

Making a NeRF Relightable With Shadows

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GAMES 06/21/2021

Lighting is crucial to realism and aesthetics.



Caravaggio's "The Calling of Saint Matthew"

<https://www.caravaggio-foundation.org/The-Calling-Of-Saint-Matthew.html>

Paintings



Games

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Paintings



Games



"This Is the Way: How Innovative Technology Immersed Us in the World of the Mandalorian"

<https://www.starwars.com/news/the-mandalorian-stagecraft-feature>

Movies

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Paintings



Games



"This Is the Way: How Innovative Technology Immersed Us in the World of the Mandalorian"

<https://www.starwars.com/news/the-mandalorian-stagecraft-feature>

Movies



"Understanding Photography Lighting - The Essential Beginners Guide"

<https://www.pixpa.com/blog/photography-lighting>

Photography

Relighting has wide applications, ...



Guo et al. [SIGGRAPH Asia 2019]

VR and AR

Relighting has wide applications, ...



Guo et al. [SIGGRAPH Asia 2019]

VR and AR



Google's Portrait Light

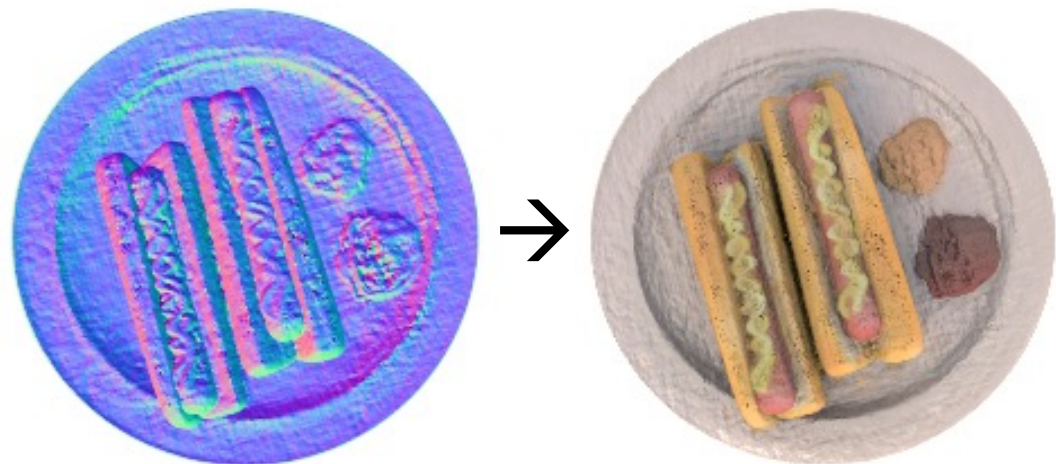
Photo Enhancement

... but it is hard.

Local

Non-Local

... but it is hard.

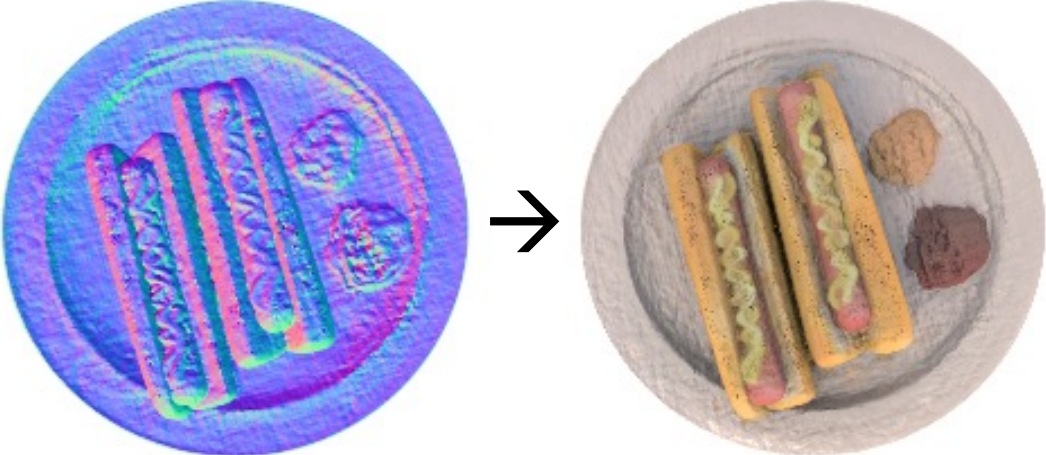


Geometry: bumpy normals \rightarrow noisy render

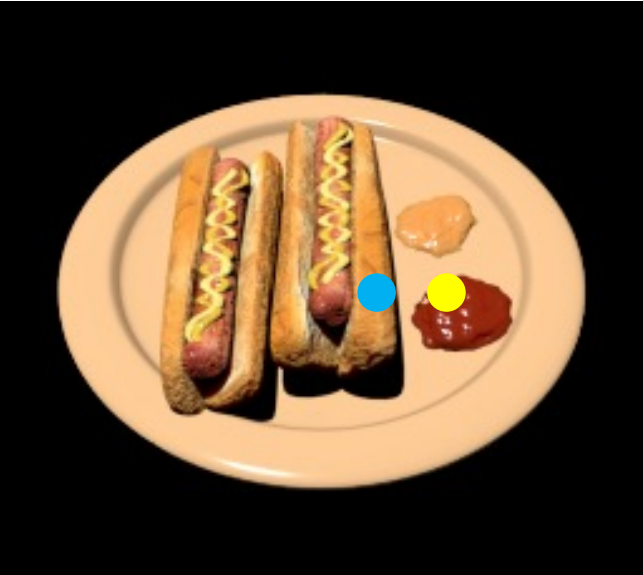
Local

Non-Local

... but it is hard.



Geometry: bumpy normals → noisy render

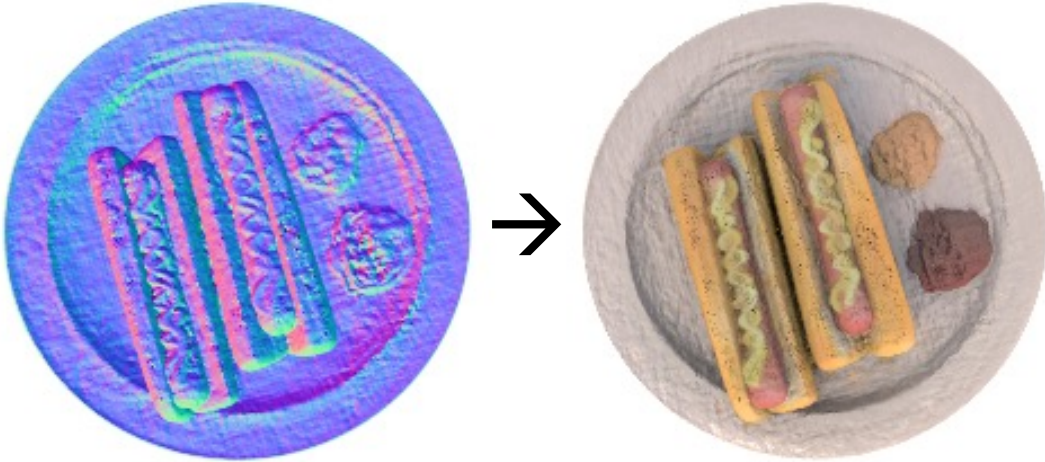


BRDFs: high-dimensional & spatially-varying

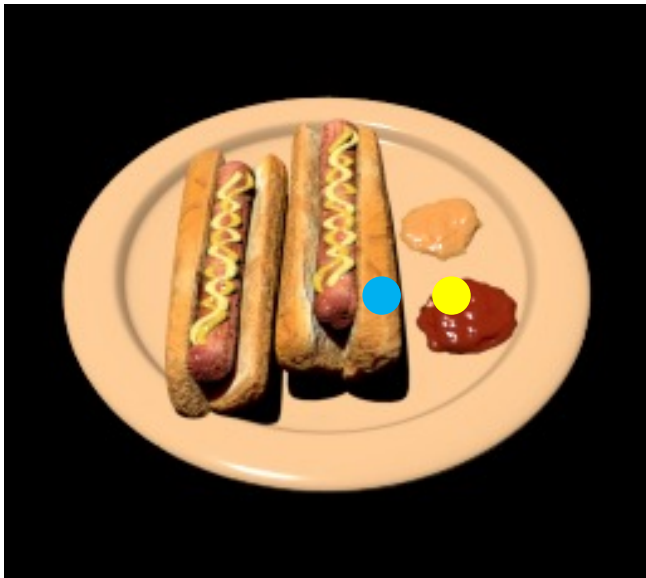
Local

Non-Local

... but it is hard.



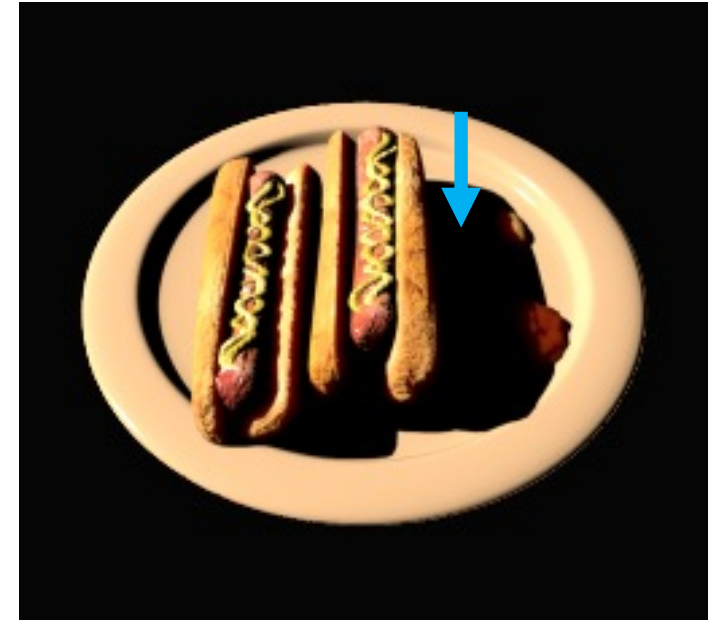
Geometry: bumpy normals → noisy render



BRDFs: high-dimensional & spatially-varying

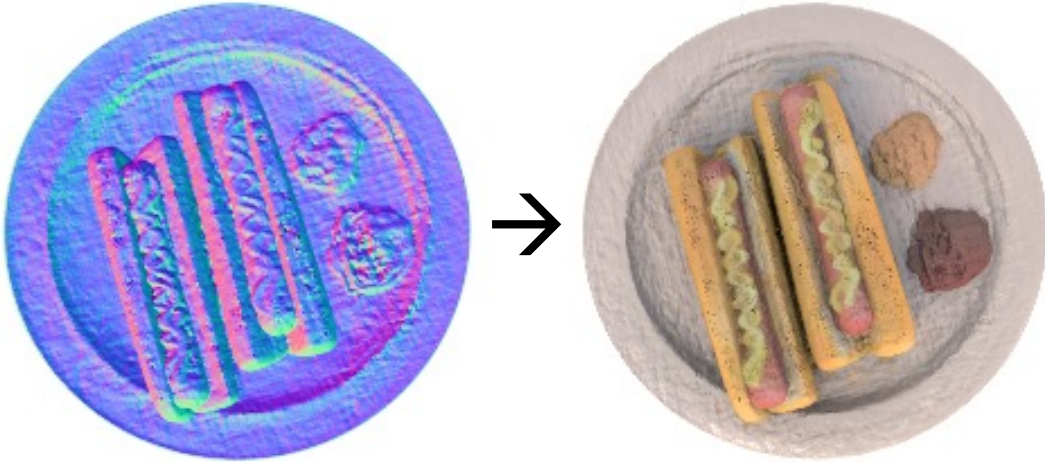
Local

Shadowing: non-local geometry casting shadows

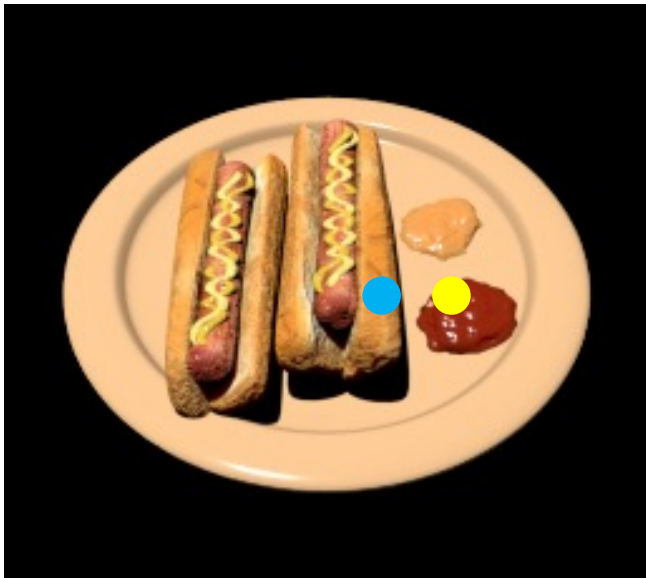


Non-Local

... but it is hard.



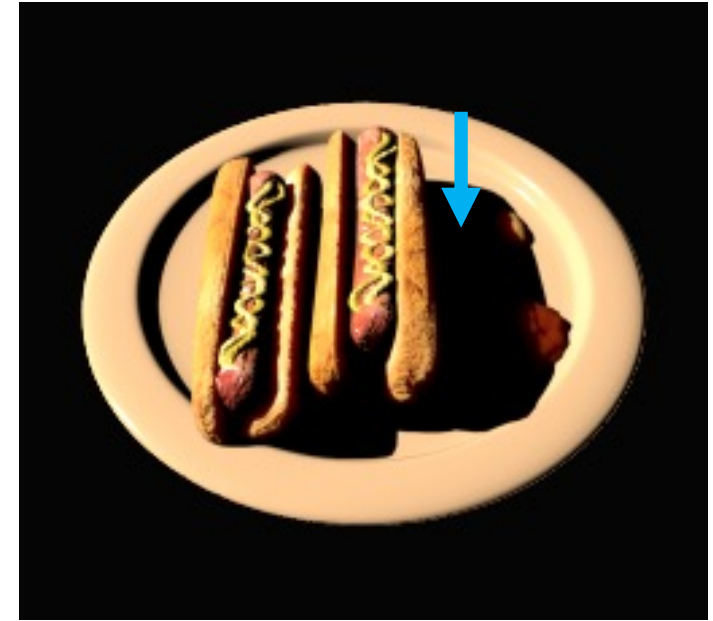
Geometry: bumpy normals → noisy render



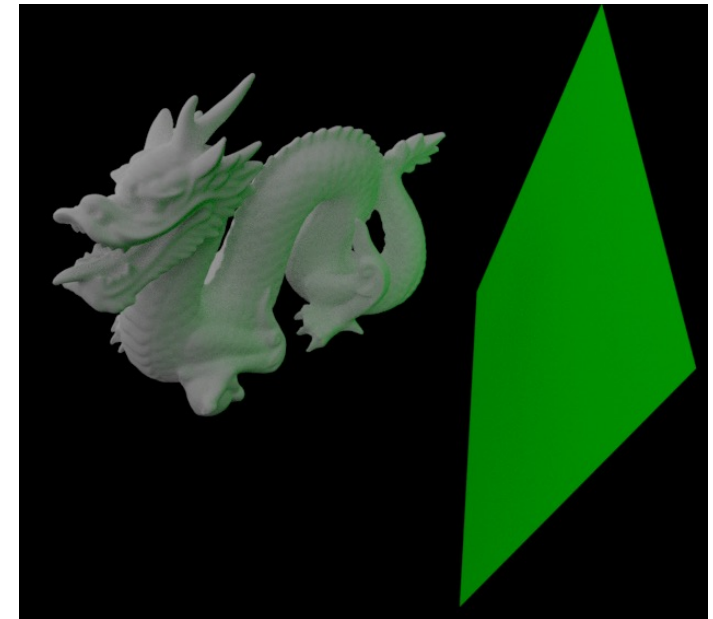
BRDFs: high-dimensional & spatially-varying

Local

Shadowing: non-local geometry casting shadows

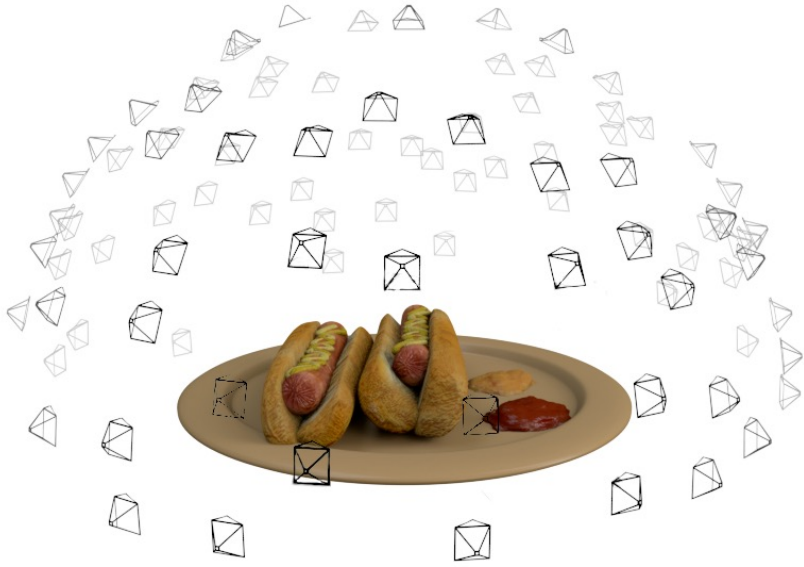


Global Illumination

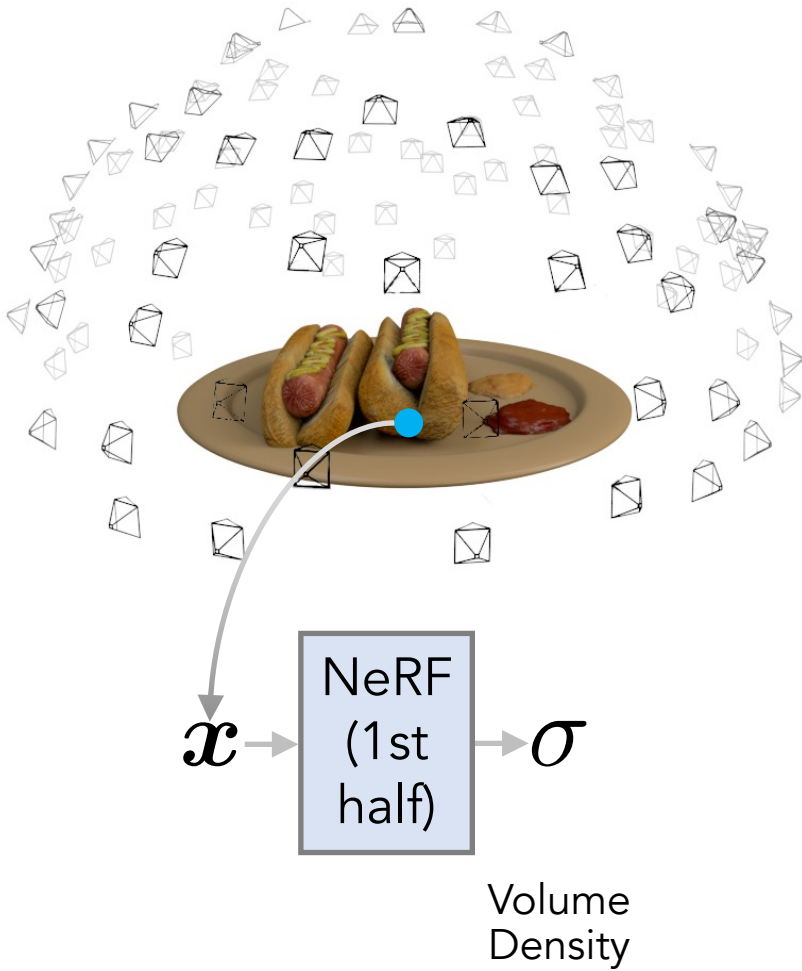


Non-Local

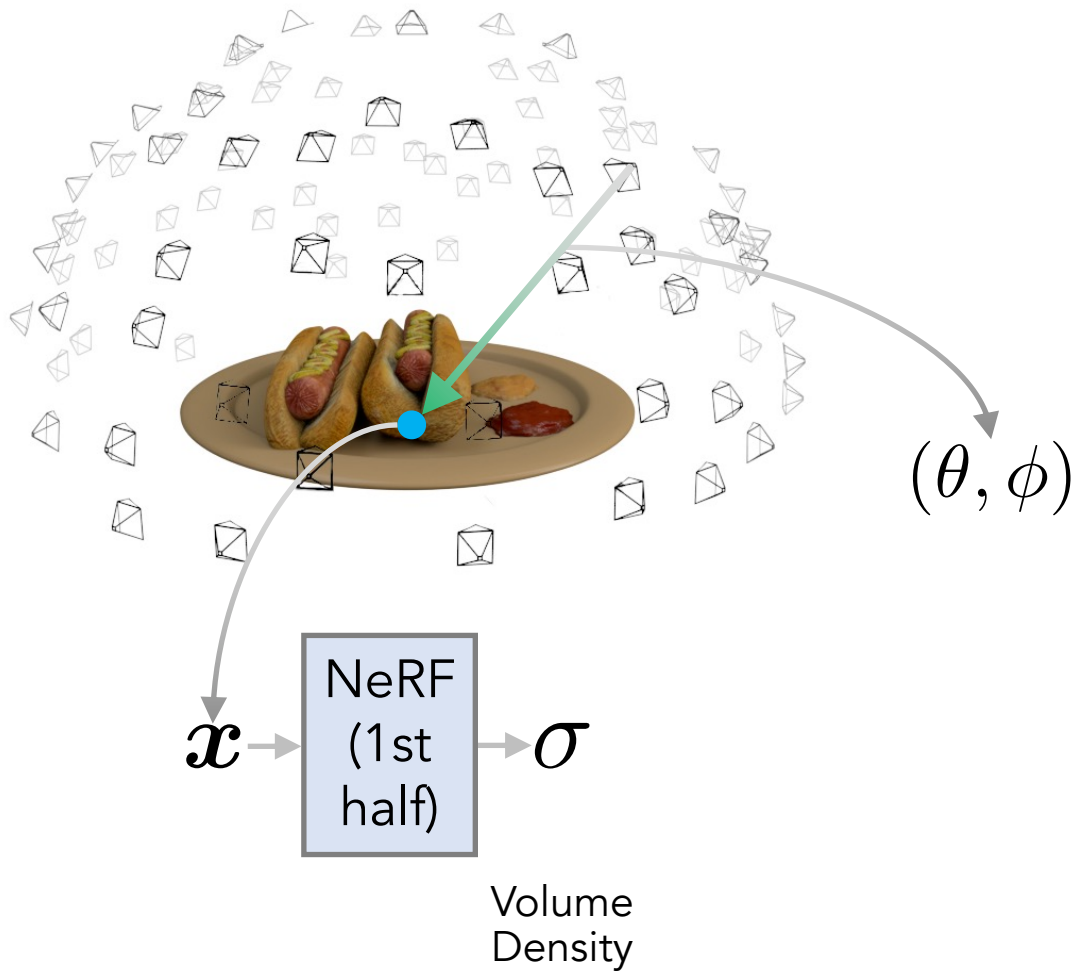
Neural Radiance Fields (NeRF) [Mildenhall et al. 2020]



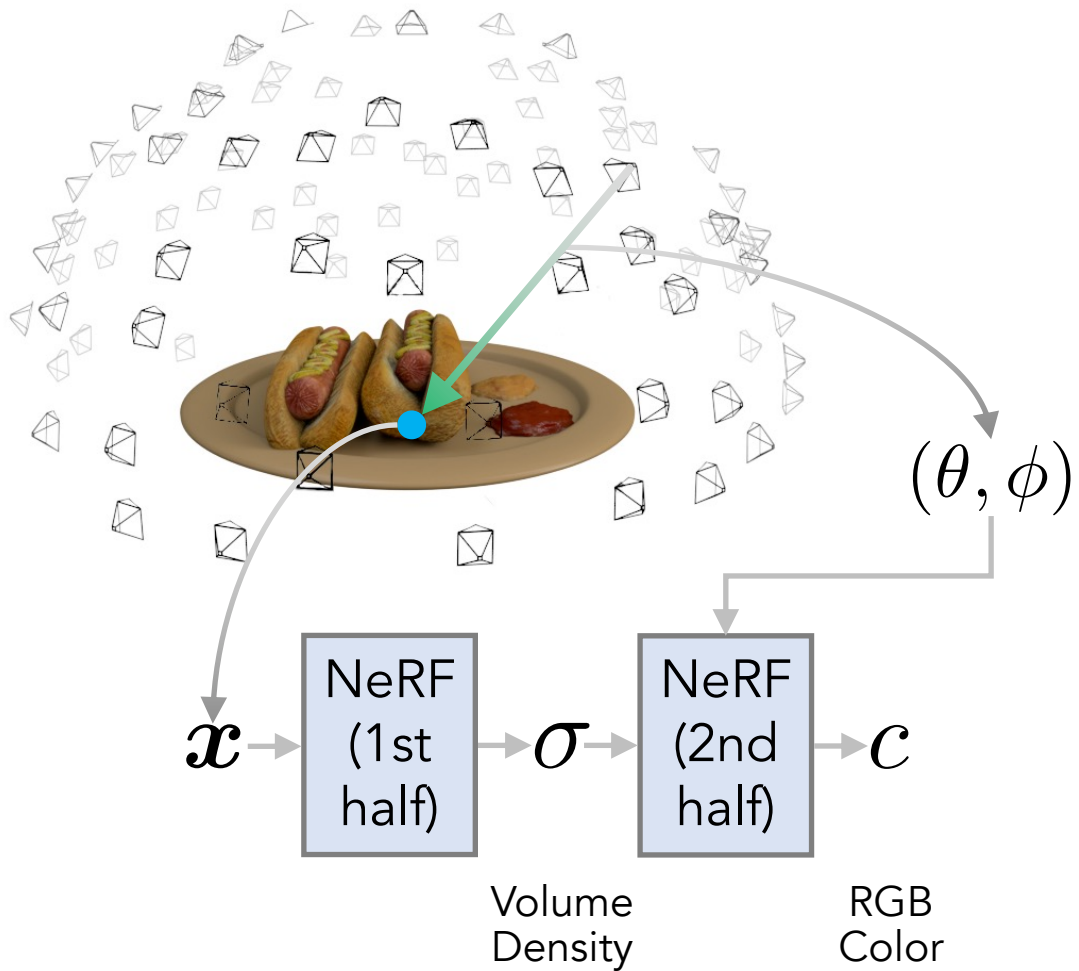
Neural Radiance Fields (NeRF) [Mildenhall et al. 2020]



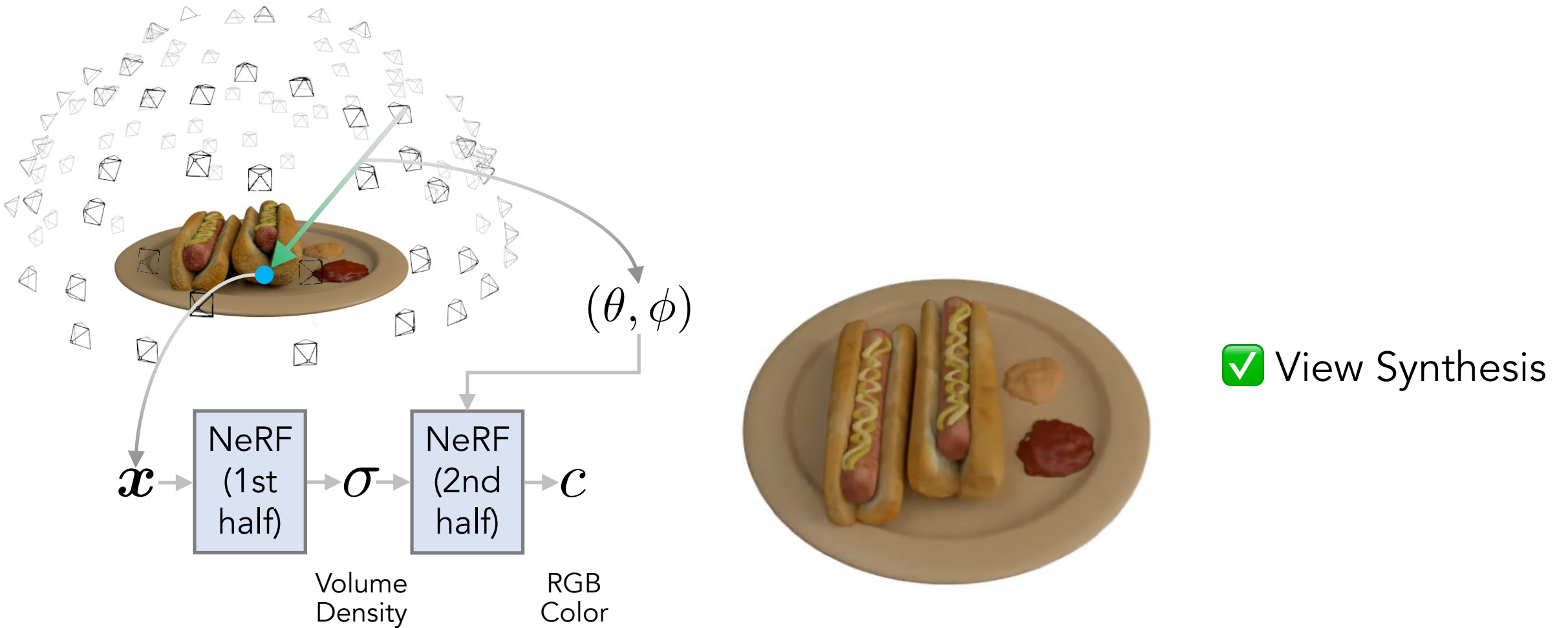
Neural Radiance Fields (NeRF) [Mildenhall et al. 2020]



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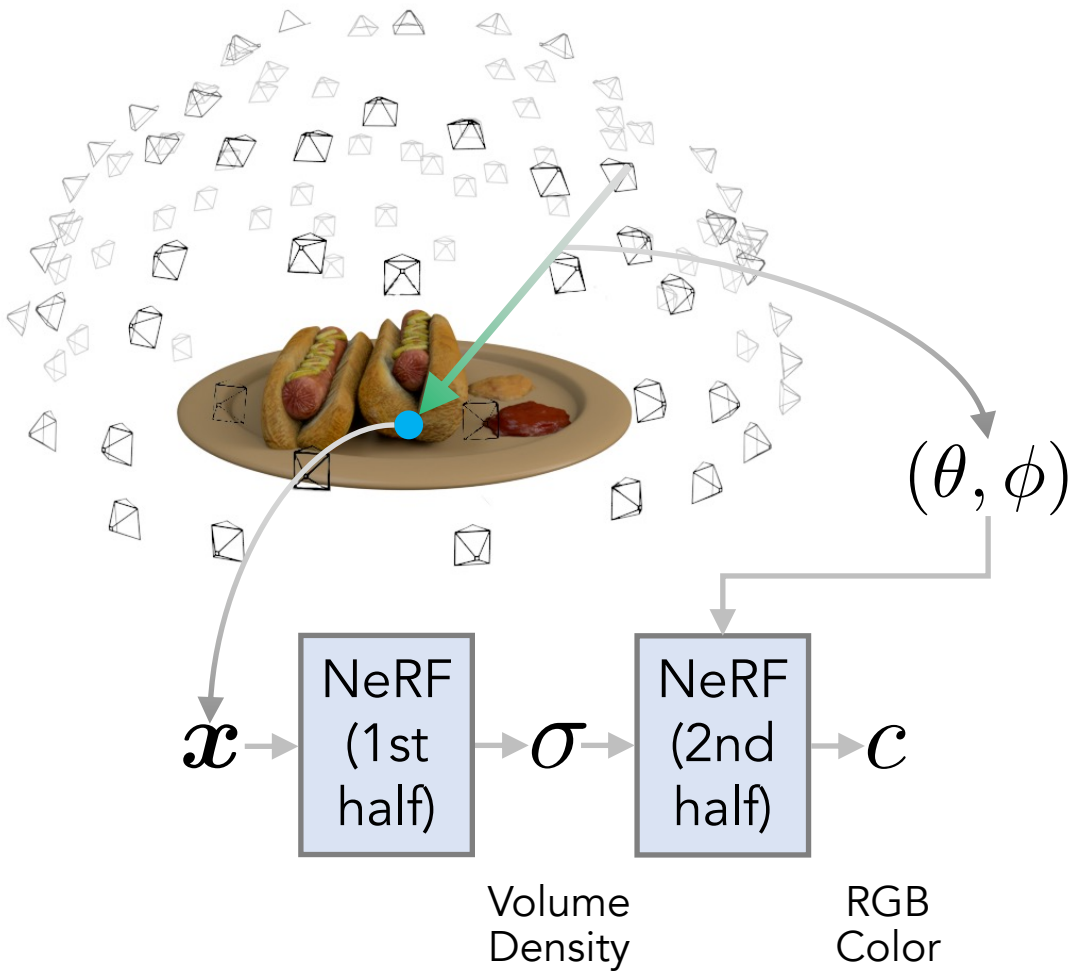


Neural Radiance Fields (NeRF) [Mildenhall et al. 2020]



NeRF

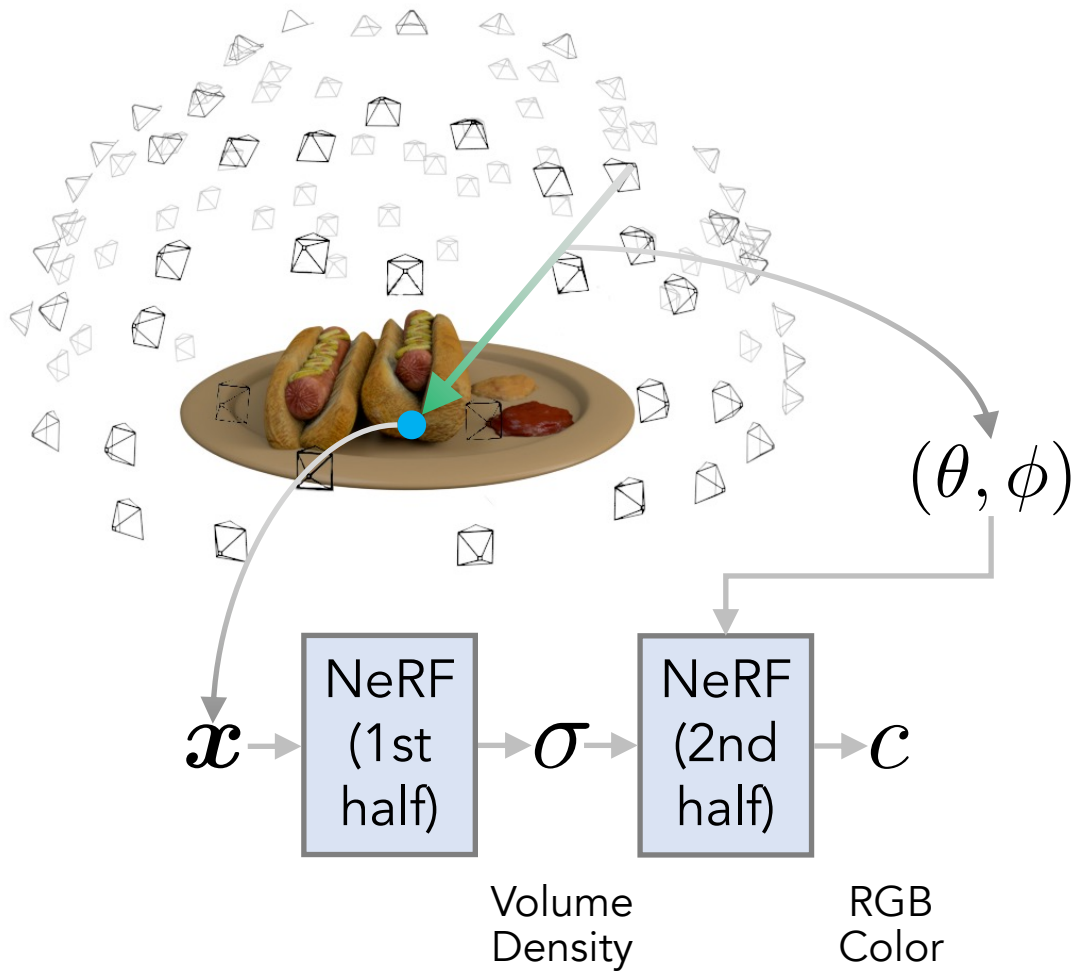
Neural Radiance Fields (NeRF) [Mildenhall et al. 2020]



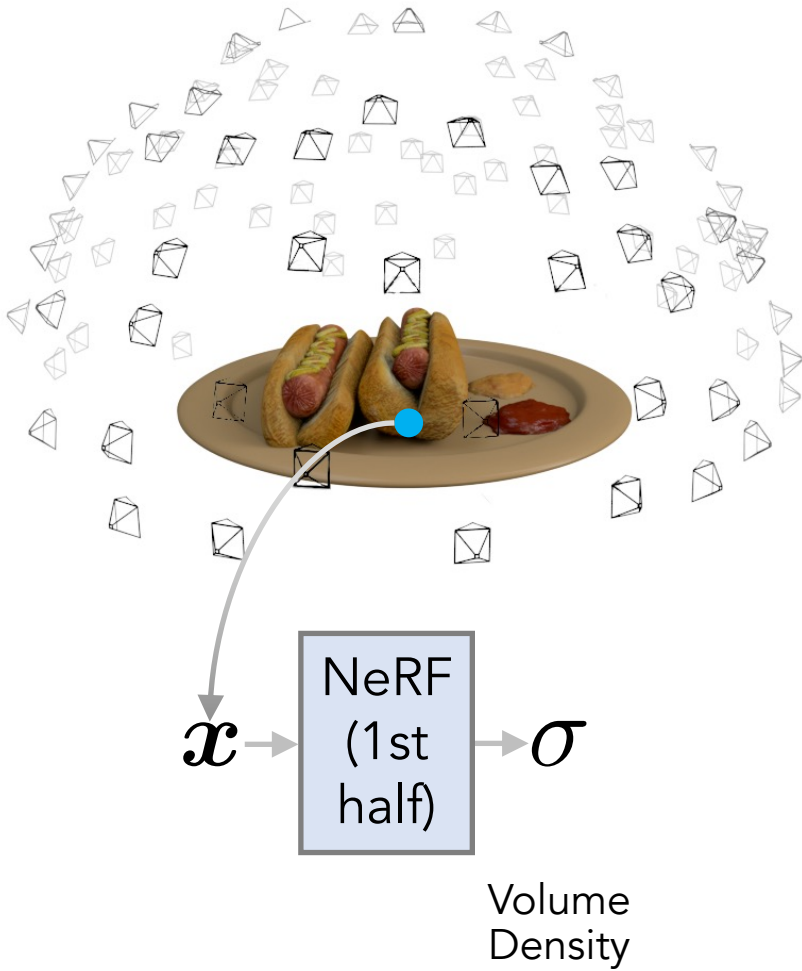
- ✓ View Synthesis
- ✗ Relighting
- ✗ Material Editing

NeRF

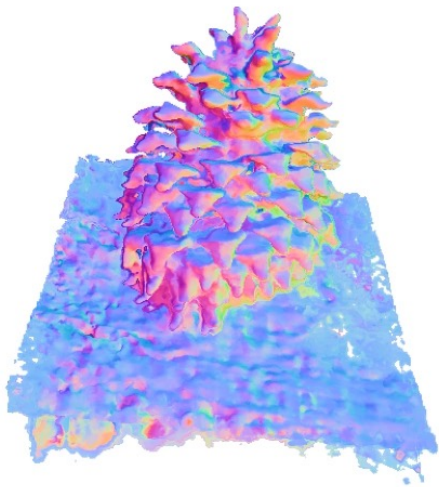
Neural Radiance Fields (NeRF) [Mildenhall et al. 2020]



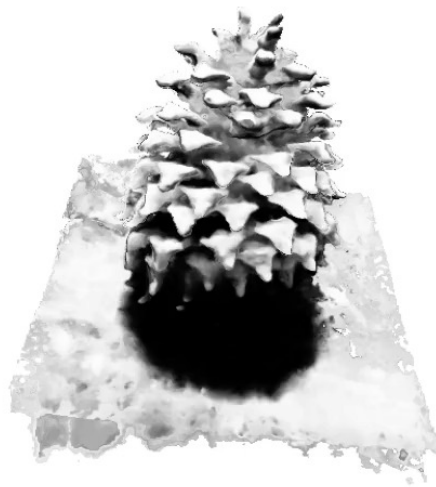
Neural Radiance Fields (NeRF) [Mildenhall et al. 2020]



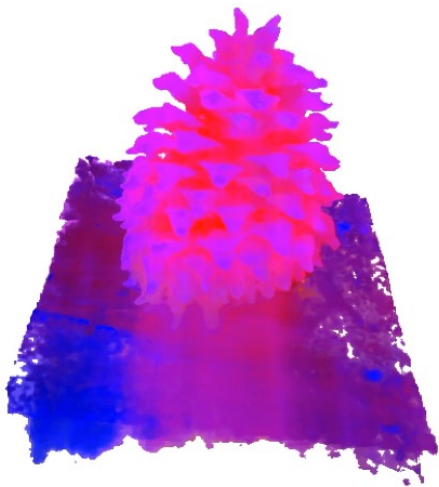
Normals



Visibility



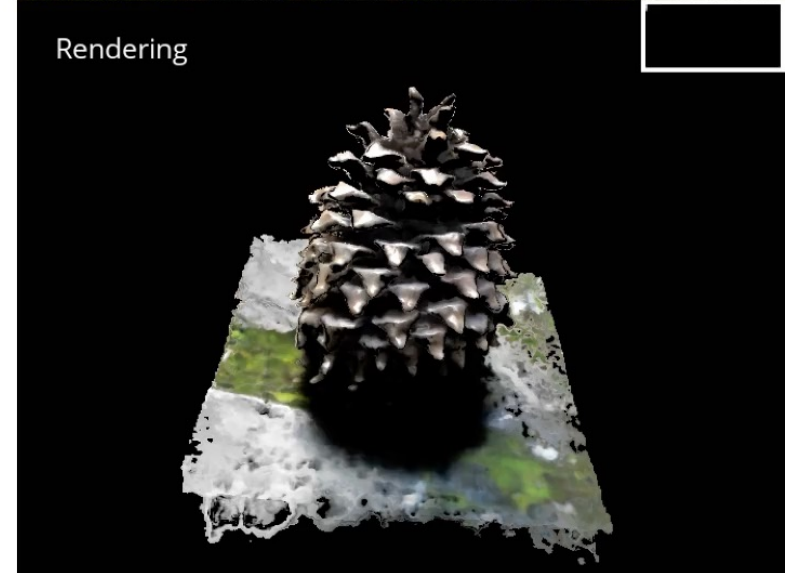
BRDF



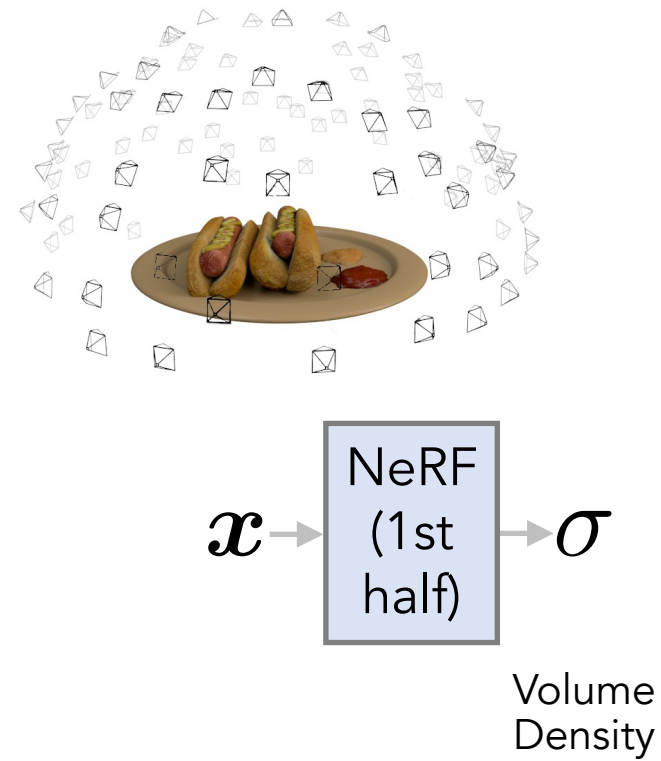
Albedo



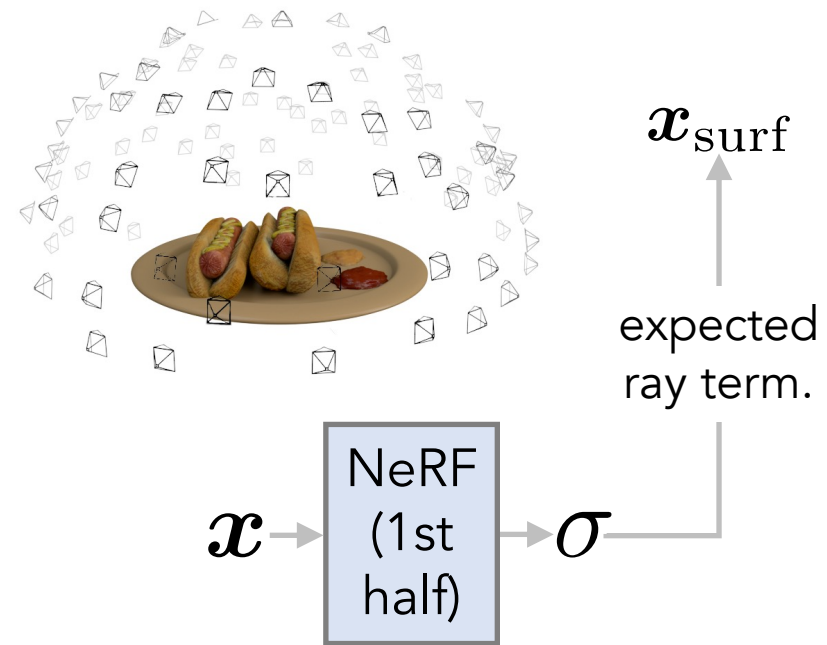
Rendering



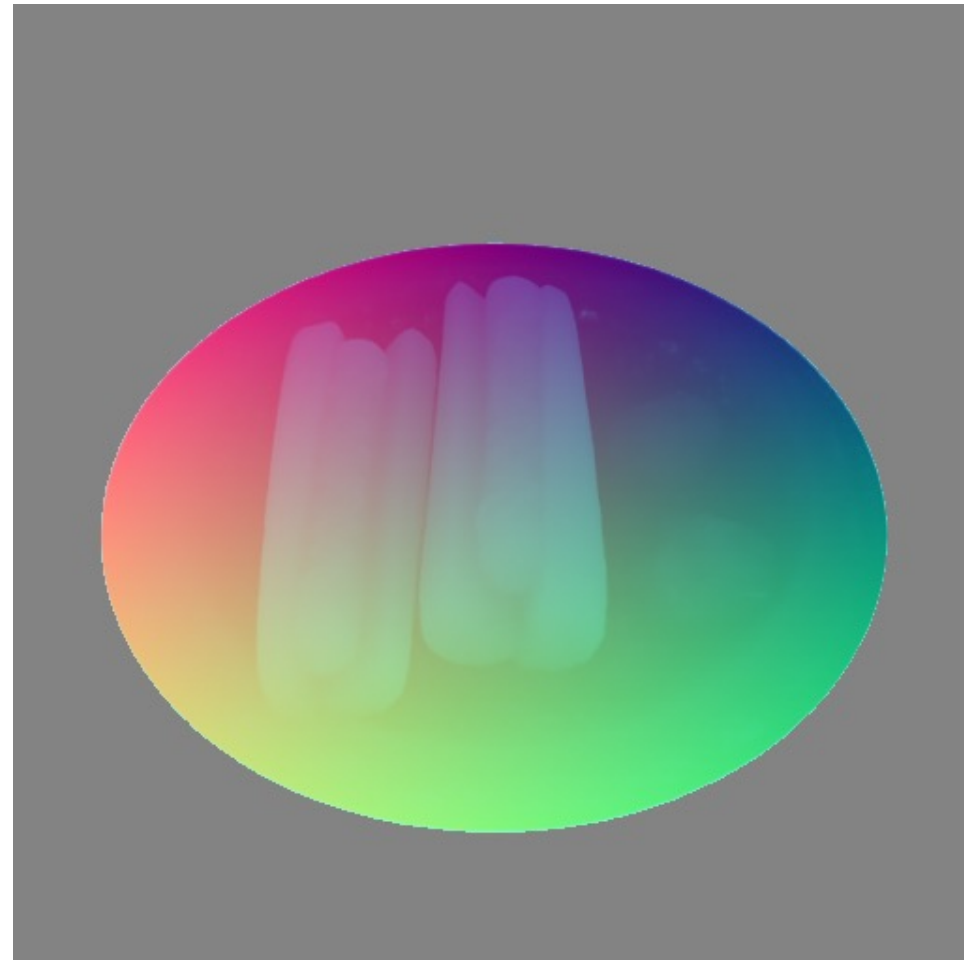
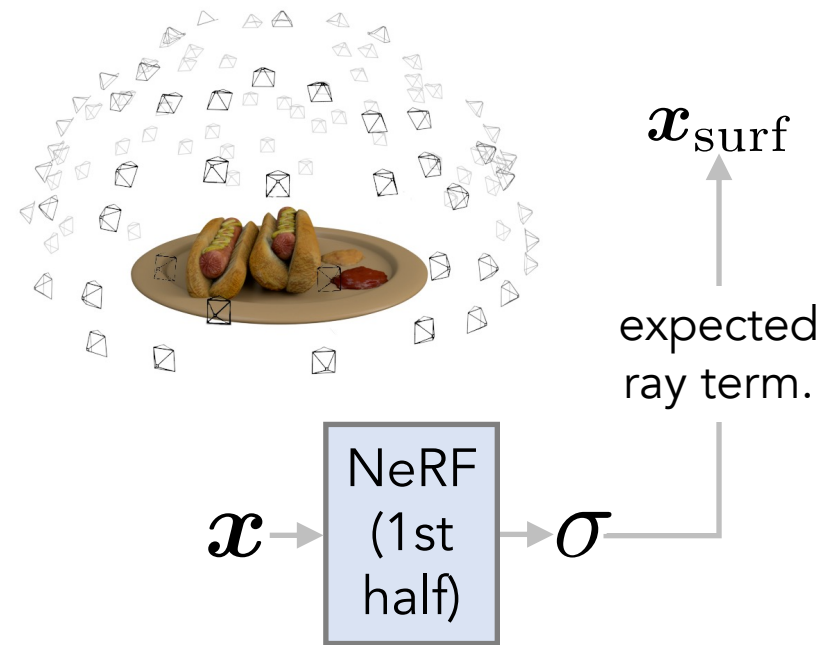
NeRFactor



NeRFactor

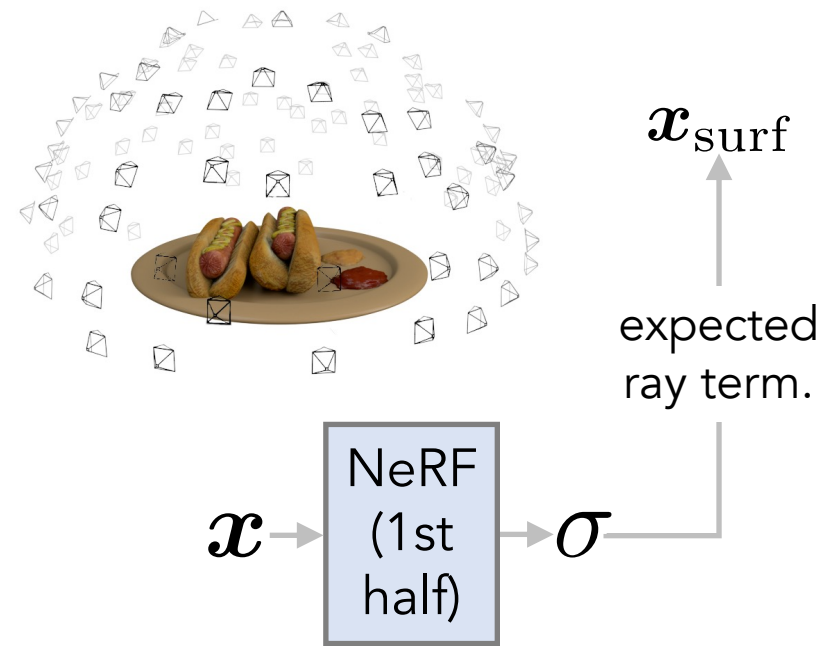


NeRFactor

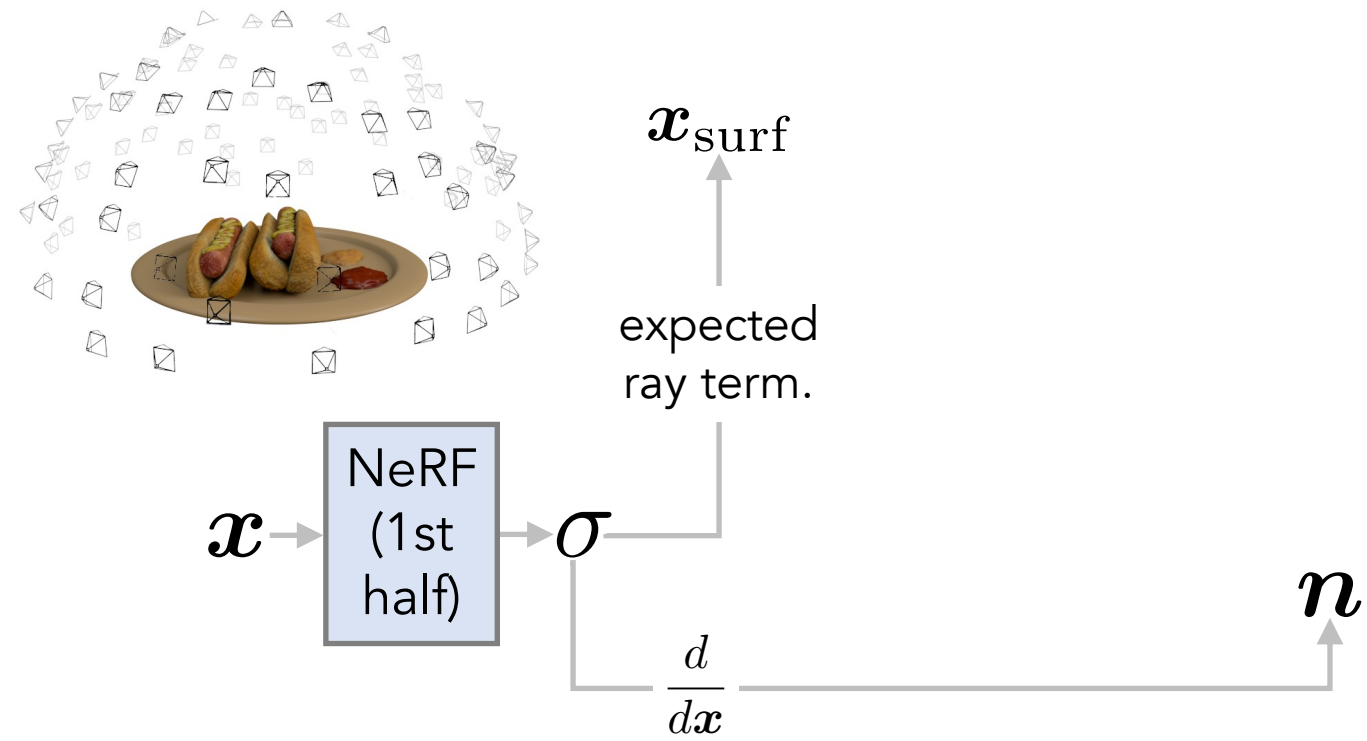


NeRF's Surface XYZs

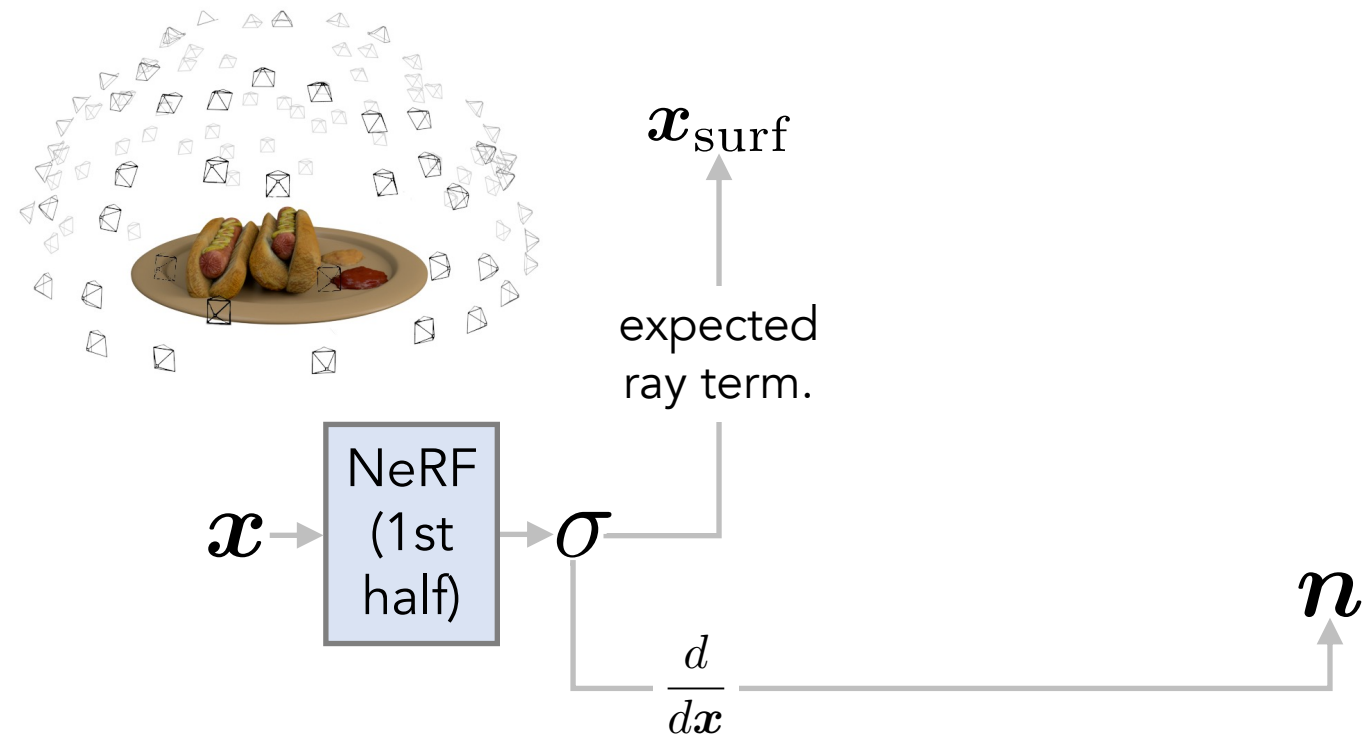
NeRFactor



NeRFactor

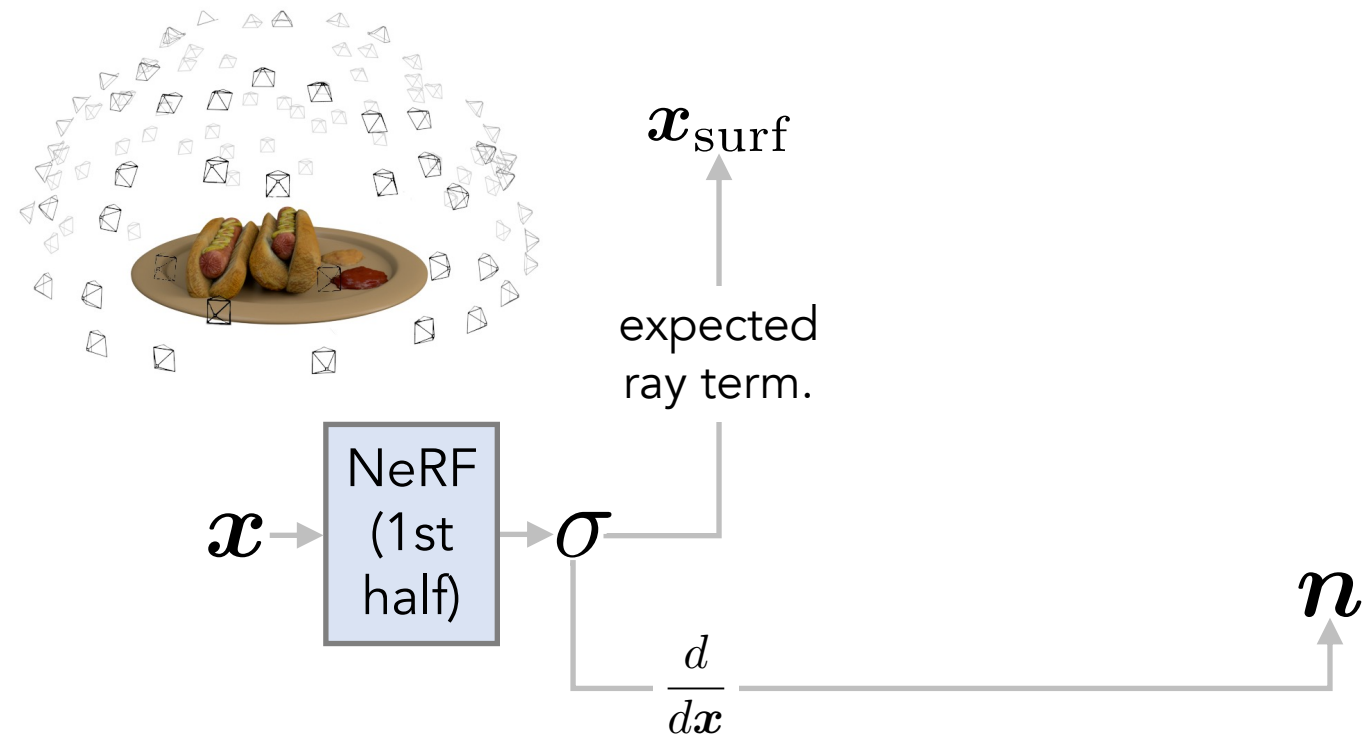


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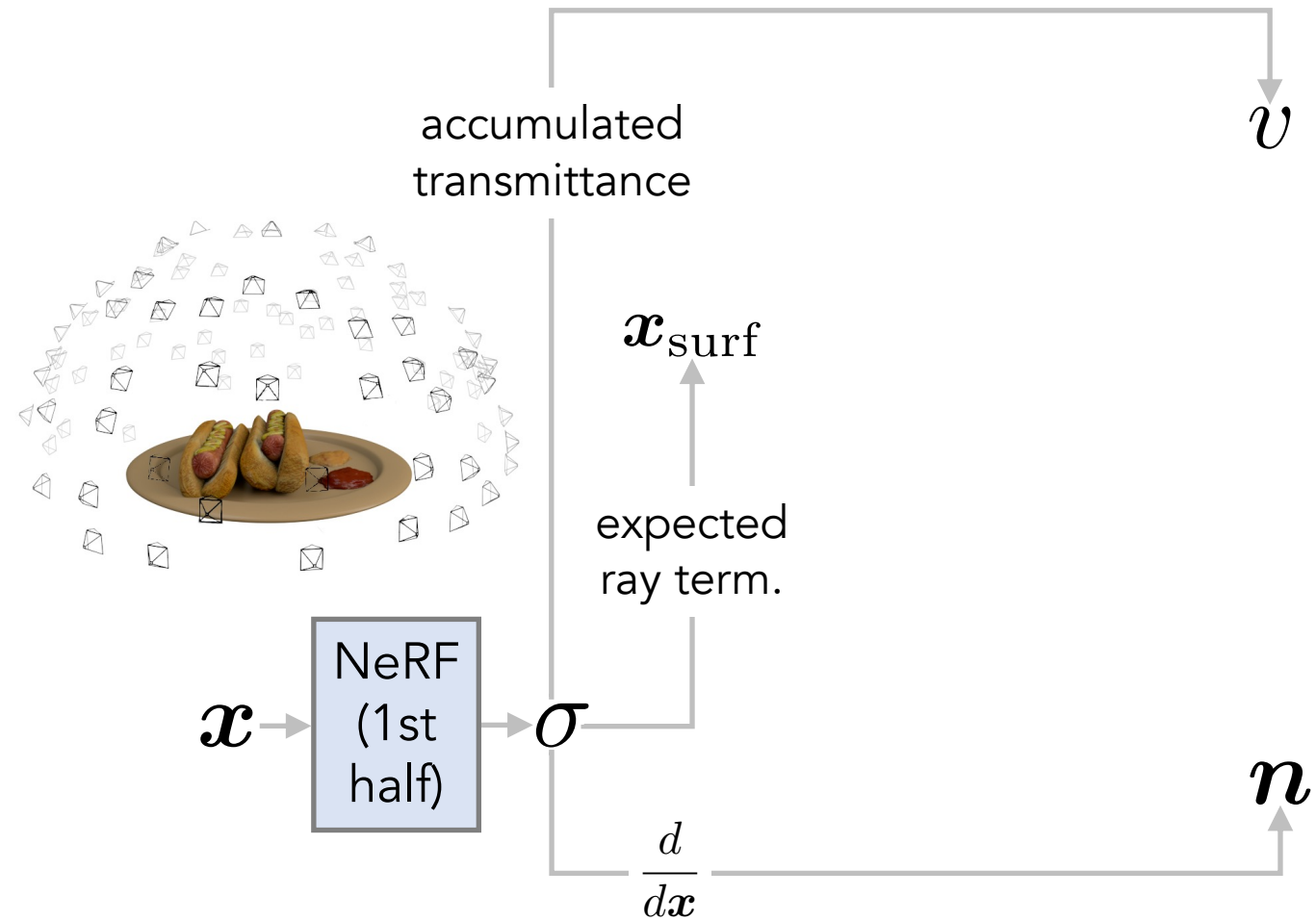


NeRF's Surface Normals

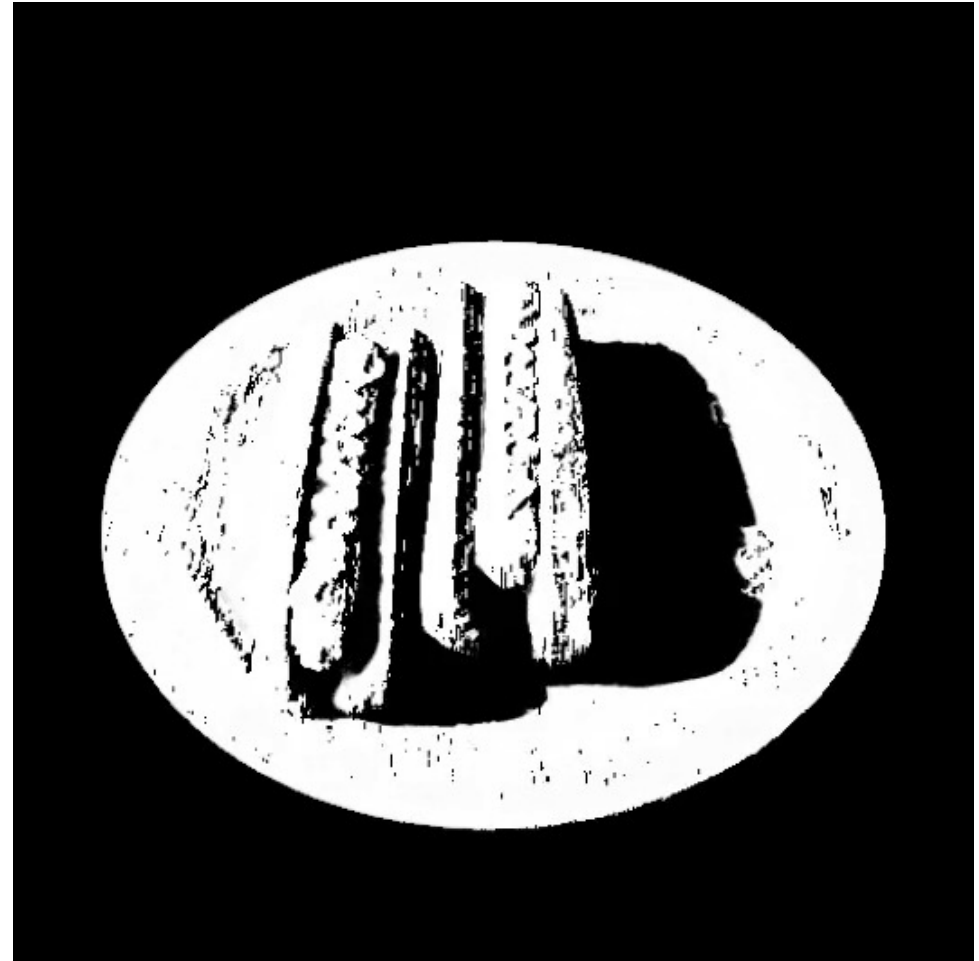
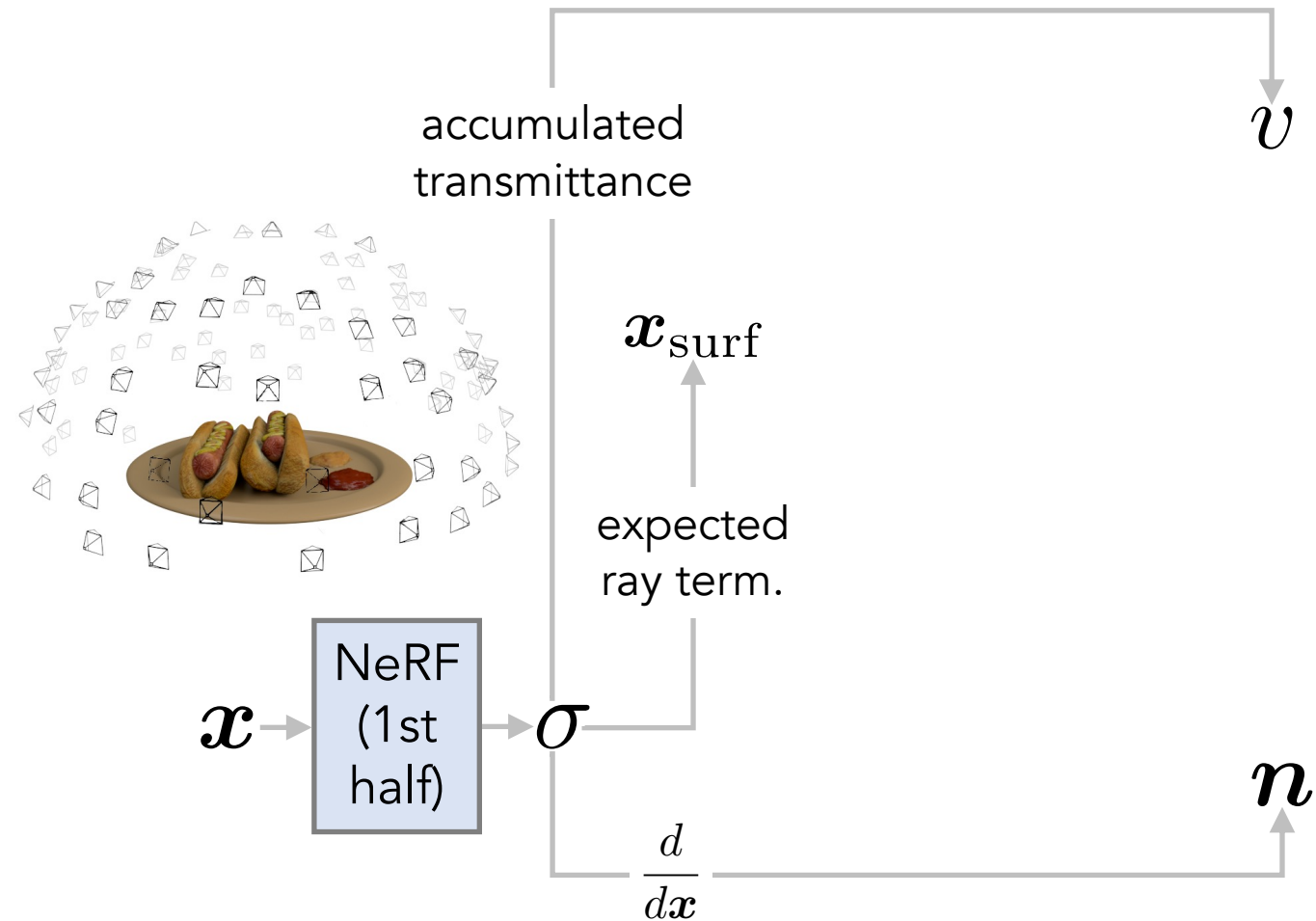
NeRFactor



NeRFactor

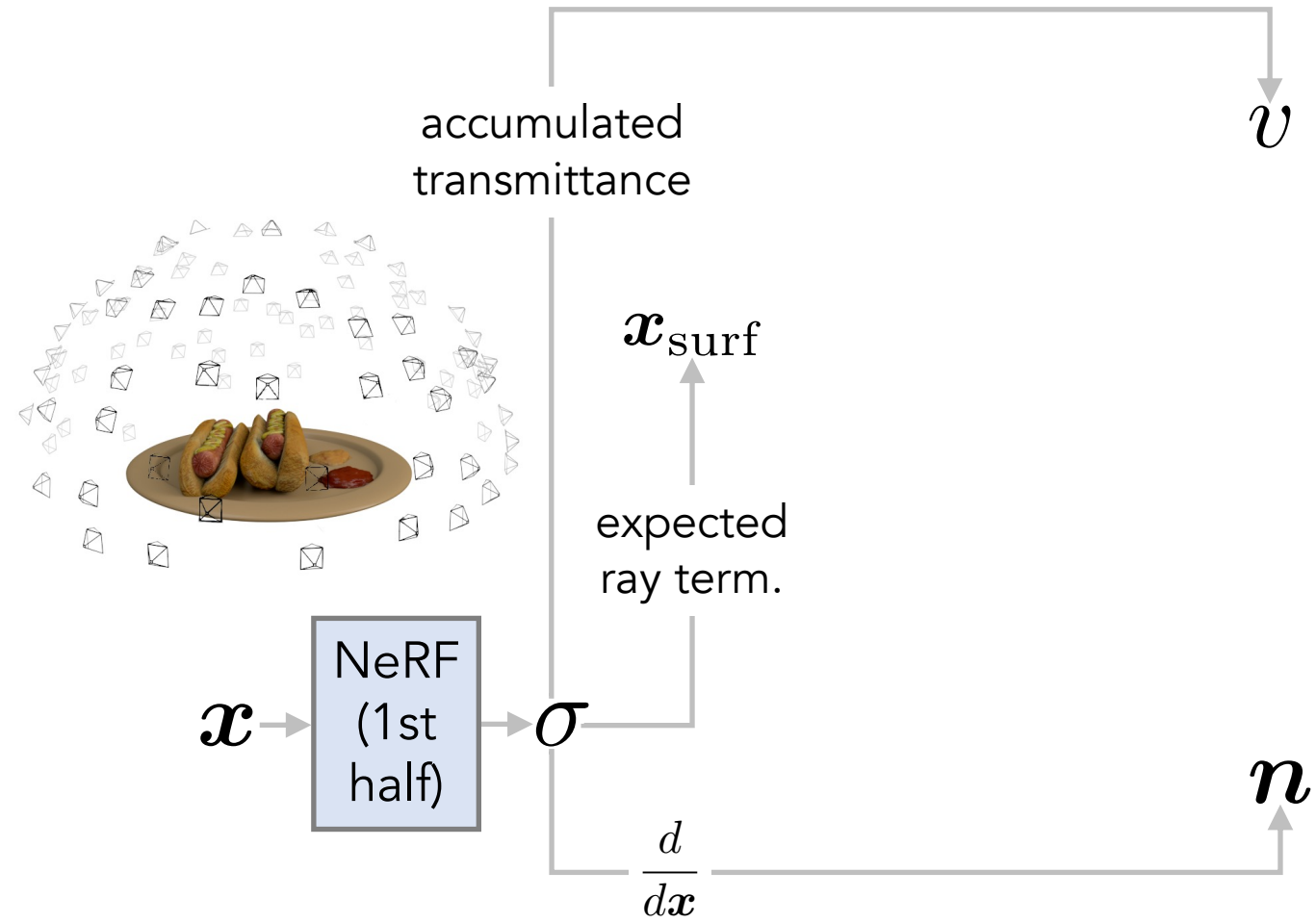


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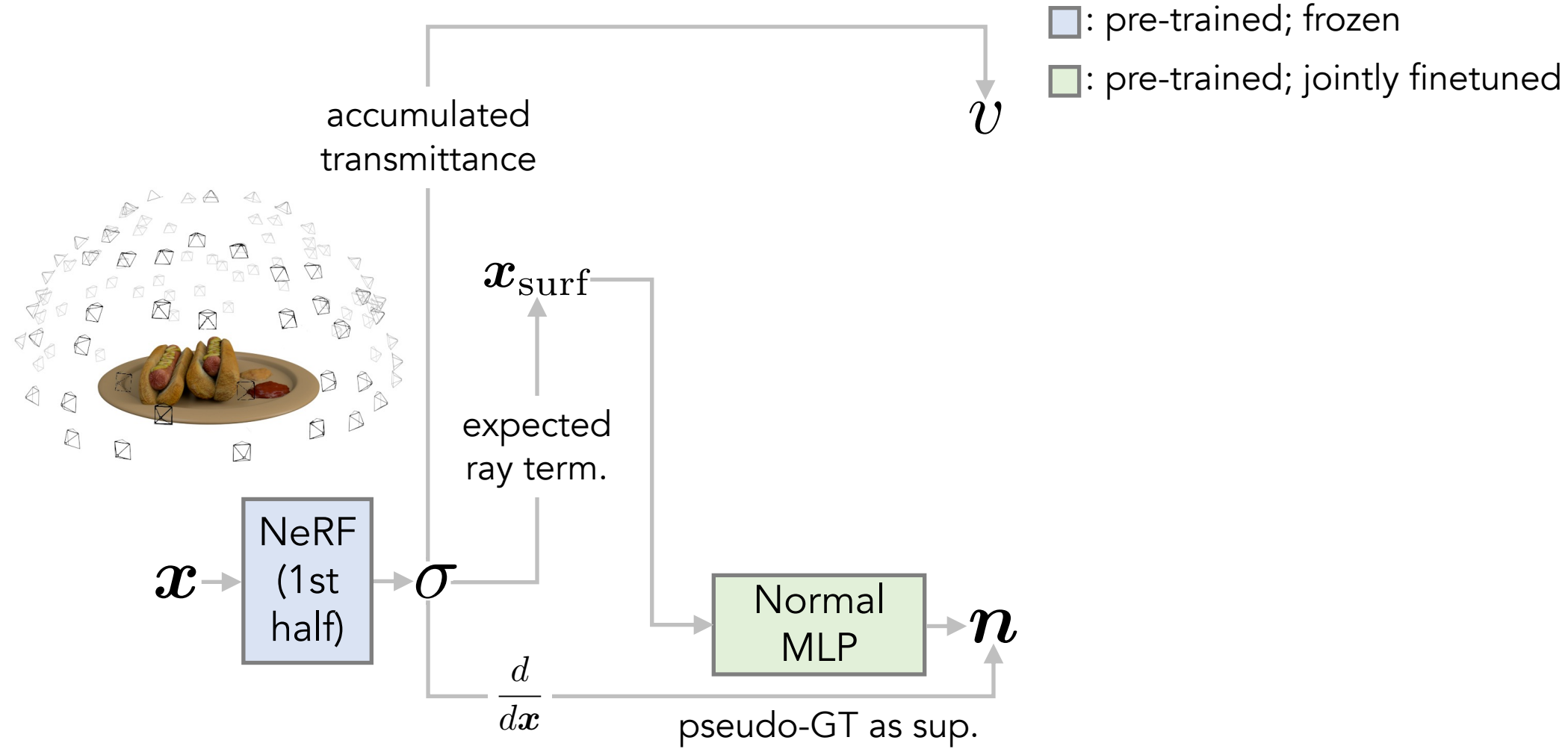


NeRF's Light Visibility

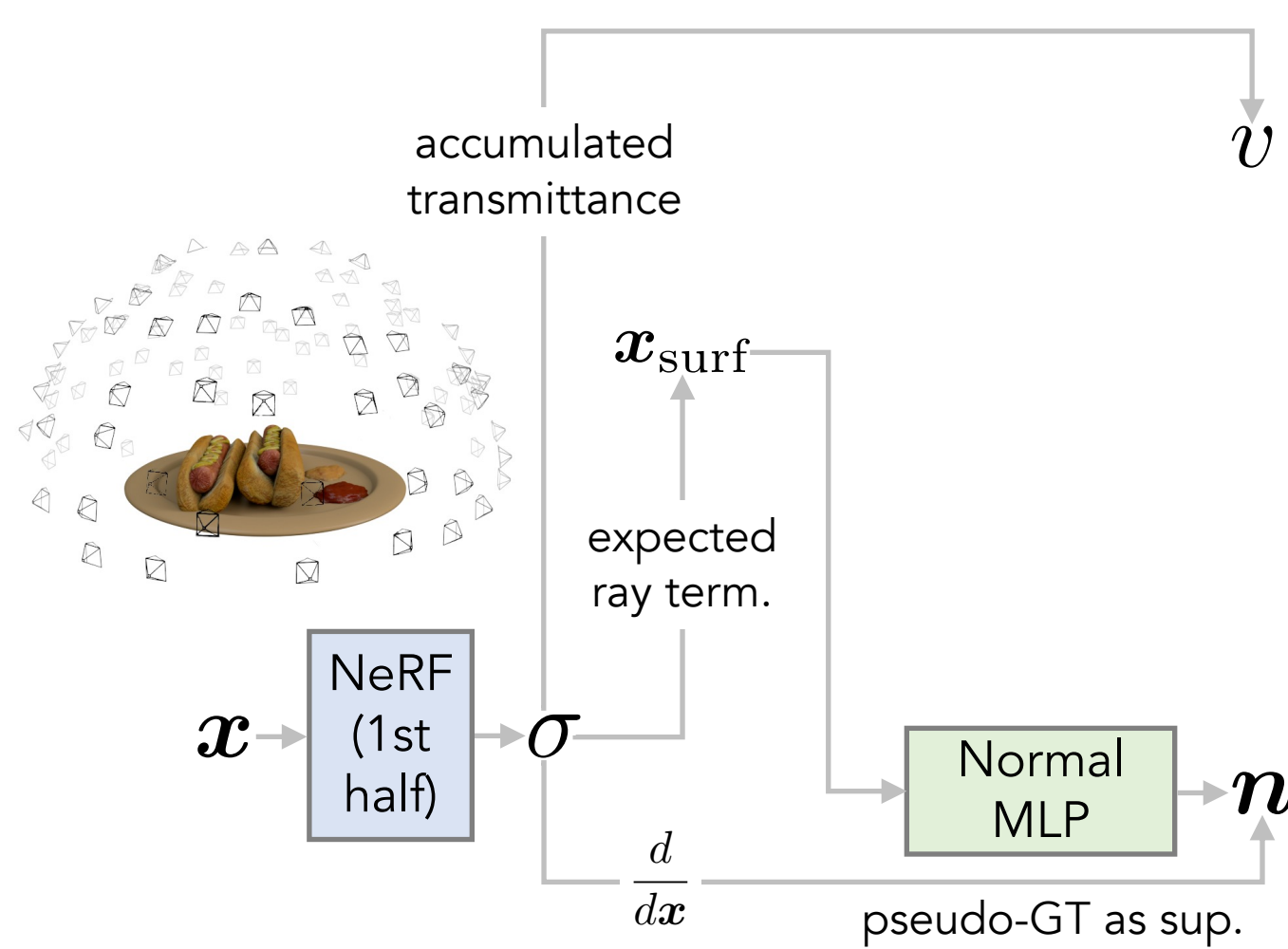
NeRFactor



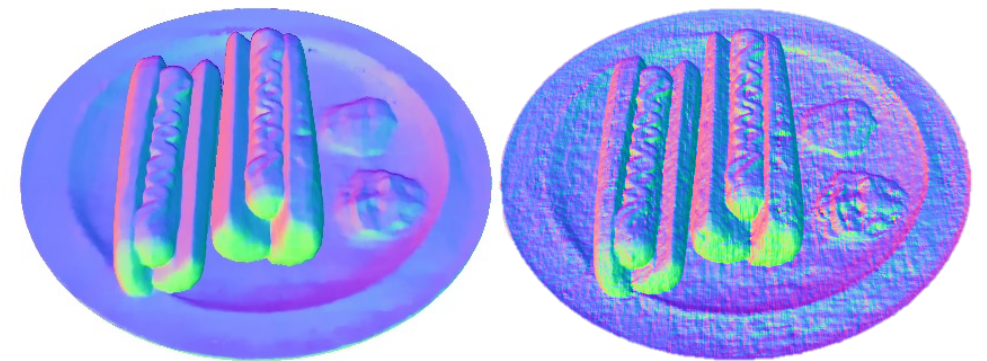
NeRFactor



NeRFactor



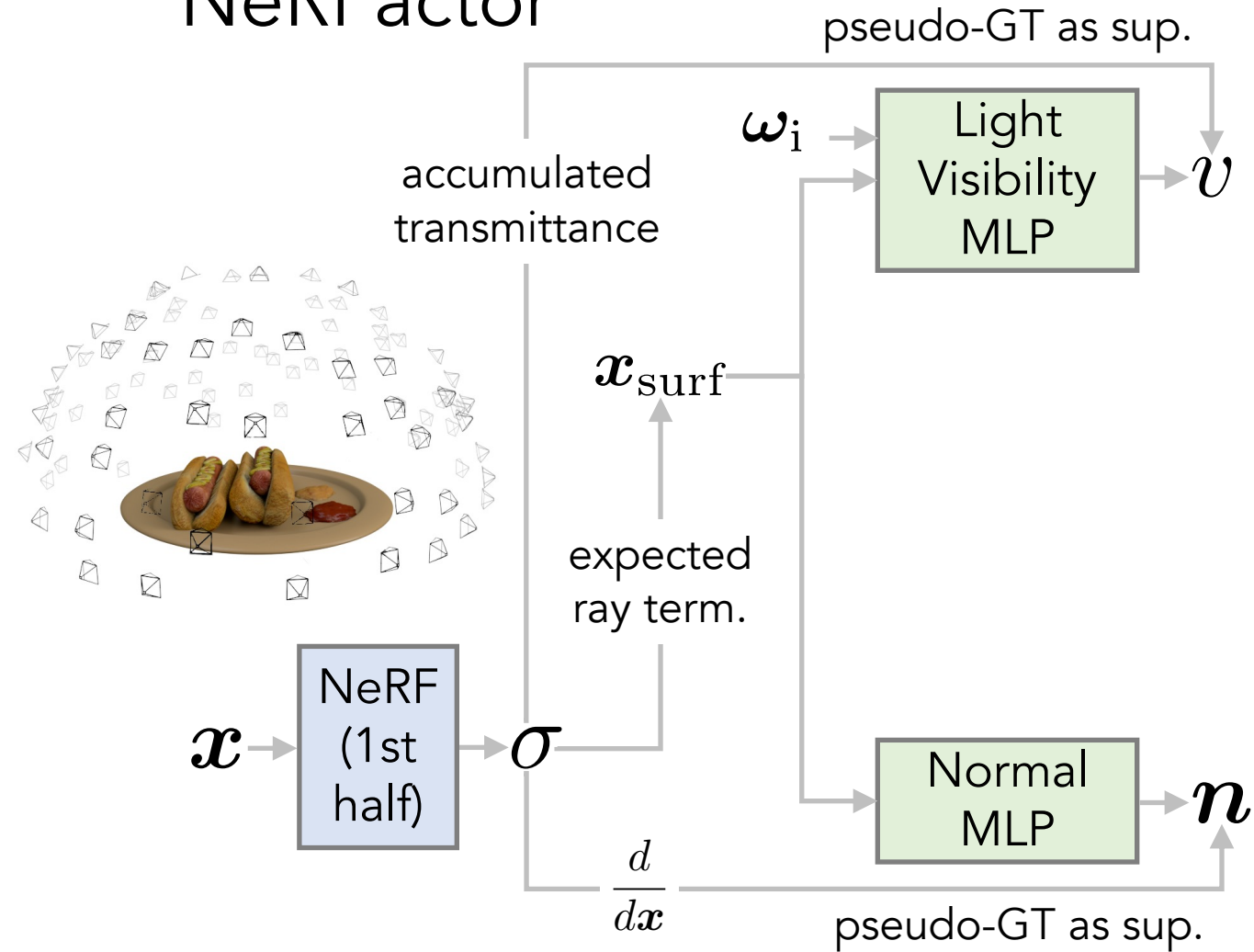
- : pre-trained; frozen
- : pre-trained; jointly finetuned



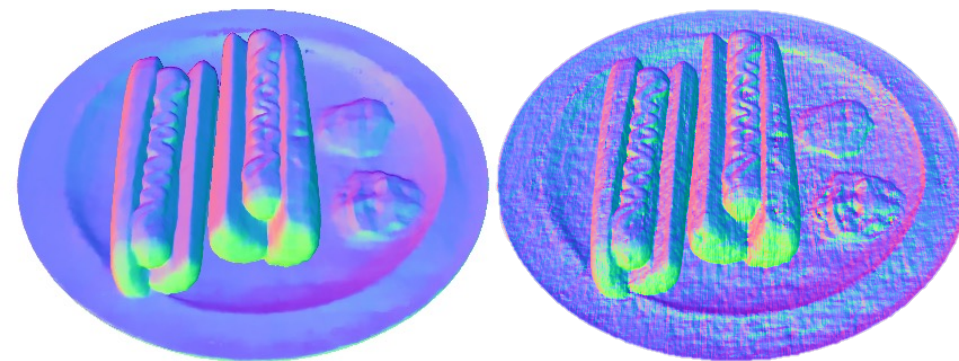
NeRFactor

NeRF

NeRFactor



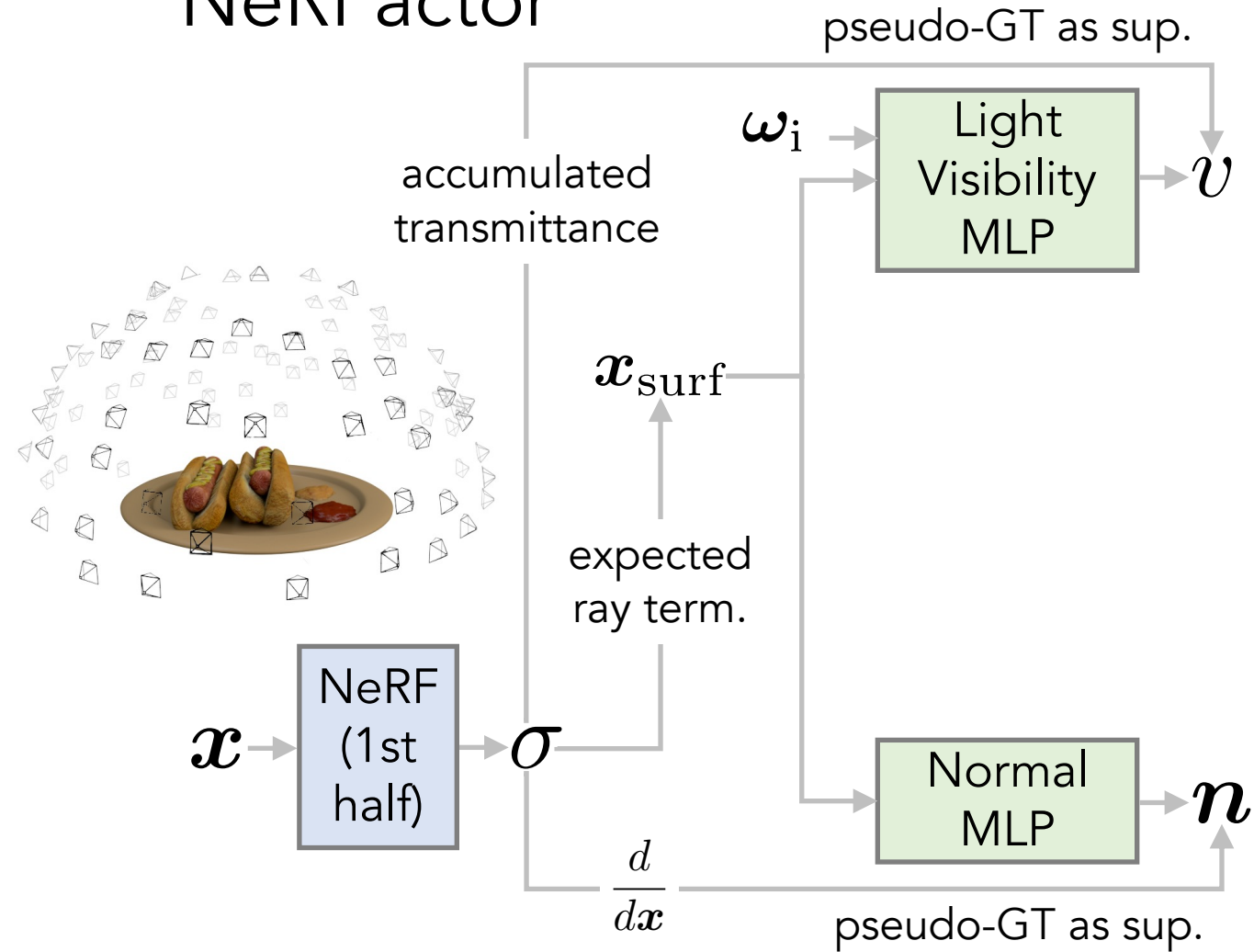
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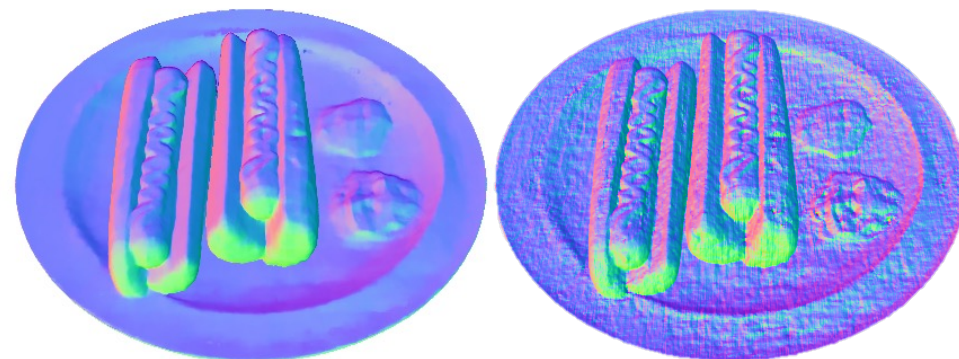
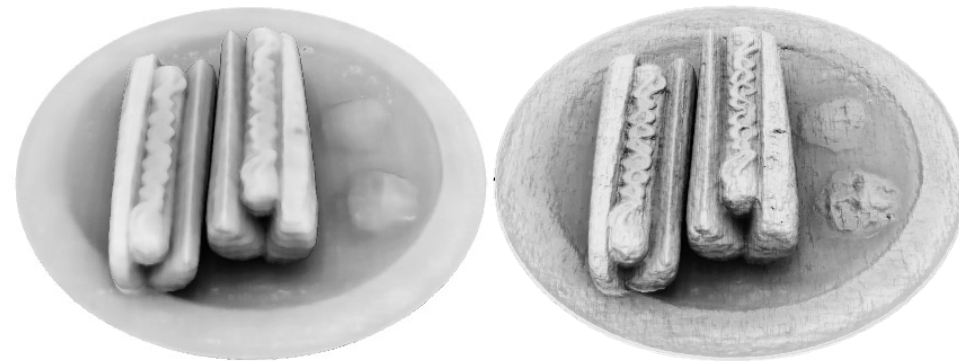
NeRFactor

NeRF

NeRFactor



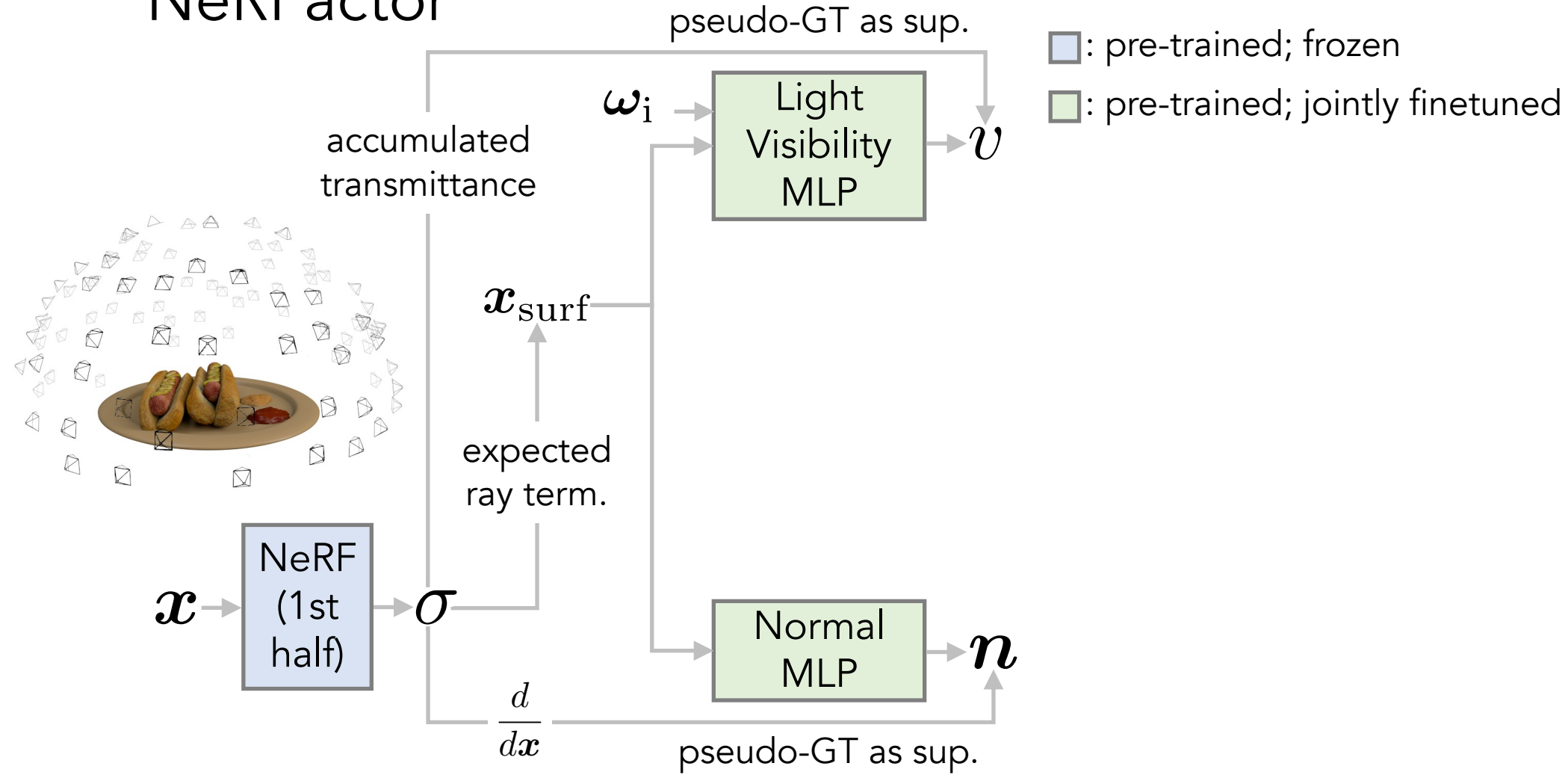
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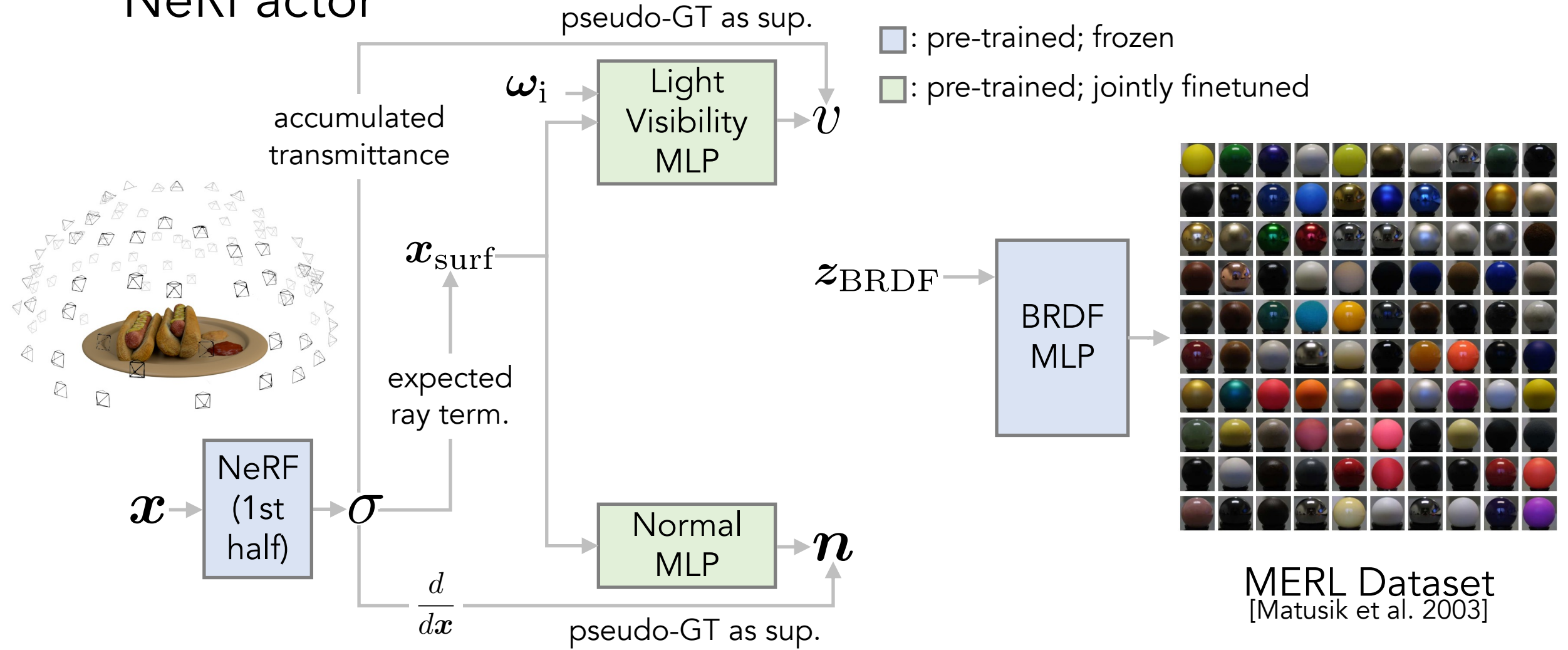
NeRFactor

NeRF

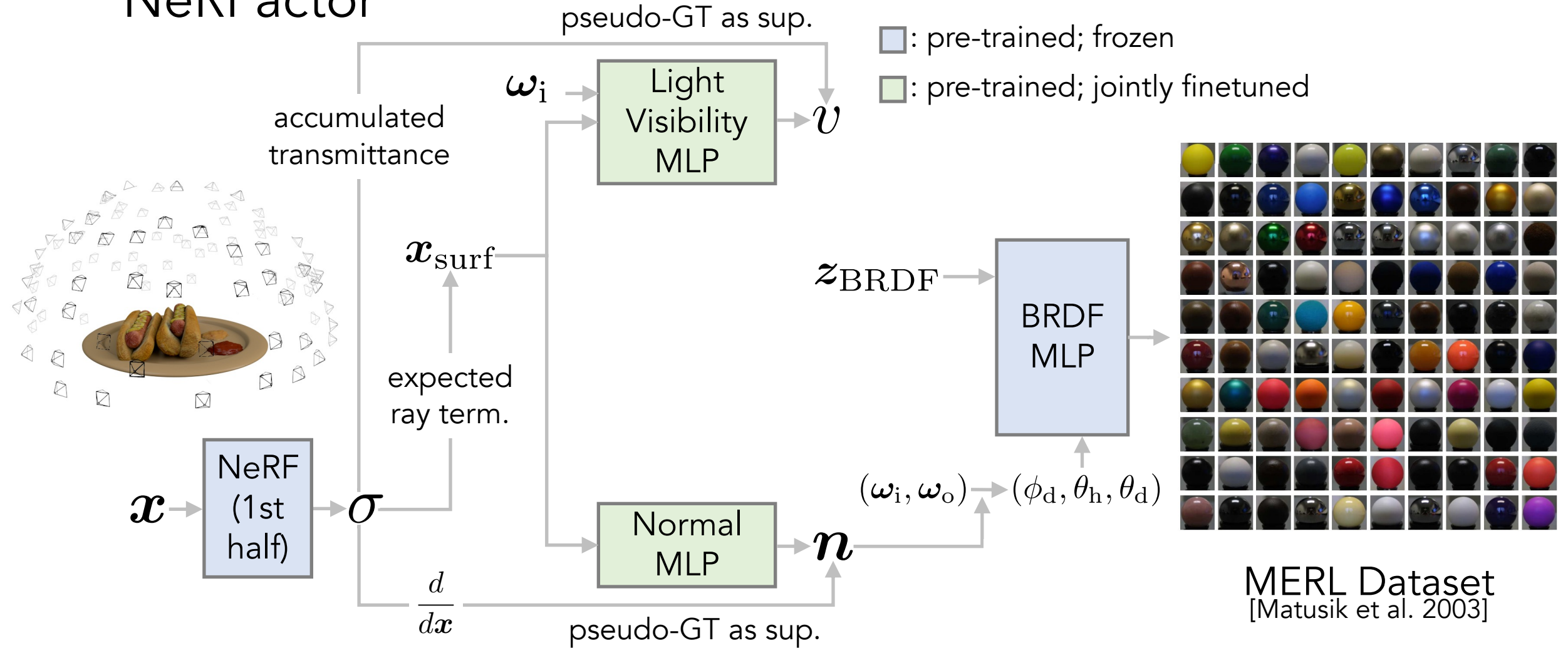
NeRFactor



NeRFactor

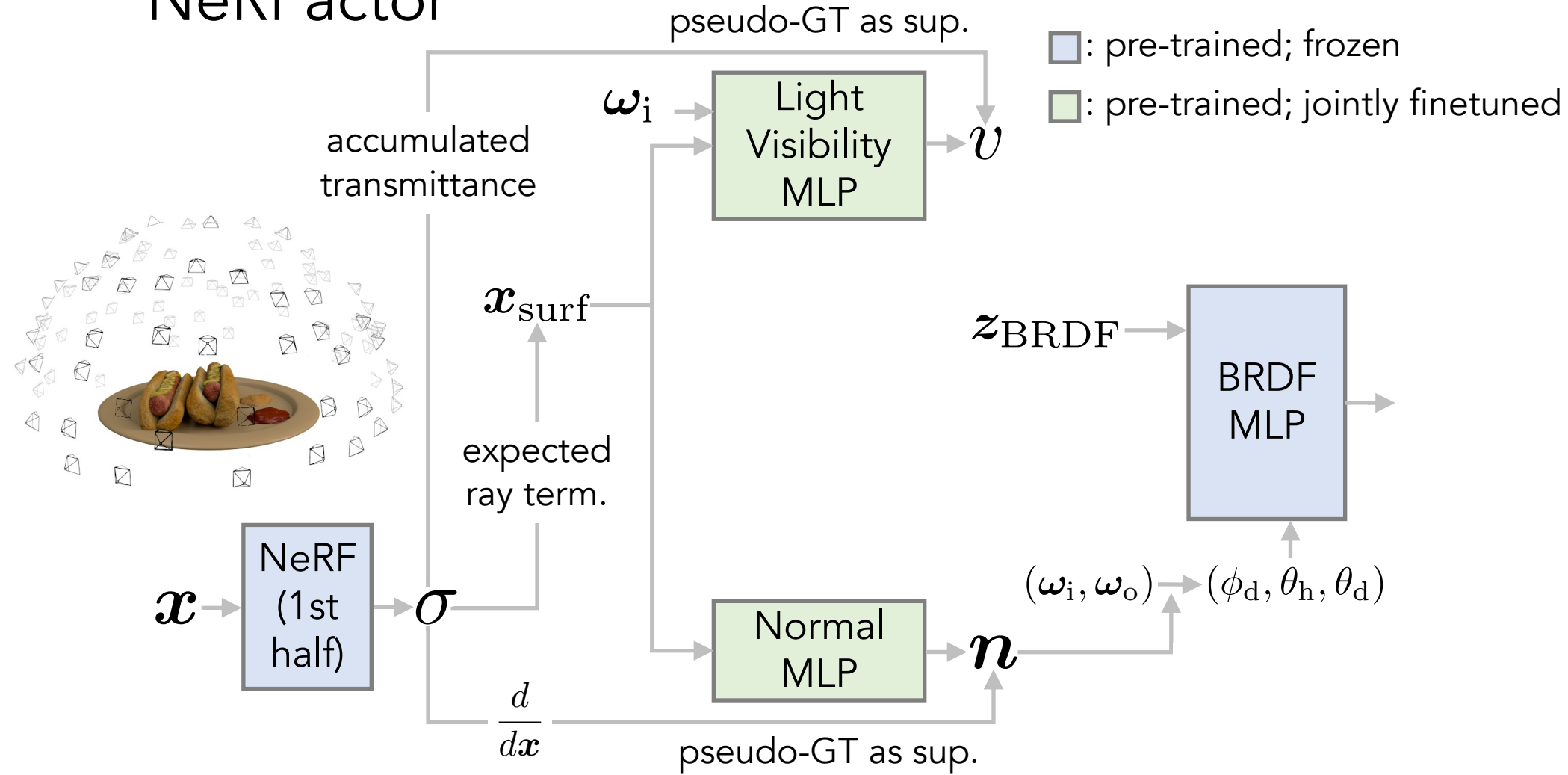


NeRFactor

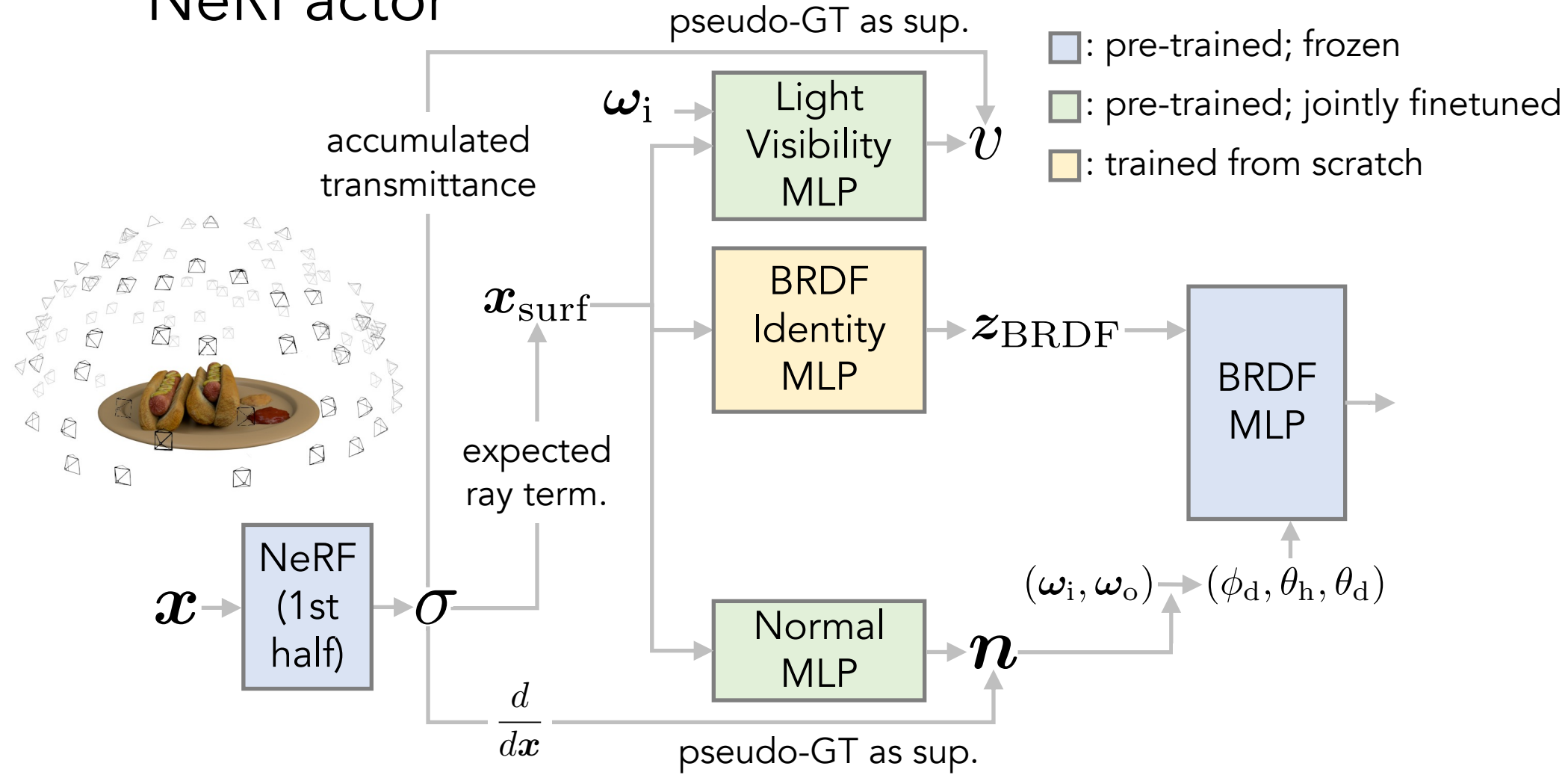


MERL Dataset
[Matusik et al. 2003]

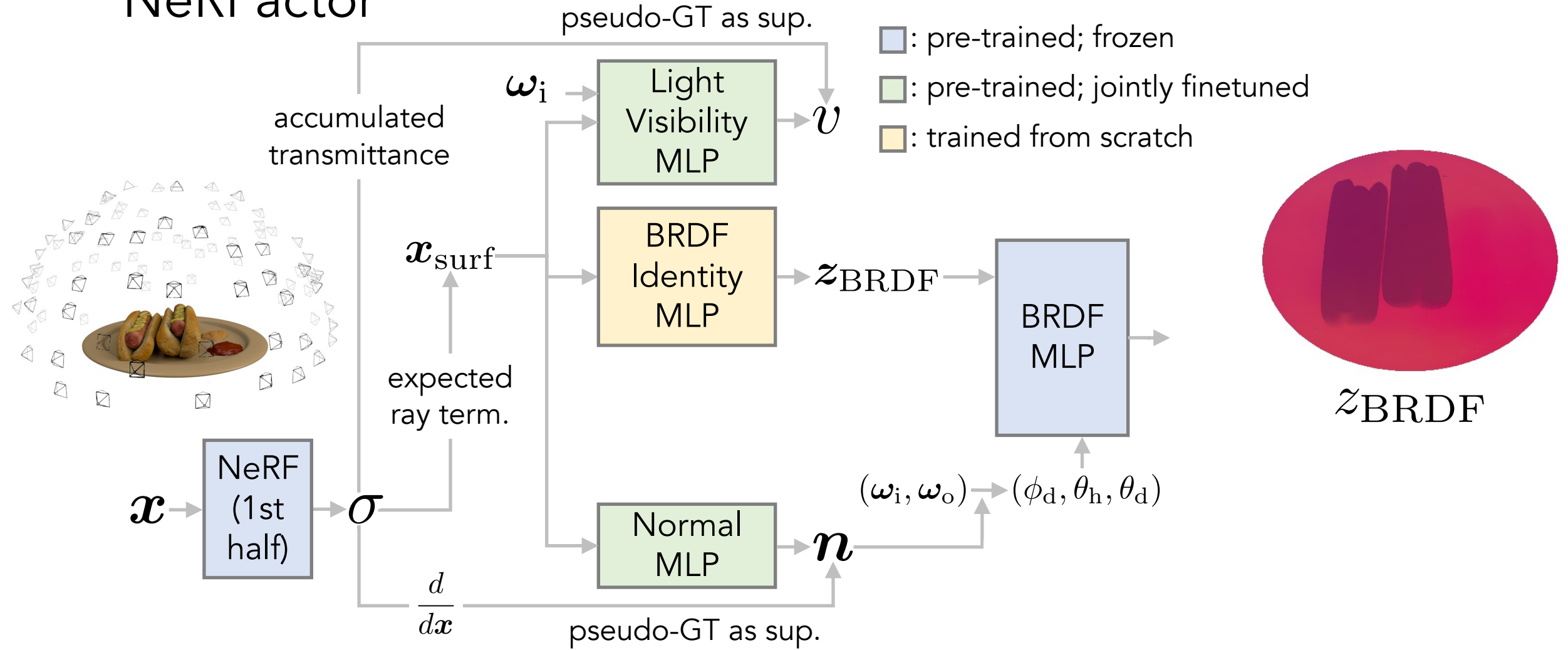
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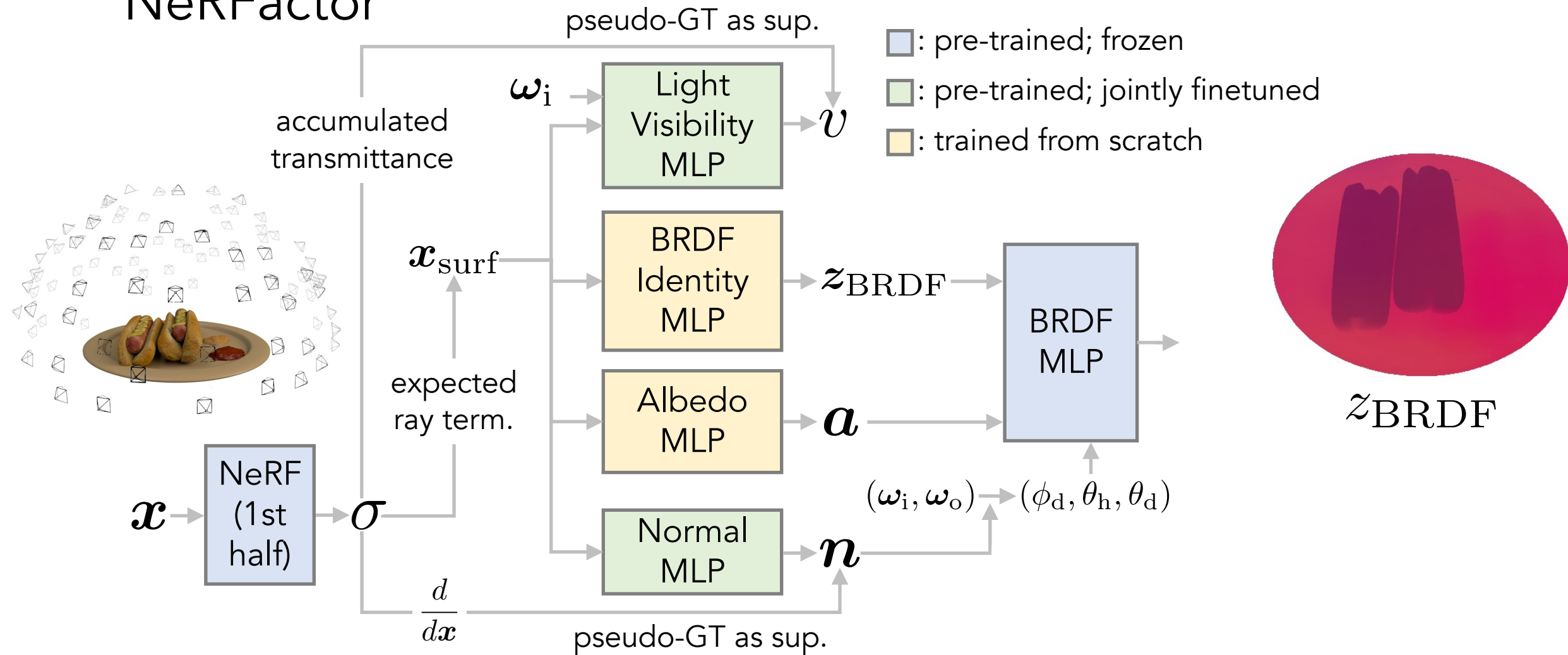
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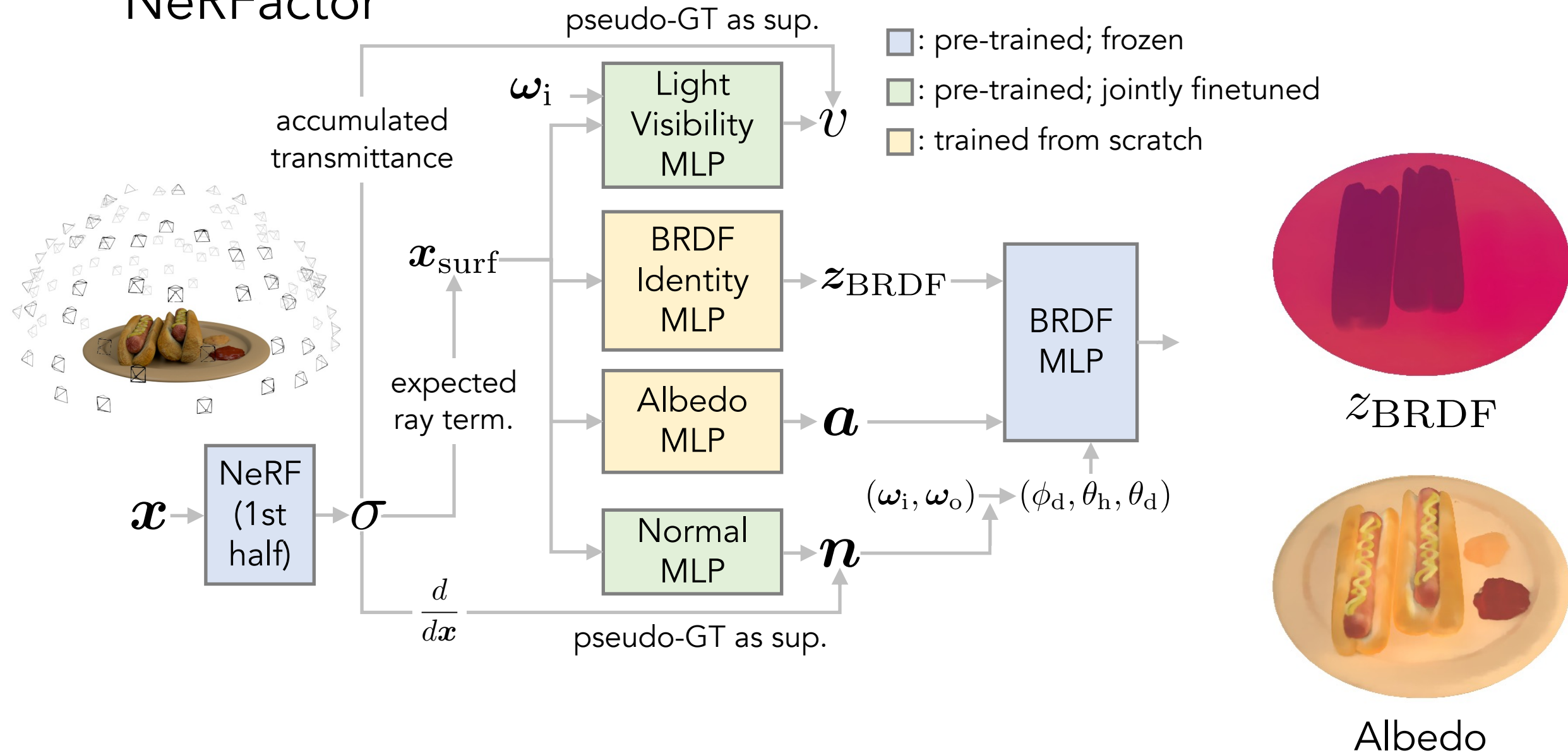
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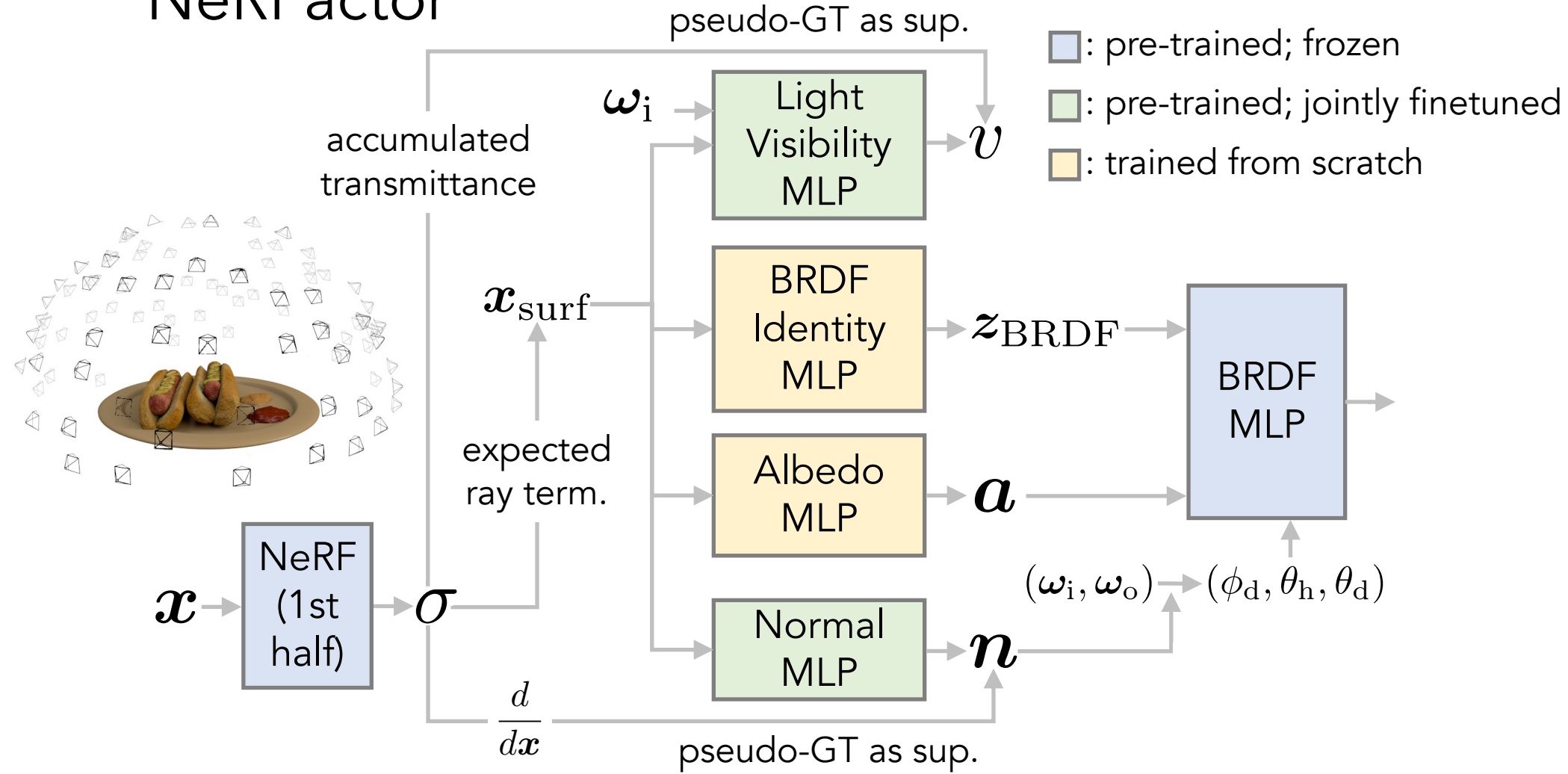
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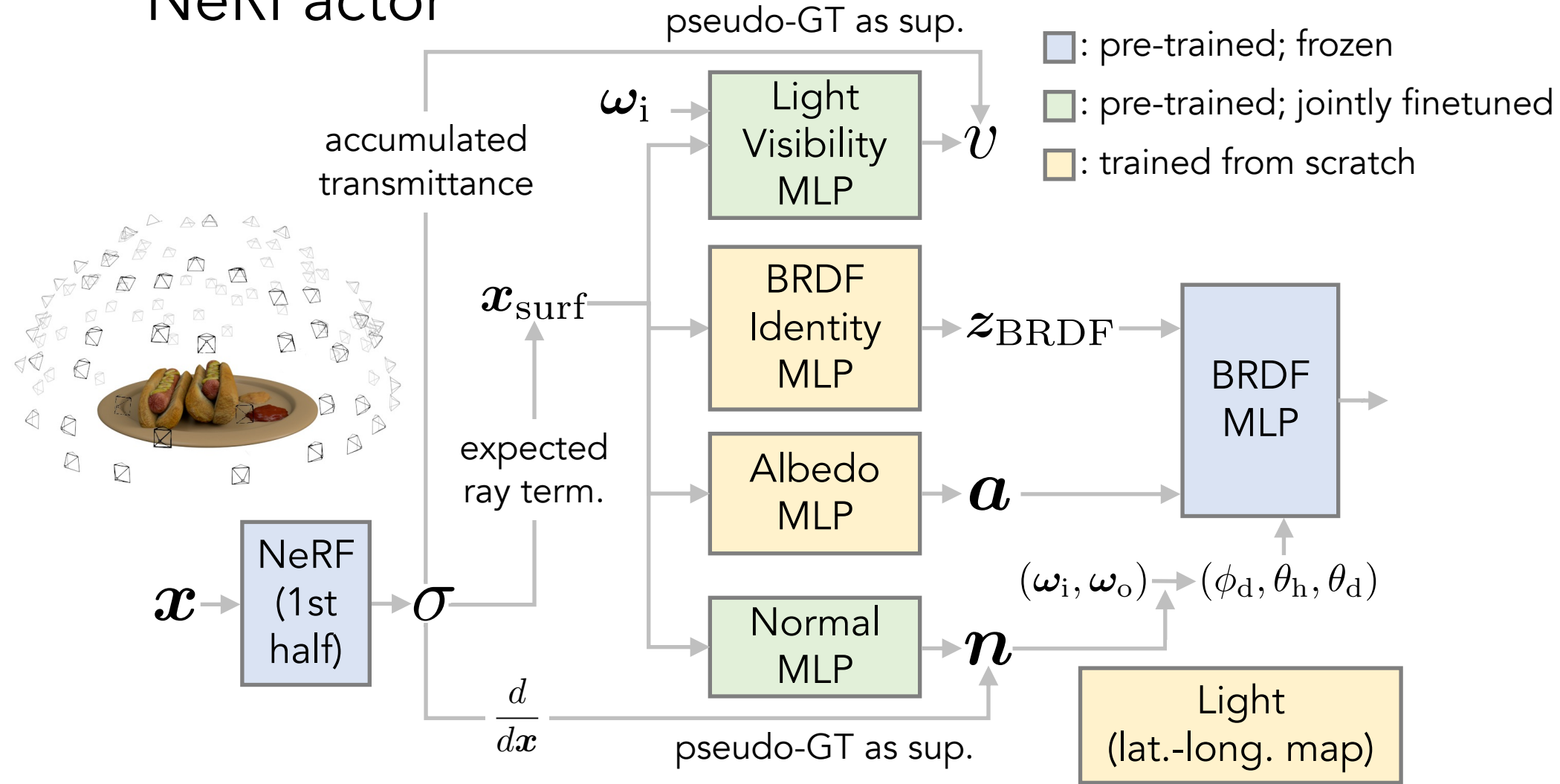
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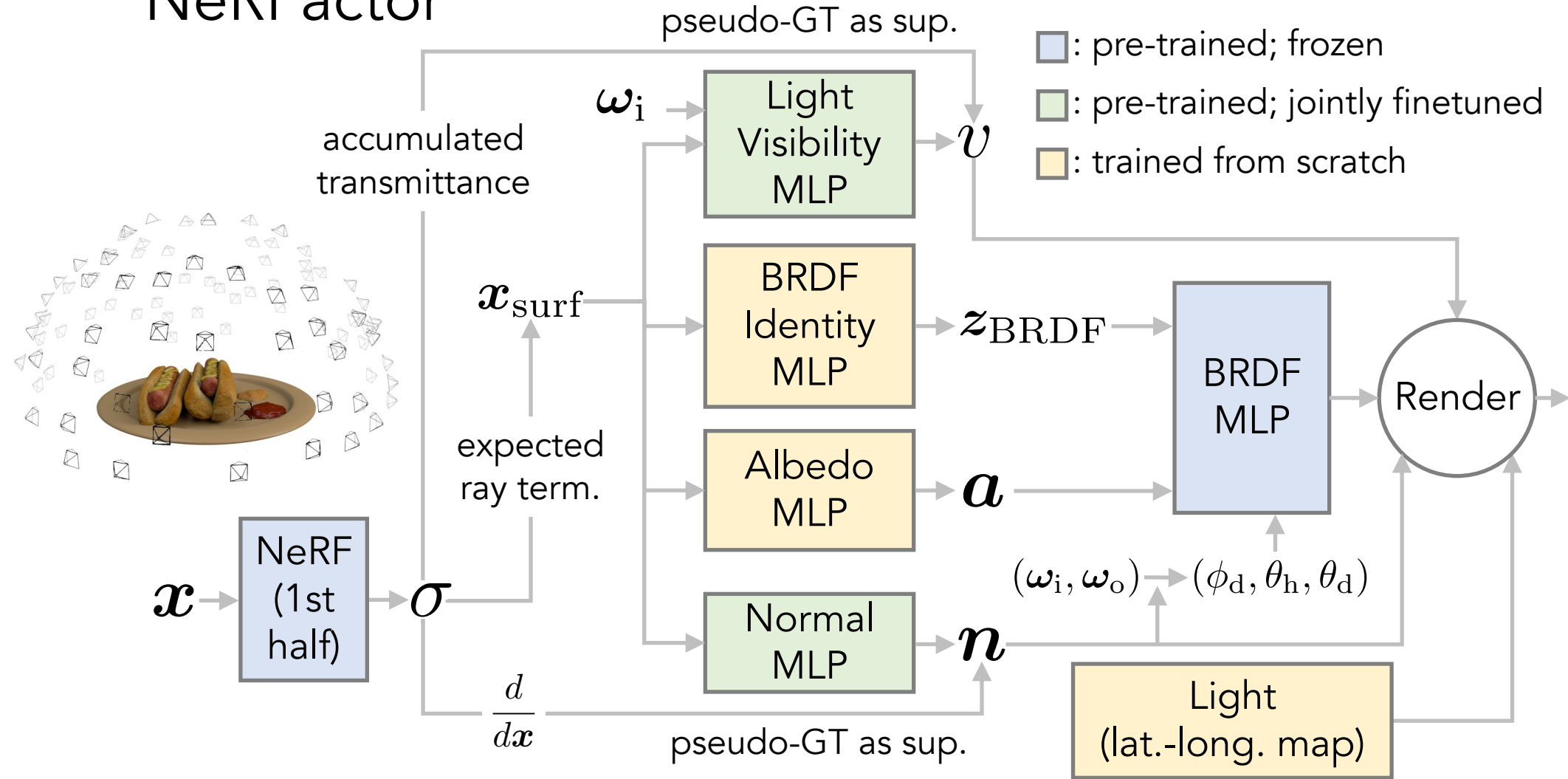
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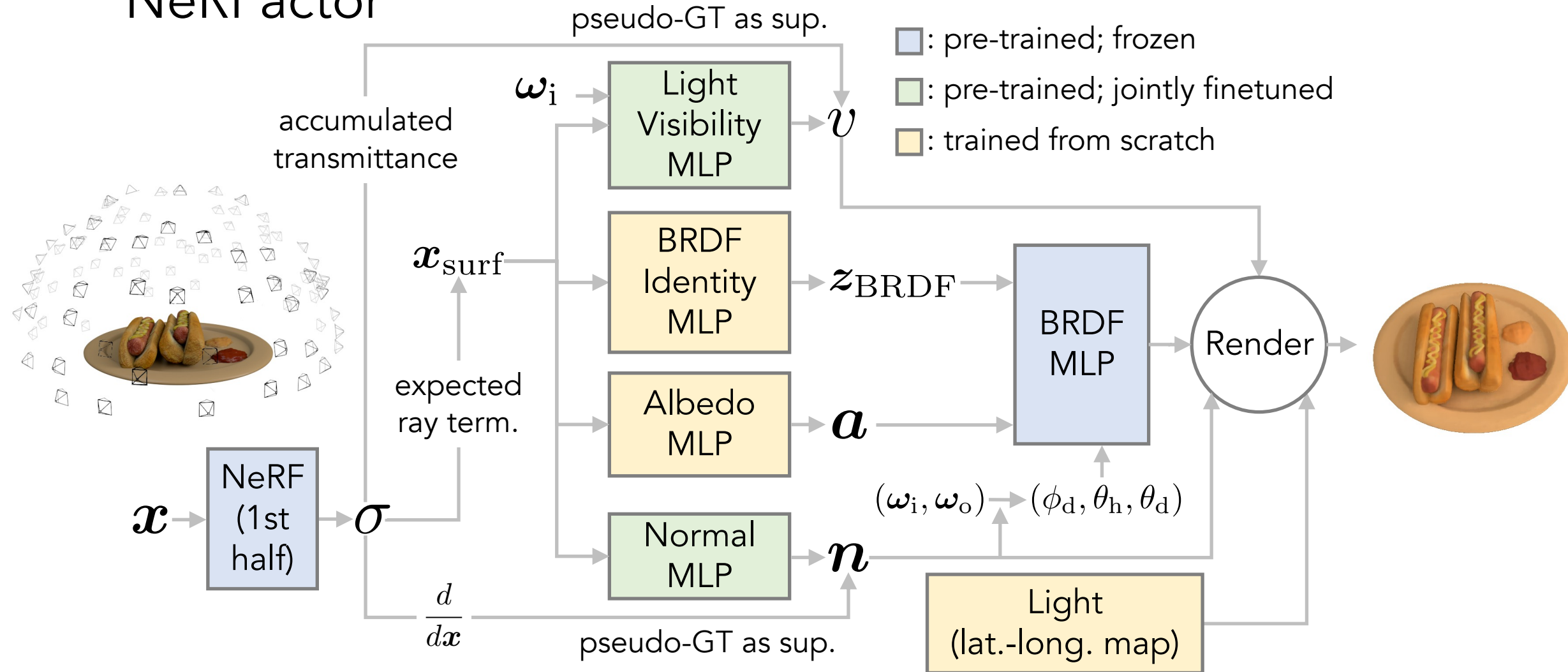
NeRFactor



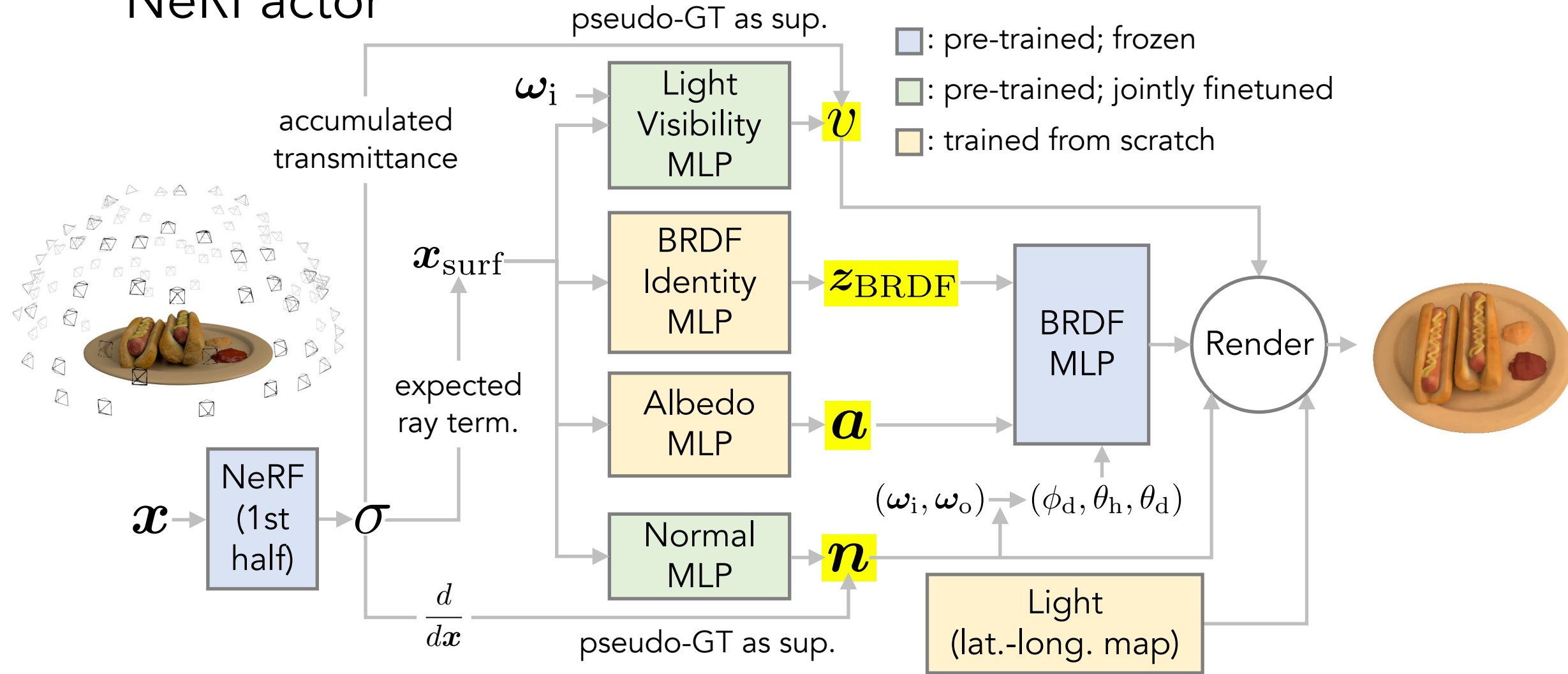
NeRFactor



NeRFactor



NeRFactor



L1 smoothness regularization

Results

on Appearance Factorization, Free-Viewpoint Relighting, & Material Editing

Normals



Visibility



Nearest Input



BRDF



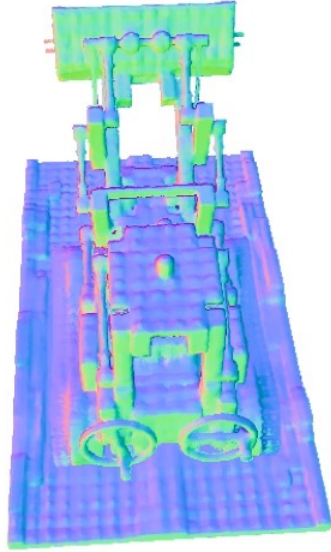
Albedo



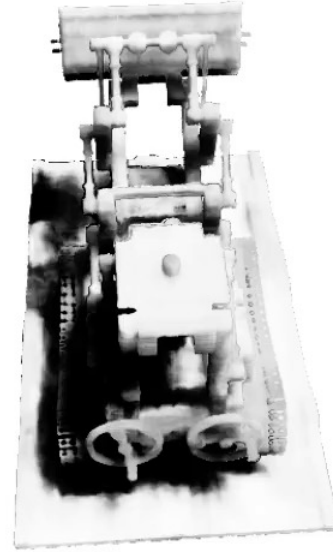
Rendering



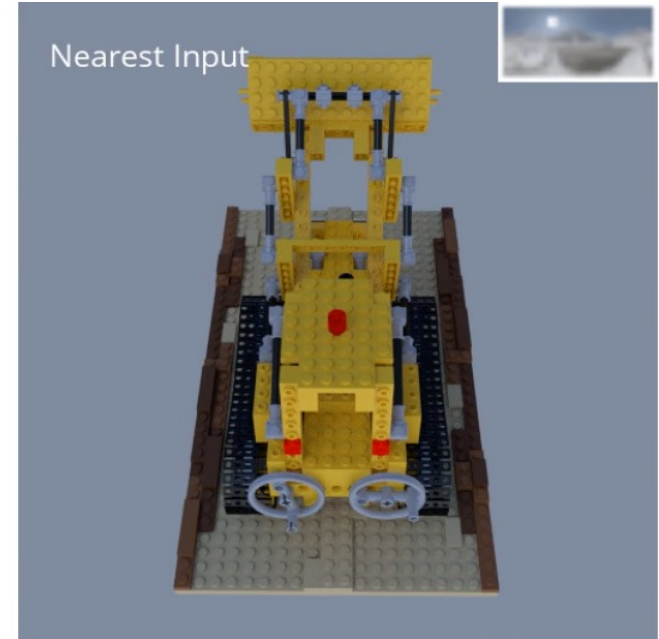
Normals



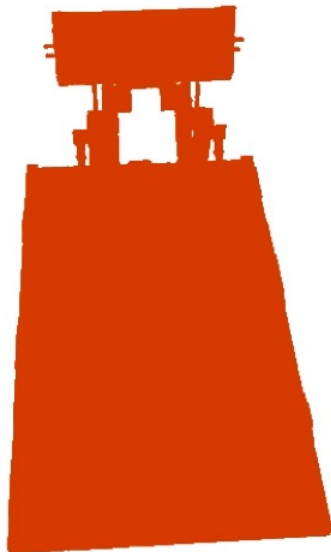
Visibility



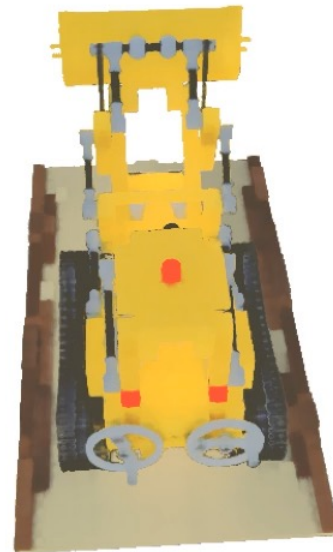
Nearest Input



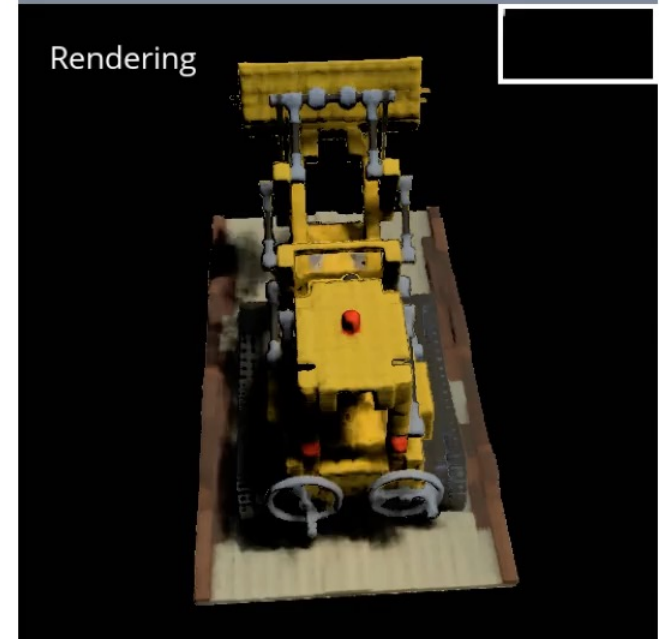
BRDF



Albedo

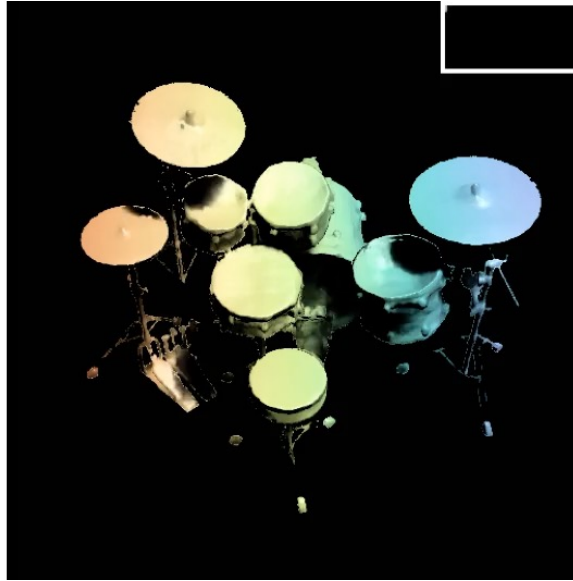


Rendering

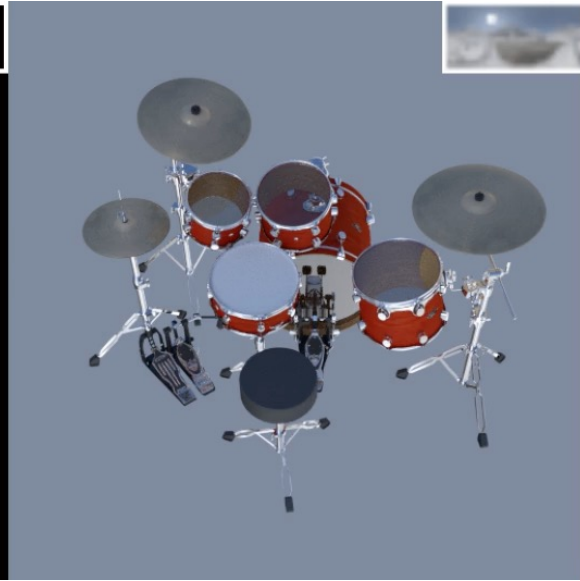




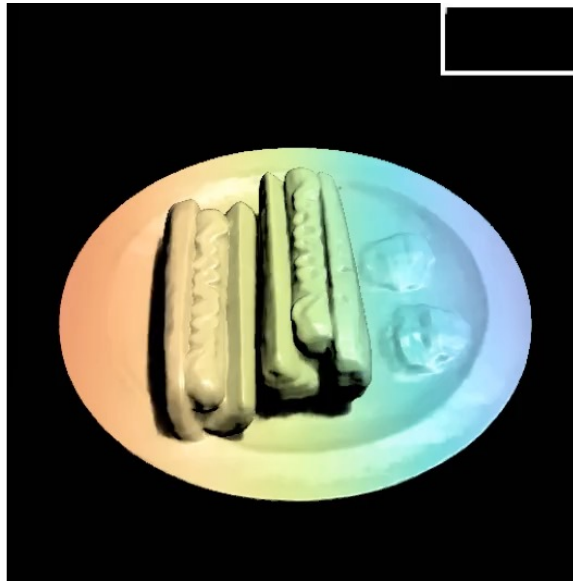
Edited Albedo



Relighting

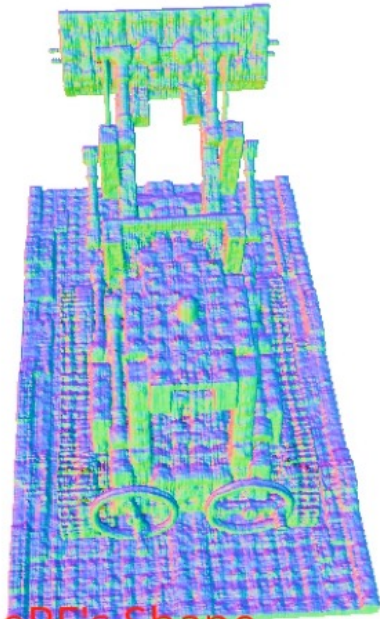


Nearest Input



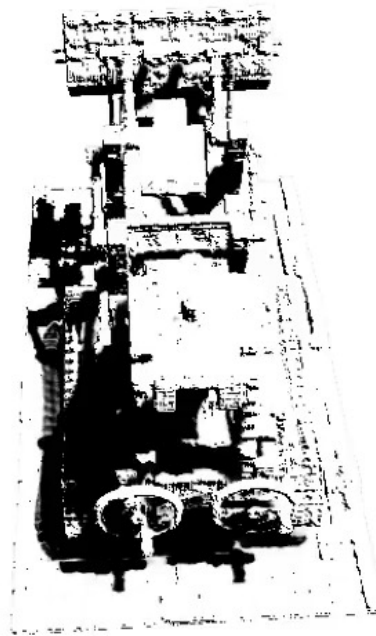
Ablation Studies

NeRF's shape is too noisy for relighting.

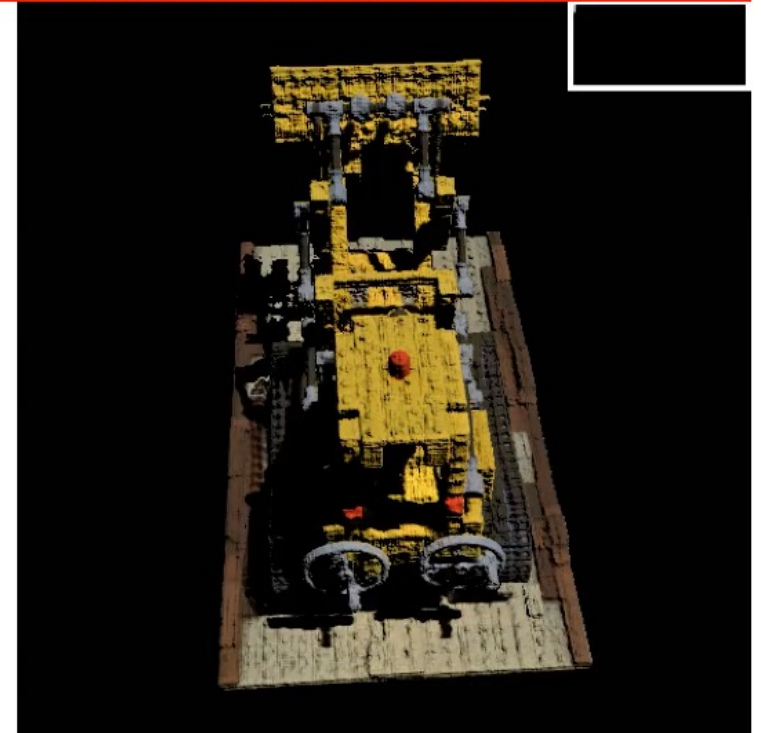


Using NeRF's Shape

Surface Normals



Light Visibility



Relighting

Smoothness constraints are crucial.

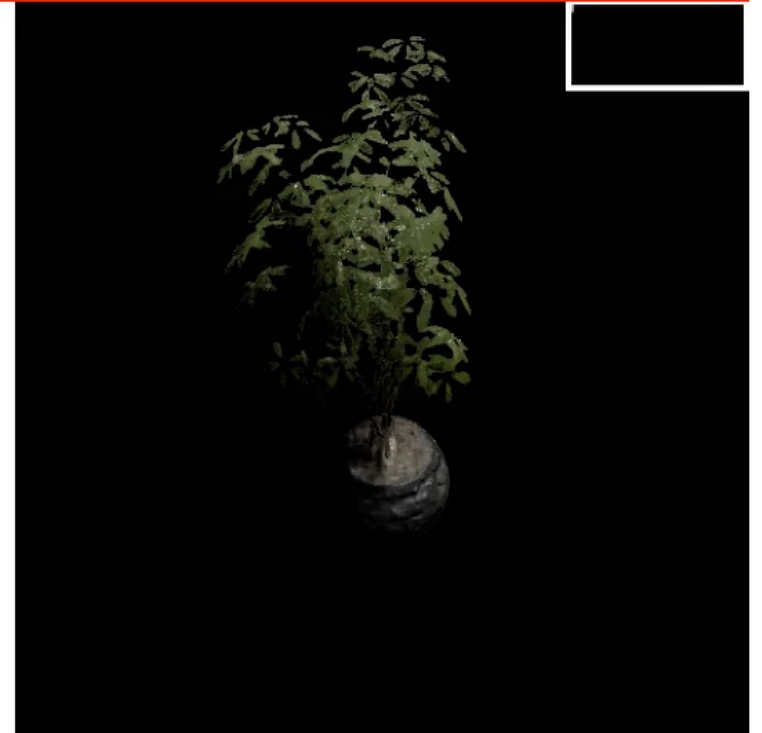


No Smooth.

Surface Normals

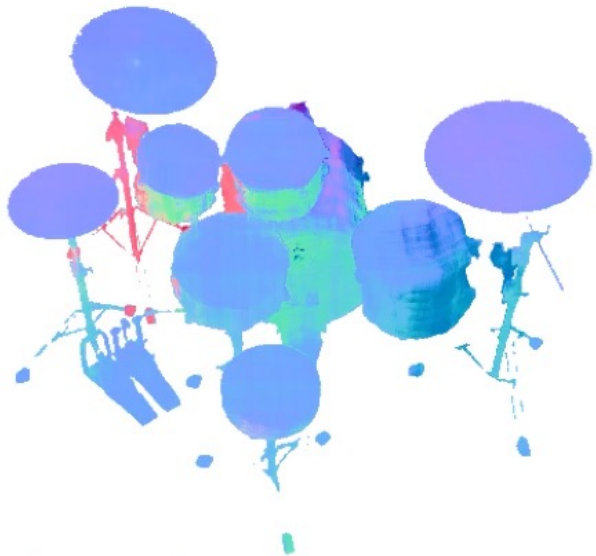


BRDFs



Relighting

Geometry pretraining improves shape and reflectance.



No Geom. Pretrain.

Surface Normals

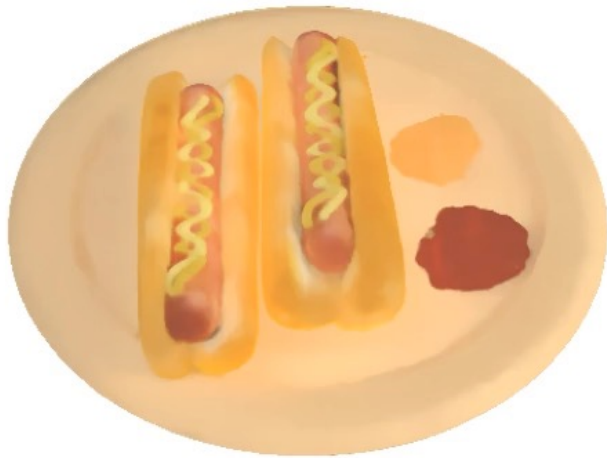


Albedo



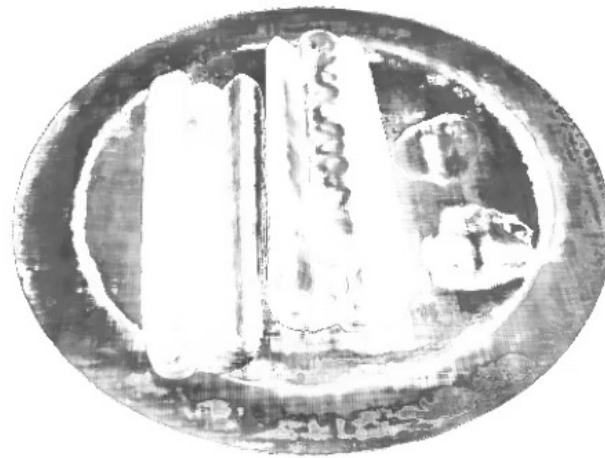
Relighting

Learned BRDFs are more optimization-friendly.

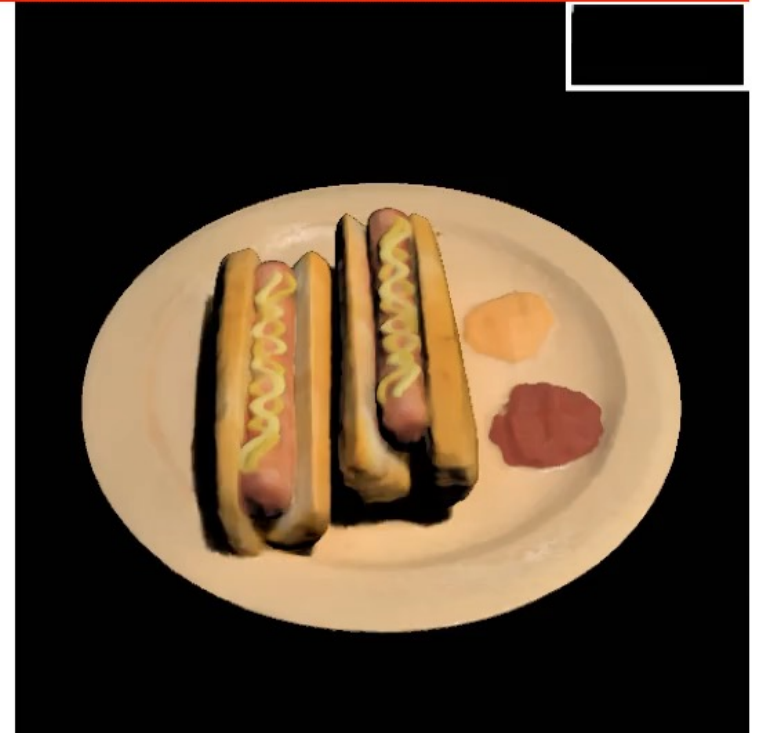


Microfacet

Albedo



BRDFs

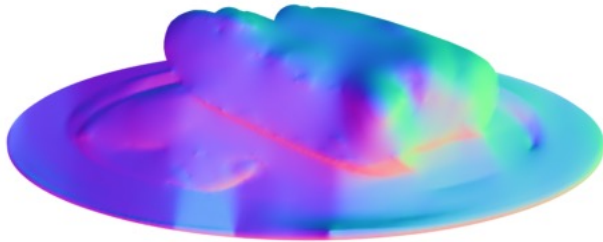


Relighting

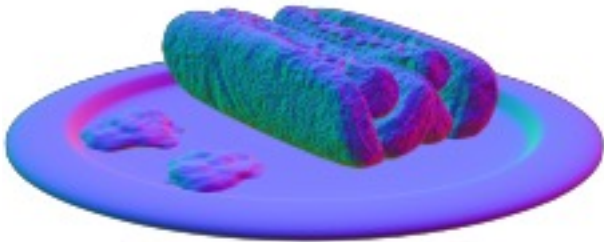
Baseline Comparisons

SIRFS does not exploit multiple views.

SIRFS

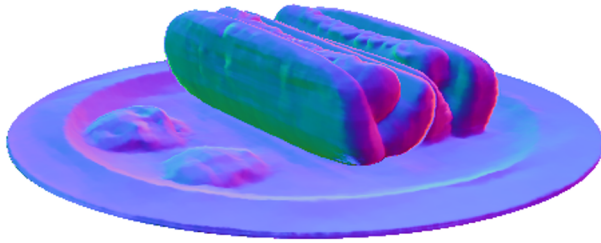


Ground
Truth

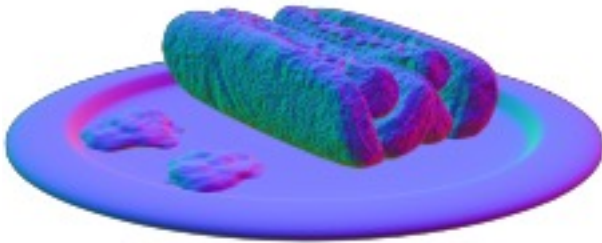


SIRFS does not exploit multiple views.

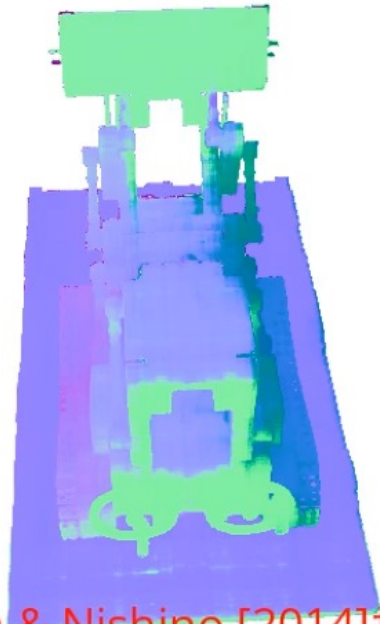
NeRFactor
(ours)



Ground
Truth



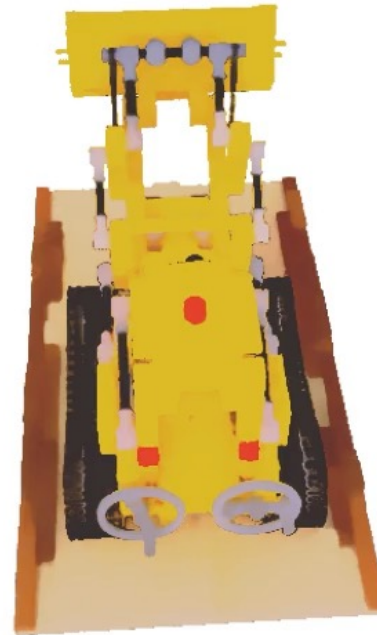
Oxholm & Nishino do not support SVBRDFs or shadows.



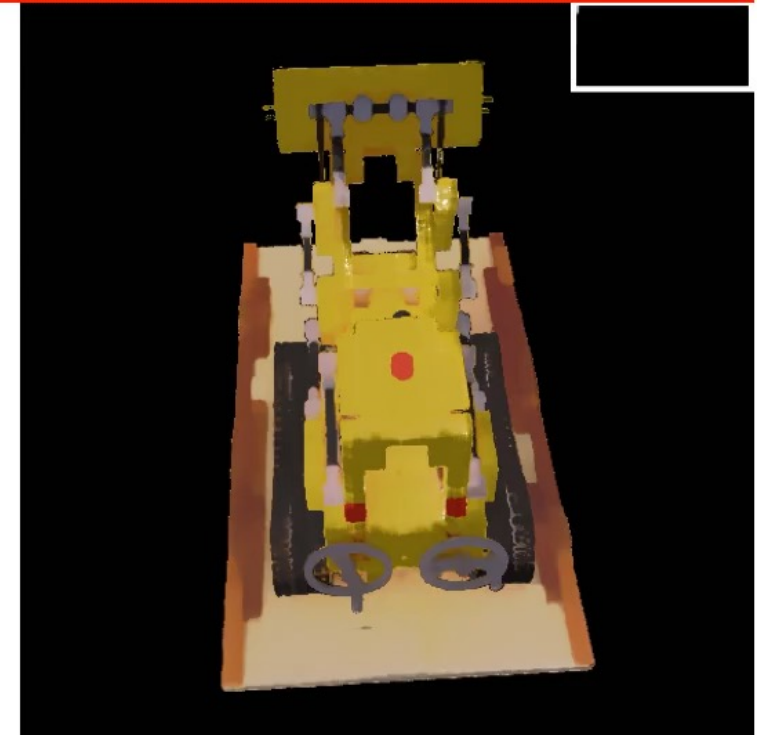
Oxholm & Nishino [2014]†

†Enhanced and Requiring Ground-Truth Lighting

Surface Normals



Albedo



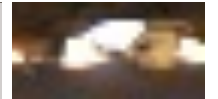
Rendering

Philip et al. do not support arbitrary relighting.

Philip et al.
[2019]

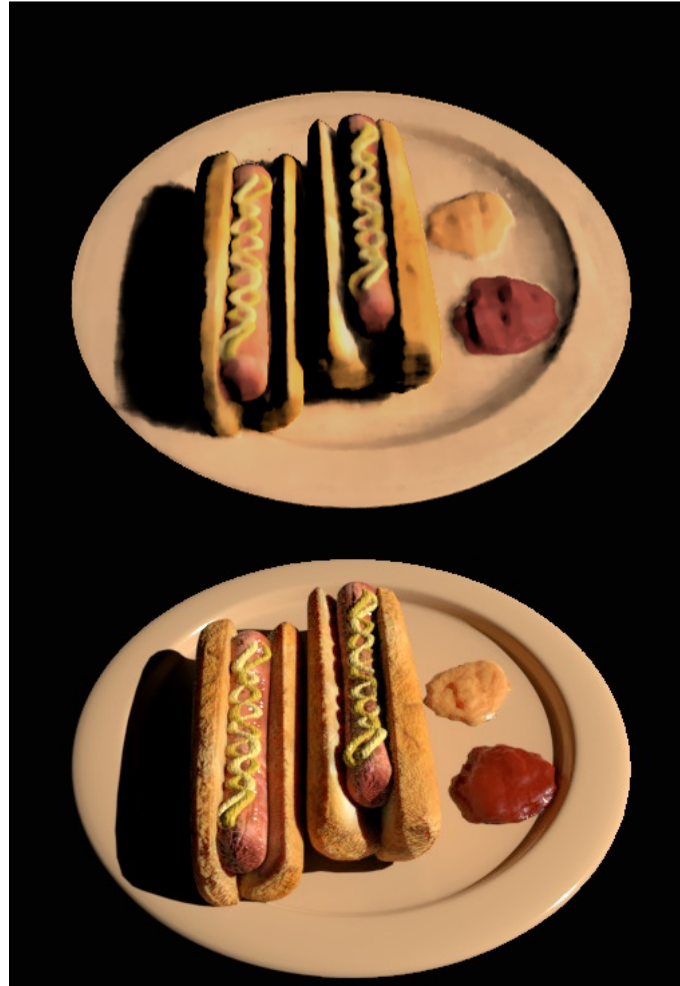


Ground
Truth

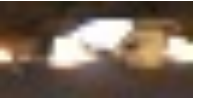


Philip et al. do not support arbitrary relighting.

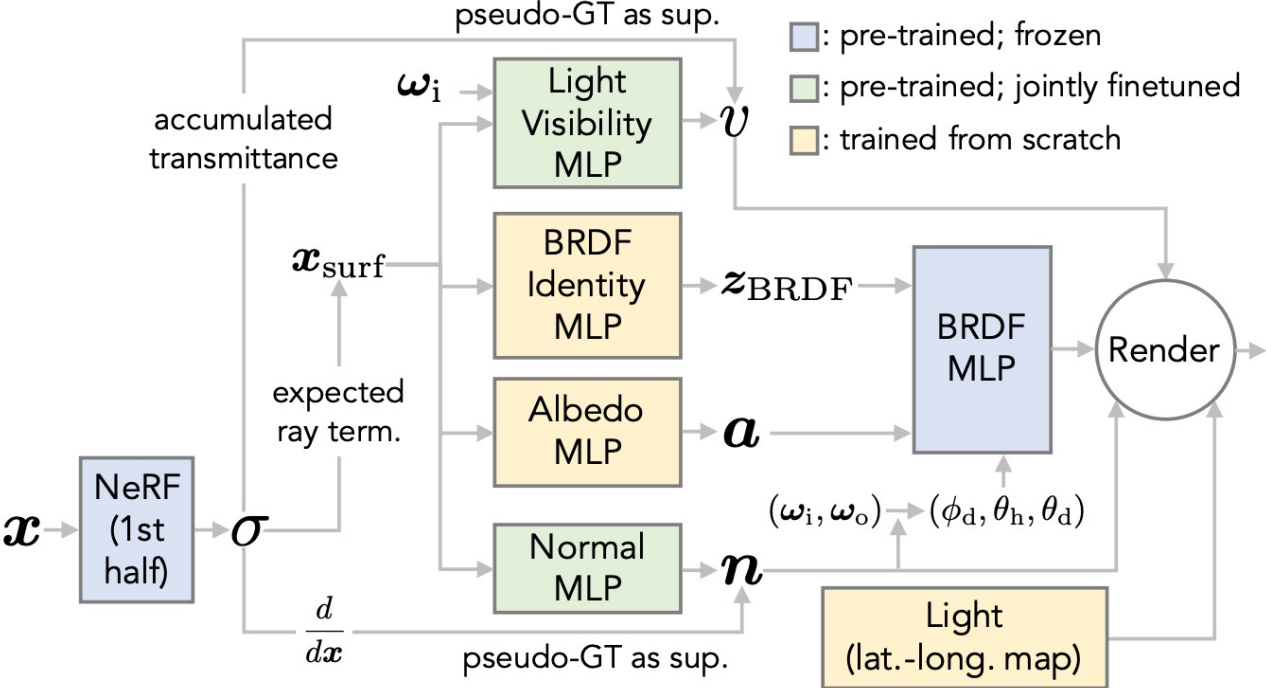
NeRFactor
(ours)



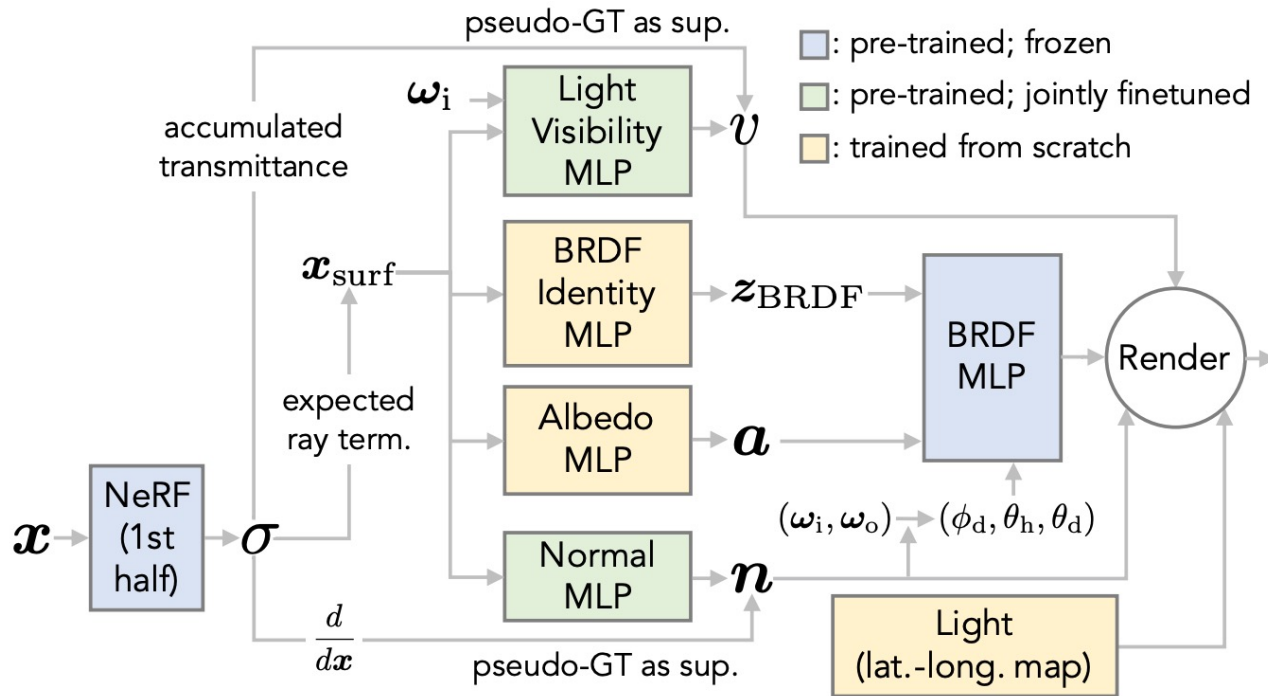
Ground
Truth



Neural Factorization of Shape and Reflectance (NeRFactor)



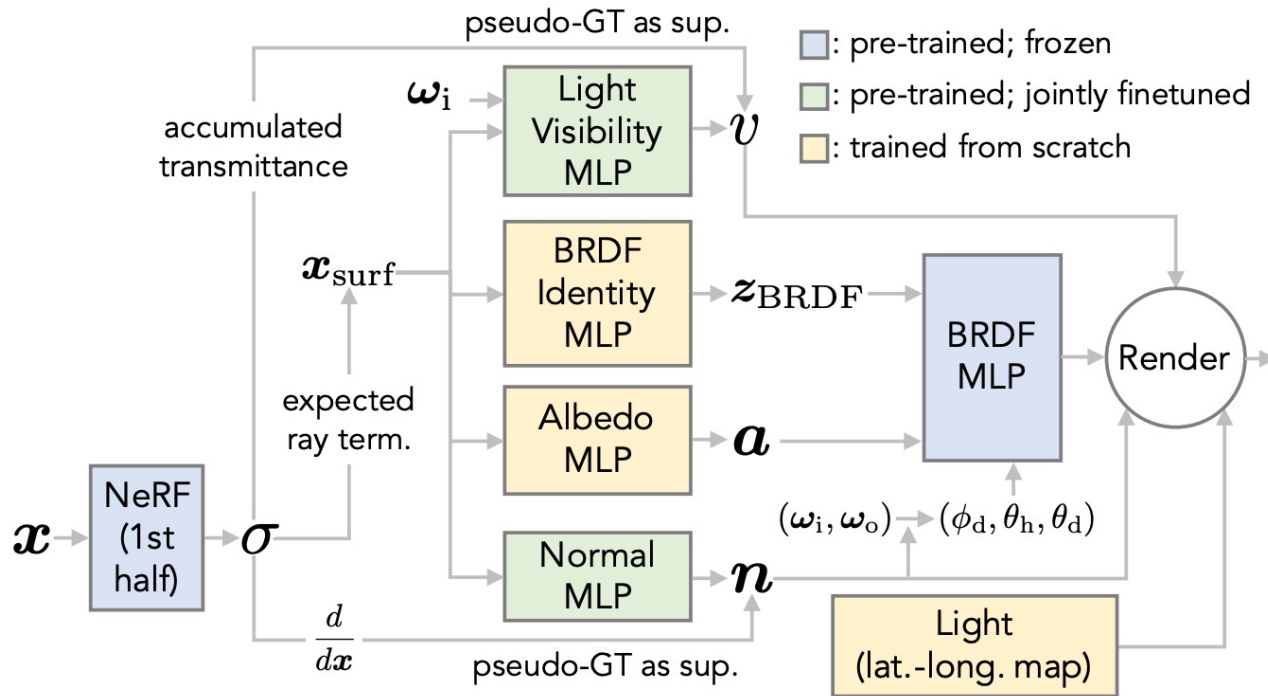
Neural Factorization of Shape and Reflectance (NeRFactor)



Contributions:

1. A method for factorizing appearance into shape and reflectance, under *one unknown* lighting condition.

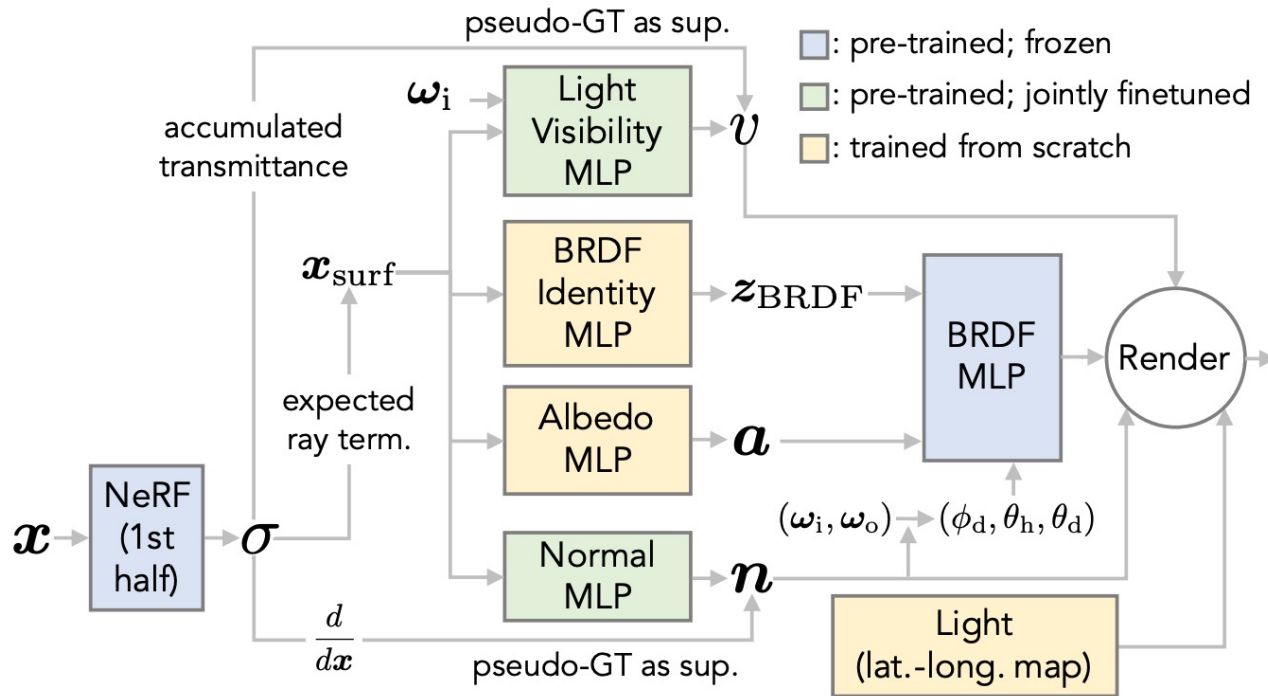
Neural Factorization of Shape and Reflectance (NeRFactor)



Contributions:

1. A method for factorizing appearance into shape and reflectance, under *one unknown* lighting condition.
2. A strategy to distill NeRF-estimated geometry and then refine it.

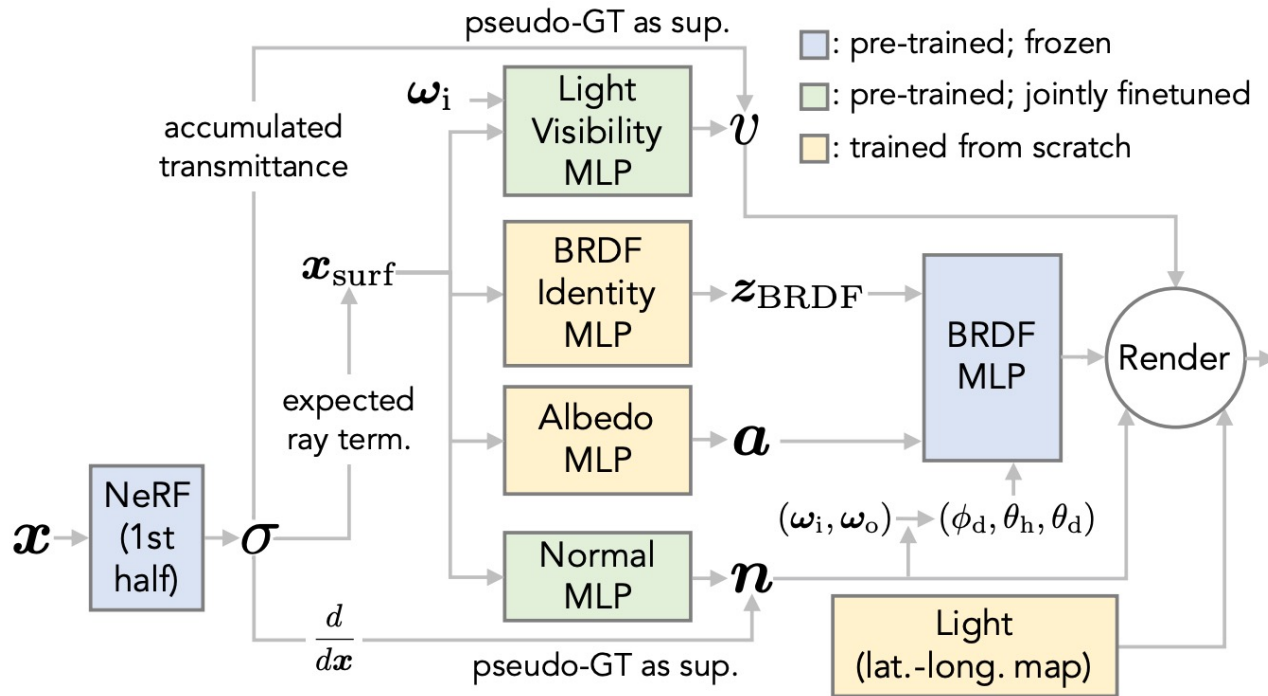
Neural Factorization of Shape and Reflectance (NeRFactor)



Contributions:

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Neural Factorization of Shape and Reflectance (NeRFactor)



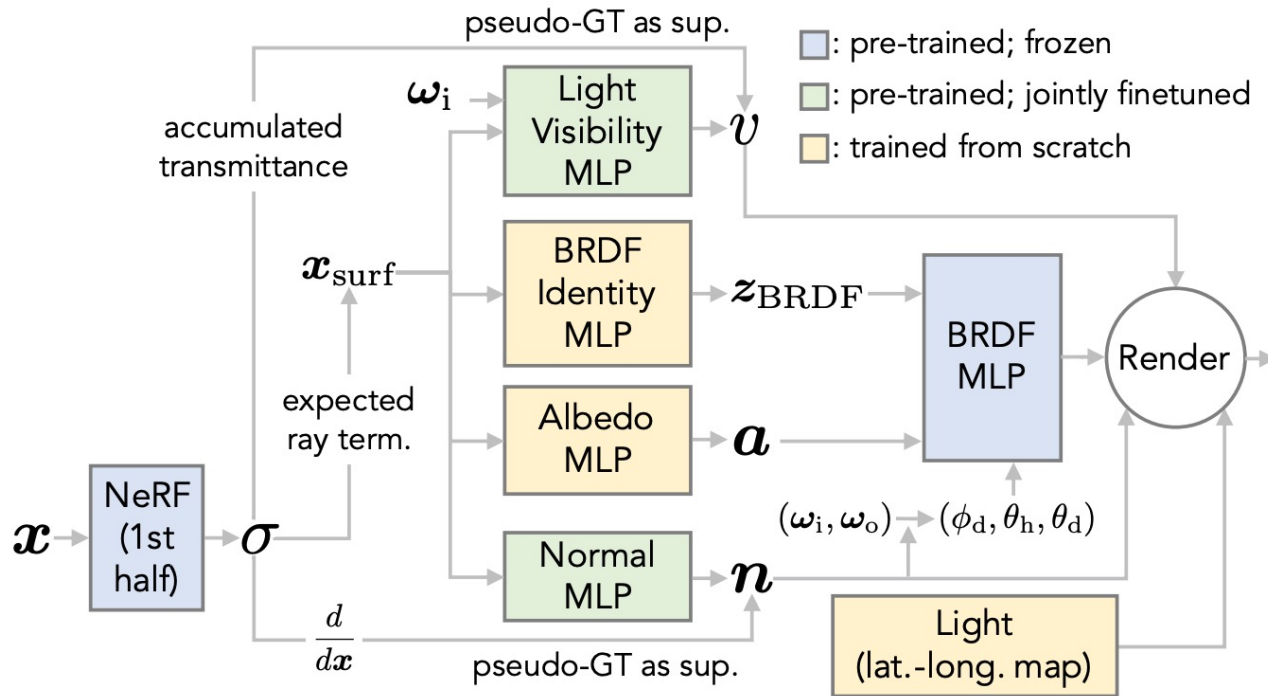
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✗ No indirect illumination

✗ Relies on NeRF geometry

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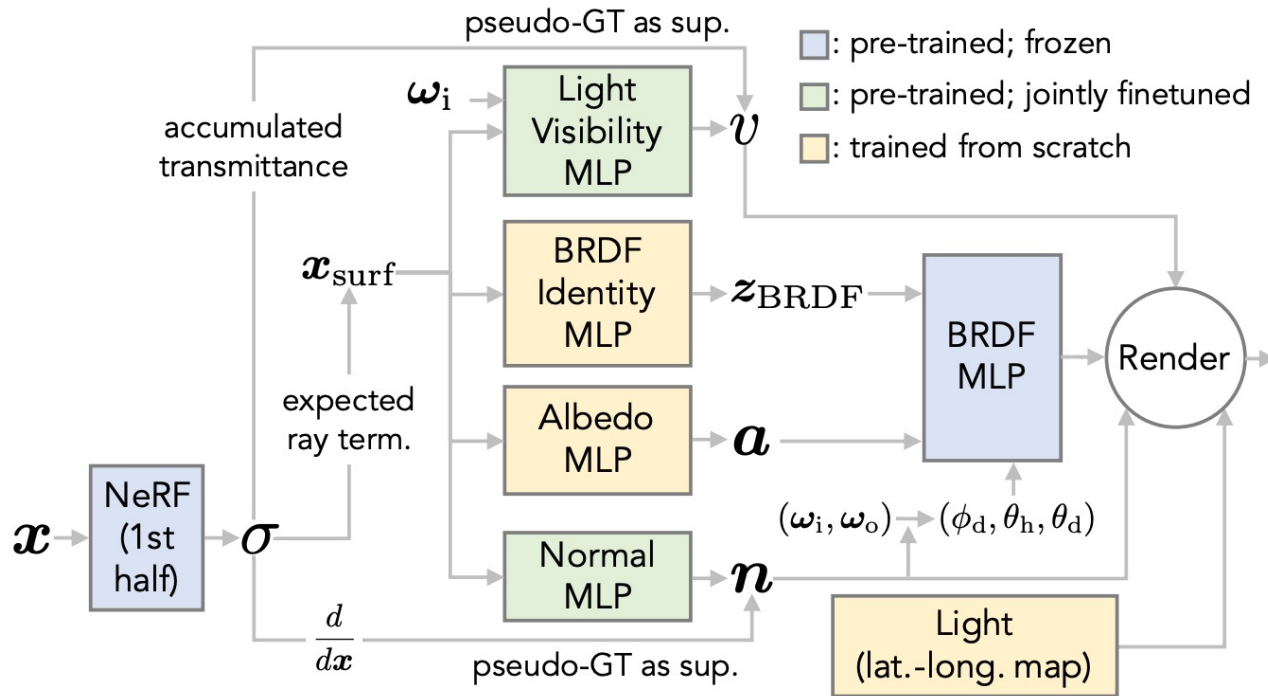
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Pratul P. Srinivasan, Boyang Deng, Xiuming Zhang, Matthew Tancik, Ben Mildenhall, Jonathan T. Barron
NeRV: Neural Reflectance and Visibility Fields for Relighting and View Synthesis
 CVPR 2021

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Pratul P. Srinivasan, Boyang Deng, Xiuming Zhang, Matthew Tancik, Ben Mildenhall, Jonathan T. Barron
NeRV: Neural Reflectance and Visibility Fields for Relighting and View Synthesis
 CVPR 2021

Key differences:

1. Models indirect illumination,
2. Optimizes shape from scratch, and
3. Learns from multiple, known lighting conditions.

Neural Visibility Fields (NeRV)

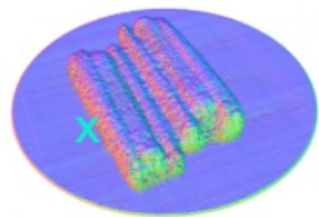


(a) Our Rendered Image
(Novel View and Lighting)

Neural Visibility Fields (NeRV)

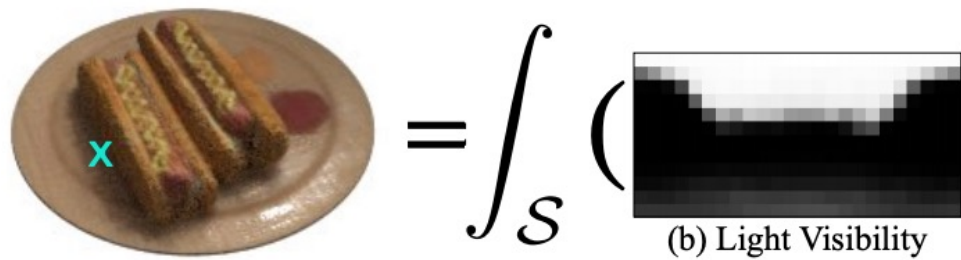


(a) Our Rendered Image
(Novel View and Lighting)

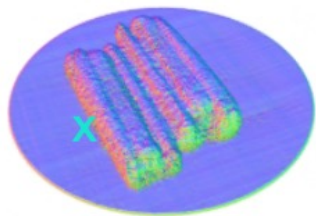


(f) Normals

Neural Visibility Fields (NeRV)

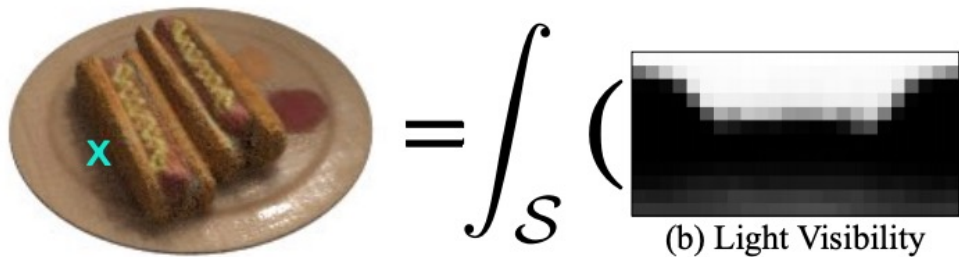


(a) Our Rendered Image
(Novel View and Lighting)

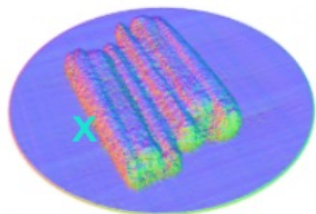


(f) Normals

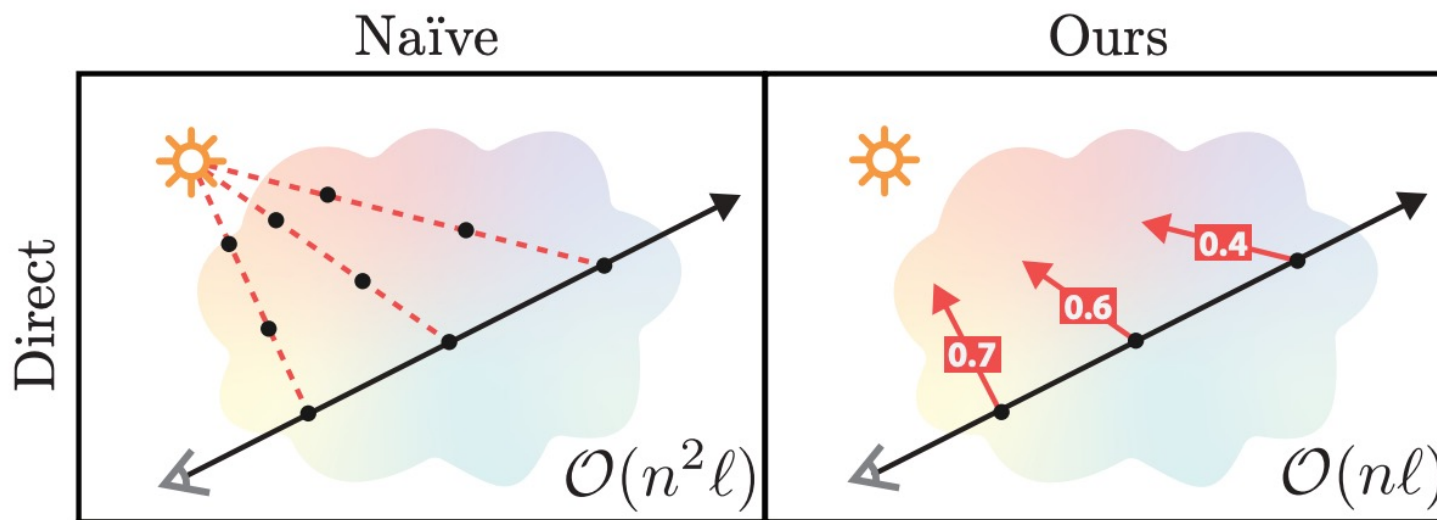
Neural Visibility Fields (NeRV)



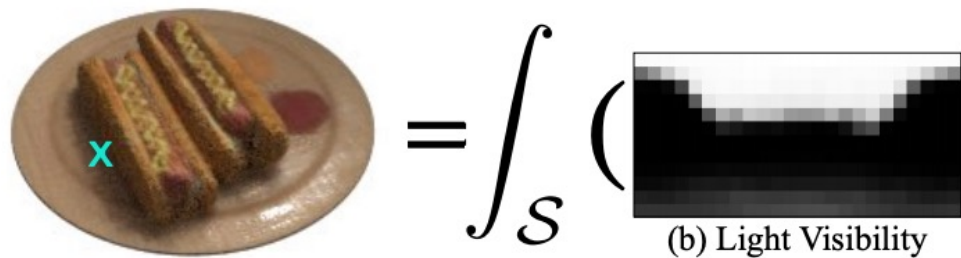
(a) Our Rendered Image
(Novel View and Lighting)



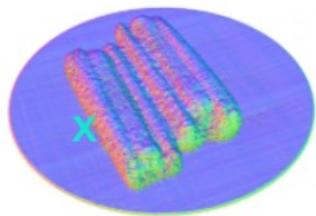
(f) Normals



Neural Visibility Fields (NeRV)

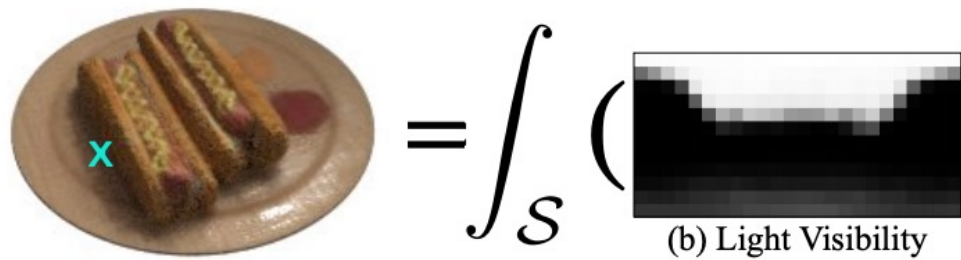


(a) Our Rendered Image
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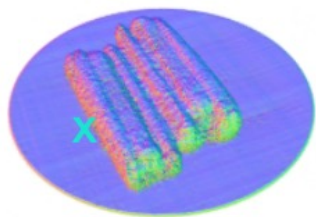


(f) Normals

Neural Visibility Fields (NeRV)



(a) Our Rendered Image
(Novel View and Lighting)

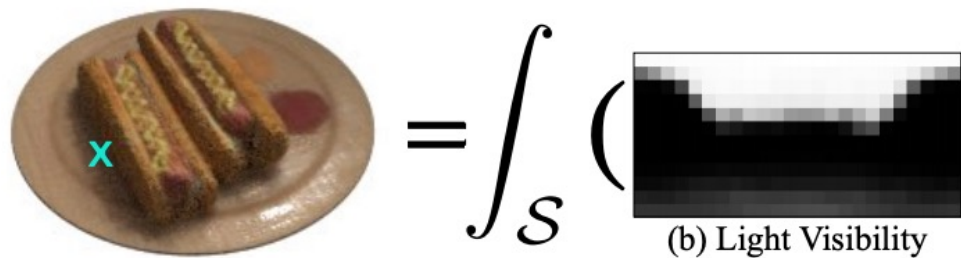


(f) Normals

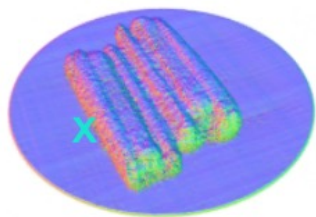


(i) Shadow Map

Neural Visibility Fields (NeRV)



(a) Our Rendered Image
(Novel View and Lighting)



(f) Normals

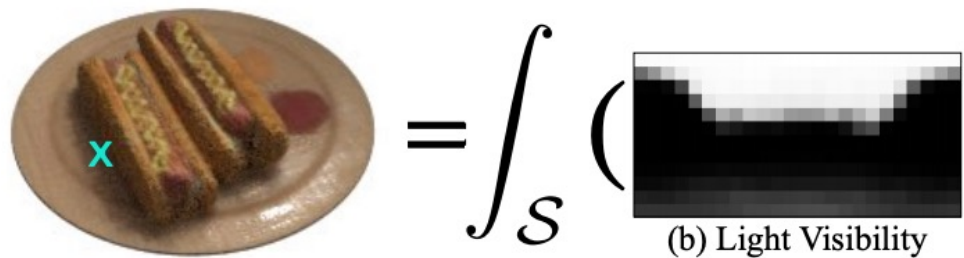


(g) Albedo

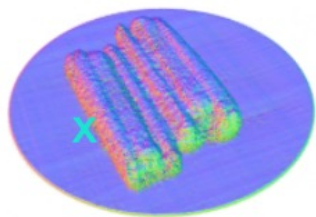


(i) Shadow Map

Neural Visibility Fields (NeRV)



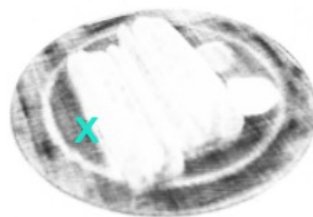
(a) Our Rendered Image
(Novel View and Lighting)



(f) Normals



(g) Albedo



(h) Roughness



(i) Shadow Map

Neural Visibility Fields (NeRV)

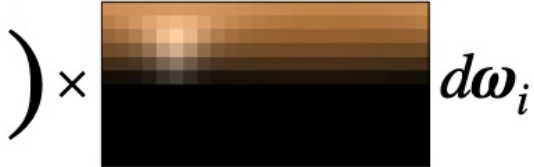


(a) Our Rendered Image
(Novel View and Lighting)

$$= \int_{\mathcal{S}}$$

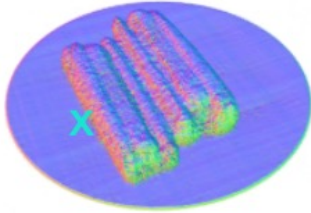


(b) Light Visibility



(e) BRDF

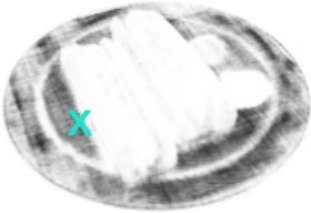
$d\omega_i$



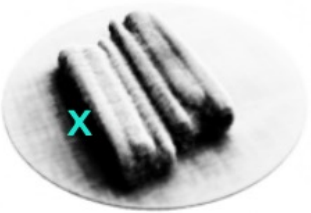
(f) Normals



(g) Albedo



(h) Roughness

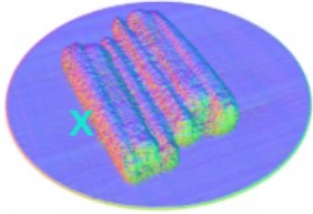


(i) Shadow Map

Neural Visibility Fields (NeRV)

$$(a) = \int_S \left((b) \times (c) \right) \times (e) d\omega_i$$

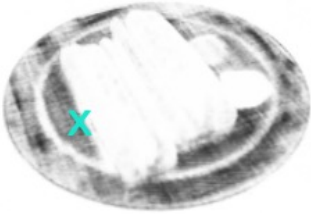
(a) Our Rendered Image
(Novel View and Lighting)



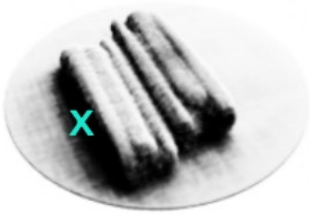
(f) Normals



(g) Albedo



(h) Roughness

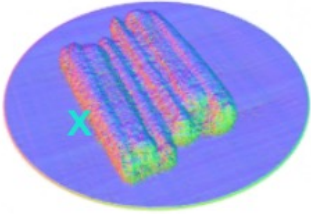


(i) Shadow Map

Neural Visibility Fields (NeRV)

$$(a) \text{ Our Rendered Image (Novel View and Lighting)} = \int_S \left((b) \text{ Light Visibility} \times (c) \text{ Direct Illumination} \right) \times (e) \text{ BRDF} d\omega_i$$

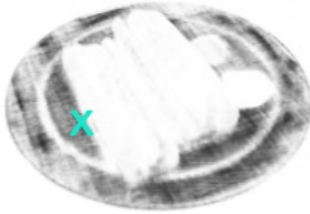
(a) Our Rendered Image (Novel View and Lighting)



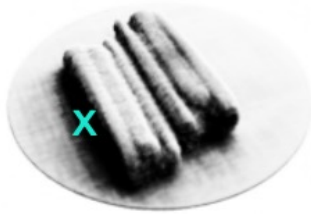
(f) Normals



(g) Albedo



(h) Roughness




(i) Shadow Map



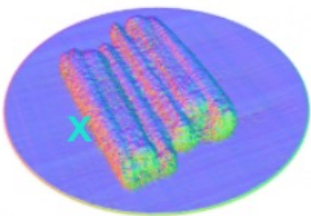
(j) Direct

Neural Visibility Fields (NeRV)


$$= \int_{\mathcal{S}} \left(\text{(b) Light Visibility} \times \text{(c) Direct Illumination} + \text{(d) Indirect Illumination} \right) \times \text{(e) BRDF} d\omega_i$$

(b) Light Visibility (c) Direct Illumination (d) Indirect Illumination (e) BRDF

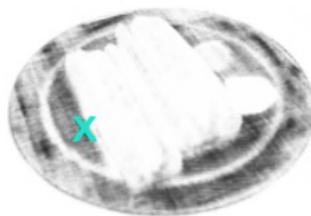
(a) Our Rendered Image
(Novel View and Lighting)



(f) Normals



(g) Albedo



(h) Roughness

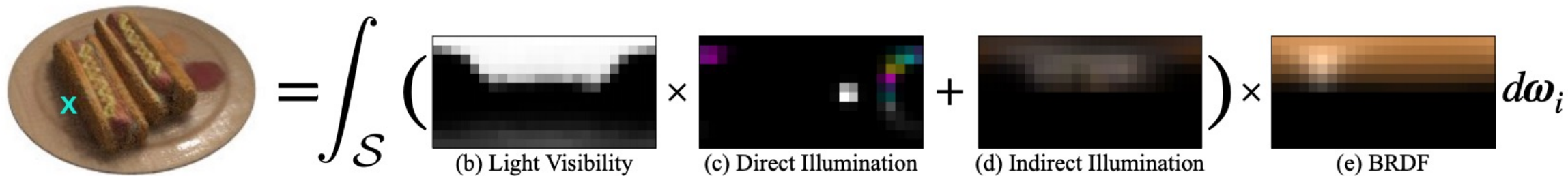


(i) Shadow Map



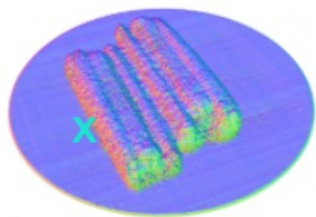
(j) Direct

Neural Visibility Fields (NeRV)



(a) Our Rendered Image (Novel View and Lighting) = $\int_{\mathcal{S}} \left((b) \text{ Light Visibility} \times (c) \text{ Direct Illumination} + (d) \text{ Indirect Illumination} \right) \times (e) \text{ BRDF} d\omega_i$

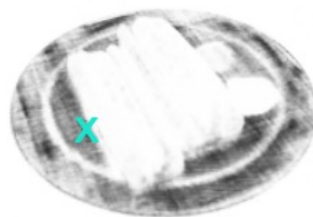
(a) Our Rendered Image (Novel View and Lighting)



(f) Normals



(g) Albedo



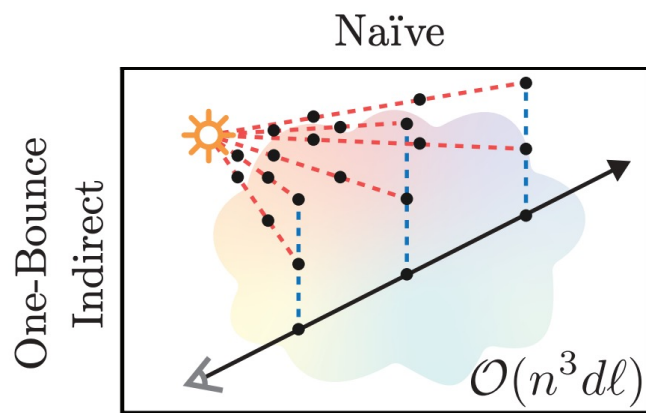
(h) Roughness



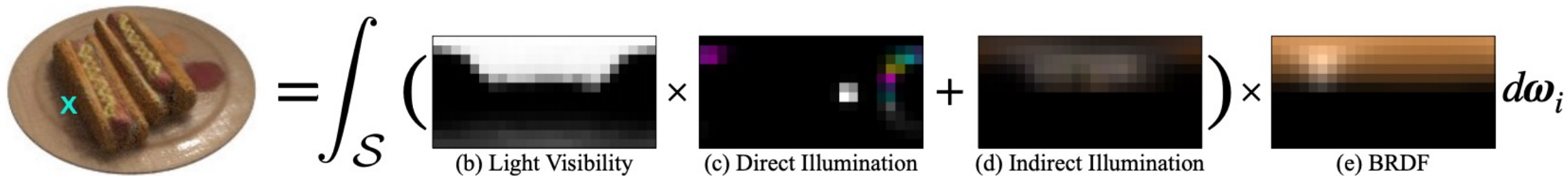
(i) Shadow Map



(j) Direct

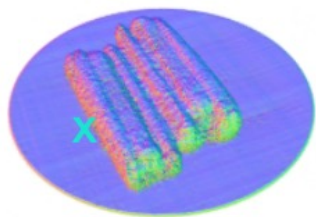


Neural Visibility Fields (NeRV)



$$(a) \text{ Our Rendered Image (Novel View and Lighting)} = \int_{\mathcal{S}} \left((b) \text{ Light Visibility} \times (c) \text{ Direct Illumination} + (d) \text{ Indirect Illumination} \right) \times (e) \text{ BRDF} d\omega_i$$

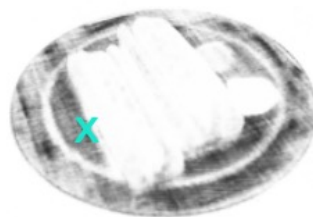
(a) Our Rendered Image (Novel View and Lighting)



(f) Normals



(g) Albedo



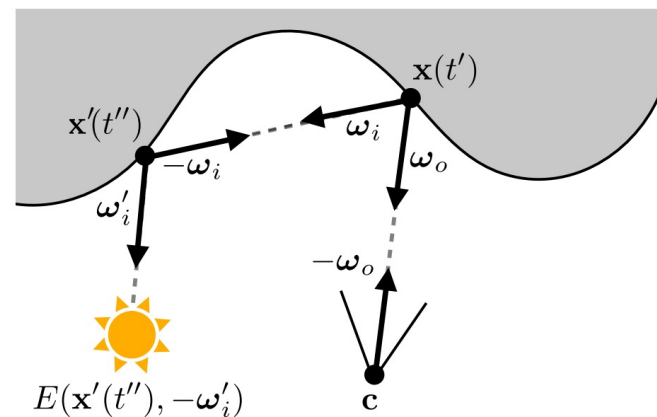
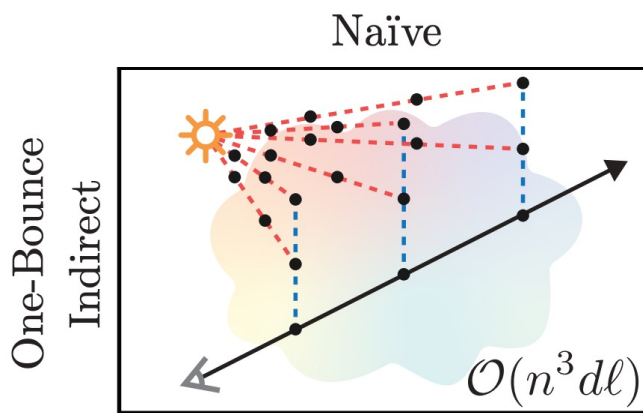
(h) Roughness



(i) Shadow Map

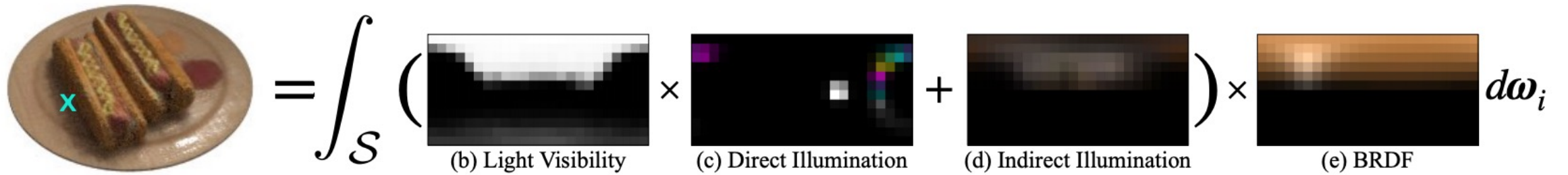


(j) Direct



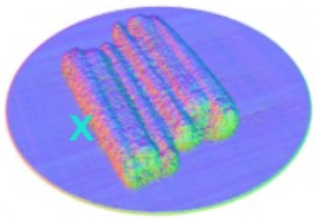
\mathbf{c} = camera center
 E = light source
 t' = expected termination depth along camera ray
 $t'' = \tilde{D}_\phi(\mathbf{x}(t'), \omega_i)$, estimated termination depth along indirect bounce ray

Neural Visibility Fields (NeRV)



$$(a) \text{ Our Rendered Image} = \int_{\mathcal{S}} \left((b) \text{ Light Visibility} \times (c) \text{ Direct Illumination} + (d) \text{ Indirect Illumination} \right) \times (e) \text{ BRDF} d\omega_i$$

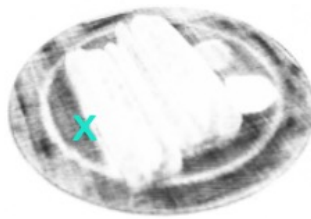
(a) Our Rendered Image
(Novel View and Lighting)



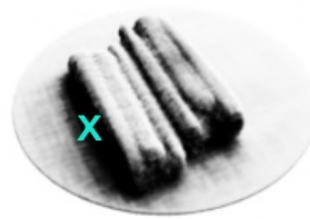
(f) Normals



(g) Albedo



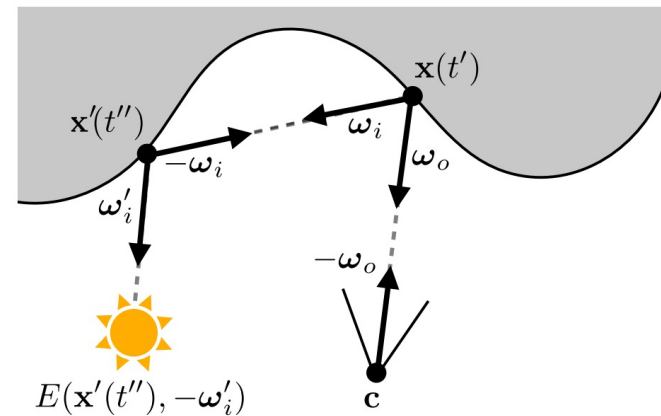
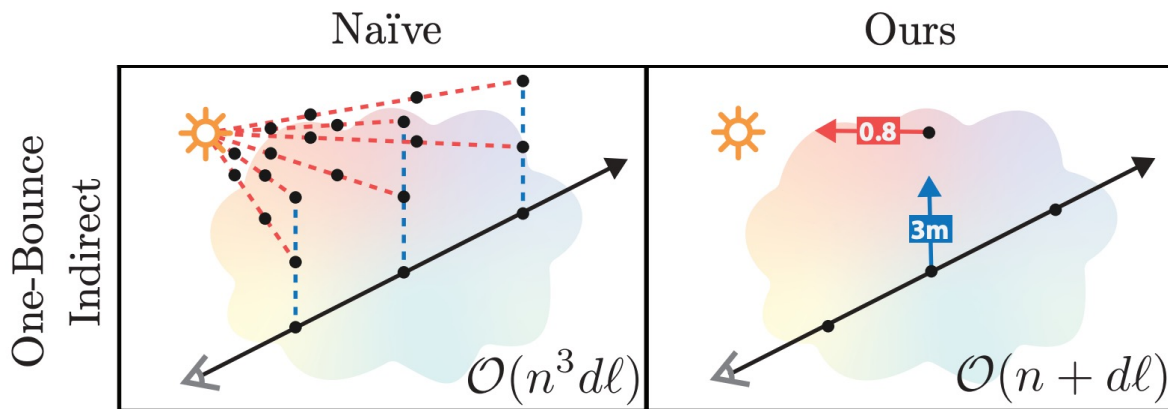
(h) Roughness



(i) Shadow Map




(j) Direct



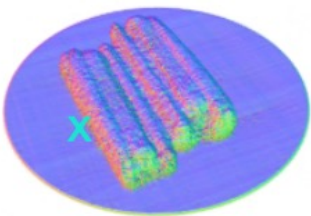
c = camera center
 E = light source
 t' = expected termination depth along camera ray
 $t'' = \tilde{D}_\phi(x(t'), \omega_i)$, estimated termination depth along indirect bounce ray

Neural Visibility Fields (NeRV)


$$= \int_{\mathcal{S}} \left(\begin{array}{c} \text{(b) Light Visibility} \\ \times \\ \text{(c) Direct Illumination} \\ + \\ \text{(d) Indirect Illumination} \end{array} \right) \times \begin{array}{c} \text{(e) BRDF} \\ d\omega_i \end{array}$$

(b) Light Visibility (c) Direct Illumination (d) Indirect Illumination (e) BRDF

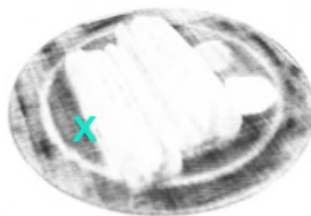
(a) Our Rendered Image
(Novel View and Lighting)



(f) Normals



(g) Albedo



(h) Roughness




(i) Shadow Map



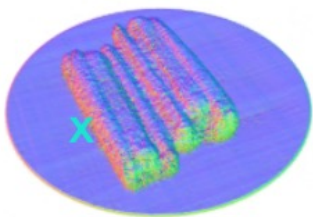
(j) Direct

Neural Visibility Fields (NeRV)


$$= \int_{\mathcal{S}} \left(\text{(b) Light Visibility} \times \text{(c) Direct Illumination} + \text{(d) Indirect Illumination} \right) \times \text{(e) BRDF} d\omega_i$$

(b) Light Visibility (c) Direct Illumination (d) Indirect Illumination (e) BRDF

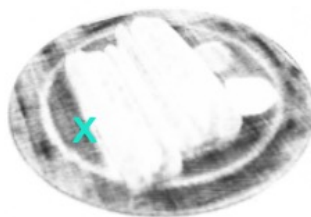
(a) Our Rendered Image
(Novel View and Lighting)



(f) Normals



(g) Albedo



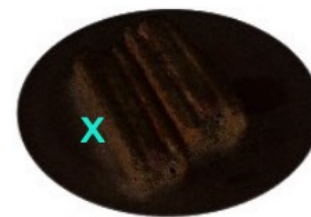
(h) Roughness



(i) Shadow Map




(j) Direct



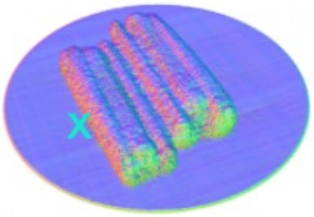
(k) Indirect

NeRV models (first-bounce) indirect illumination.


$$= \int_{\mathcal{S}} \left(\begin{array}{c} \text{(b) Light Visibility} \\ \times \\ \text{(c) Direct Illumination} \\ + \\ \text{(d) Indirect Illumination} \end{array} \right) \times \begin{array}{c} \text{(e) BRDF} \\ d\omega_i \end{array}$$

(b) Light Visibility (c) Direct Illumination (d) Indirect Illumination (e) BRDF

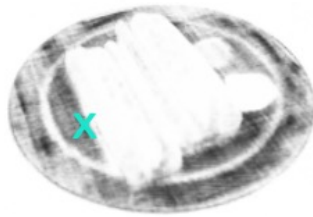
(a) Our Rendered Image
(Novel View and Lighting)



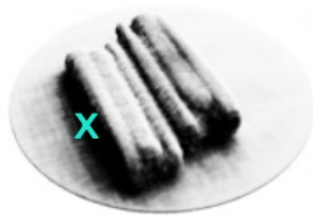
(f) Normals



(g) Albedo



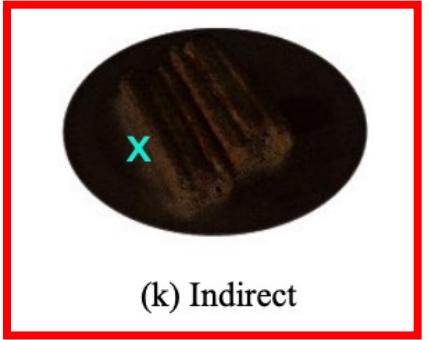
(h) Roughness



(i) Shadow Map




(j) Direct



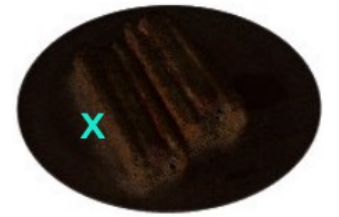
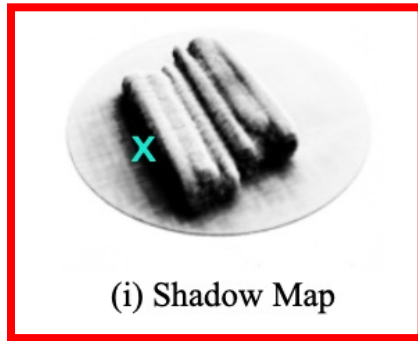
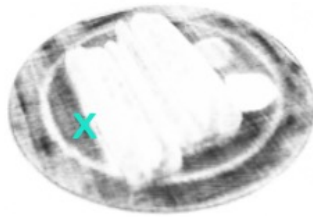
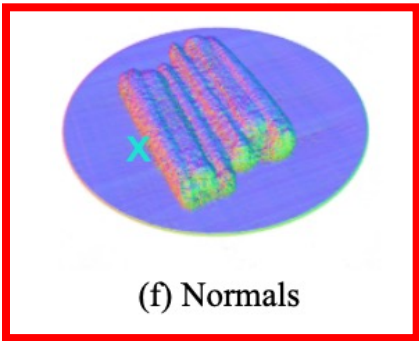
(k) Indirect

NeRV optimizes geometry from scratch.

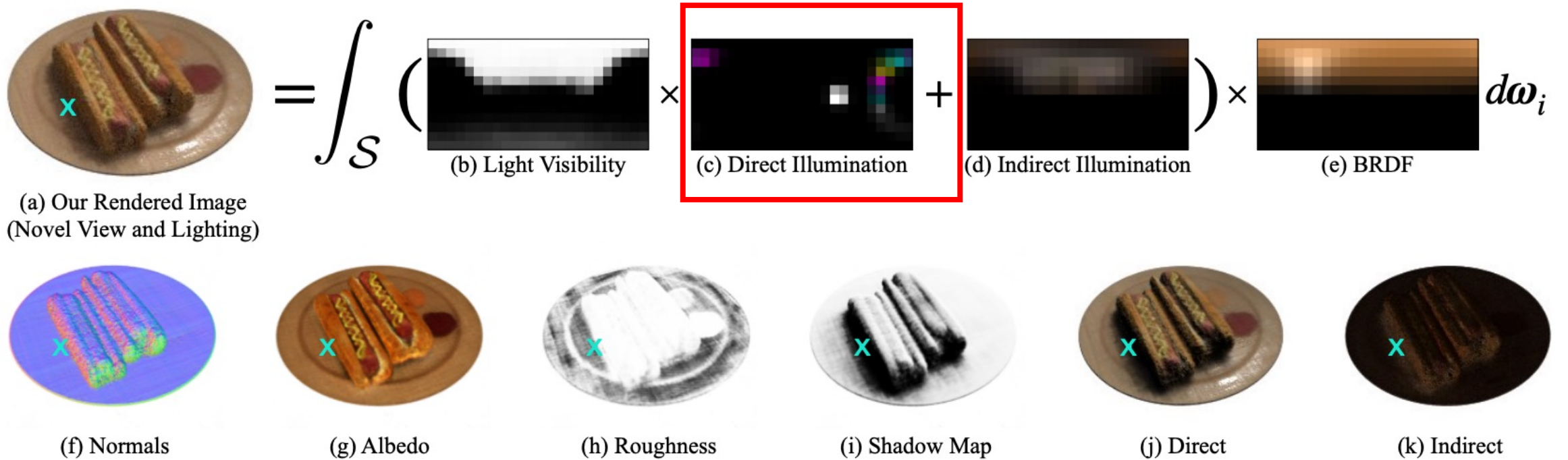

$$= \int_{\mathcal{S}} \left(\text{(b) Light Visibility} \times \text{(c) Direct Illumination} + \text{(d) Indirect Illumination} \right) \times \text{(e) BRDF} d\omega_i$$

(b) Light Visibility (c) Direct Illumination (d) Indirect Illumination (e) BRDF

(a) Our Rendered Image
(Novel View and Lighting)



NeRV learns from multiple known lighting conditions.

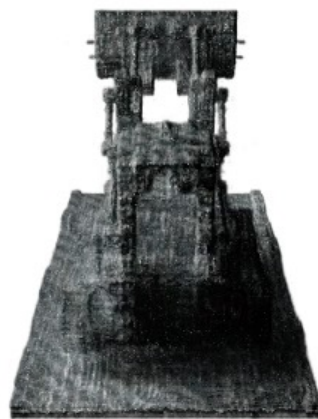


NeRV Results

Novel Views and Lighting



Material Editing



Acknowledgements



Bill Freeman



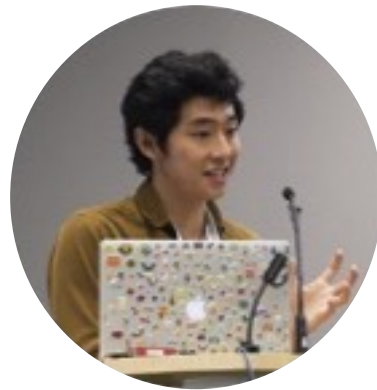
Jon Barron



Paul Debevec



Pratul Srinivasan



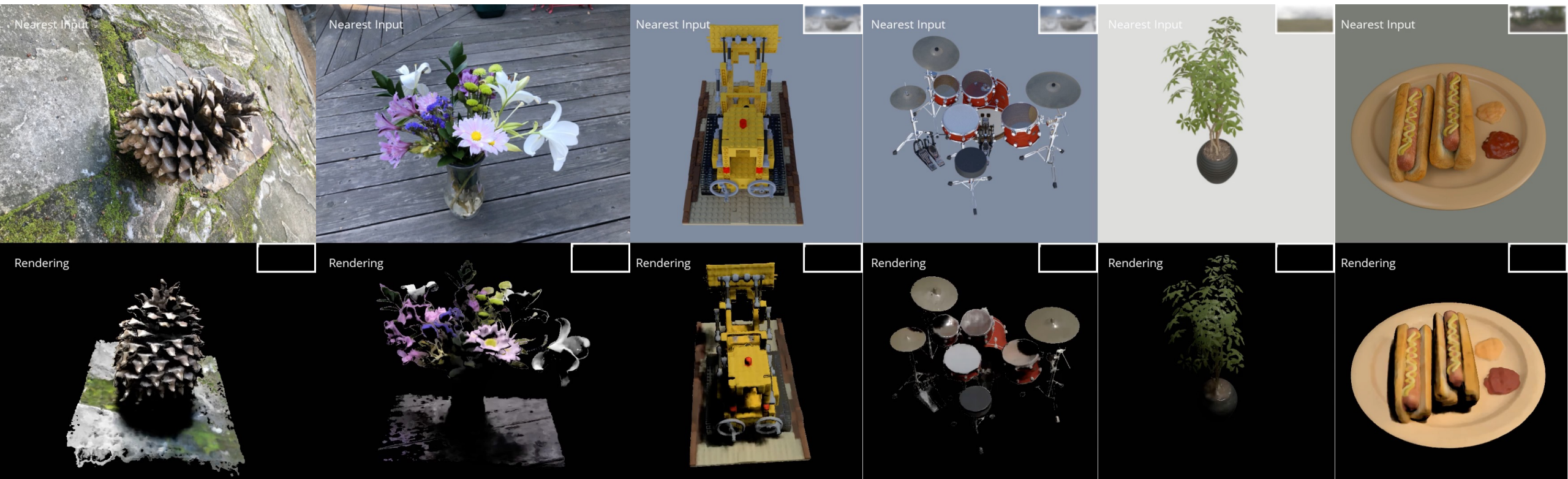
Boyang Deng



Ben Mildenhall



Matt Tancik



Questions?



NeRFactor:

Paper, videos, code, & data:

<https://people.csail.mit.edu/xiuming/projects/nerfactor>

Backup

NeRF doesn't require geometry, but doesn't support relighting.



NeRF

Mildenhall*, Srinivasan*, Tancik*, Barron,
Ramamoorthi, Ng
ECCV 2020

$$L(\mathbf{c}, \boldsymbol{\omega}_o) = \int_0^\infty V(\mathbf{x}(t), \mathbf{c}) \sigma(\mathbf{x}(t)) L_e(\mathbf{x}(t), \boldsymbol{\omega}_o) dt,$$

$$V(\mathbf{x}(t), \mathbf{c}) = \exp\left(-\int_0^t \sigma(\mathbf{x}(s)) ds\right).$$

✗ Not relightable



Neural Reflectance Fields

Bi*, Xu*, Srinivasan, Mildenhall, Sunkavalli,
Hašan, Hold-Geoffroy, Kriegman,
Ramamoorthi
arXiv 2020

$$L(\mathbf{c}, \boldsymbol{\omega}_o) = \int_0^\infty V(\mathbf{x}(t), \mathbf{c}) \sigma(\mathbf{x}(t)) L_r(\mathbf{x}(t), \boldsymbol{\omega}_o) dt,$$

$$L_r(\mathbf{x}, \boldsymbol{\omega}_o) = \int_S L_i(\mathbf{x}, \boldsymbol{\omega}_i) R(\mathbf{x}, \boldsymbol{\omega}_i, \boldsymbol{\omega}_o) d\boldsymbol{\omega}_i,$$

✗ Trainable only with lights collocated with cameras

✗ direct illumination only



NeRV: Neural Reflectance and Visibility Fields for Relighting and View Synthesis

Srinivasan, Deng, Zhang, Tancik, Mildenhall, Barron
arXiv 2020

Direct lighting (amortizing visibility computation):

$$\int_0^\infty V(\mathbf{x}(t), \mathbf{c}) \sigma(\mathbf{x}(t)) \int_S \tilde{V}_\phi(\mathbf{x}(t), \boldsymbol{\omega}_i) E(\mathbf{x}(t), -\boldsymbol{\omega}_i) R(\mathbf{x}(t), \boldsymbol{\omega}_i, \boldsymbol{\omega}_o) d\boldsymbol{\omega}_i dt$$

Indirect lighting (one bounce only & hard surface assumption):

$$\iint_S \tilde{V}_\phi(\mathbf{x}'(t''), \boldsymbol{\omega}'_i) E(\mathbf{x}'(t''), -\boldsymbol{\omega}'_i) R(\mathbf{x}'(t''), \boldsymbol{\omega}'_i, -\boldsymbol{\omega}_i) d\boldsymbol{\omega}'_i$$

$$R(\mathbf{x}(t'), \boldsymbol{\omega}_i, \boldsymbol{\omega}_o) d\boldsymbol{\omega}_i$$

✓ Trainable with any lights (including full light probes)

✓ Considers one-bounce indirect illumination

* indicates equal contribution