Unsupervised Learning of Probably Symmetric Deformable 3D Objects from Images in the Wild

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Agenda

- Problem Introduction
- Method Overview
- Results
- Discussions
- Conclusions

What is 3D Reconstruction?





2D Observations

3D Representation

Multi-view 3D Reconstruction





Building Rome in a Day. Agarwal et al. ICCV'09

static scene



but.. the world is dynamic

Multi-view 3D Reconstruction



~100x 12MP cameras @ 60Hz

Building Rome in a Day. Agarwal et al. ICCV'09

static scene

The Relightables: Volumetric Performance Capture of Humans with Realistic Relighting. Guo et al. SIGGRAPH Asia'19

100 cameras too expensive for me :(

Learning-based Single-view 3D Reconstruction



Supervision during Training



3D ground truth or shape models



multi-views





depth maps



silhouettes



keypoints



camera viewpoint

Unsupervised Learning of 3D Objects



3D ground truth or shape models



multi-views



depth maps



silhouettes



keypoints



camera viewpoint

Unsupervised Learning of 3D Objects

Training Data

Output



single-view images of a category NO other supervision!

instance-specific 3D shapes











input























































reconstruction

Unsupervised Learning of 3D Objects

Training Data

Output



single-view images of a category NO other supervision!

instance-specific 3D shapes

Symmetries in the World







Training Pipeline: Photo-Geometric Autoencoding





Q1: How to avoid degenerate solutions?



Q1: How to avoid degenerate solutions?

A1: Enforce symmetry



Q1: How to avoid degenerate solutions?



Q1: How to avoid degenerate solutions?



Q1: How to avoid degenerate solutions?



Q1: How to avoid degenerate solutions?



Q1: How to avoid degenerate solutions?



Q2: What about non-symmetric lighting?





Q2: What about non-symmetric lighting?

A2: Enforce symmetry on albedo



Q3: Non-symmetric albedo, deformation, etc?





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Q3: Non-symmetric albedo, deformation, etc?

A3: Predict uncertainty



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Q3: Non-symmetric albedo, deformation, etc?



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Q3: Non-symmetric albedo, deformation, etc?





Results on human faces

Images taken from CelebA, 3DFAW











input















reconstruction











input

























reconstruction



Results on face paintings

Images taken from [1]

[1] Elliot J. Crowley, Omkar M. Parkhi, and Andrew Zisserman. Face painting: querying art with photos. In Proc. BMVC, 2015.

















reconstruction





































reconstruction

64



Results on abstract faces

Images taken from [1] and the Internet

































































input

reconstruction





Results on video frames

Video clips taken from VoxCeleb2

We do **not** use videos for training or fine-tuning. These results are obtained by applying our model trained on CelebA **frame by frame**.



input



input







new view



rotated





recon.

new view

rotated



input









recon.

new view

recon.

new view

rotated































Relighting effects

Images taken from CelebA











input













reconstruction











input



















reconstruction



Results on cat faces

Images taken from [2] and [3]

[2] Weiwei Zhang, Jian Sun, and Xiaoou Tang. Cat head detection - how to effectively exploit shape and texture features. In Proc. ECCV, 2008.
 [3] Omkar M. Parkhi, Andrea Vedaldi, Andrew Zisserman, and C. V. Jawahar. Cats and dogs. In Proc. CVPR, 2012.











input















reconstruction



































input

reconstruction



Results on synthetic cars

Images rendered using ShapeNet



Symmetry Plane Visualization



Asymmetry Visualization





Discussion: Ablation Studies

Ablation – Symmetry





Ablation – Lighting (Shape from Shading)



Insight #2: Lighting avoids bumpy shapes and provides cues for shape

Ablation – Confidence Maps

Asymmetry perturbation



conf. σ conf. σ'



input



recon. w/ conf.



Insight #3: Confidence maps allows for asymmetry modelling



Discussion:

Limitations

Limitation #1: Poor side reconstruction



Why?

- Canonical depth map cannot represent the shape of the side

Limitation #2: Side pose input





input



reconstructions

Why?

- There are no/few symmetric correspondences present in the image, which voids the symmetry regularization
- No enough side images in the training set

Limitation #3: Lambertian shading



input





reconstructions

Why?

- We assume Lambertian shading with one dominant directional light, and do not model specularity and shadow

Limitation #4: Dark texture vs. dark shading



input



reconstructions

Why?

- Disentangling dark texture and dark shading is hard. The model may produce dark shading with spiky shape to reconstruct dark texture.

Conclusions

- We present an <u>unsupervised</u> method for learning deformable
 3D objects from only raw single-view images
- <u>Bilateral symmetry</u> in common objects provides a powerful constraint for learning 3D shapes
- <u>Shading</u> provides important geometric cues and helps regularize shape
- By modeling symmetric albedo and non-symmetric shading separately, our model automatically learns <u>intrinsic image</u> <u>decomposition</u> without supervision
- Confidence maps can be used to model asymmetries

Key Takeaways

- 3D understanding is possible from only single-view 2D observations; image recognition should go beyond 2D
- Reducing supervision in training is important for 3D understanding in the wild
- Physical cues and visual patterns are useful, such as symmetry, shading, planes, repetitions, etc

Demo



He more a cost of the contracted integrited high, where which 3 will be automatically determined. The optimated integrals talk cases for any other purposes



Thank you!



Demo: <u>bit.ly/2zBNjXx</u> Code: <u>github.com/elliottwu/unsup3d</u>



