

# Singularity-Constrained Octahedral Fields for Hexahedral Meshing

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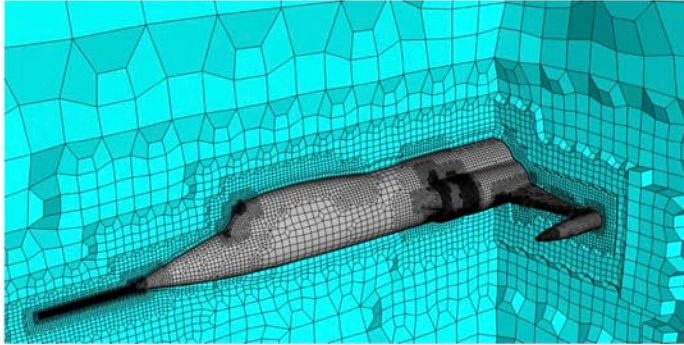
David Bommes, RWTH Aachen University



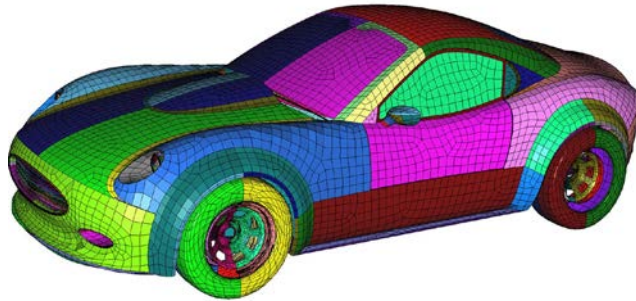
RWTHAACHEN  
UNIVERSITY



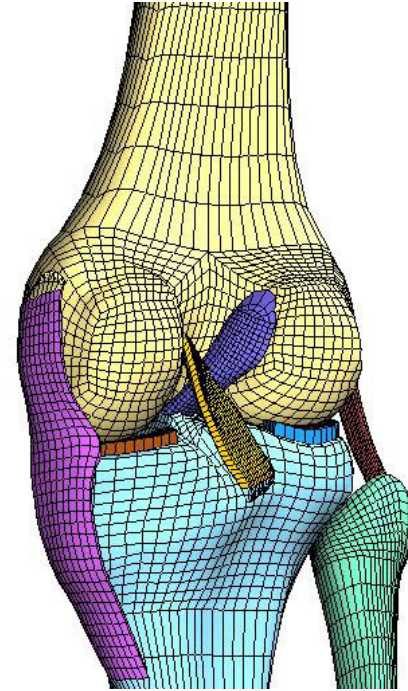
# Why Hexahedral Meshes?



Aerospace [MeshGems]

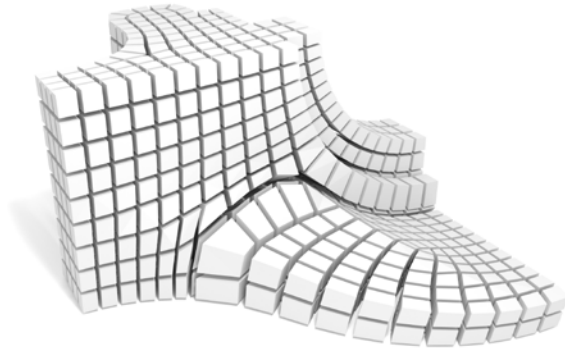


Automotive [CM2 MeshTools]



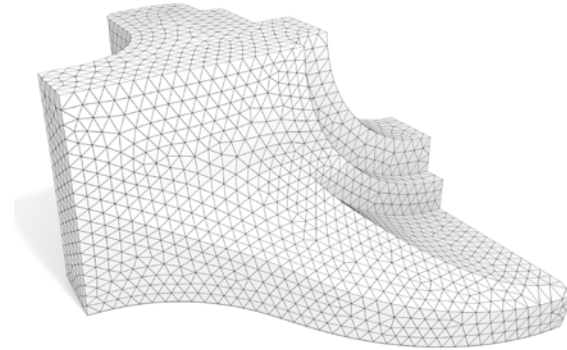
Biomechanics [TrueGrid]

# Motivation



hexahedral mesh

VS

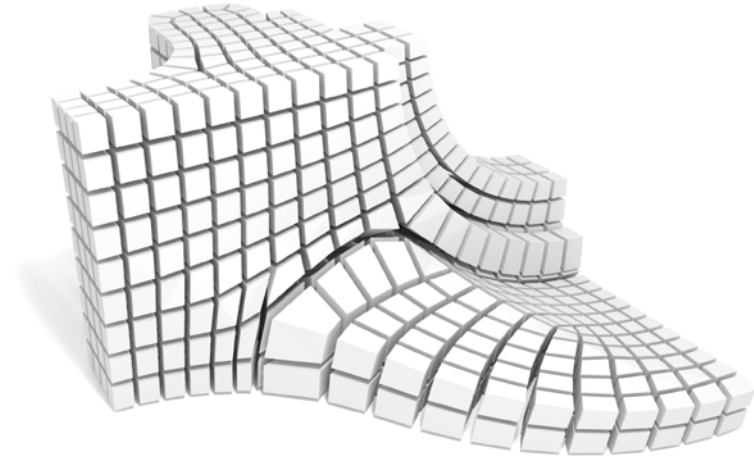


tetrahedral mesh

- **Advantage:**  
superior numerical properties,  
e.g. performance, accuracy
- **Problem:**  
difficult to generate good quality hex meshes

# Motivation

- **Problem:**  
difficult to generate good quality hex meshes.
- **Good quality:**
  - approximation
    - faithful & boundary aligned
  - regularity
    - few singularities/irregularities
  - element quality
    - scaled Jacobians close to 1
  - ...

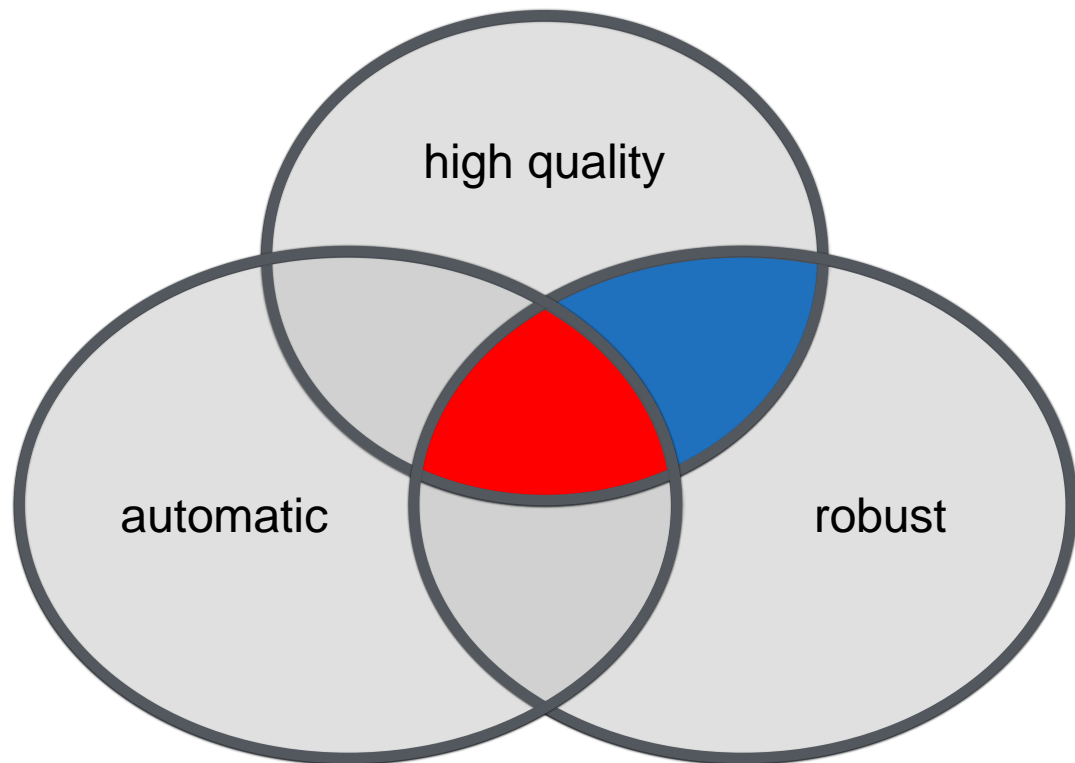


hexahedral mesh

# Motivation

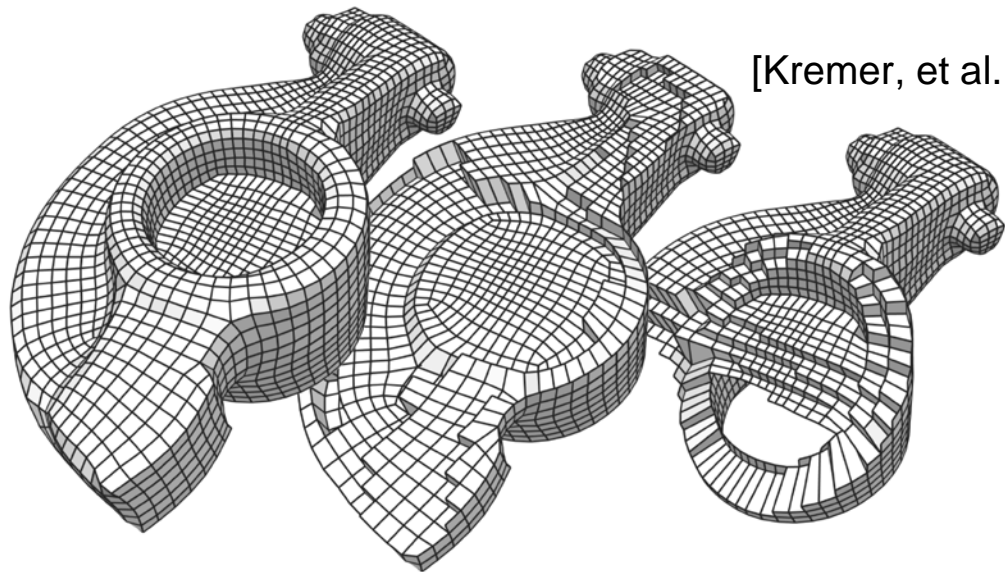
- **Hex Meshing**
  - automation
  - robustness
  - high quality

**No robust & automatic algorithm!**

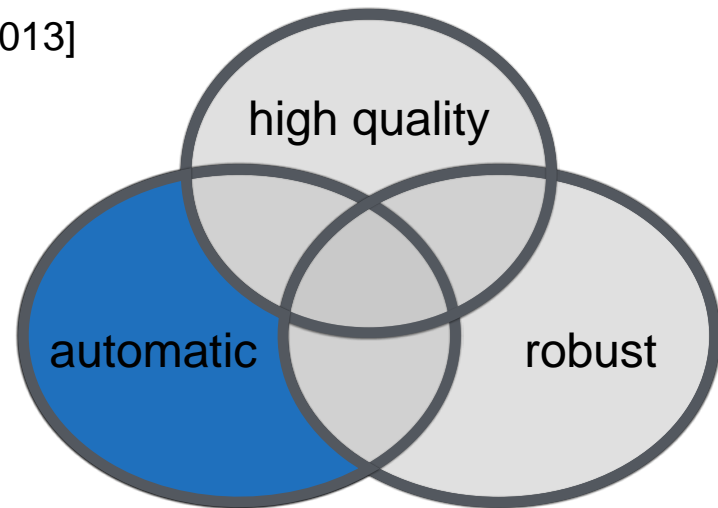


# State-of-the-art

- **Hex Meshing**
  - Advancing fronts



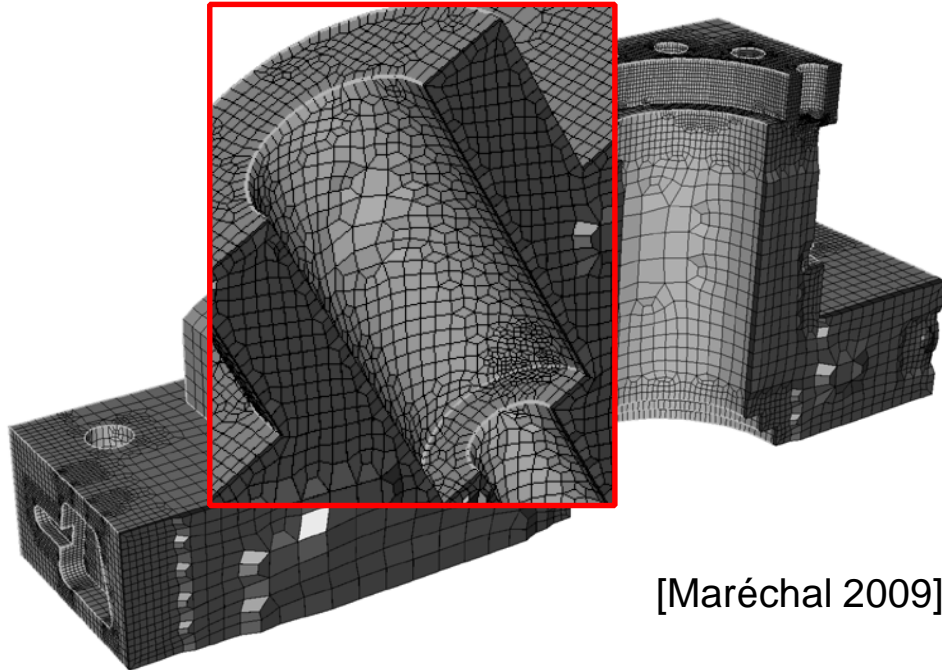
[Kremer, et al. 2013]



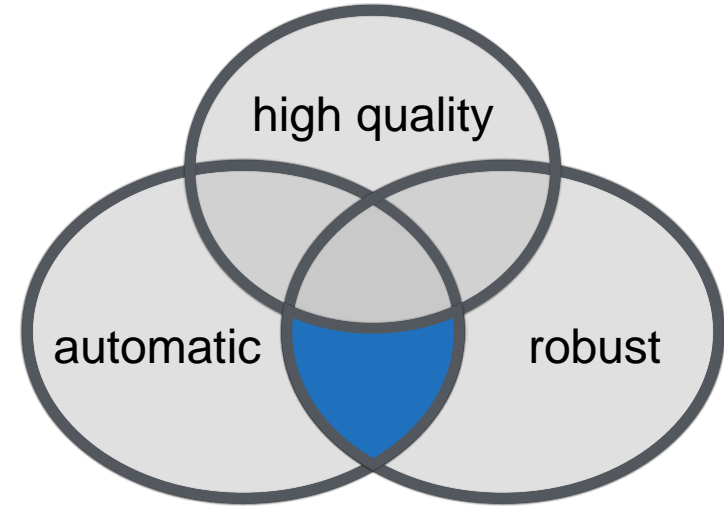
# State-of-the-art

- **Hex Meshing**

- Grid based methods

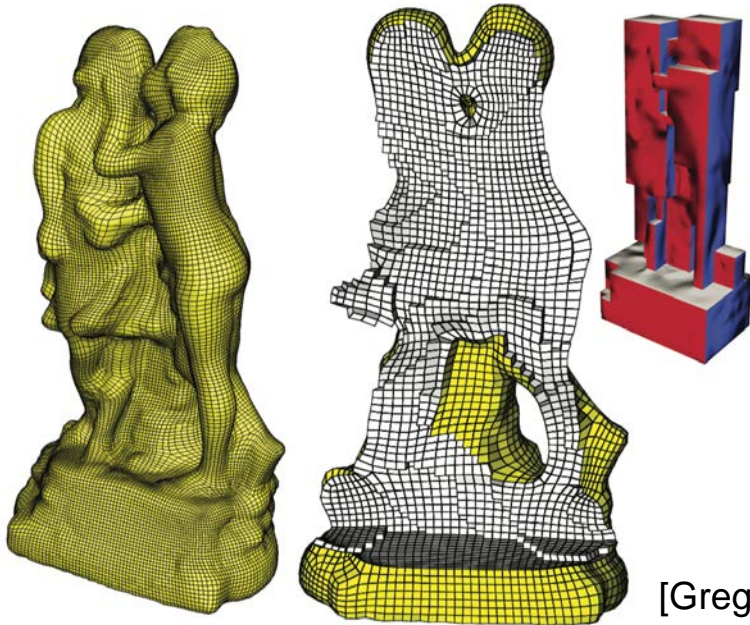


[Maréchal 2009]

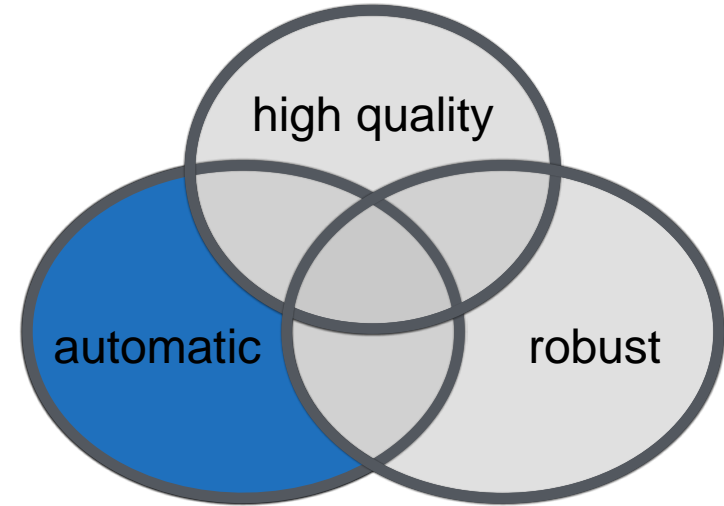


## • Hex Meshing

- Polycube based: Gregson et al. 2011, Livesu et al. 2013, Huang et al. 2014, Fu et al. 2016, Fang et al. 2016, Xu et al. 2017...



[Gregson, et al. 2011]



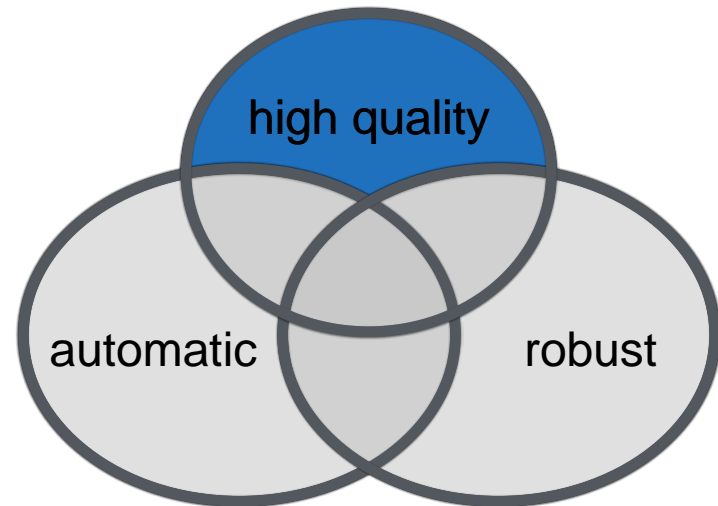
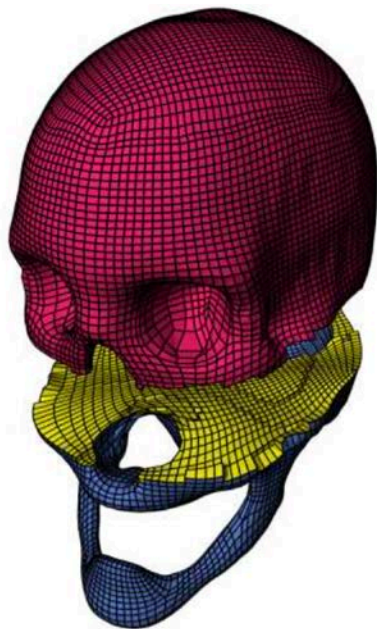
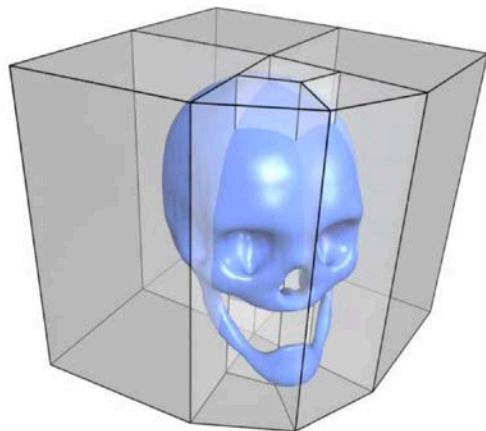


# State-of-the-art

- **Hex Meshing**

- Octahedral field based

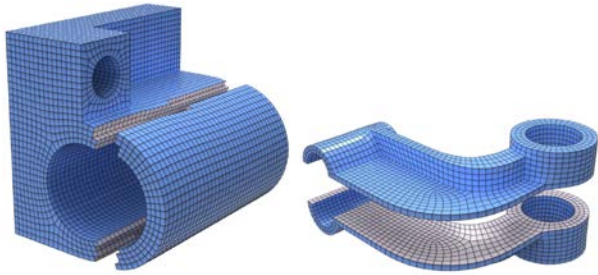
[Nieser, et al. 2011]



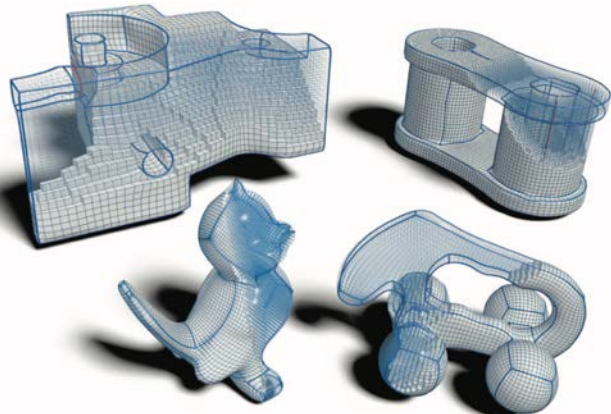
# State-of-the-art

- **Hex Meshing**

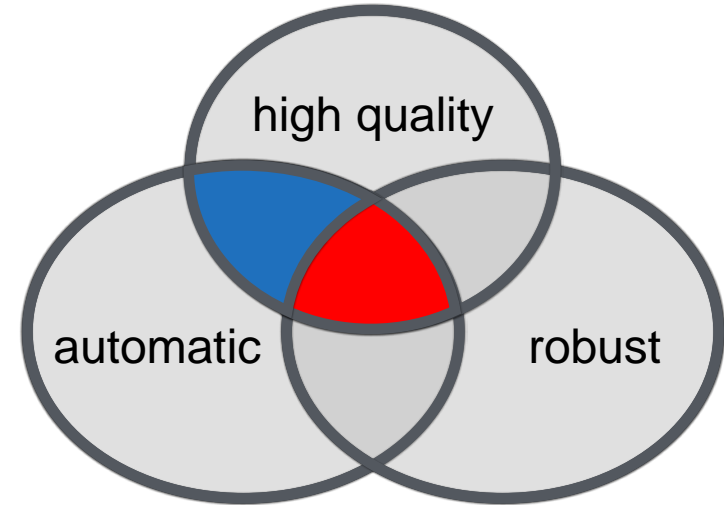
- Octahedral field based



[Li, et al. 2012]

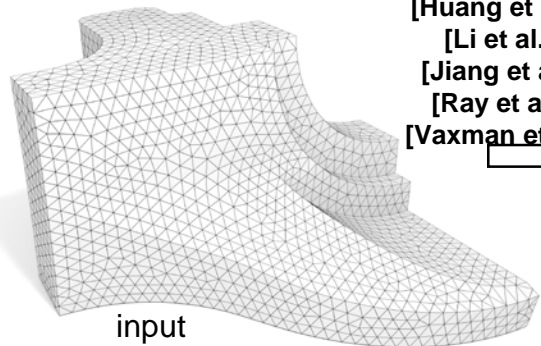


[Jiang, et al. 2013]

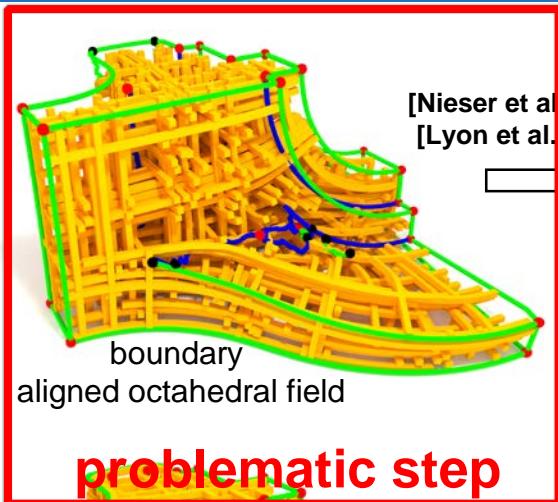


# Octahedral Field Based Hex Meshing

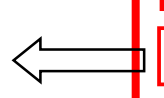
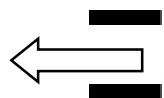
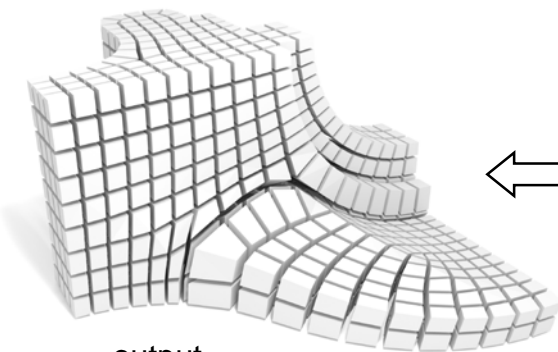
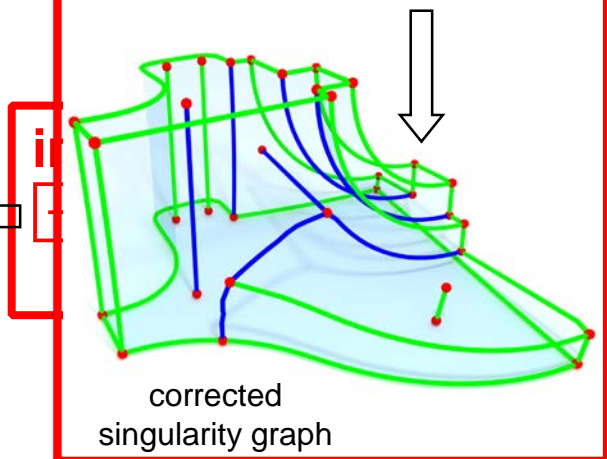
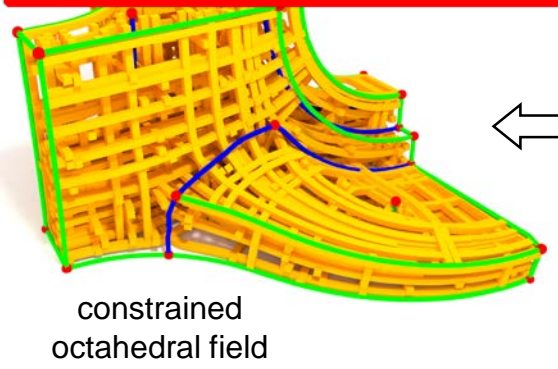
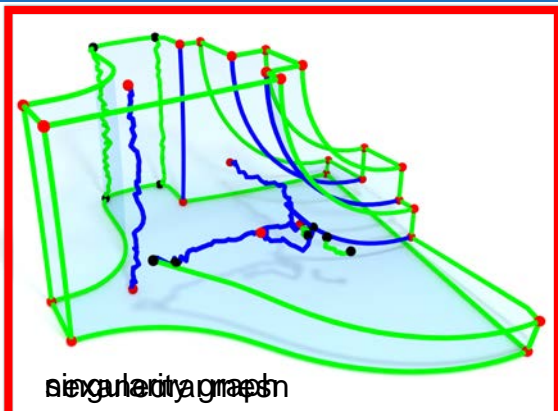
# Modified All-Joint Based Hex Meshing



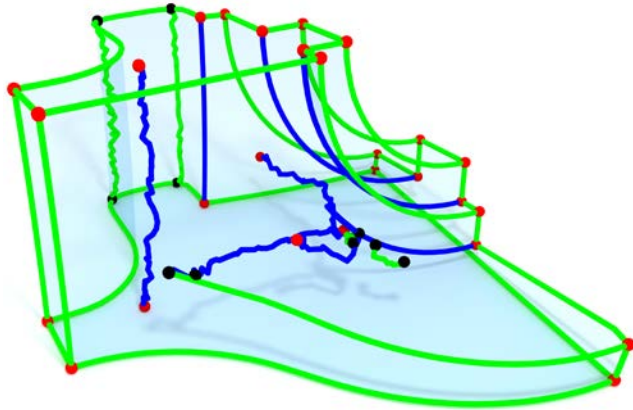
[Huang et al. 2011]  
[Li et al. 2012]  
[Jiang et al. 2014]  
[Ray et al. 2016]  
[Vaxman et al. 2017]



[Nieser et al. 2011]  
[Lyon et al. 2016]

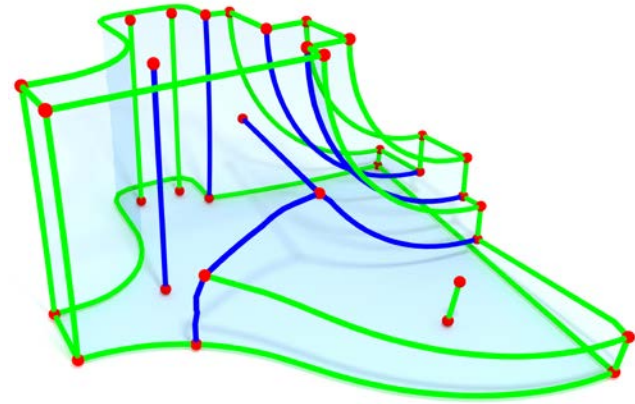
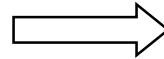


# Contribution 1

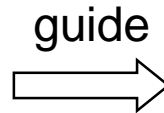


singularity graph

- local configurations
- global necessary condition



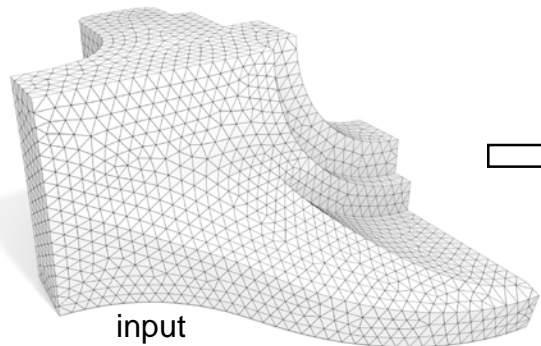
corrected singularity graph



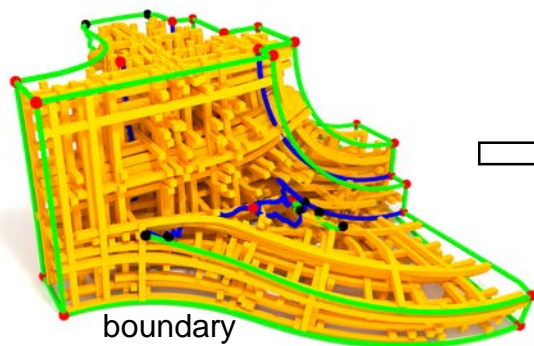
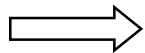
guide

singularity graph correction  
current: manual & future: automatic

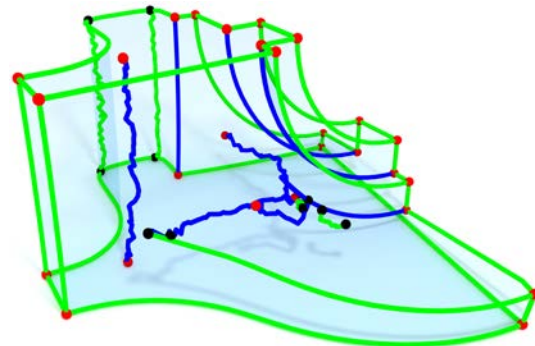
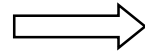
# Modified Algorithm



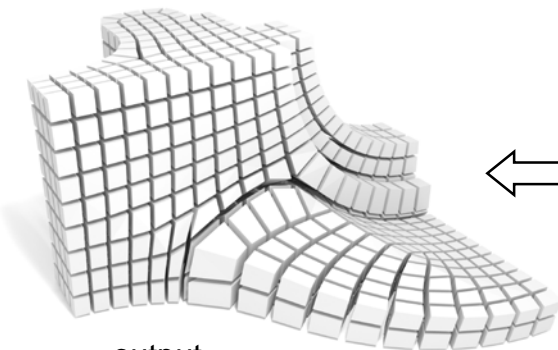
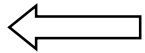
input  
tetrahedral mesh



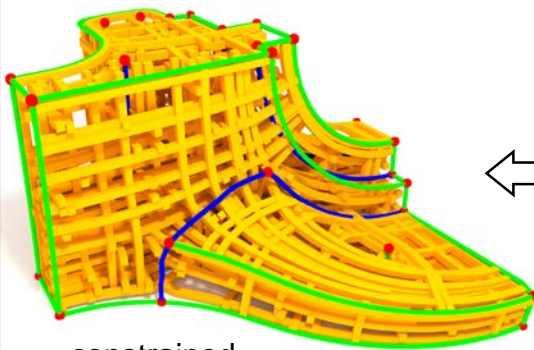
boundary  
aligned octahedral field



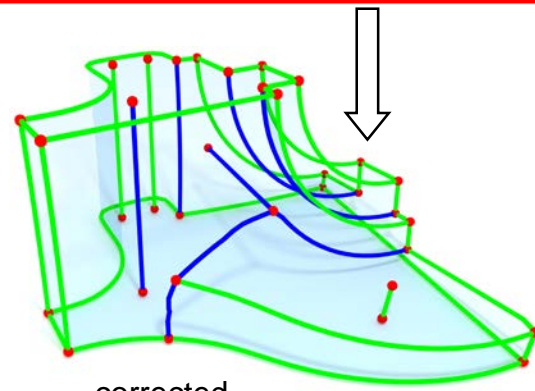
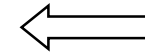
singularity graph



output  
hexahedral mesh

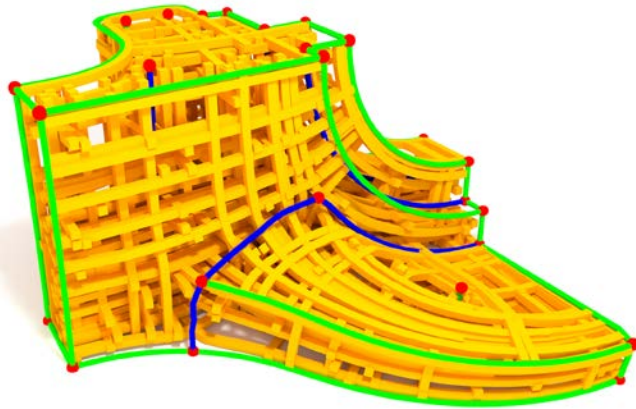


constrained  
octahedral field

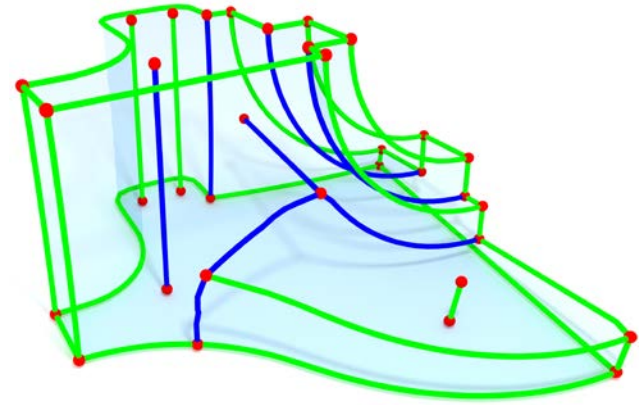
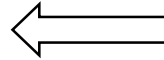


corrected  
singularity graph

# Contribution 2



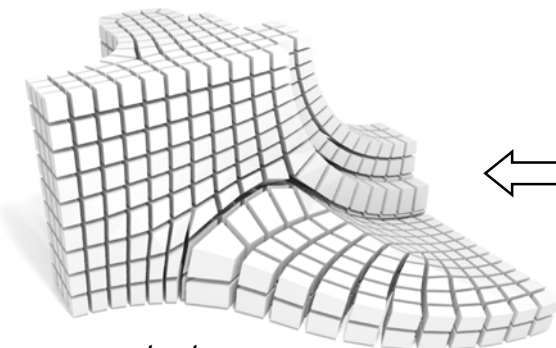
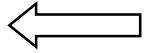
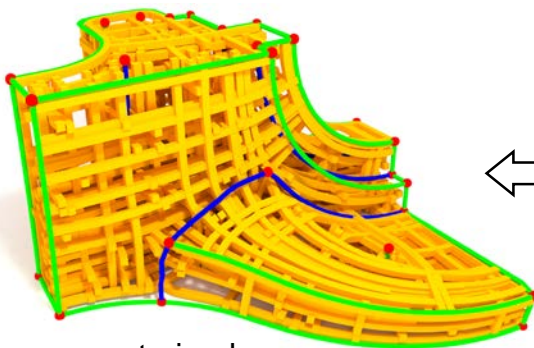
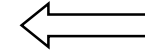
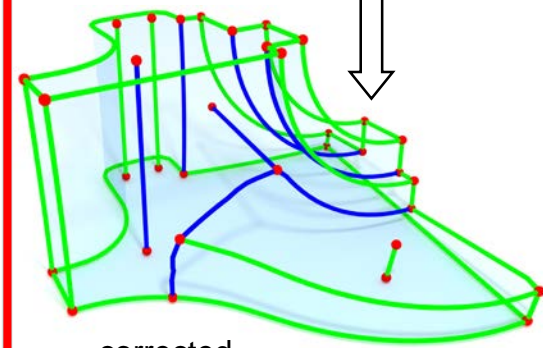
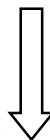
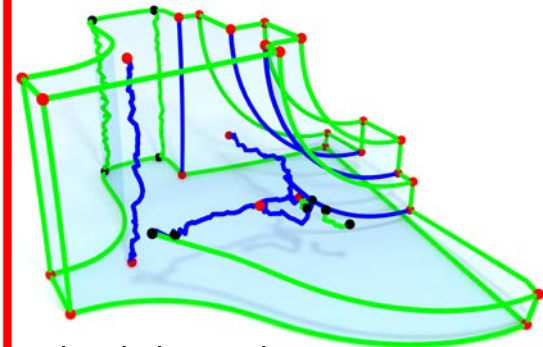
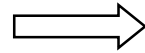
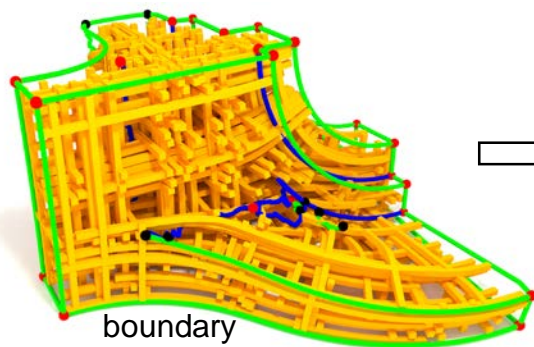
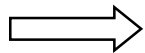
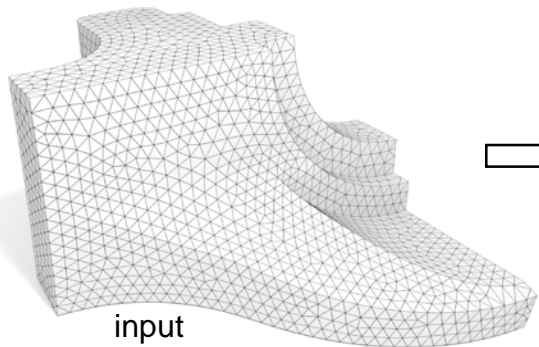
constrained octahedral field



corrected singularity graph

- algorithm to generate octahedral fields with prescribed hex-meshable singularity graphs

# Modified Algorithm

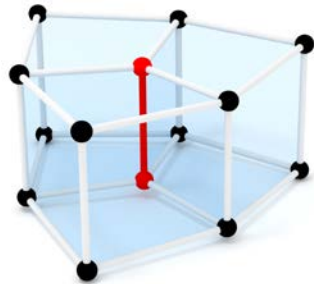




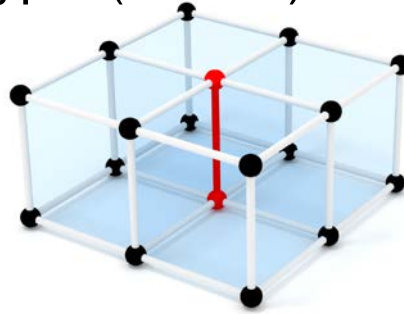
# What are hex mesh singularities?

# Hex Mesh Singularities

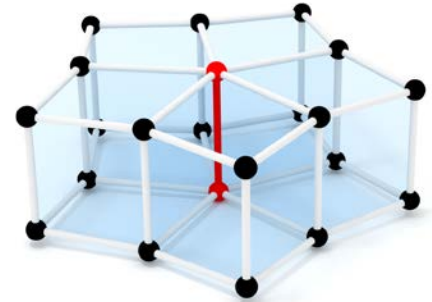
- Local Conditions - Edge types(interior)



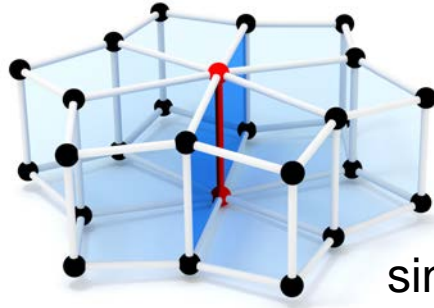
singular  
valence 3



regular  
valence 4



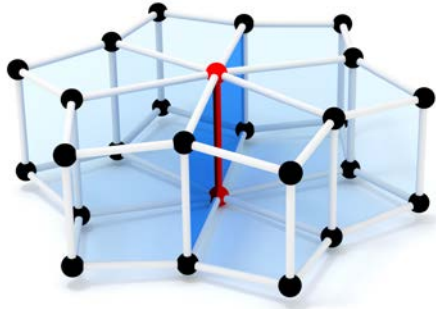
singular  
valence 5



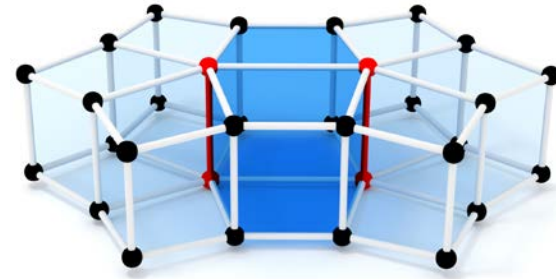
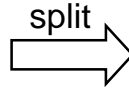
singular  
valence 6

# Hex Mesh Singularities

- Local Conditions - Edge types(interior)



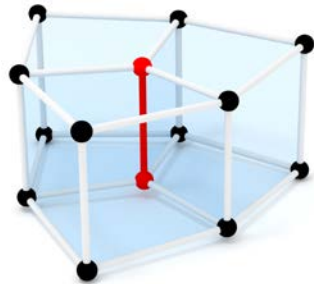
singular  
valence 6



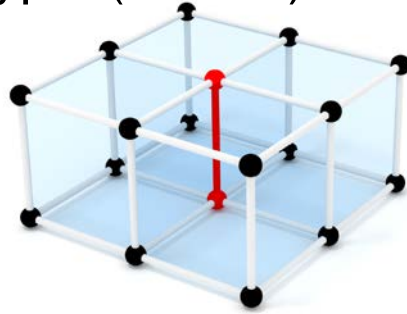
twice valence 5

# Hex Mesh Singularities

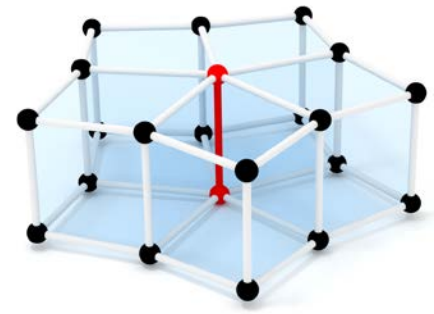
- Local Conditions - Edge types(interior)



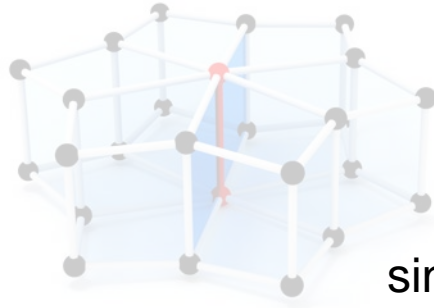
singular  
valence 3



regular  
valence 4



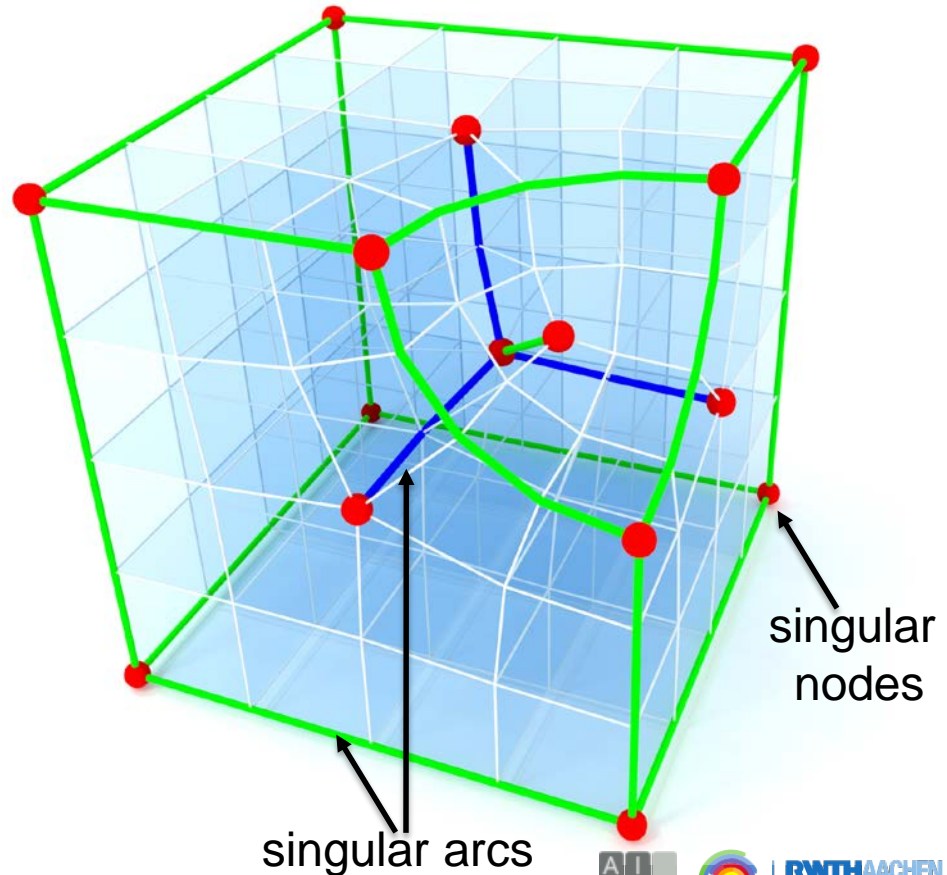
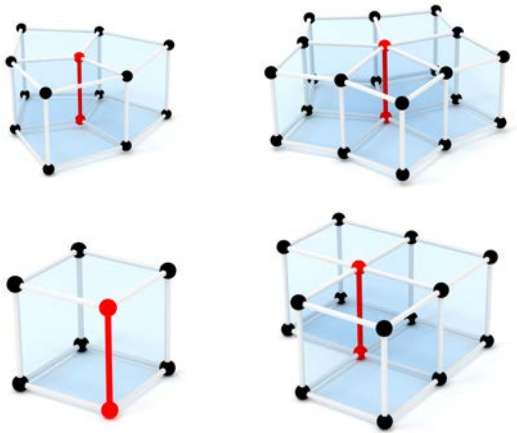
singular  
valence 5



singular  
valence 6

# Hex Mesh Singularities

- Singularity graph  
 $\mathcal{S} = (V_S, E_S)$



# Hex Mesh Singularities

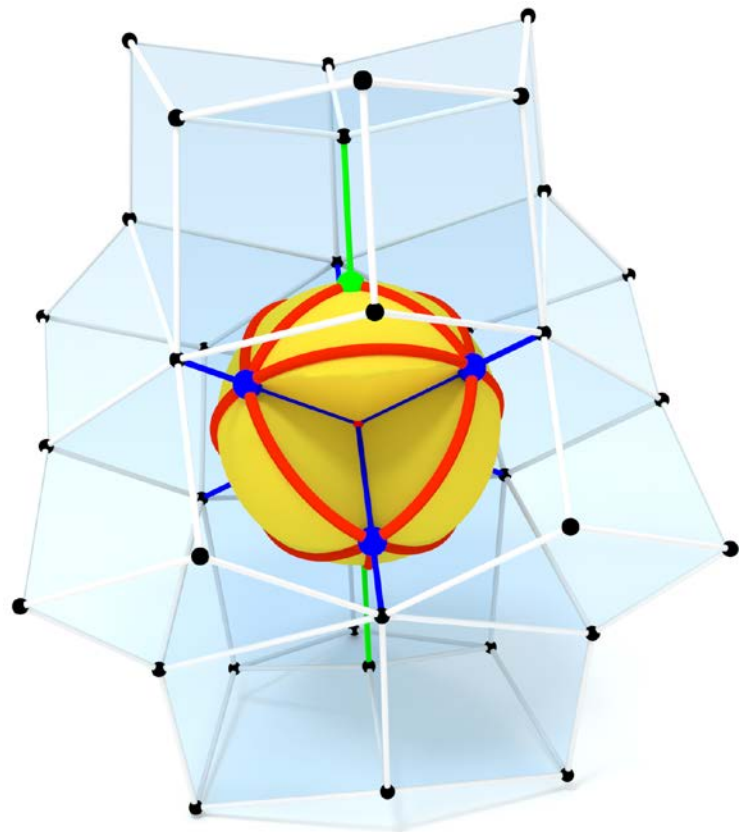
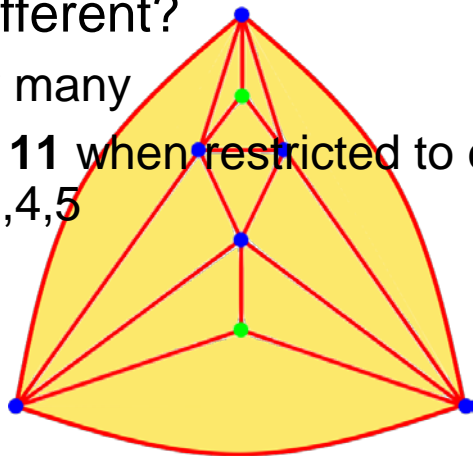
- Vertex types

hex mesh vertices are isomorphic to triangulations of the sphere

- How many different?

→ infinitely many

→ but only **11** when restricted to edge valence 3,4,5

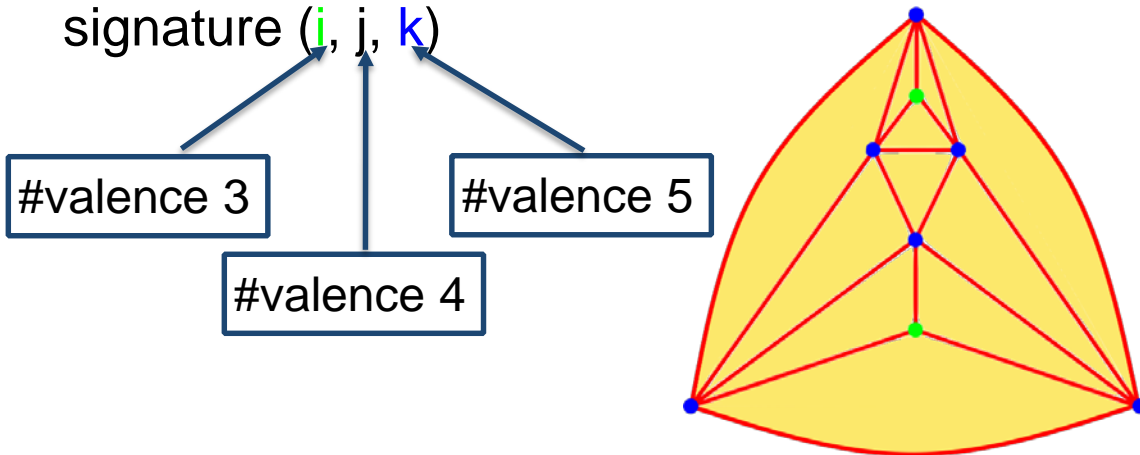


# Hex Mesh Singularities

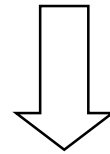
- How many sphere triangulations exist with vertex valences restricted to 3, 4, 5?

→ Answer: **only 11**

- Assume triangulation has  $\#V$  vertices with signature  $(i, j, k)$



$$\text{Euler formula} \\ \#V - \#E + \#F = 2$$



$$3i + 2j + k = 12 \\ \text{with} \\ i + j + k = \#V$$

consequences:

1. minimal  $\#V = 4$  ( $i=4$ )
2. maximal  $\#V = 12$  ( $k=12$ )

# Hex Mesh Singularities

$$3i + 2j + k = 12$$

with

$$i+j+k = \#V$$

- **#V=4**  
(4,0,0)
- **#V=5**  
~~(3,1,1)~~, (2,3,0) valence 5 with 5 vertices requires self-connection
- **#V=6**  
~~(3,0,3)~~, ~~(2,2,2)~~, ~~(1,4,1)~~, (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3), ~~(2,1,4)~~
- **#V=8**  
(0,4,4), ~~(1,2,5)~~, (2,0,6)
- **#V=9**  
(0,3,6), ~~(1,1,7)~~
- **#V=10**  
(0,2,8), ~~(1,0,9)~~
- **#V=11**  
~~(0,1,10)~~
- **#V=12**  
(0,0,12)

**[Schmeichel and Hakimi 1977]**

“On Planar Graphical Degree Sequences”

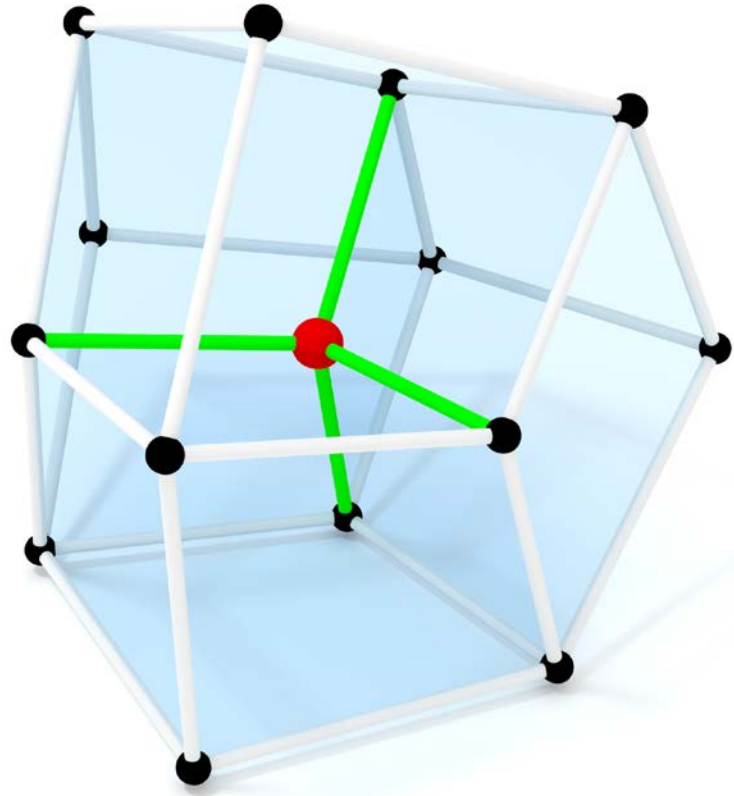
**[Mishra and Sarvate 2007]**

“A note on Non-Regular Planar Graphs”



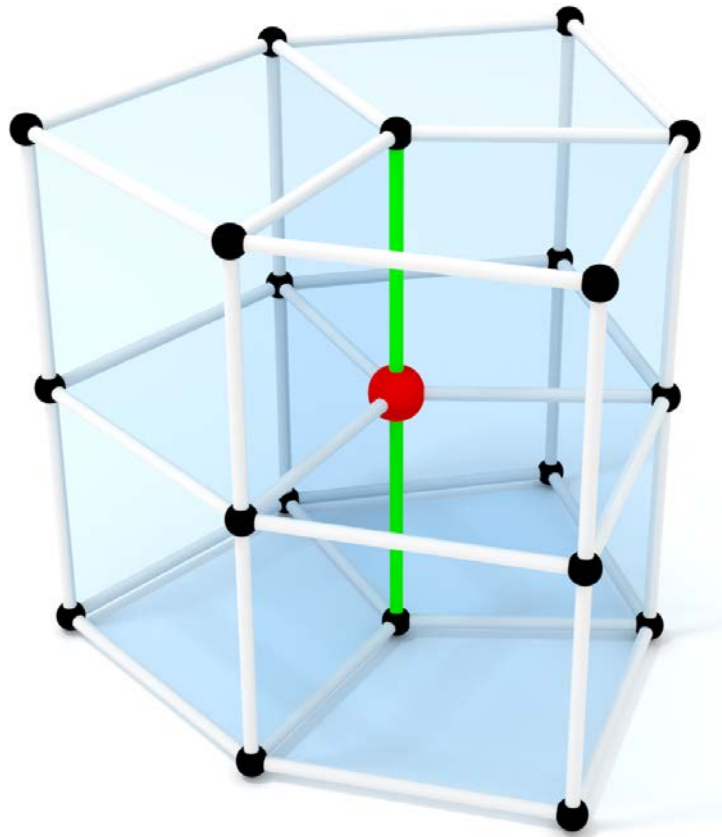
# Hex Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



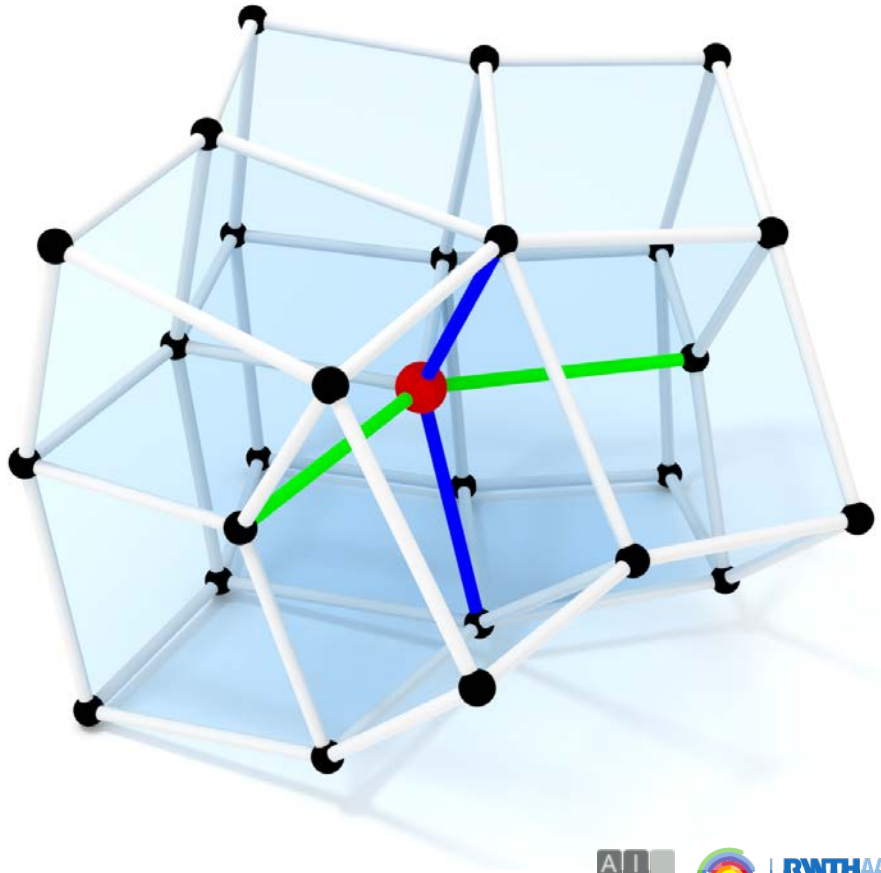
# Hex Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
**(2,3,0)**
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



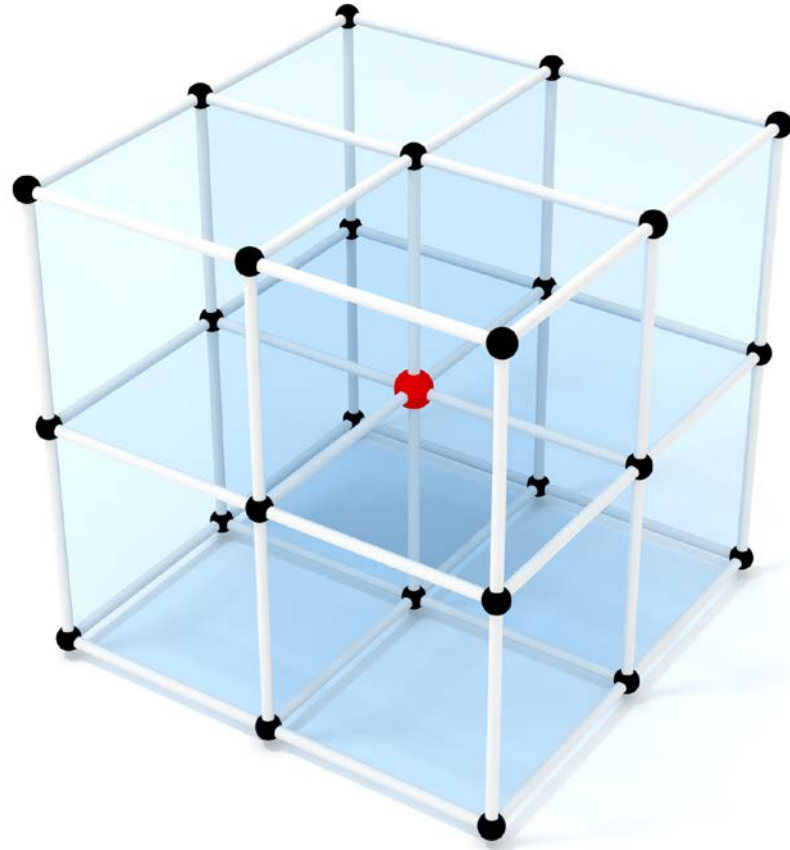
# Hex Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
**(2,2,2)**, (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



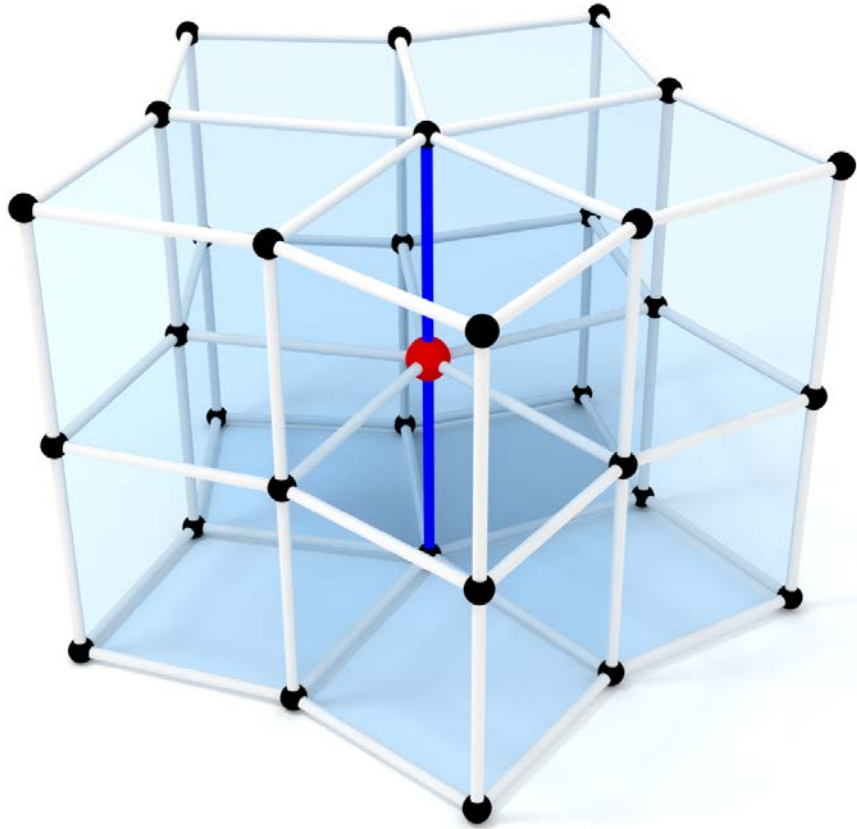
# Hex Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), **(0,6,0)**
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



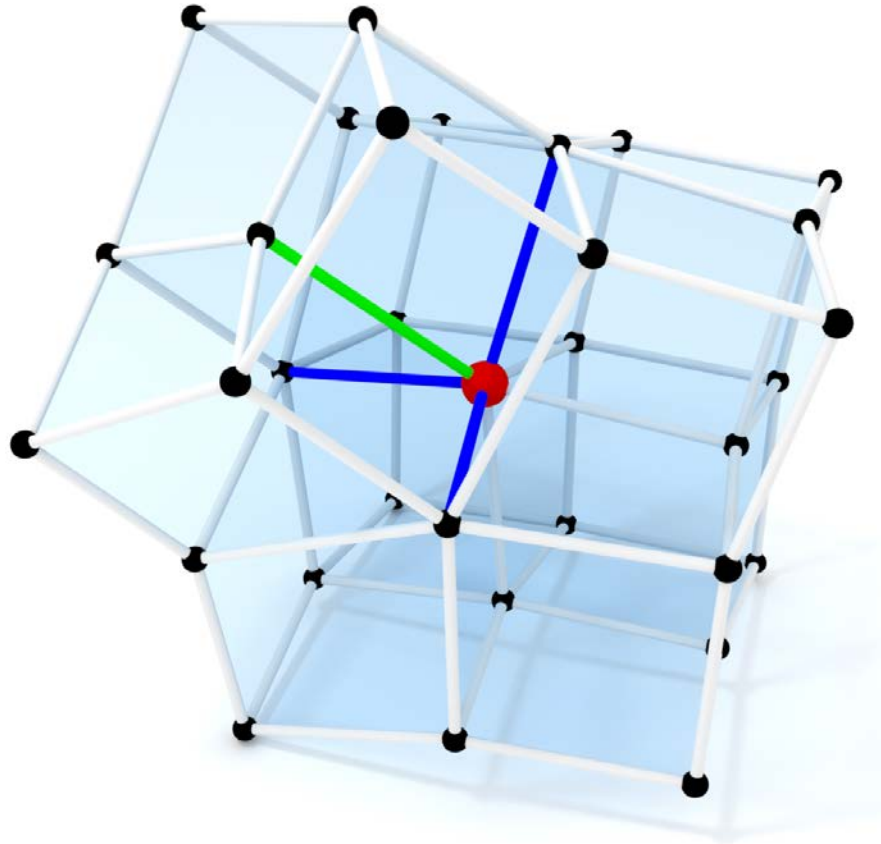
# Hex Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
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**(0,5,2)**, (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



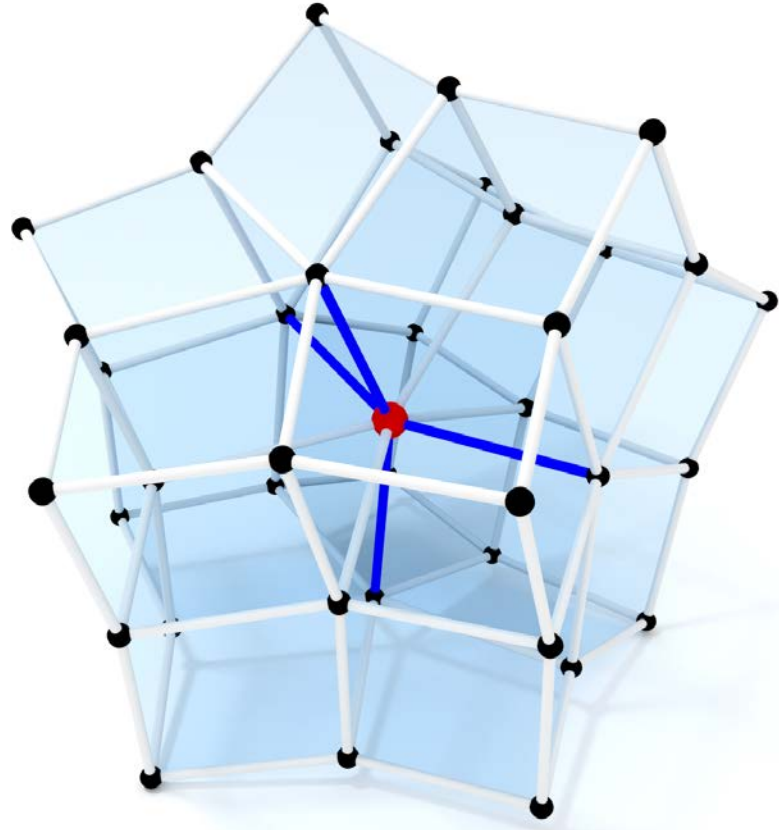
# Hex Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
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(0,5,2), **(1,3,3)**
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



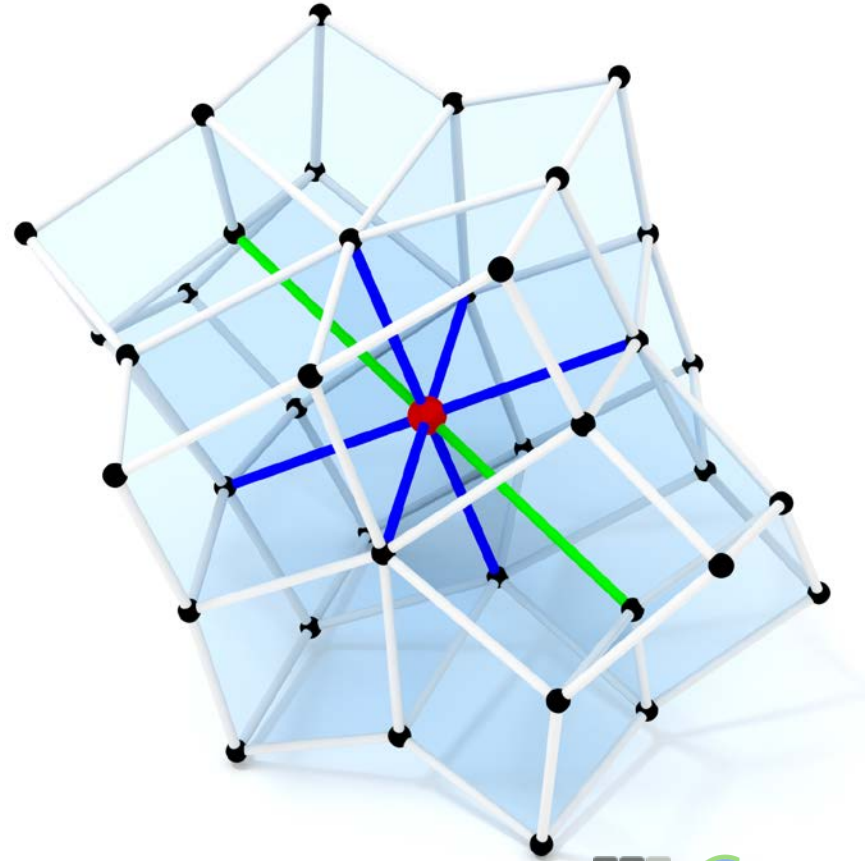
# Hex Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
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(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



# Hex Mesh Singularities

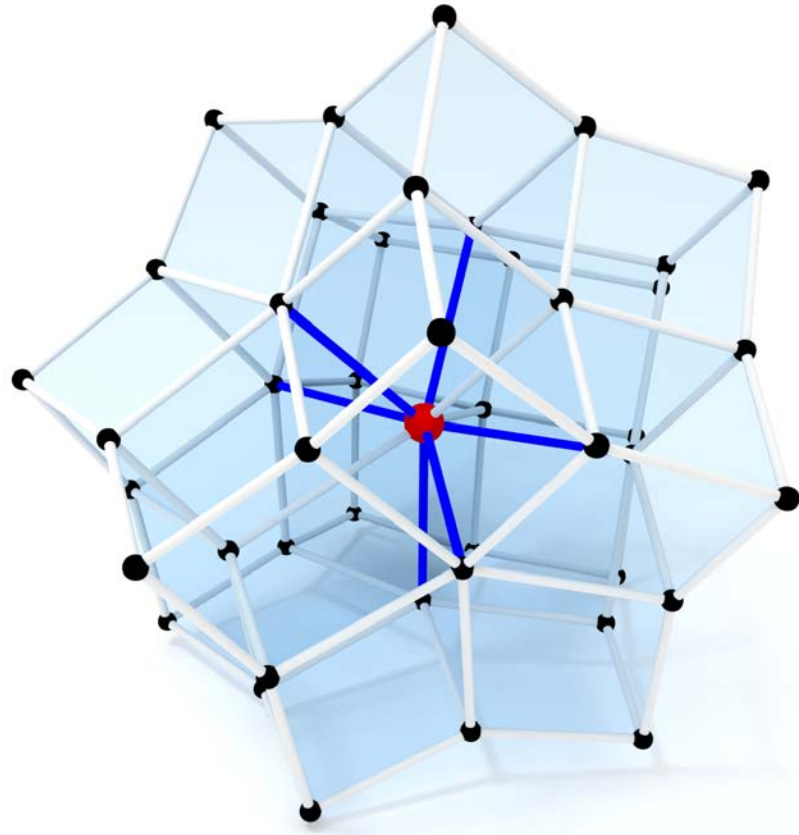
- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)





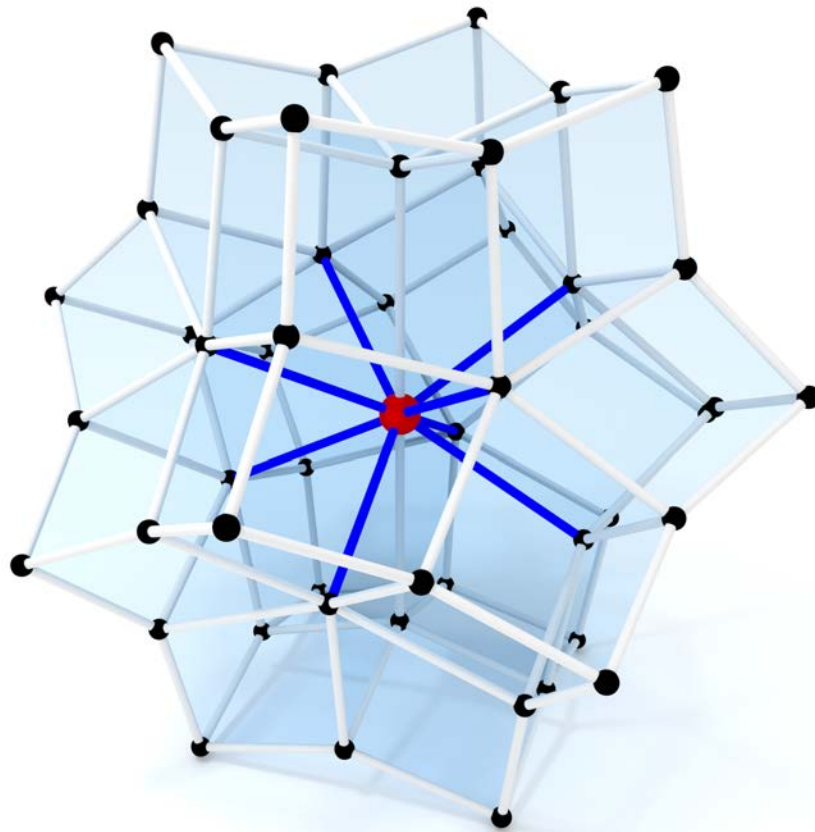
# Hex Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
**(0,3,6)**
- **#V=10**  
(0,2,8)
- **#V=12**  
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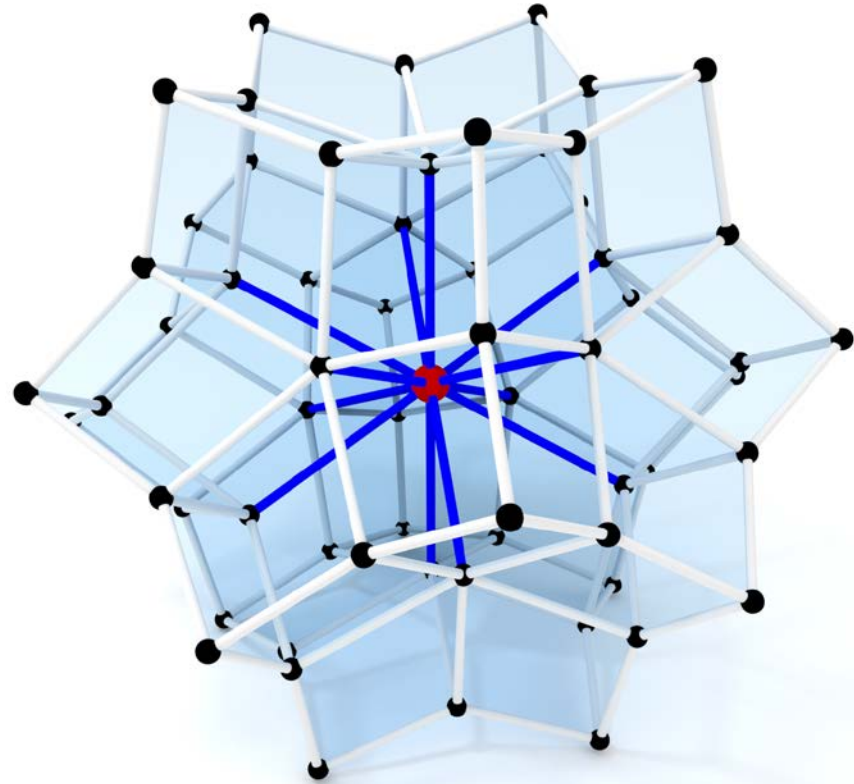
# Hex Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
**(0,2,8)**
- **#V=12**  
(0,0,12)



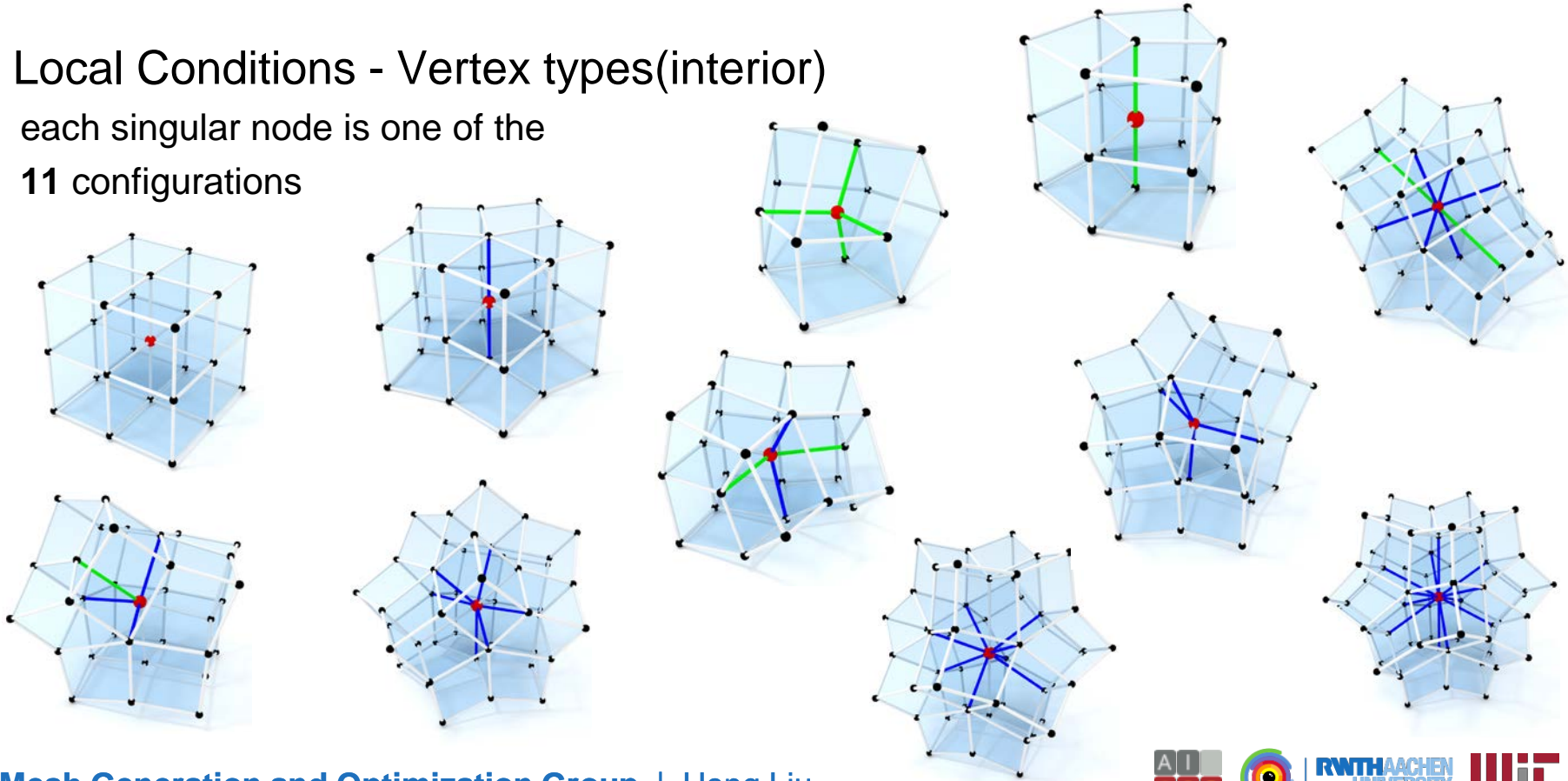
# Hex Mesh Singularities

- **#V=4**  
(4,0,0)
- **#V=5**  
(2,3,0)
- **#V=6**  
(2,2,2), (0,6,0)
- **#V=7**  
(0,5,2), (1,3,3)
- **#V=8**  
(0,4,4), (2,0,6)
- **#V=9**  
(0,3,6)
- **#V=10**  
(0,2,8)
- **#V=12**  
(0,0,12)



# Hex Meshable Singularity Graphs (valence 3/4/5)

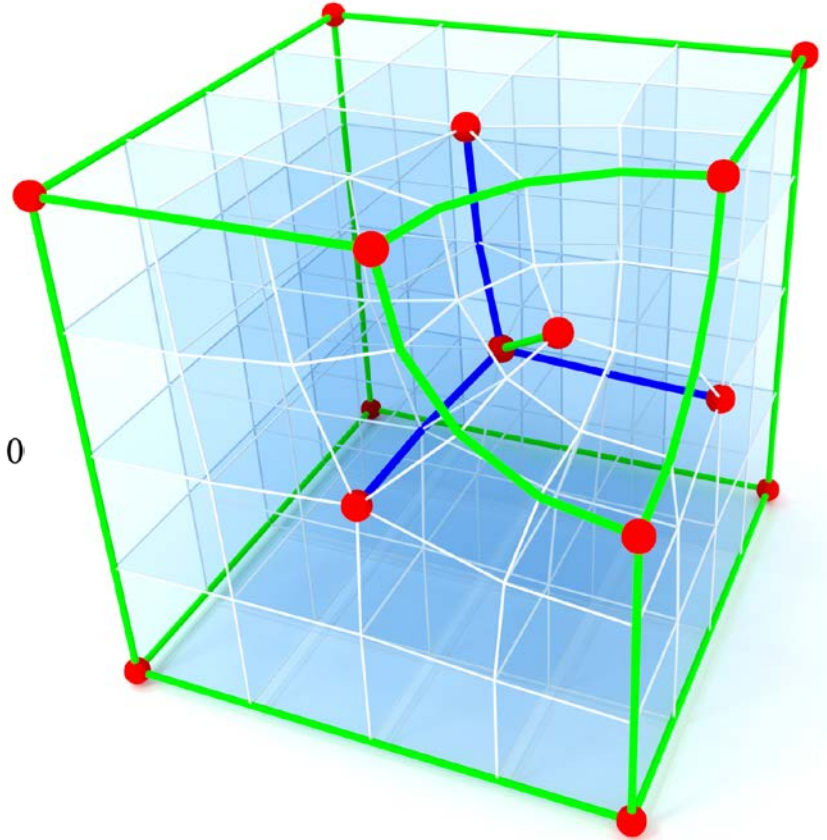
- Local Conditions - Vertex types(interior)  
each singular node is one of the  
11 configurations



# Hex Meshable Singularity Graphs (valence 3/4/5)

- Global Necessary Condition

$$\sum_{v \in \partial V_S} \frac{1}{2} \left( 1 - \frac{\text{val}_h(v)}{4} \right) - \sum_{e \in \partial E_S^-} \text{idx}(e) + \sum_{v \in \overset{\circ}{V}_S} \left( 1 - \frac{\text{val}_h(v)}{8} \right) - \sum_{e \in \overset{\circ}{E}_S^-} \text{idx}(e) = 0$$



# What are Octahedral Field singularities?

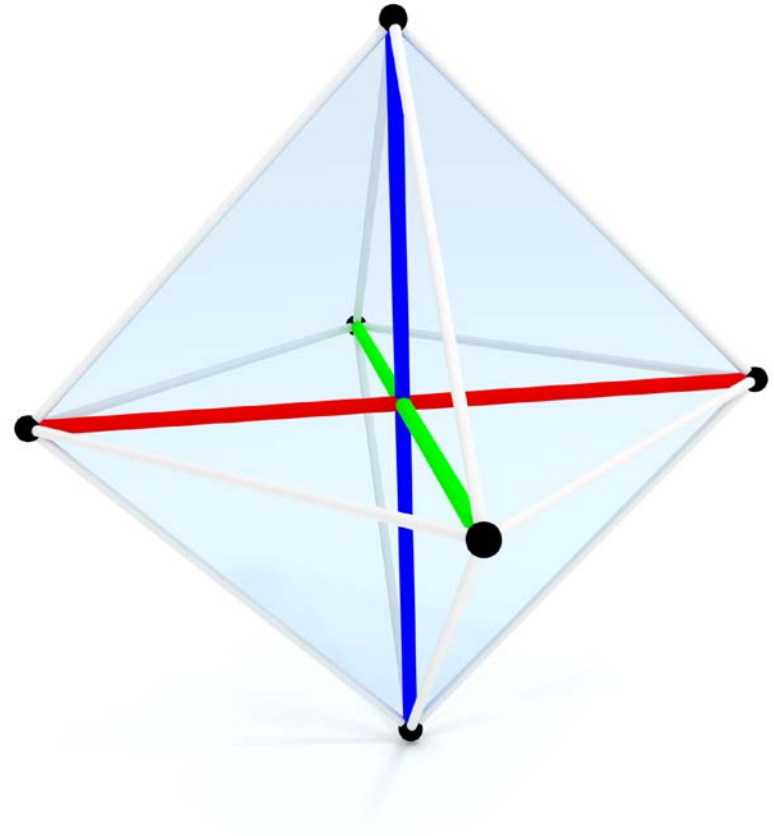
hex mesh  
singularities



octahedral-field  
singularities

# Octahedral Field Singularities

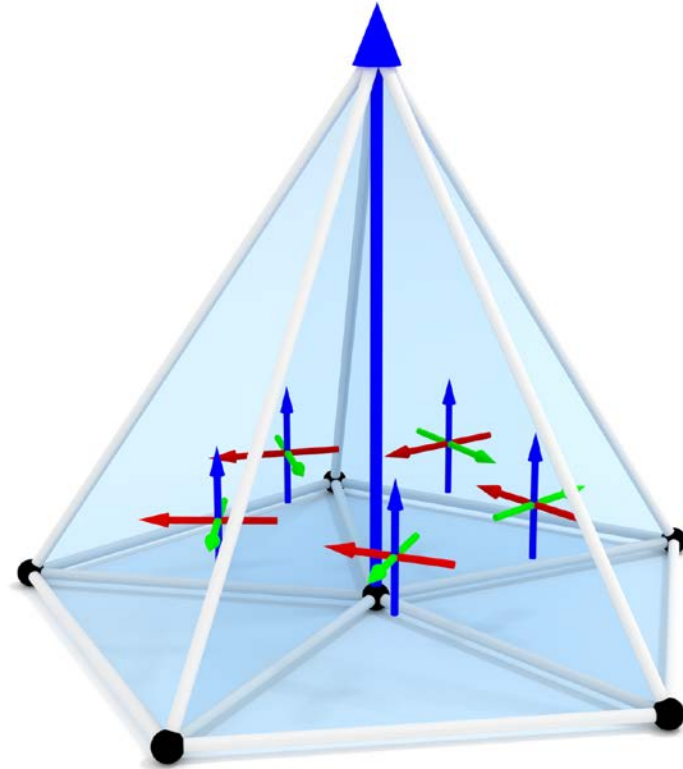
- Octahedral-Fields



# Octahedral Field Singularities

- Octahedral-Fields
  - one frame per tet  $q_i$  (unit quaternion)
  - $R \in \text{Oct}$ : matching quaternion per face
  - 24 classes of matchings

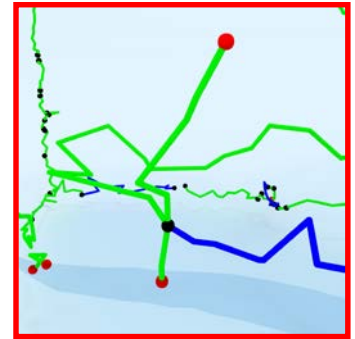
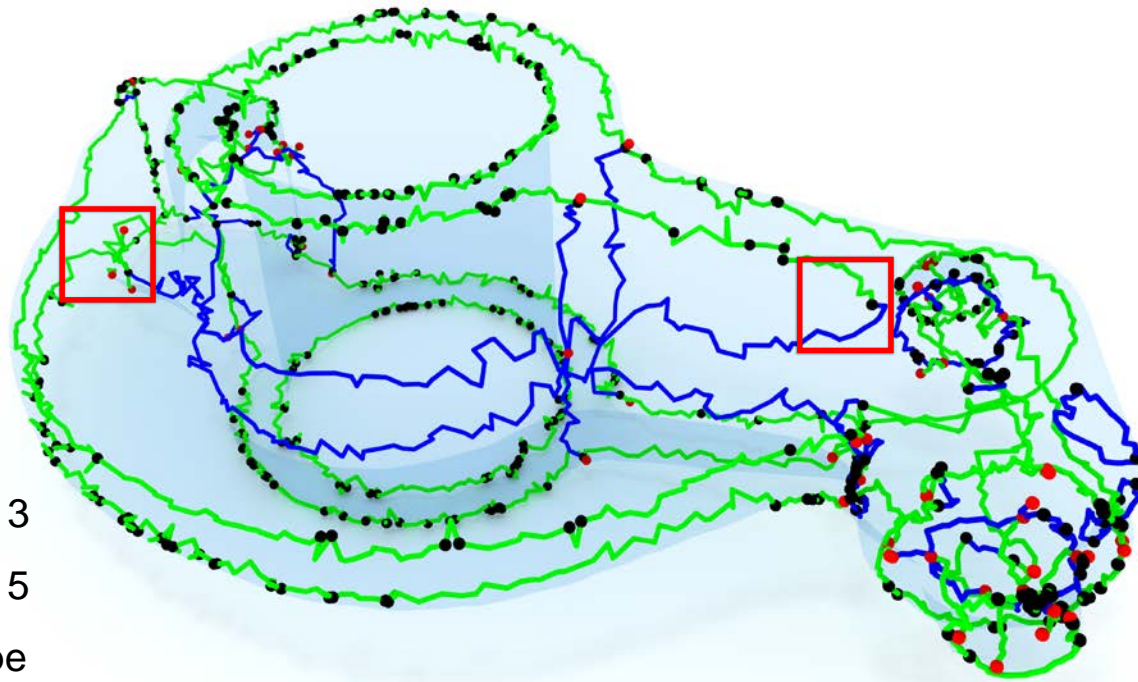
singularities form a graph









# Octahedral-Field Singularities

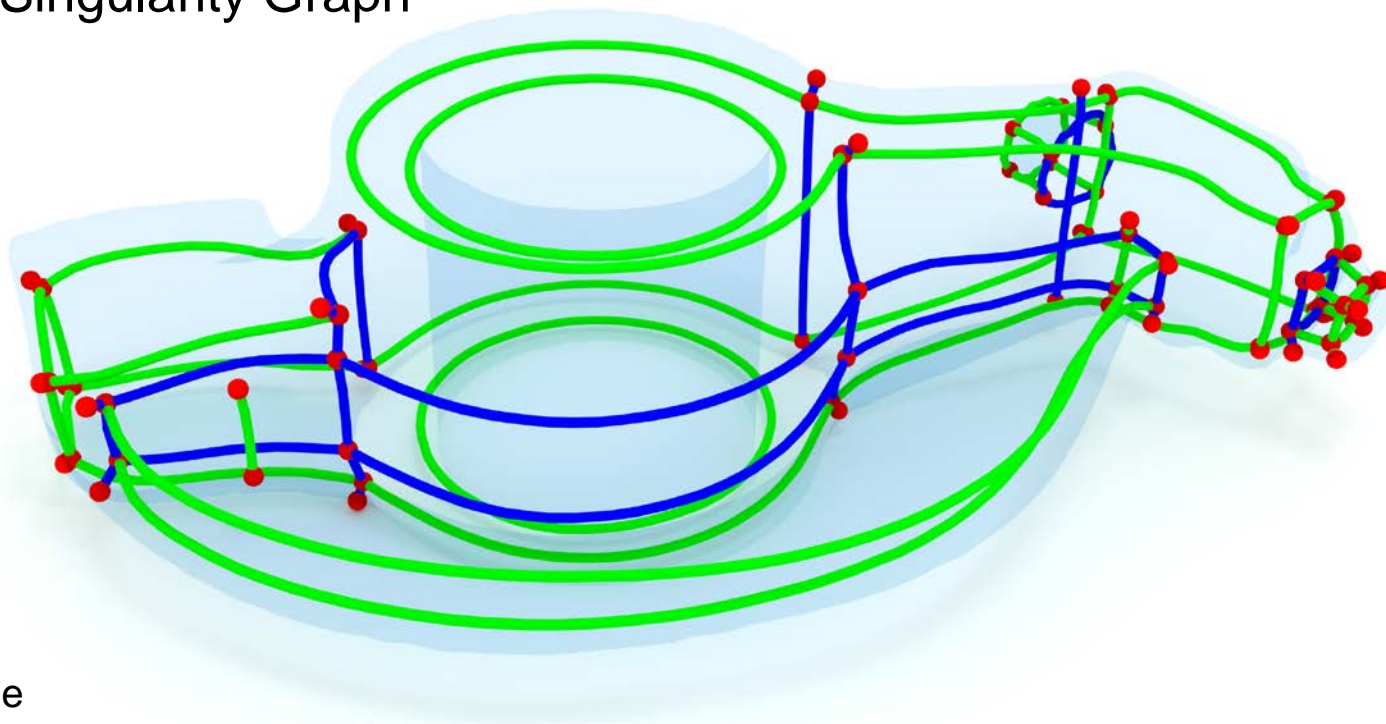
- Defects



-  : valance 3
-  : valance 5
-  : valid type
-  : invalid type

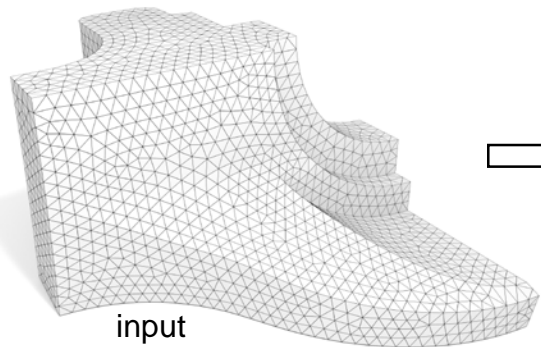
# Octahedral-Field Singularities

- Corrected Singularity Graph

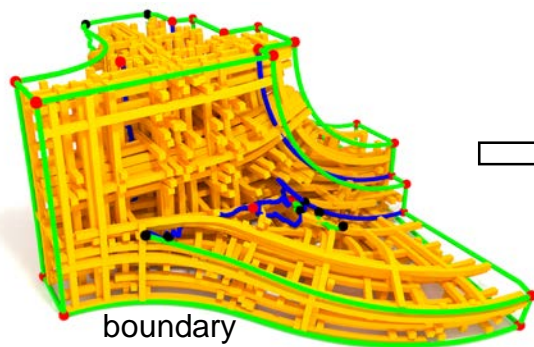
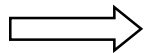


- : valance 3
- : valance 5
- : valid type
- : invalid type

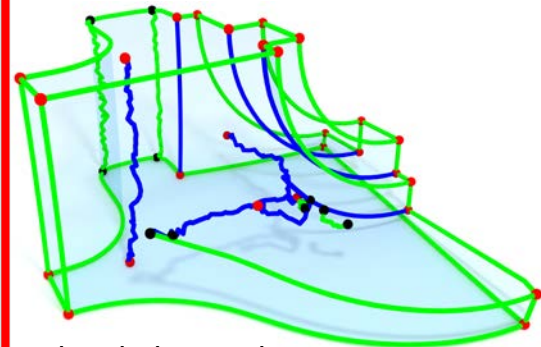
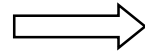
# Modified Algorithm



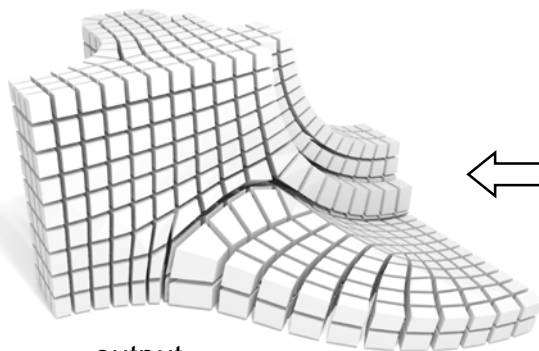
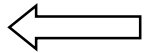
input  
tetrahedral mesh



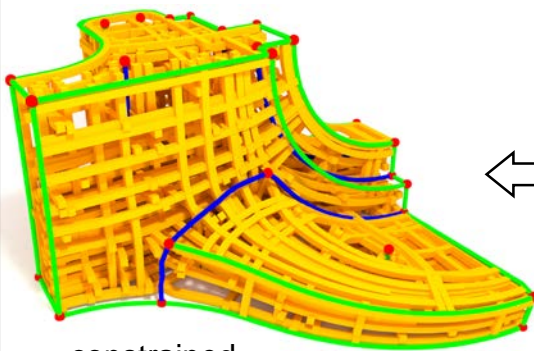
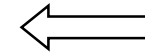
boundary  
aligned octahedral-field



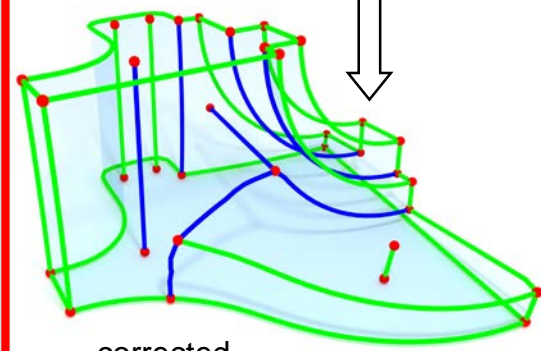
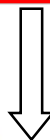
singularity graph



output  
hexahedral mesh



constrained  
octahedral-field

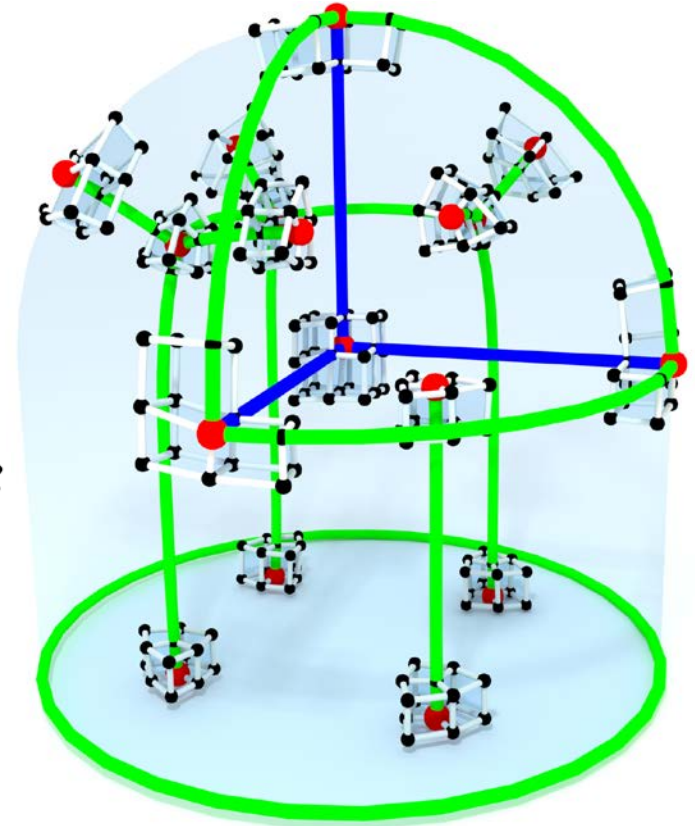


corrected  
singularity graph

# Singularity Constrained Hexable Octahedral-Fields

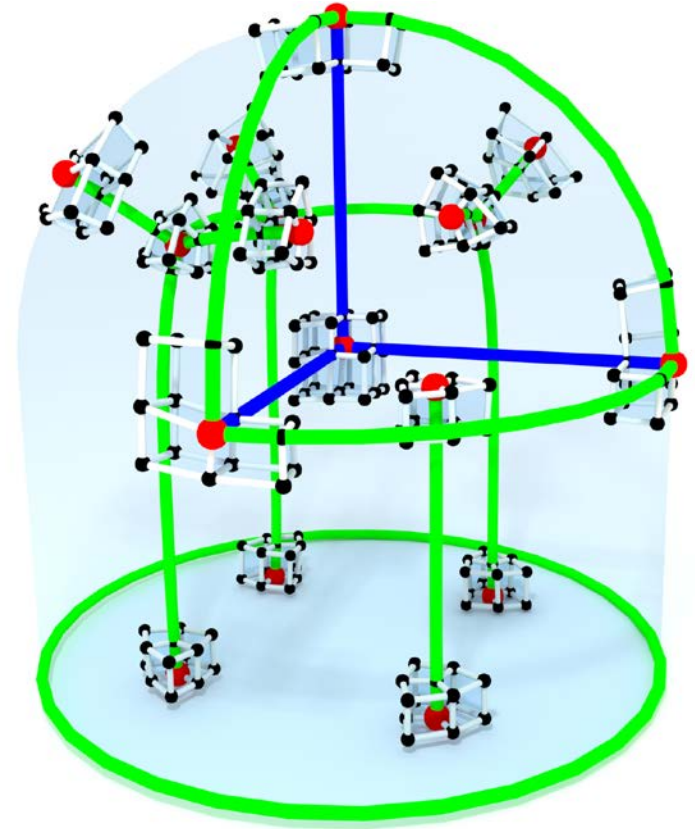
# Challenge

- **Input:**
  - Singularity graph  $\mathcal{S} = (V_{\mathcal{S}}, E_{\mathcal{S}})$ , satisfying
    - global necessary condition
    - local conditions
- **Output:**
  - an octahedral field  $\mathcal{O}$  that is boundary-aligned and matches the singularity graph  $\mathcal{S}$



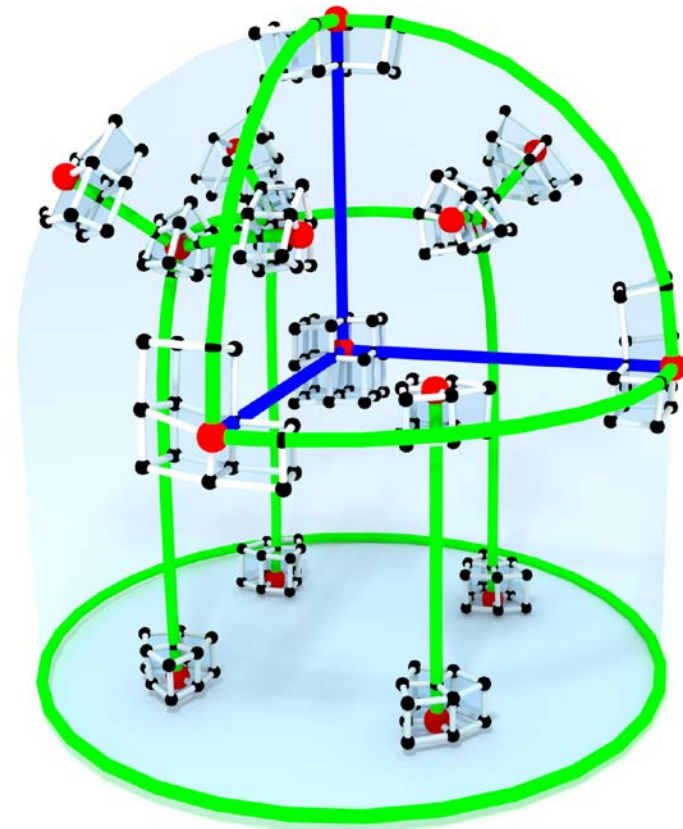
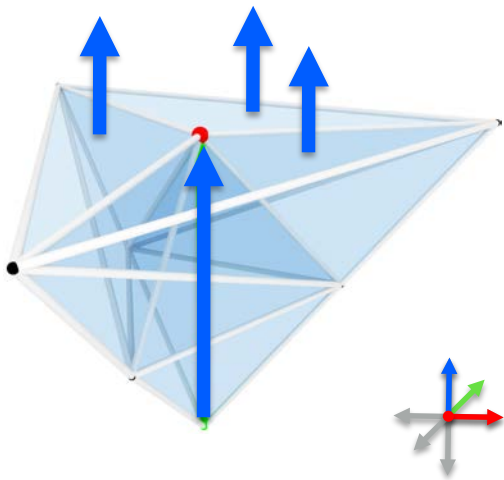
# Challenge

- **Input:**
  - alignment constraints  $A_s$
  - edge type constraints  $E_s$
  - vertex type constraints  $V_s$
- **Output:**
  - topological octahedral field
    - matchings and field alignment



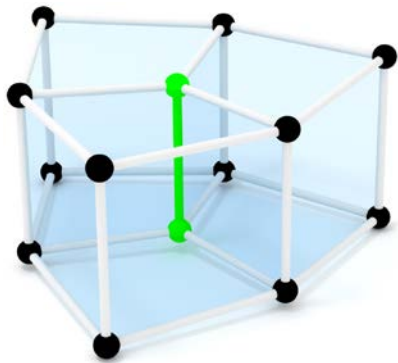
# Singularity Graph Constraints

- **Input:**
  - alignment constraints  $A_s$
  - edge type constraints  $E_s$
  - vertex type constraints  $V_s$

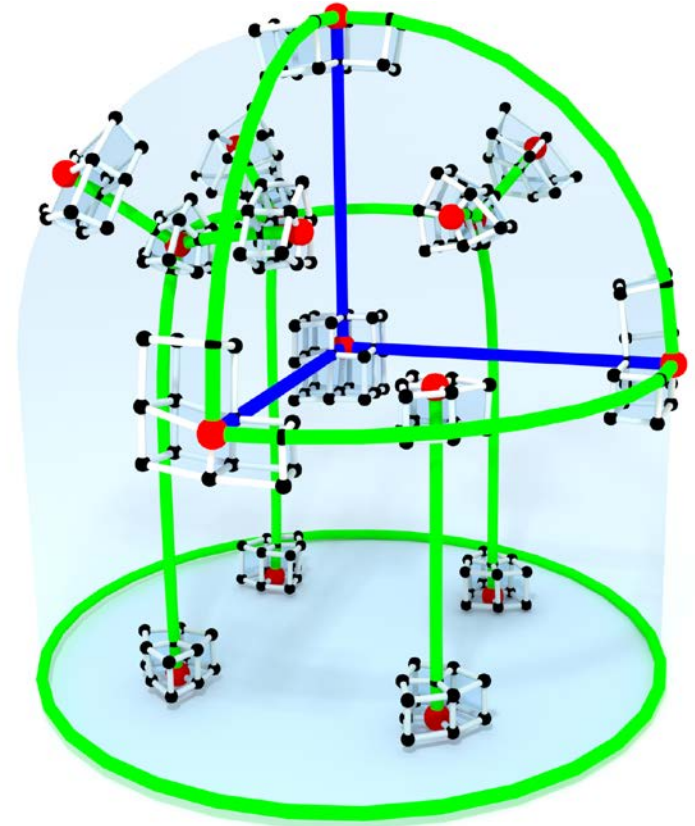


# Singularity Graph Constraints

- **Input:**
  - alignment constraints  $A_s$
  - **edge type constraints  $E_s$**
  - vertex type constraints  $V_s$



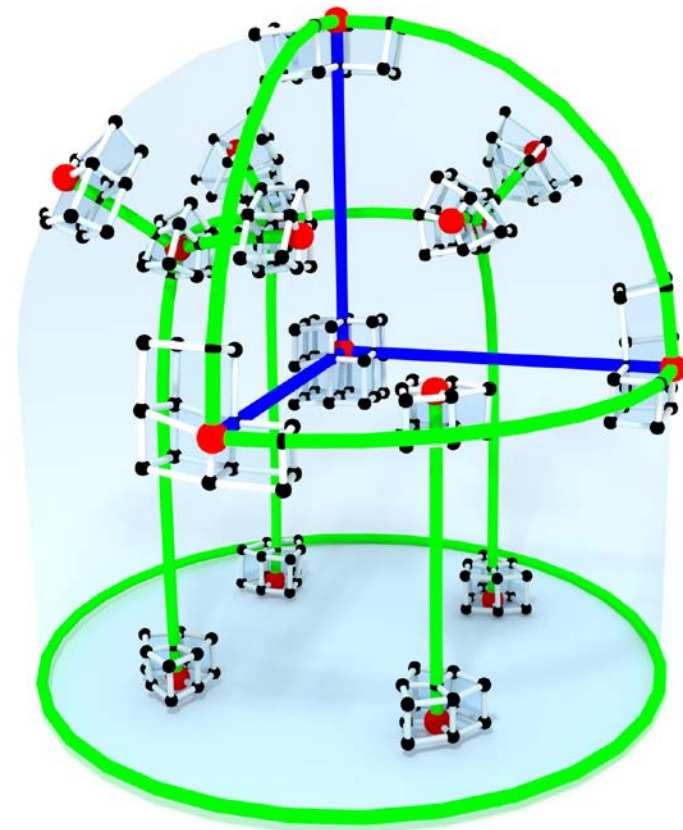
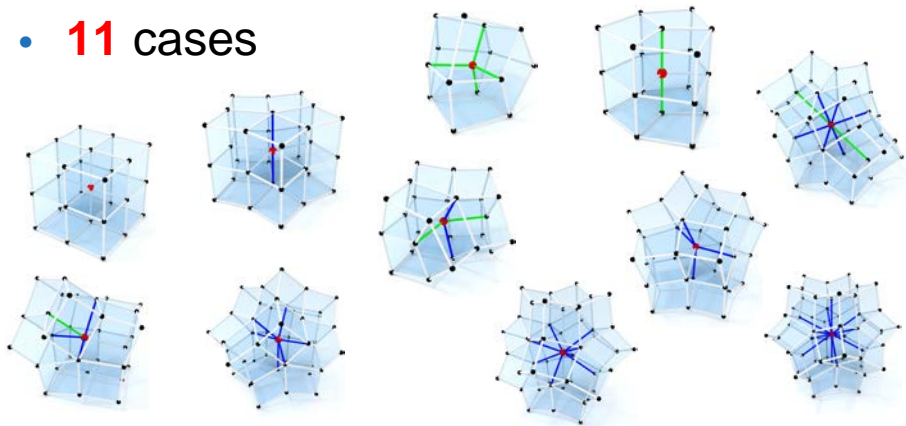
singular  
valence 3





# Singularity Graph Constraints

- **Input:**
  - alignment constraints  $A_s$
  - edge type constraints  $E_s$
  - vertex type constraints  $V_s$
- **11** cases



# Singularity Graph Constraints

- Vertex type constraints

1. “axis-to-axis”

☐ 4 possibilities

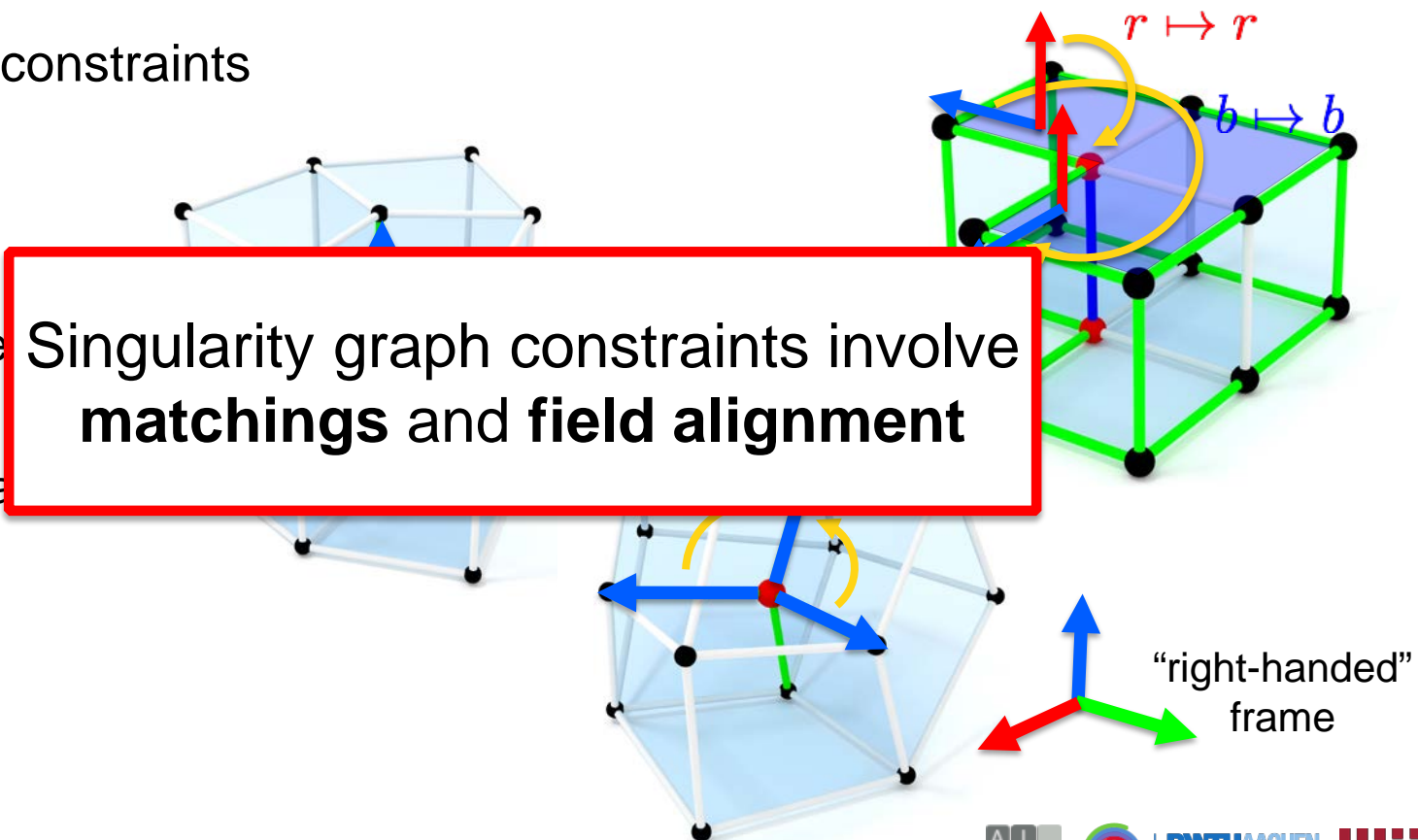
2. “3-axes-corne

☐ 4 possibilities

3. “2-axes-to-2-a

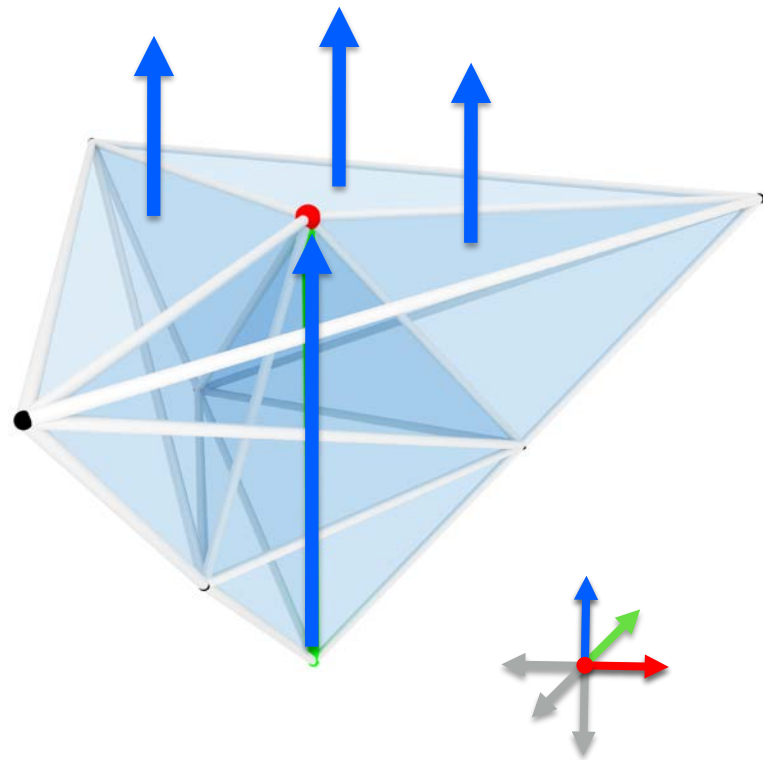
☐ unique

Singularity graph constraints involve **matchings** and **field alignment**



# Singularity Graph Constraints

- **Field alignment topologically matters for**
  - singular edges
  - surface normals
- **Idea:**
  - fix field alignment (arbitrarily) and then derive consistent matchings



# Simplified Algebraic System

- **Input:**

- axis alignment constraints
- one edge type constraint for each tetmesh edge
- vertex type constraints between adjacent singularities



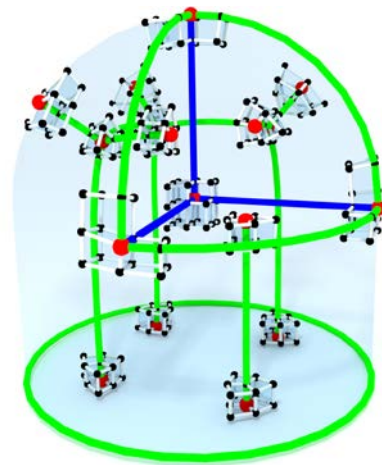
difficult  
algebraic  
system

- **Task:**

- find consistent matchings

- **Idea:**

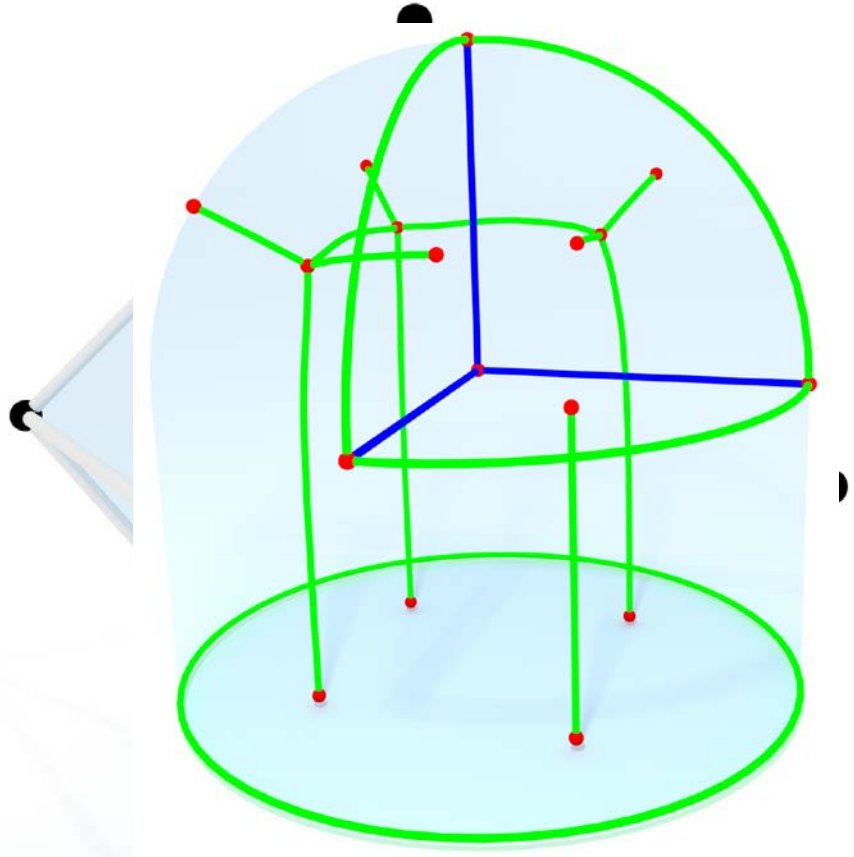
- proceed from where local constraint information is available
  1. locally unique matchings (“2-axes-to-2-axes”)
  2. partially constrained matchings (“axis-to-axis”)



# Algorithm: Chart-Merging

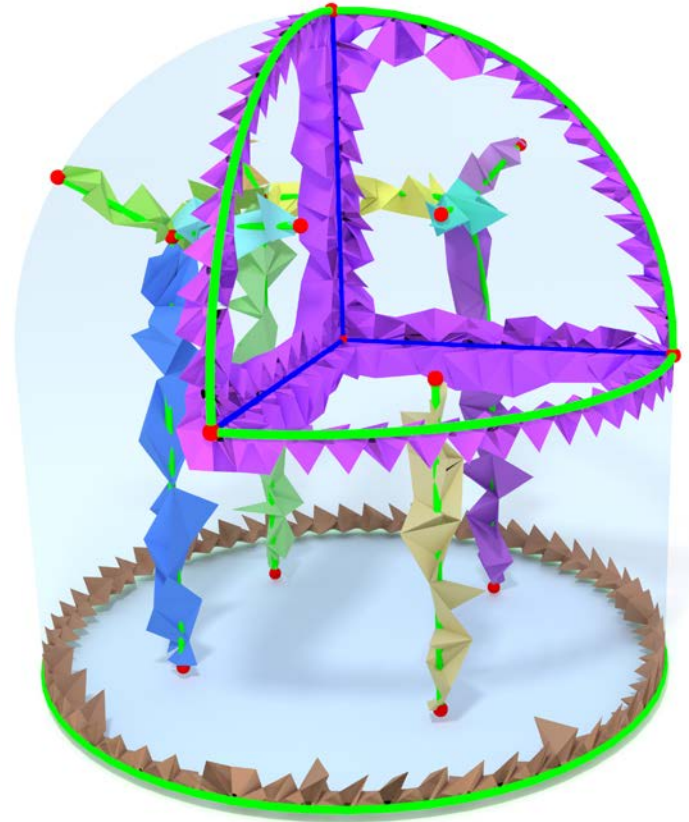
- **Algorithm**

1. MergeSingularArcCharts
2. MergeBoundaryCharts
3. MergeVolumeCharts



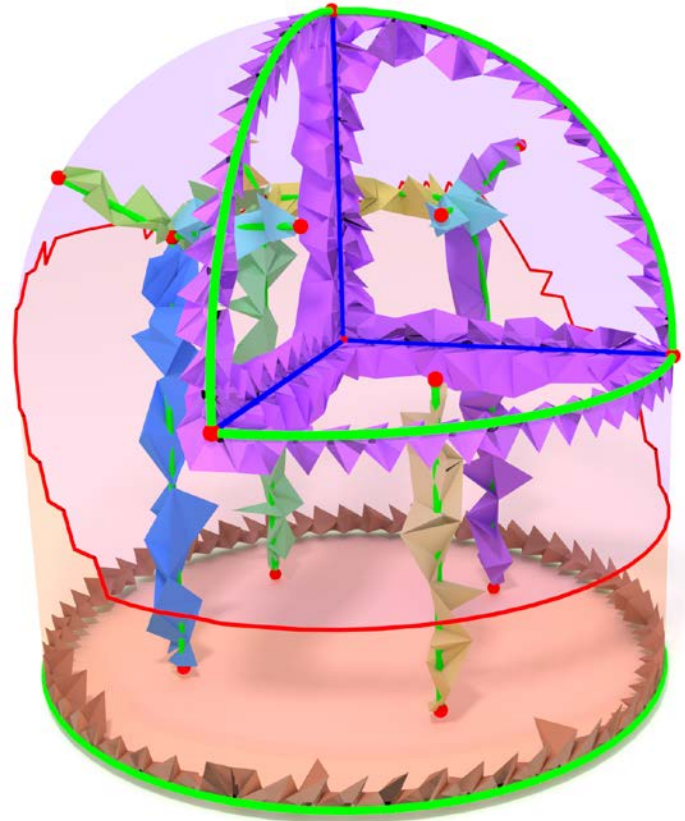
# Algorithm: Chart-Merging

- **Algorithm**
  1. MergeSingularArcCharts
  2. MergeBoundaryCharts
  3. MergeVolumeCharts



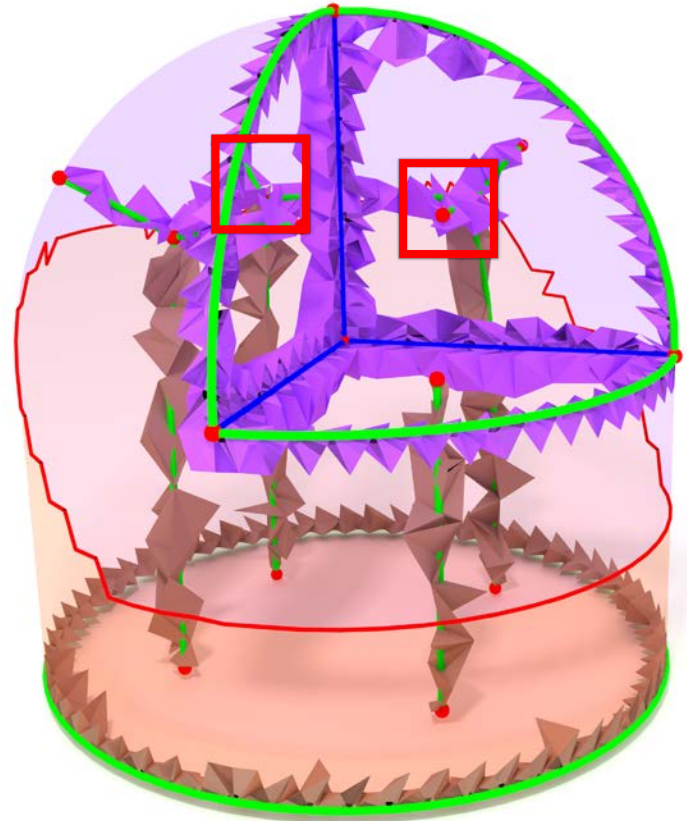
# Algorithm: Chart-Merging

- **Algorithm**
  1. MergeSingularArcCharts
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# Algorithm: Chart-Merging

- **Algorithm**
  1. MergeSingularArcCharts
  2. MergeBoundaryCharts
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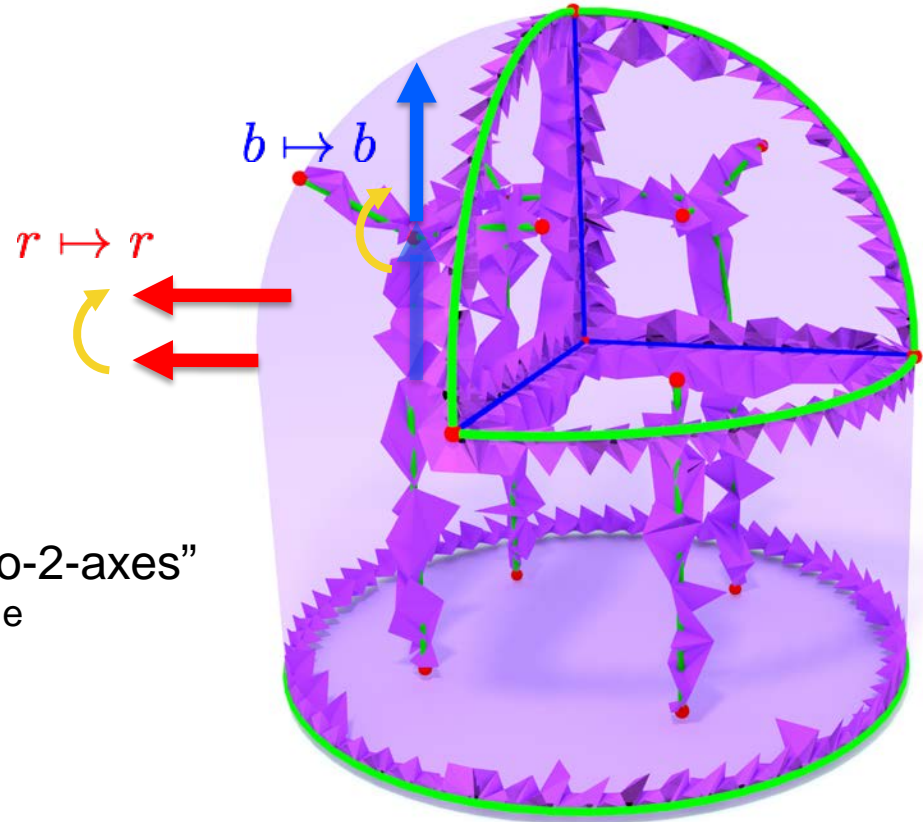




# Algorithm: Chart-Merging

- **Algorithm**

1. MergeSingularArcCharts
2. MergeBoundaryCharts
3. MergeVolumeCharts

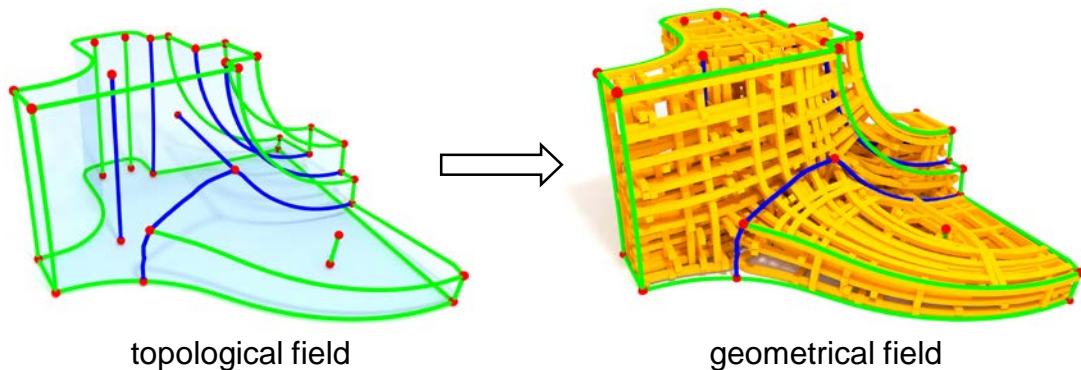


“2-axes-to-2-axes”  
☐ unique

# Algorithm: Topological Field to Geometrical Field

- **Input:**

- Axes alignment
- Matchings

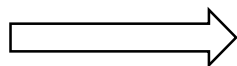


minimize  $\int_{\Omega} \|\nabla q\|^2 dV$

subject to:  $A_i q_i = 0, q_i \in B$

$\|q_i\|^2 = 1, i = 1, \dots, n$

Relaxation



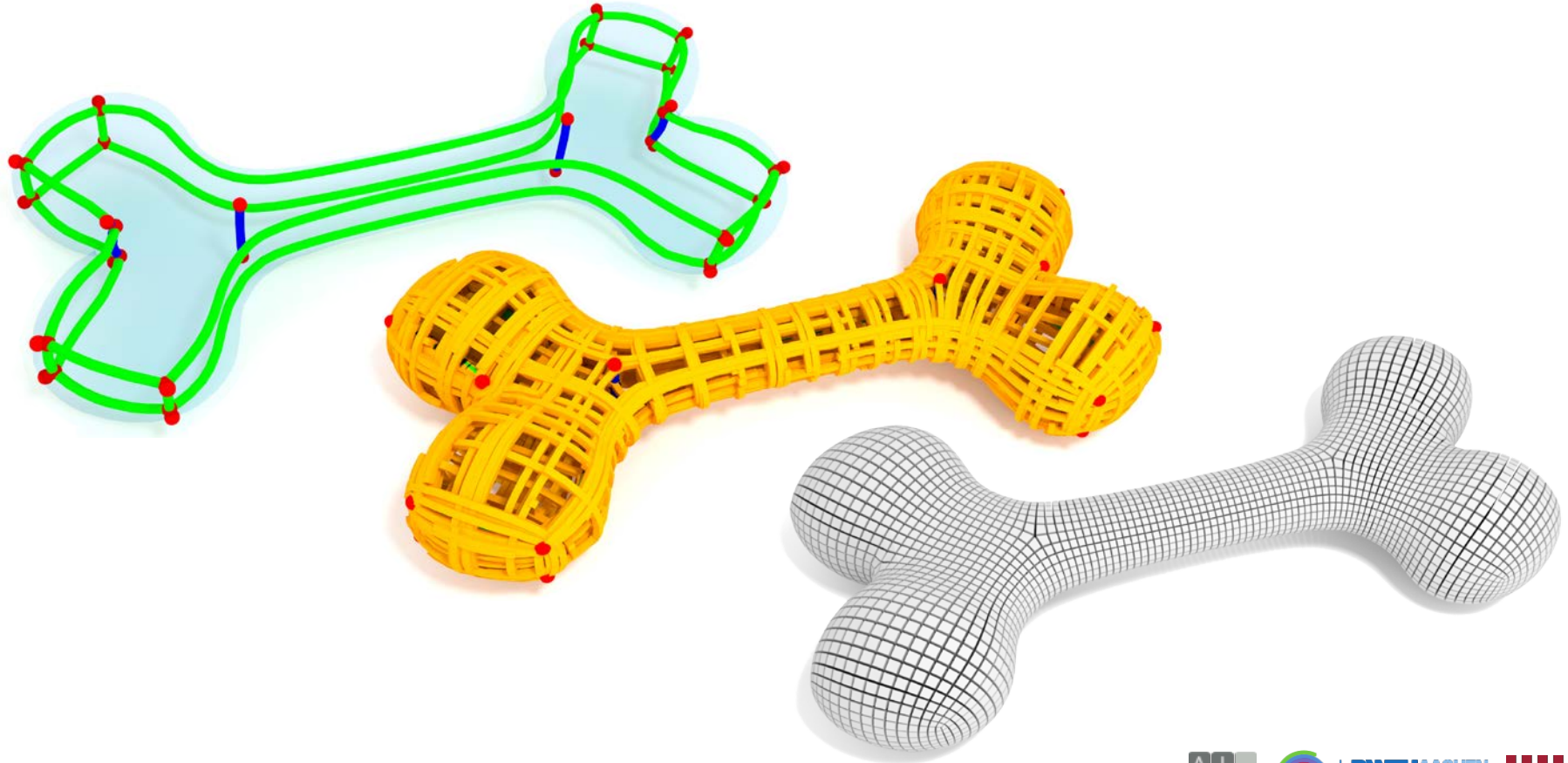
minimize  $q^T Q q$

subject to:  $\sum_i \|q_i\|^2 = n, i = 1, \dots, n$

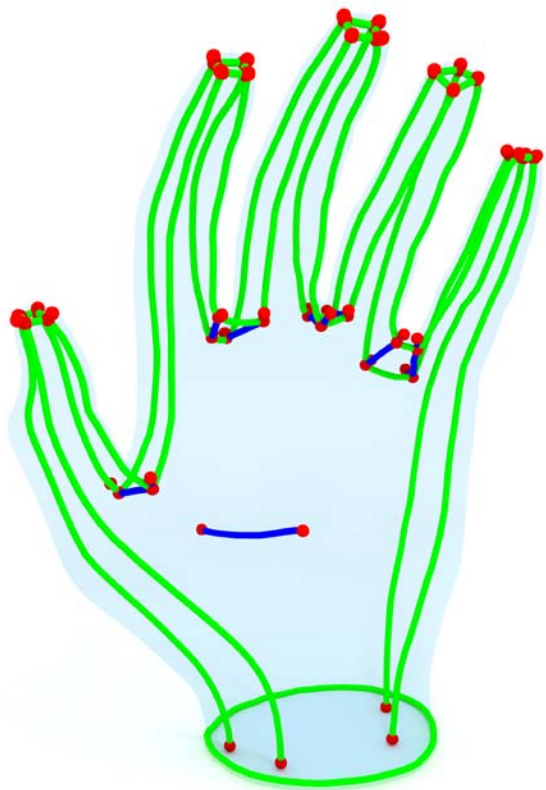
**Eigenvalue Problem**

# Results

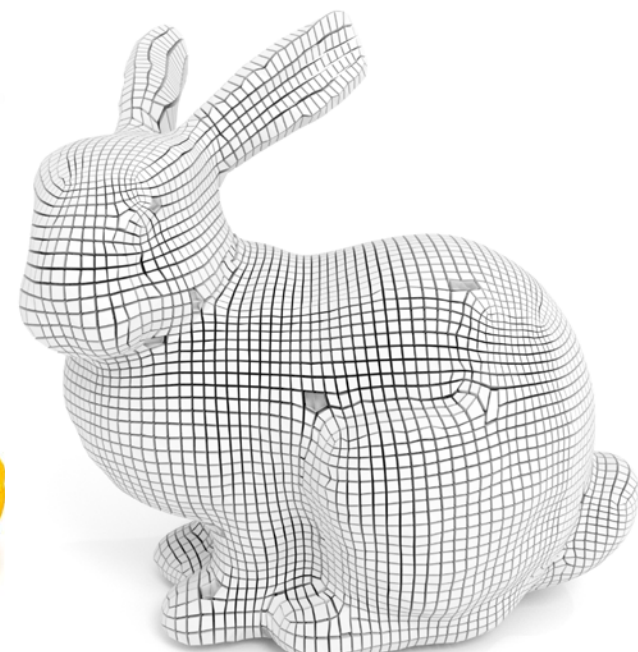
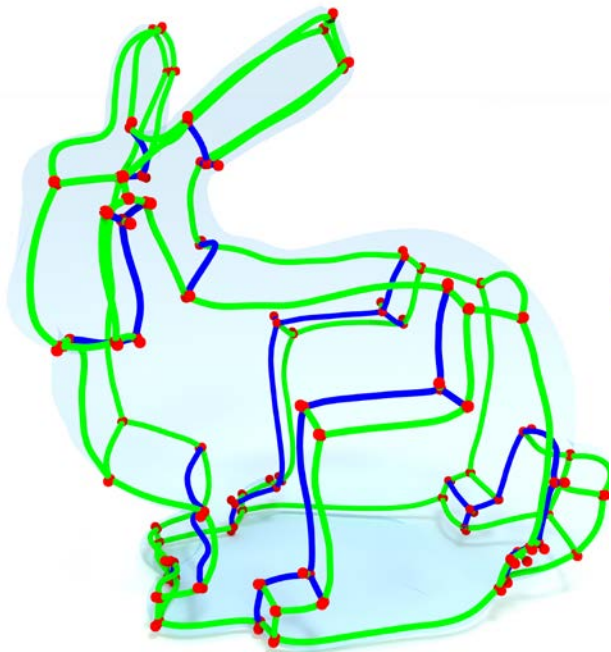
# Results-Bone[Tets: 71k Time: 0.9s/54.0s]



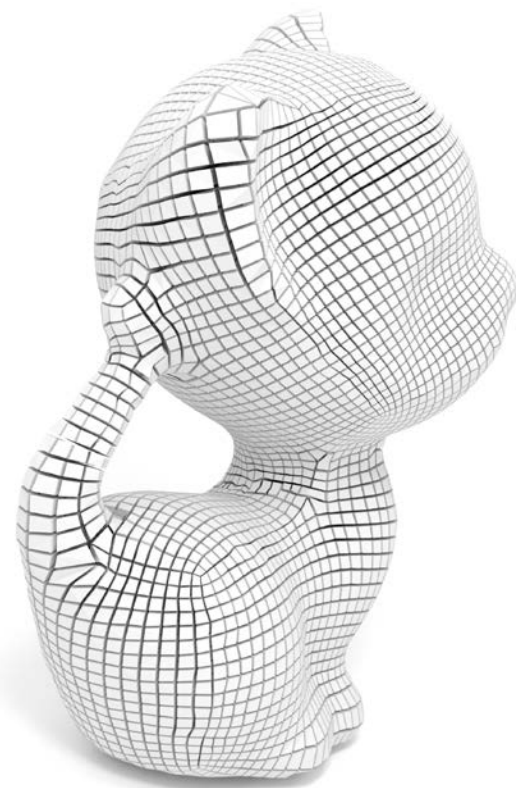
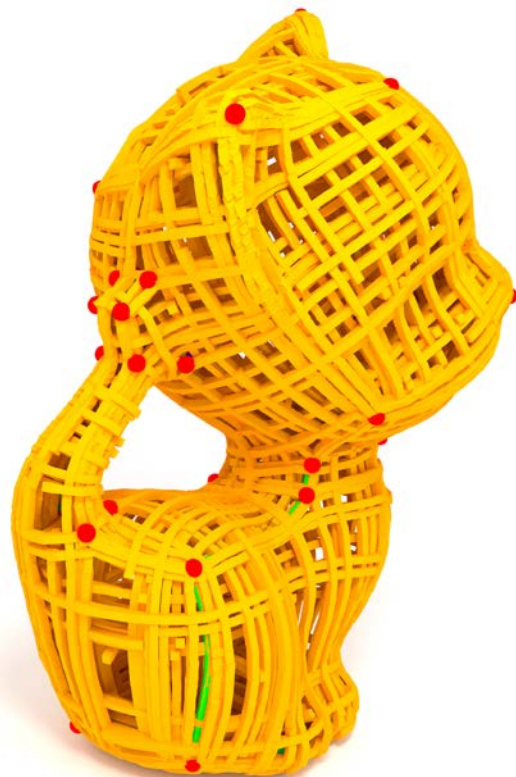
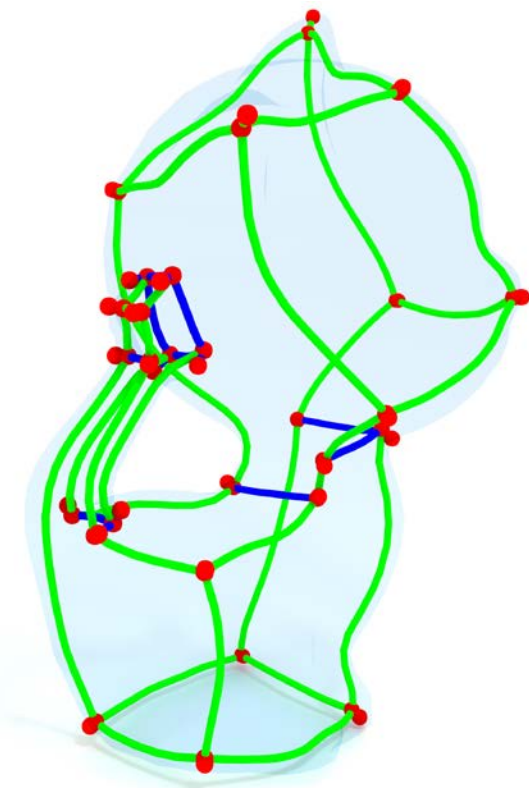
# Results-Hand[Tets: 113k Time: 1.8s/34.9s]



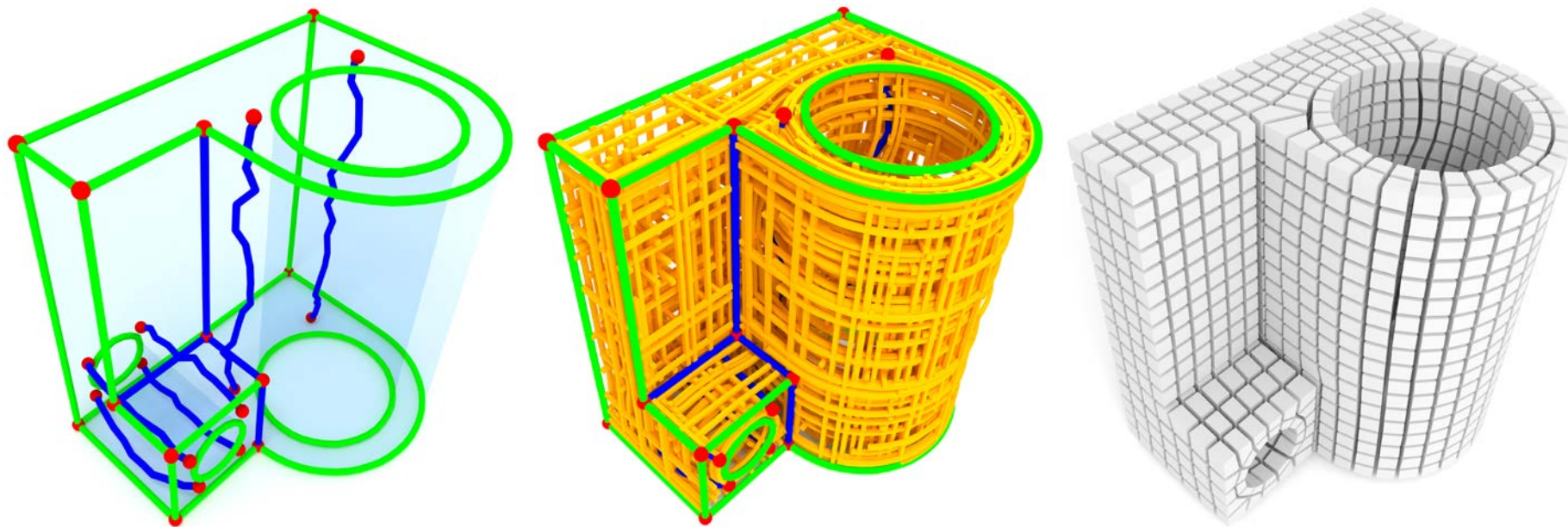
# Results-Bunny[Tets: 130k Time: 2.7s/53.2s]



# Results-Kitten[Tets: 55k Time: 1.8s/28.3s]

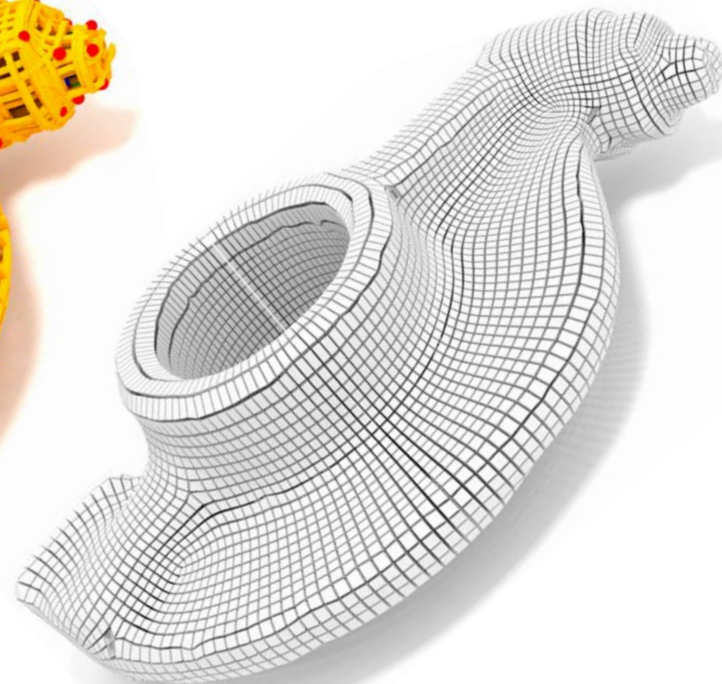
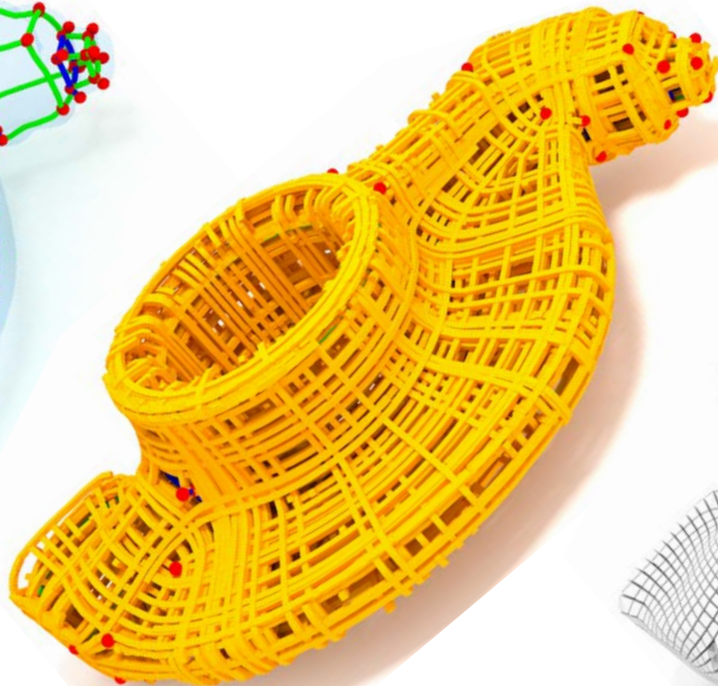
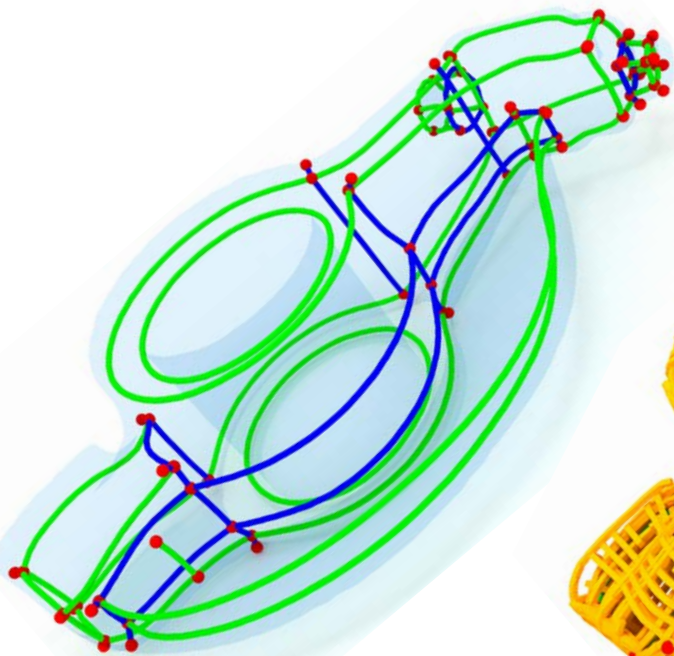


# Results-Joint[Tets: 44k Time: 0.5s/13.6s]

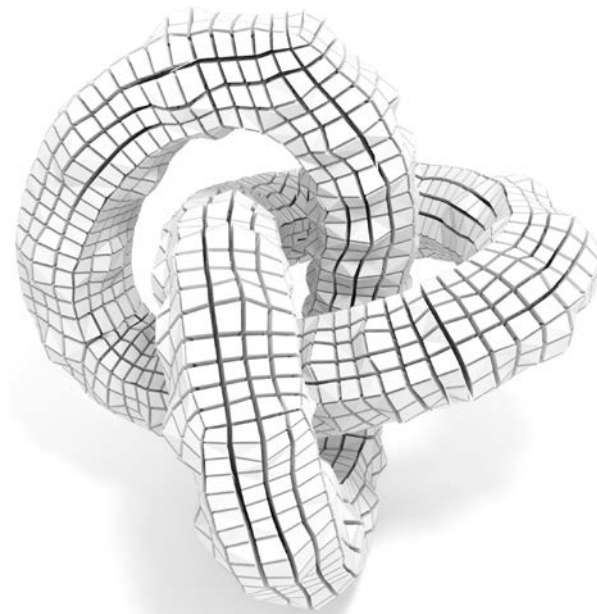
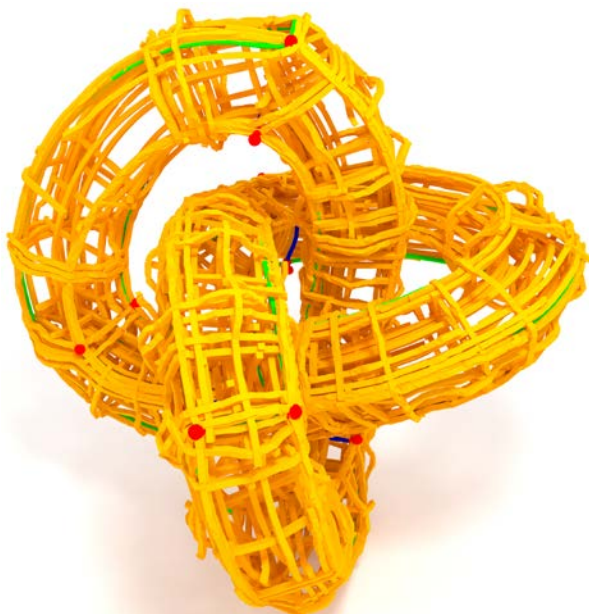
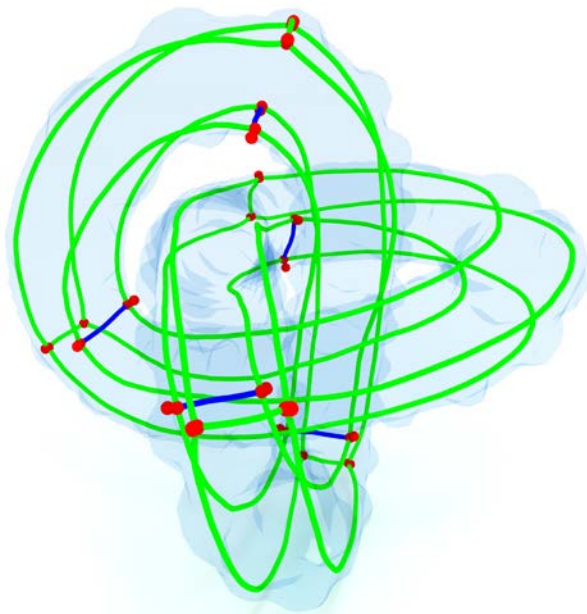




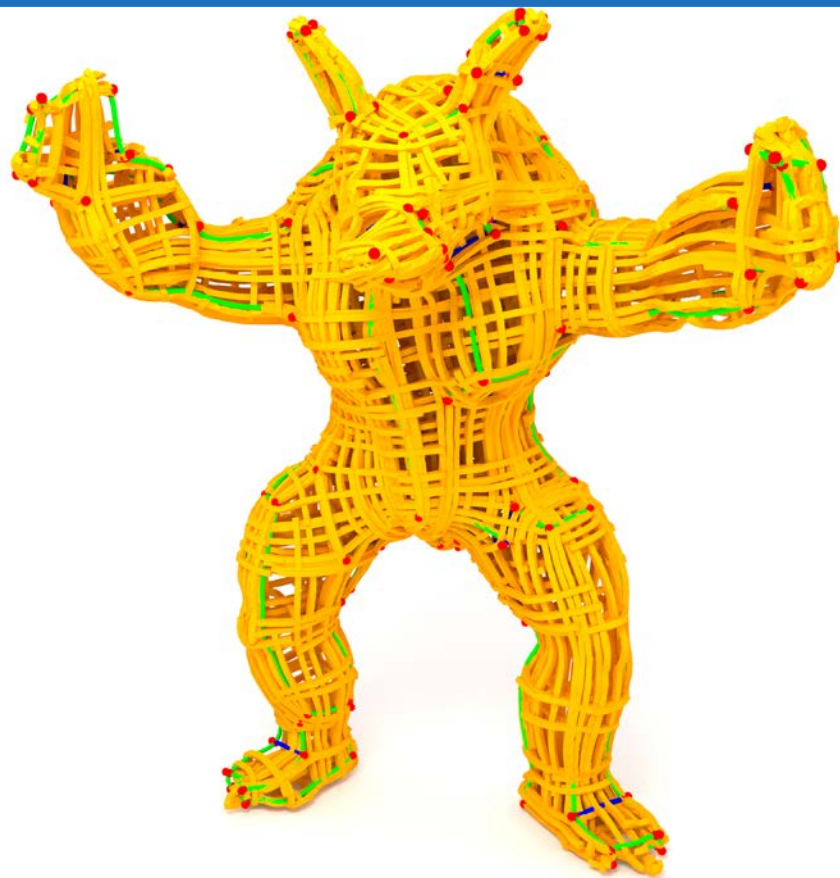
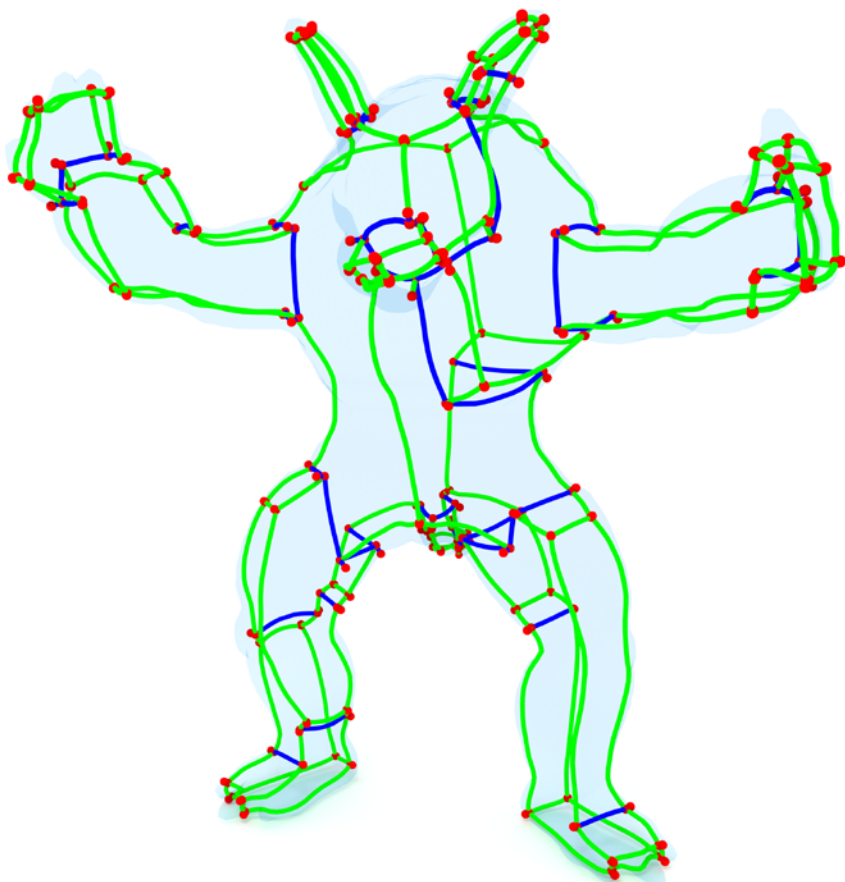
# Results-Rockerarm[Tets: 122k Time: 3.1s/67.5s]



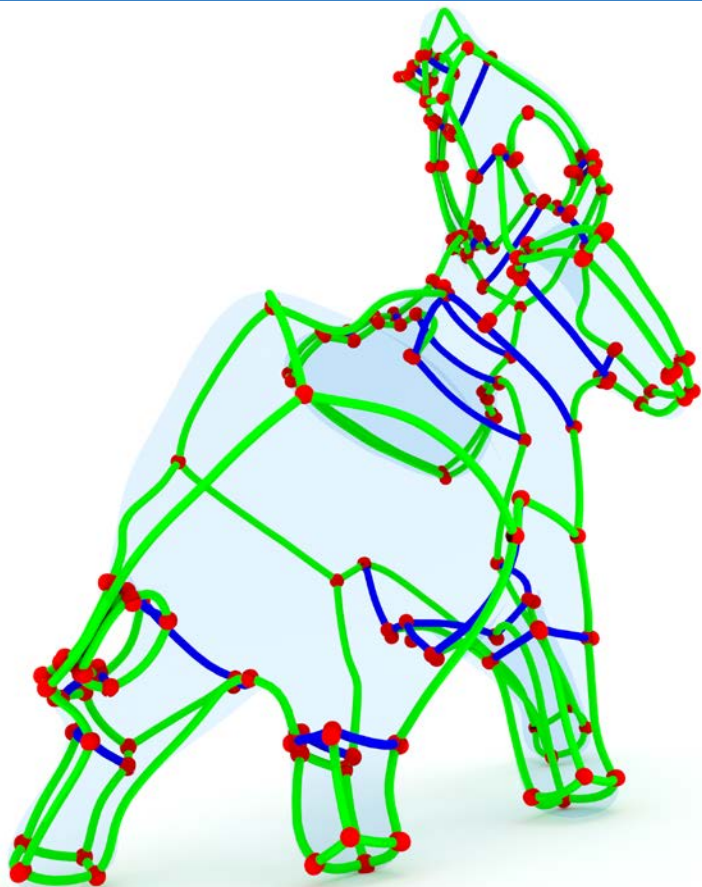
# Results-Knot[Tets: 131k Time: 1.8s/47.3s]



# Results-Armadillo[Tets: 206k Time: 6.0s/83.4s]



# Results-Elephant[Tets: 301k Time: 9.9s/88s]



# Summary & Outlook

# Summary & Outlook

- **Contribution**

- Necessary conditions: hex mesh singularities with valence 3, 4, 5 (and some more)
- Algorithm: octahedral-fields with fixed topology

- **Future Challenges**

- Sufficient conditions: local consistency & global consistency
- Automatic correction of invalid singularity graph
- Robust integer-quantization & mapping  $\Rightarrow$  automatic high-quality hex meshing

# Thank You!