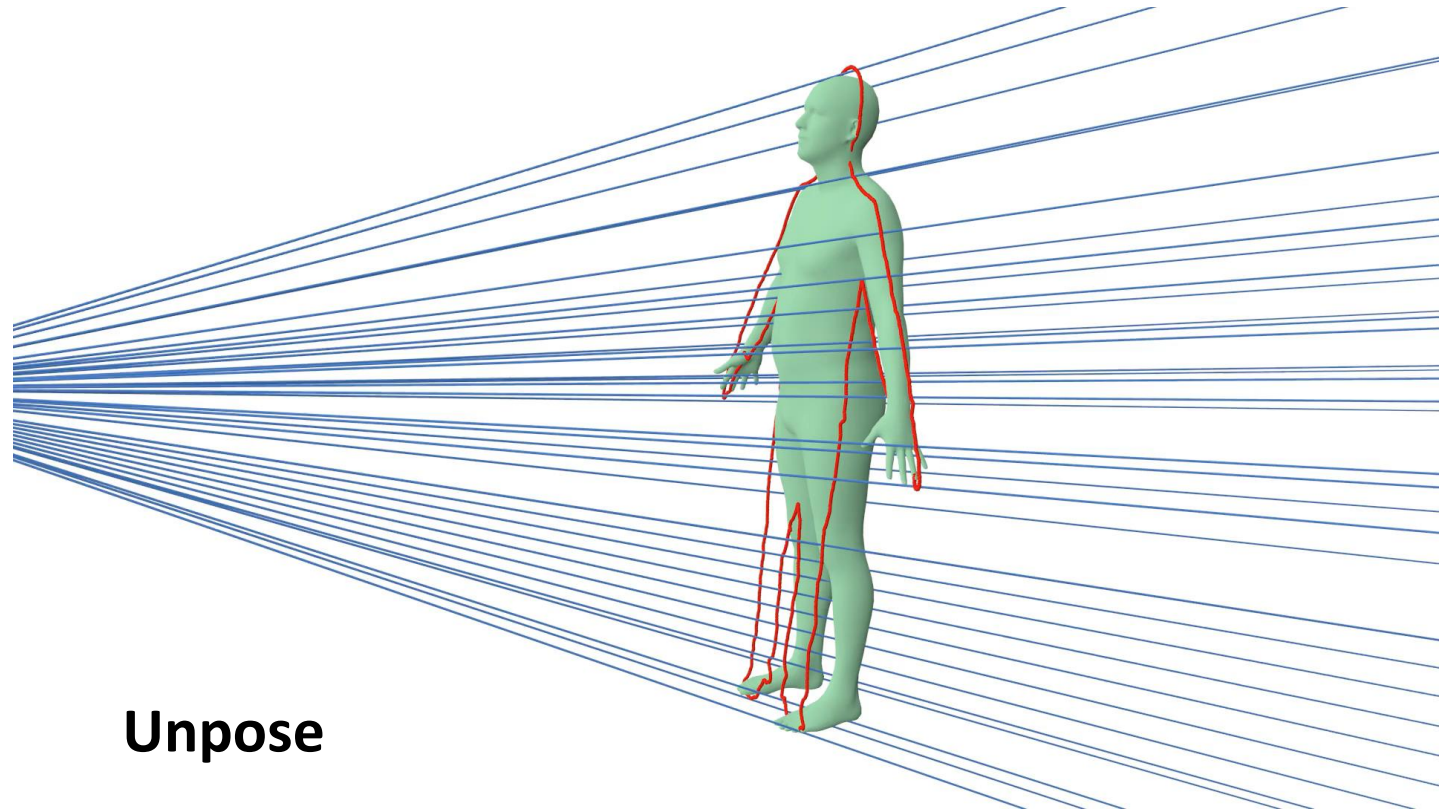
# Key idea: Extend visual hulls to dynamic human motion



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**Problem:** standard visual hull requires a **static** object captured by multiple views

# Key idea: Extend visual hulls to dynamic human motion



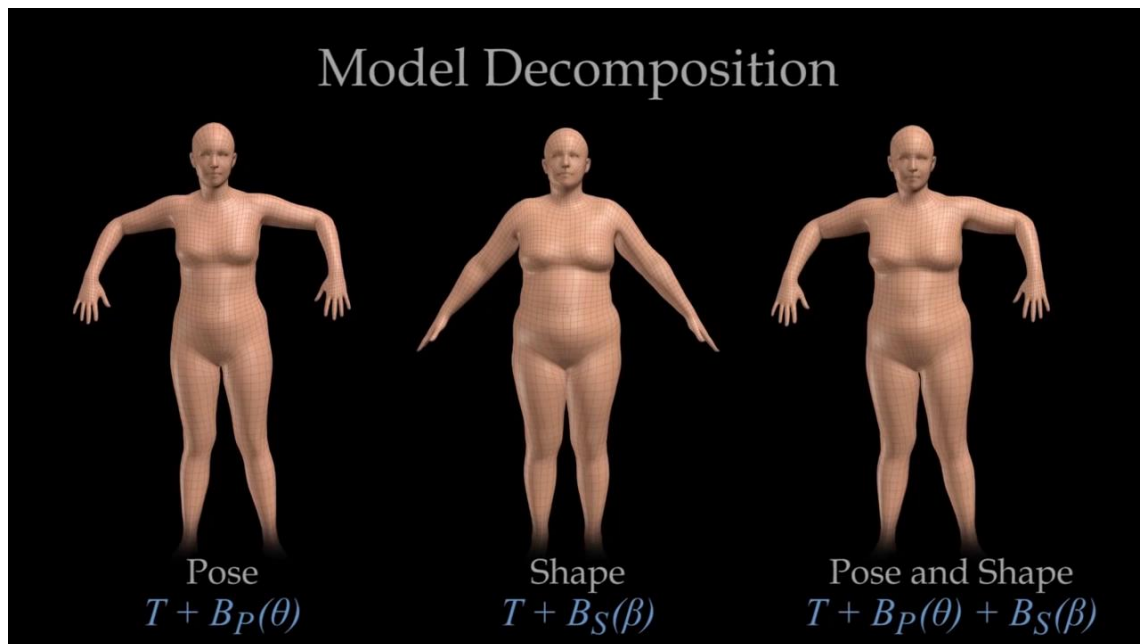
Unpose

Transform the silhouette cones according to the inverse of non-rigid motion



# Method

- Shape representative



SMPL [Loper et al, Siggraph Asia '15]

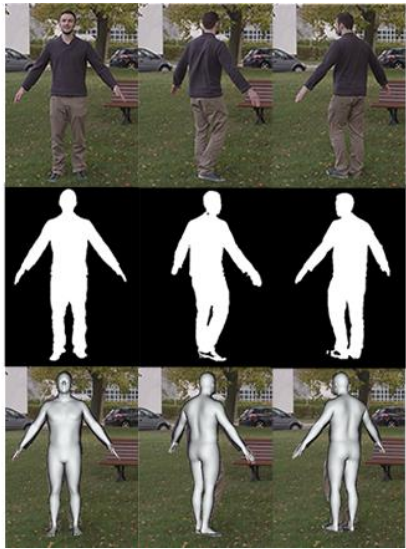
3D mesh:

$$\mathbf{T}_\mu + B_s(\beta) + B_p(\theta) + \mathbf{D}$$

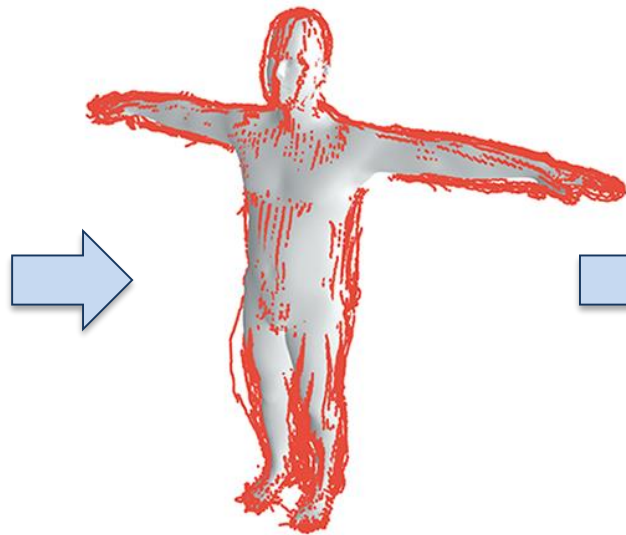
mean shape    shape    pose    offsets

*(Note: A blue bracket groups 'shape', 'pose', and 'offsets' in the original image.)*

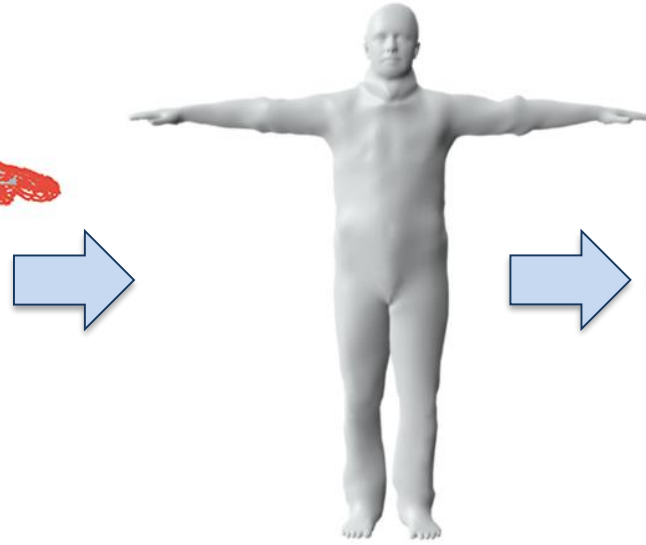
# Method



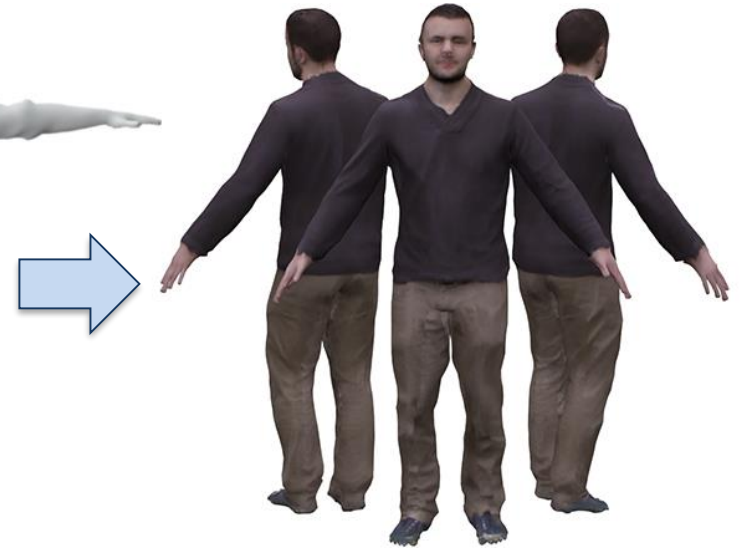
Silhouette estimation  
& Pose tracking



Silhouette cone unposing

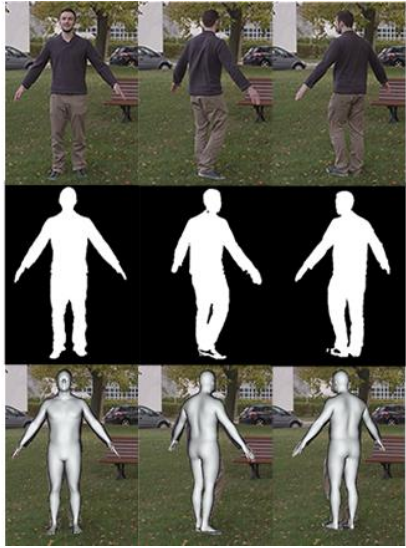


Consensus Shape  
reconstruction

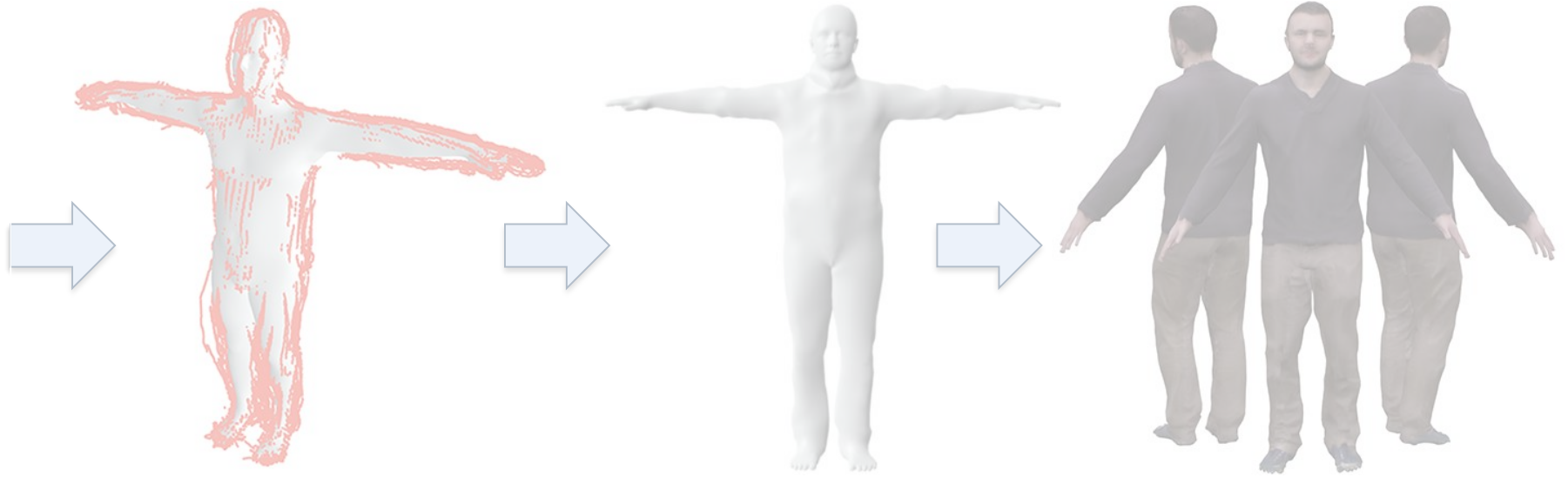


Texture generation

# Method



Silhouette estimation  
& Pose tracking



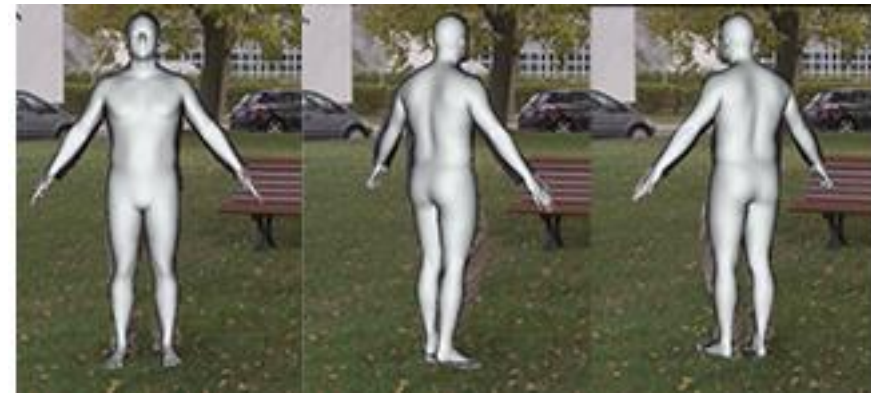
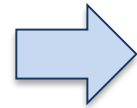
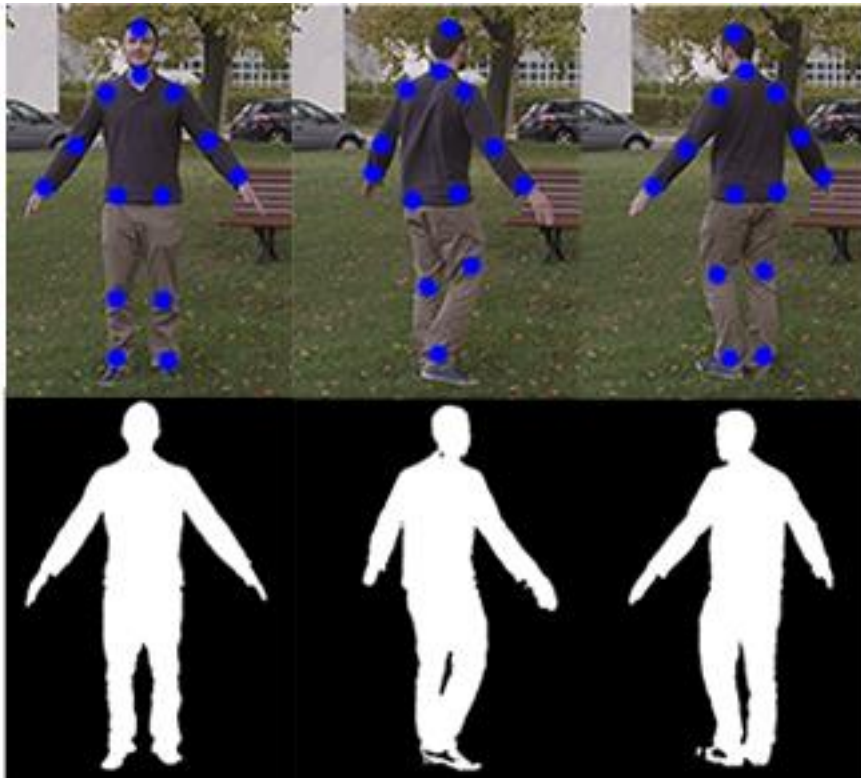
Silhouette cone unposing

Consensus Shape  
reconstruction

Texture generation

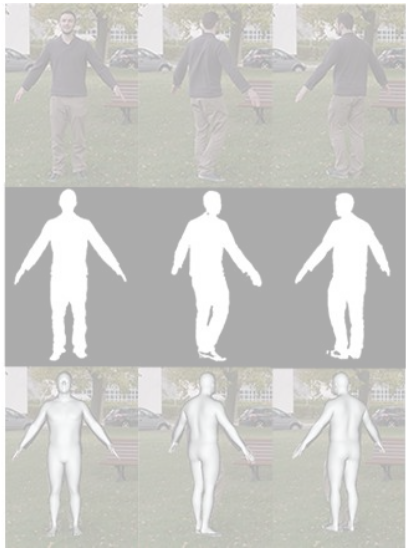
# Method

- Silhouette estimation & Pose tracking

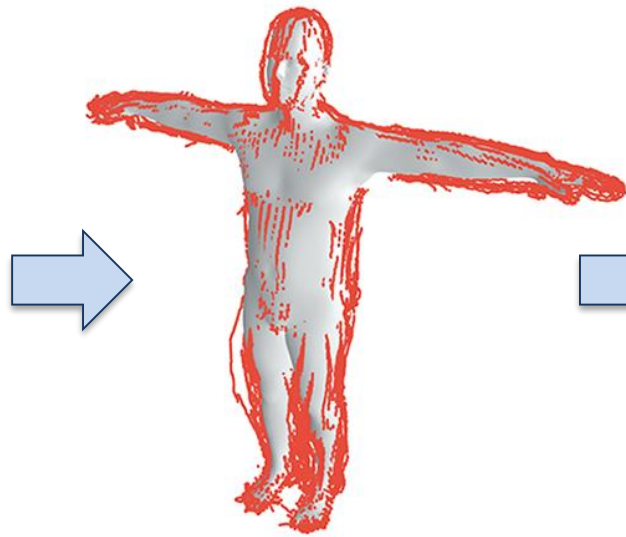


$$E_{Joint}(\theta, \beta) + E_{Silh}(\theta) + E_{Reg}(\theta, \beta)$$

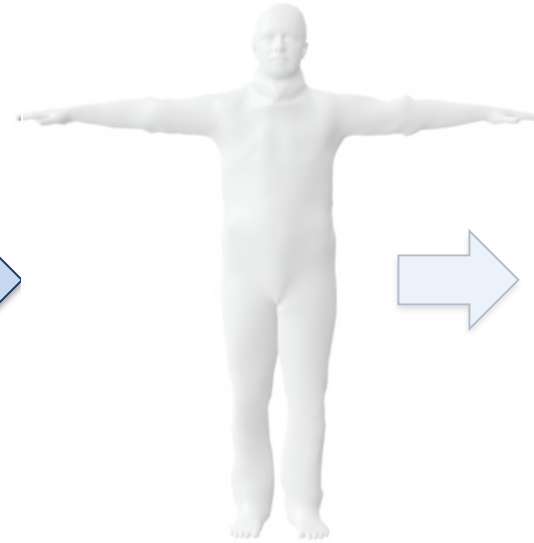
# Method



Silhouette estimation  
& Pose tracking



Silhouette cone unposing



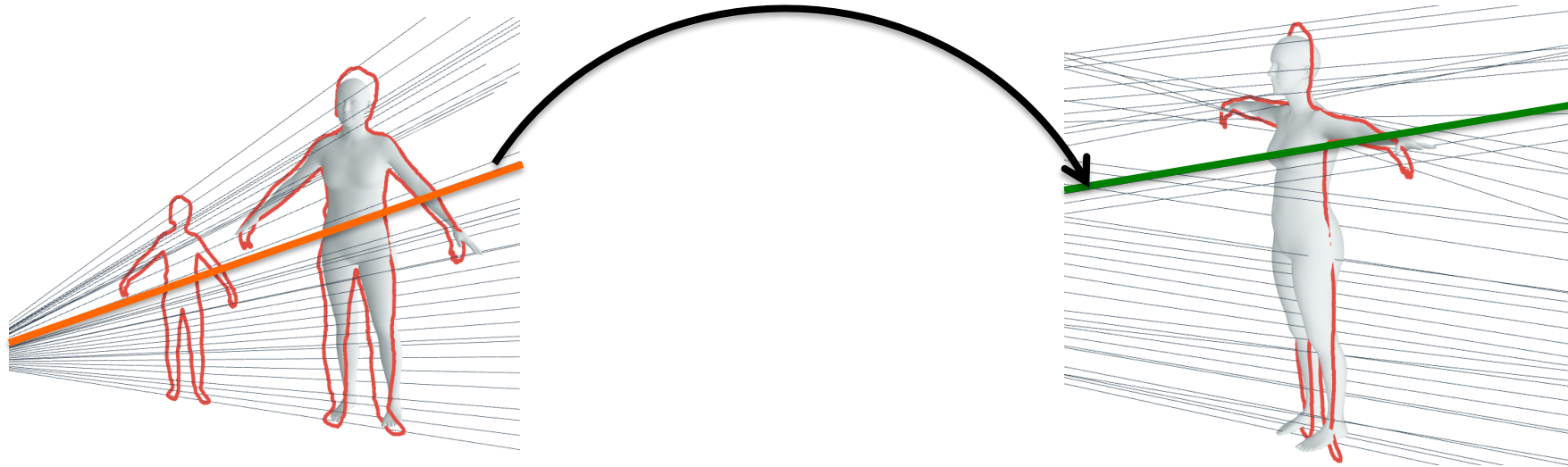
Consensus Shape  
reconstruction



Texture generation

# Method

- Silhouette cone **unposing**



# Method

- Silhouette cone **unposing**

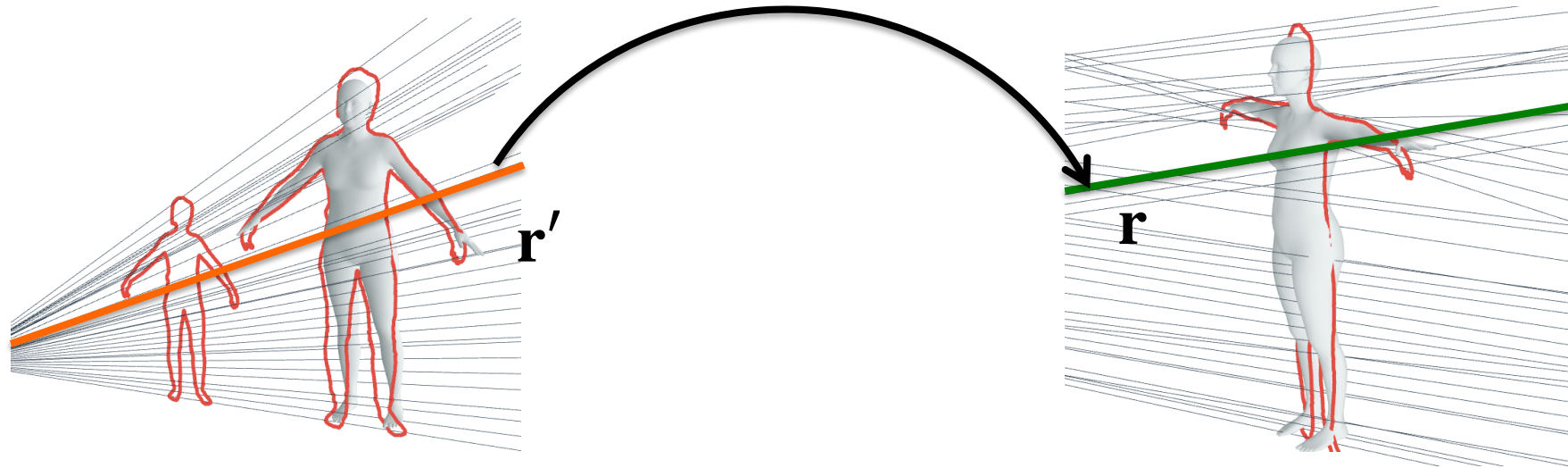


$$\boxed{\mathbf{v}'_i} = \sum_{k=1}^K w_{k,i} G_k(\boldsymbol{\theta}, J(\boldsymbol{\beta})) (\boxed{\mathbf{v}_i} + b_{s,i}(\boldsymbol{\beta}) + b_{P,i}(\boldsymbol{\theta}))$$

posed Articulated Motion unposed

# Method

- Silhouette cone **unposing**

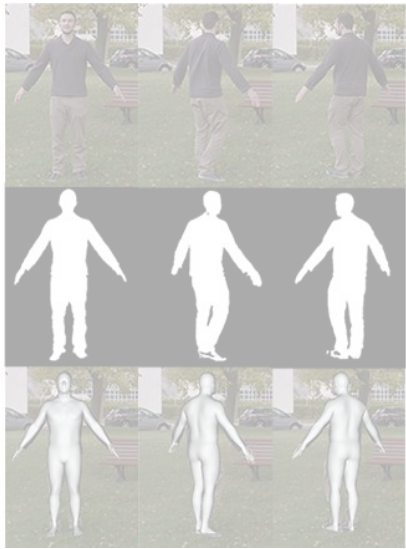


$$\mathbf{r} = \left( \sum_{k=1}^K w_{k,i} G_k(\boldsymbol{\theta}, \mathbf{J}_\beta) \right)^{-1} \mathbf{r}' - b_{P,i}(\boldsymbol{\theta}).$$

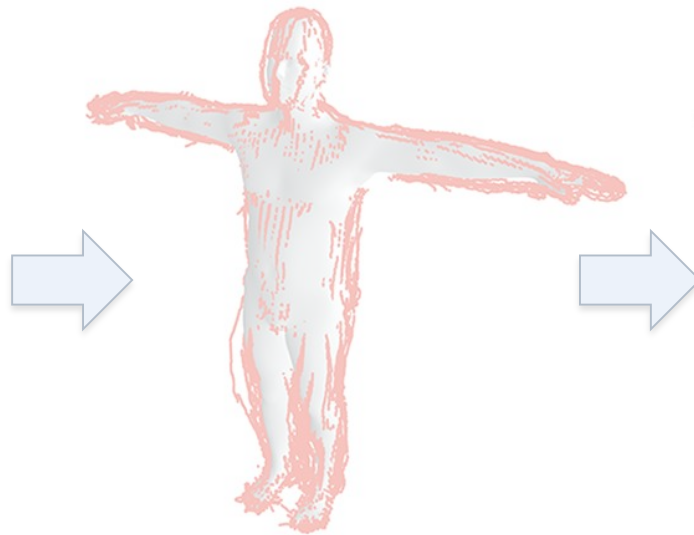
Ray in Canonical Frame      Inverse of Articulated Motion      Ray



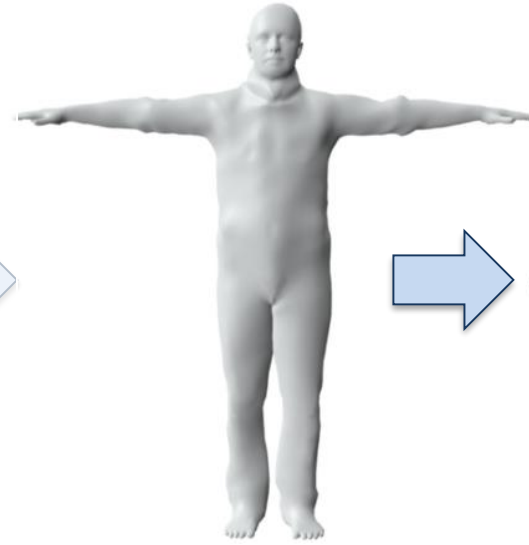
# Method



Silhouette estimation  
& Pose tracking



Silhouette cone unposing



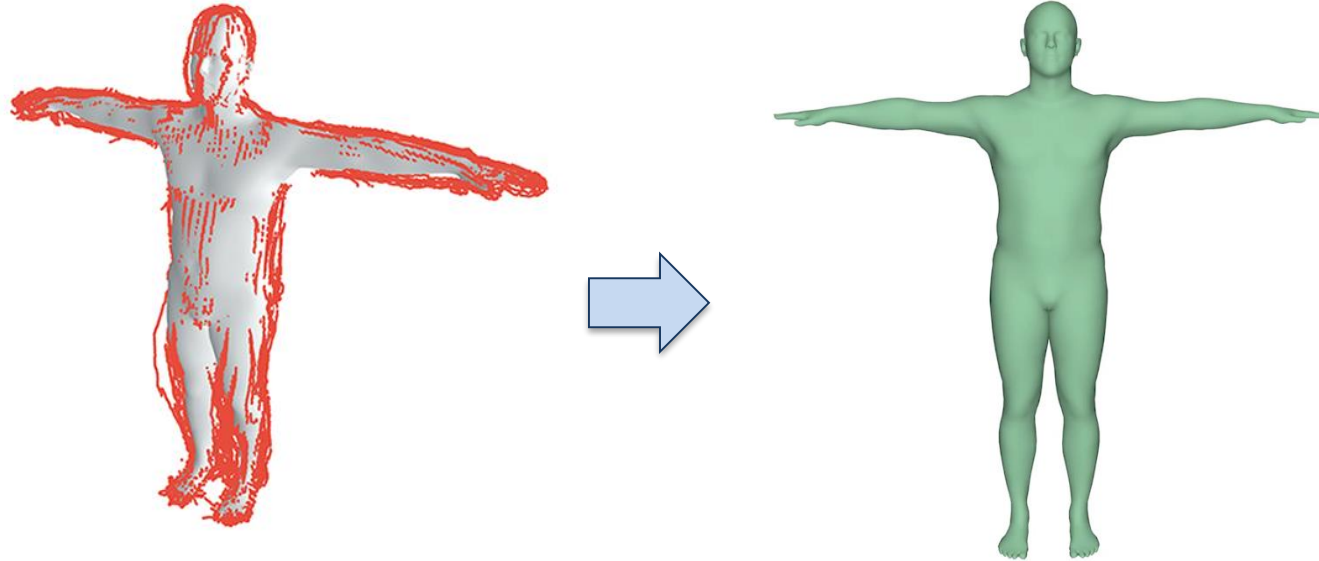
Consensus Shape  
reconstruction



Texture generation

# Method

- **Consensus shape** estimation
- Optimize a single shape to fit **unposed** silhouette cones from all frames



$$E_{\text{cons}} = E_{\text{data}} + w_{\text{lp}} E_{\text{lp}} + w_{\text{var}} E_{\text{var}} + w_{\text{sym}} E_{\text{sym}}$$

$$\sum_{(\mathbf{v}, \mathbf{r}) \in \mathcal{M}}$$

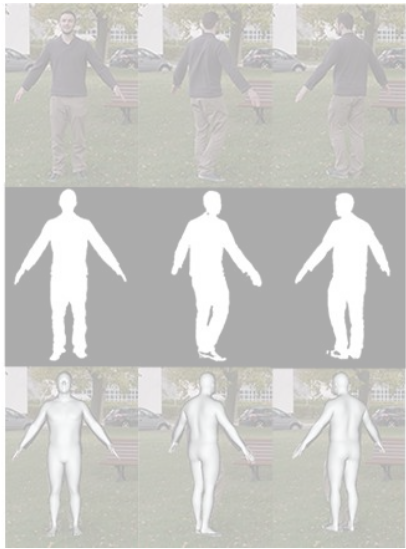
$$\rho(\mathbf{v} \times \mathbf{r}_n - \mathbf{r}_m)$$

Laplacian term

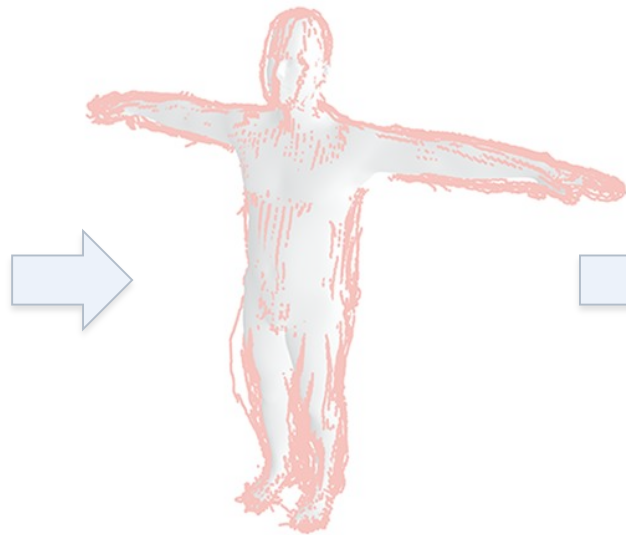
Body model term

Symmetry term

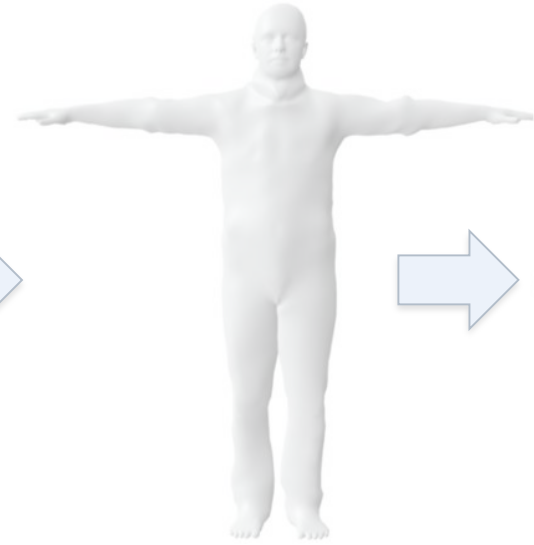
# Method



Silhouette estimation  
& Pose tracking



Silhouette cone unposing



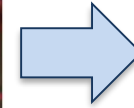
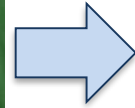
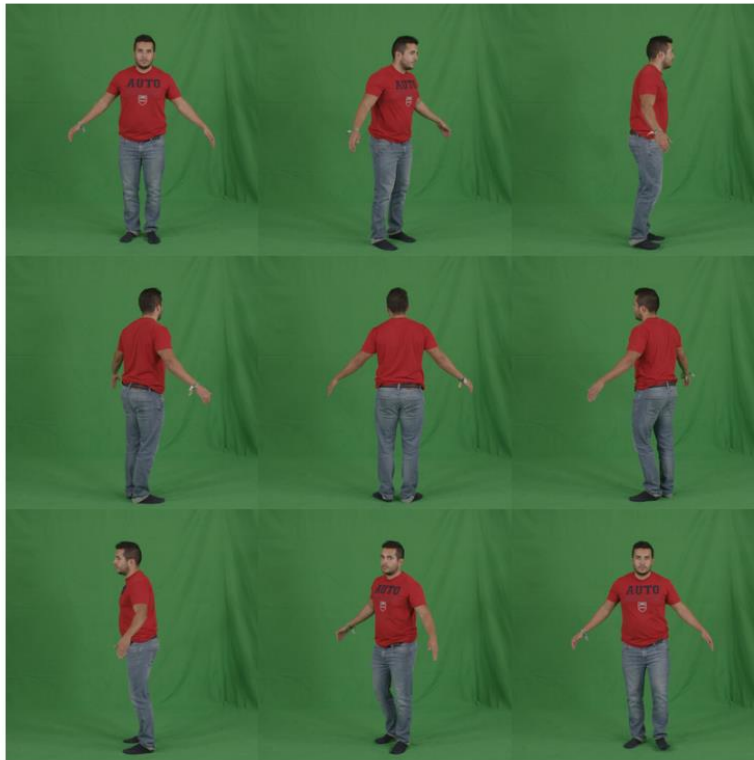
Consensus Shape  
reconstruction



Texture generation

# Method

- Texture generation



Input



Weipeng Xu

Input



Weipeng Xu









# People-Snapshot dataset



\* Dataset and code, publicly available: <https://graphics.tu-bs.de/people-snapshot>

# Thank you!

