



SIGGRAPH 2021

HIGHLIGHT-AWARE TWO-STREAM NETWORK FOR SINGLE-IMAGE SVBRDF ACQUISITION

Jie Guo¹ Shuichang Lai¹ Chengzhi Tao¹

Yuelong Cai¹ Lei Wang² Yanwen Guo¹ Ling-qi Yan³

¹State Key Lab for Novel Software Technology,
Nanjing University

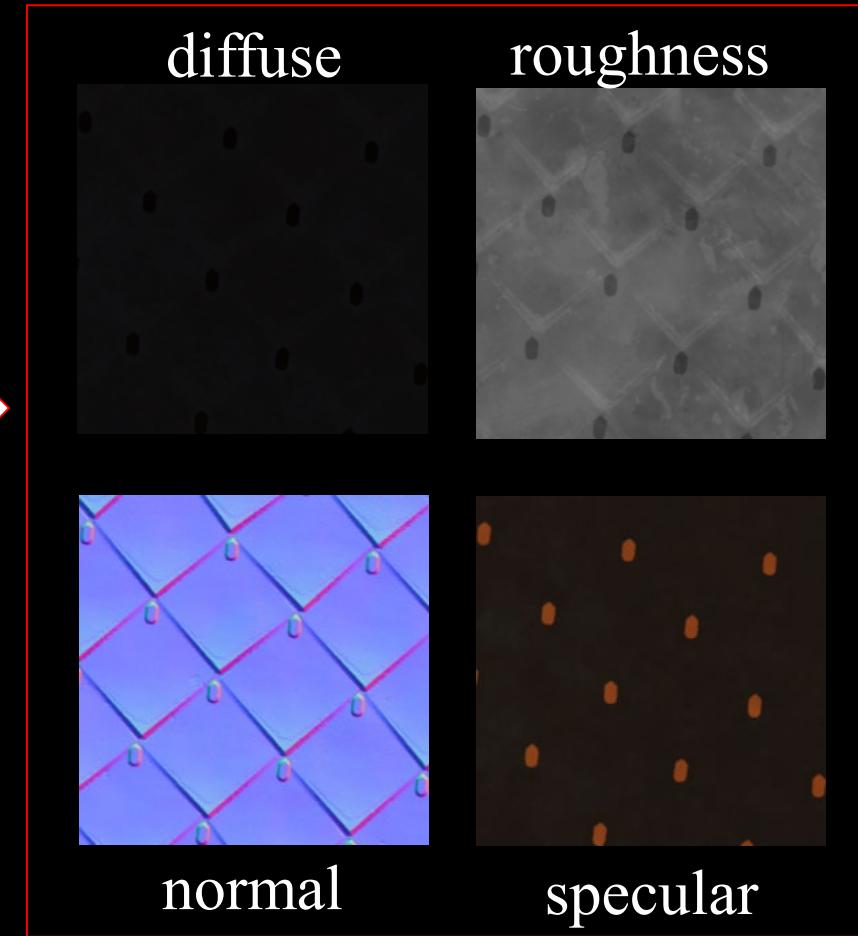
²Guangdong OPPO Mobile
Telecommunications Corp Ltd

³University of California, Santa Barbara

SVBRDF Acquisition

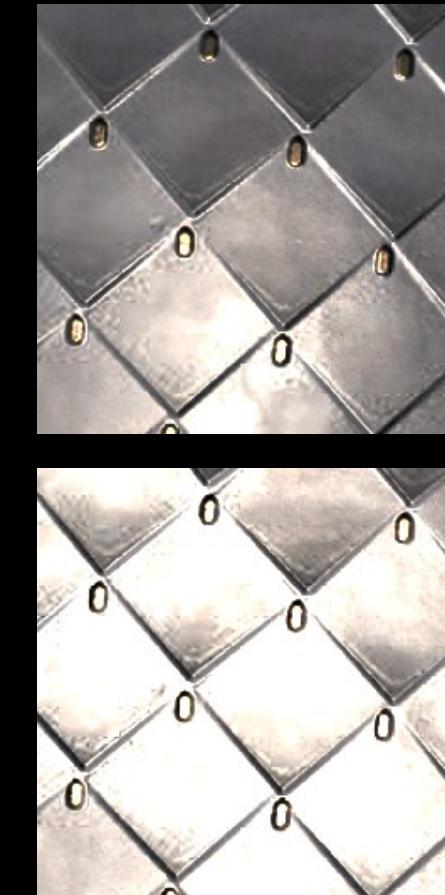


Input



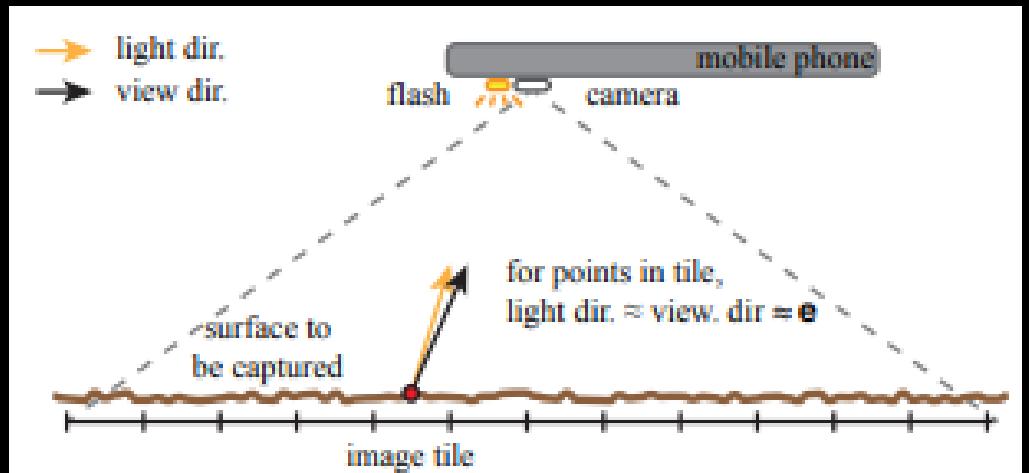
Material

Render



Related Work

Multiple input images



[Aittala et al. 2016]

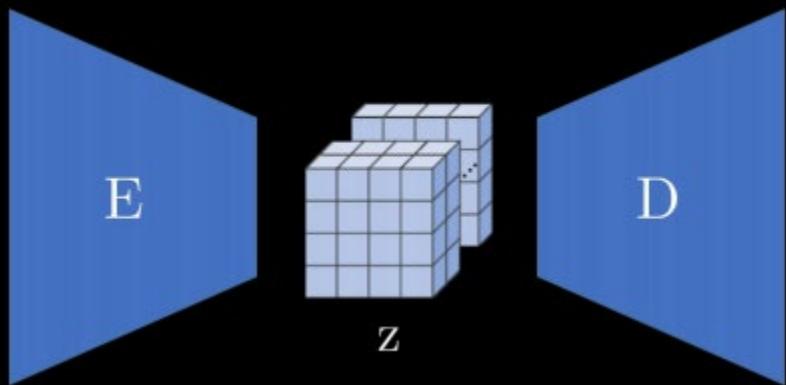
- High-quality
- Specialized hardware
- Complex operation



[Asselin et al. 2020]

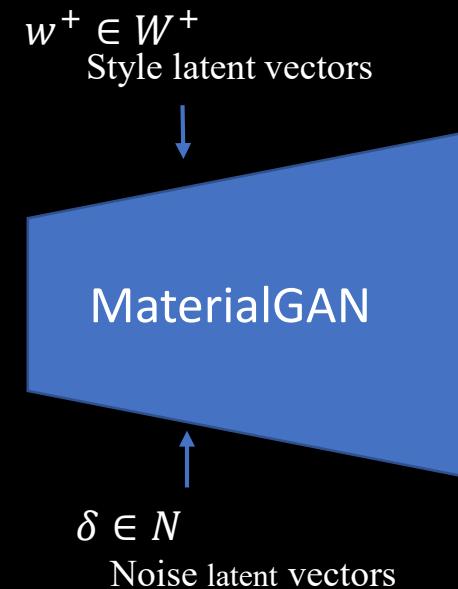
Related Work

Multiple input images



[Gao et al. 2019]

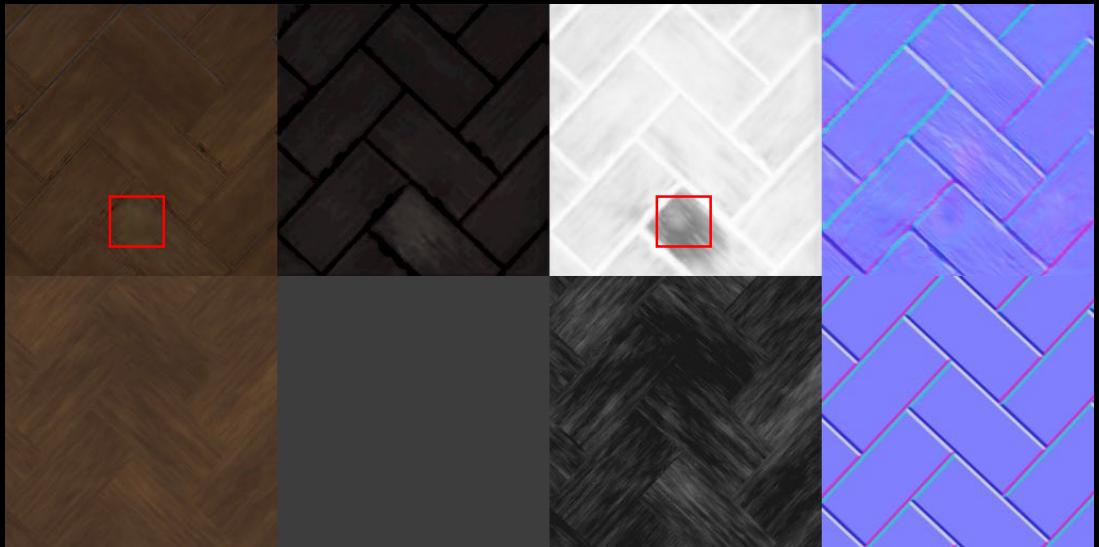
- Time-consuming
- Cumbersome optimization
- Extra camera calibration



[Guo et al. 2020]

Related Work

Single input image



[Deschaintre et al. 2018]

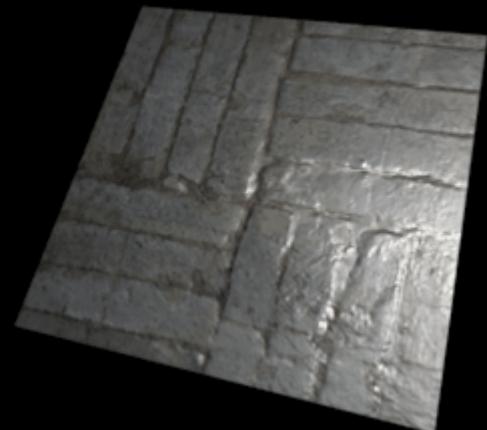
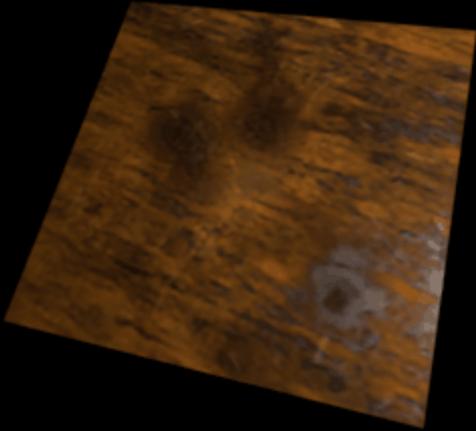
reference render



- Weak disentanglement
- Highlight ambiguity

Our Goal

- Single, casually captured image as input
(without camera calibration)
- Well disentanglement
- Highlight aware
- Fast evaluation

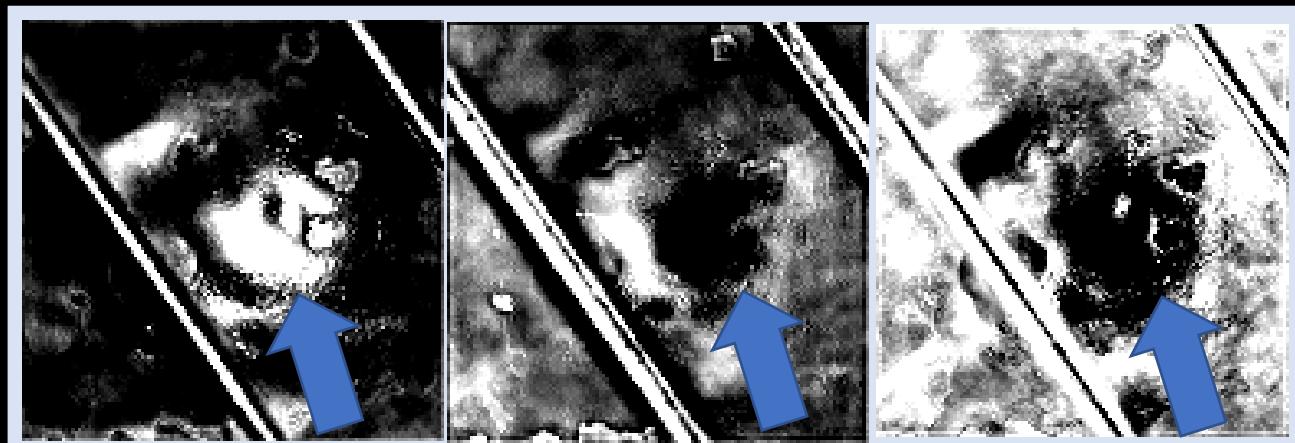
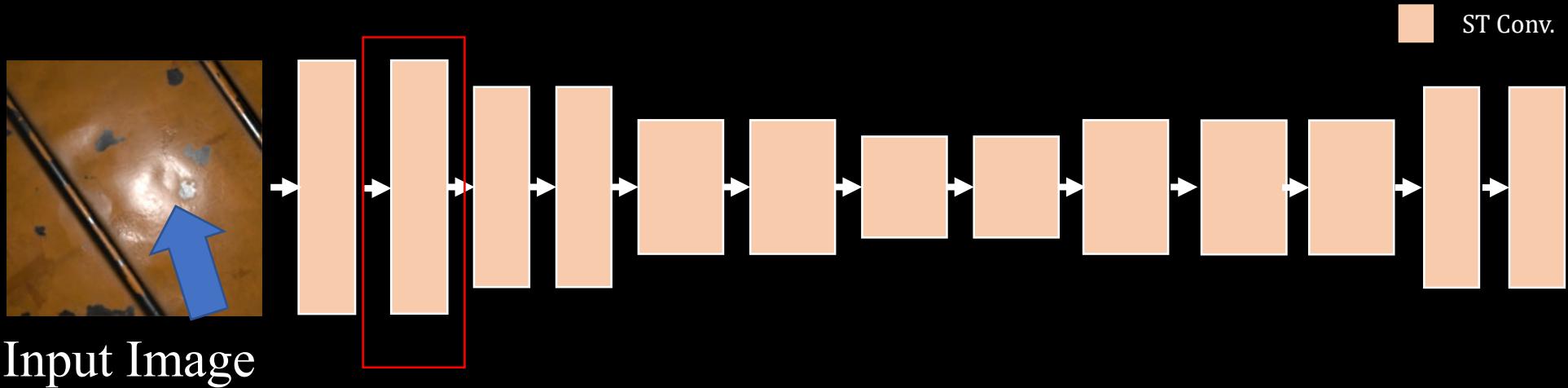


Key Challenge



Highlight pollution

Standard Unet Design



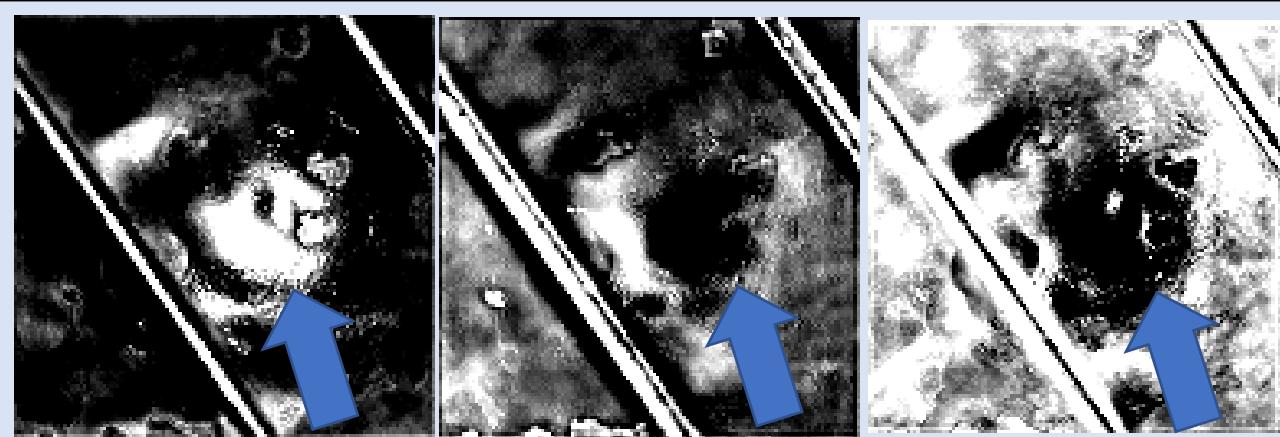
Standard features

Ambiguity

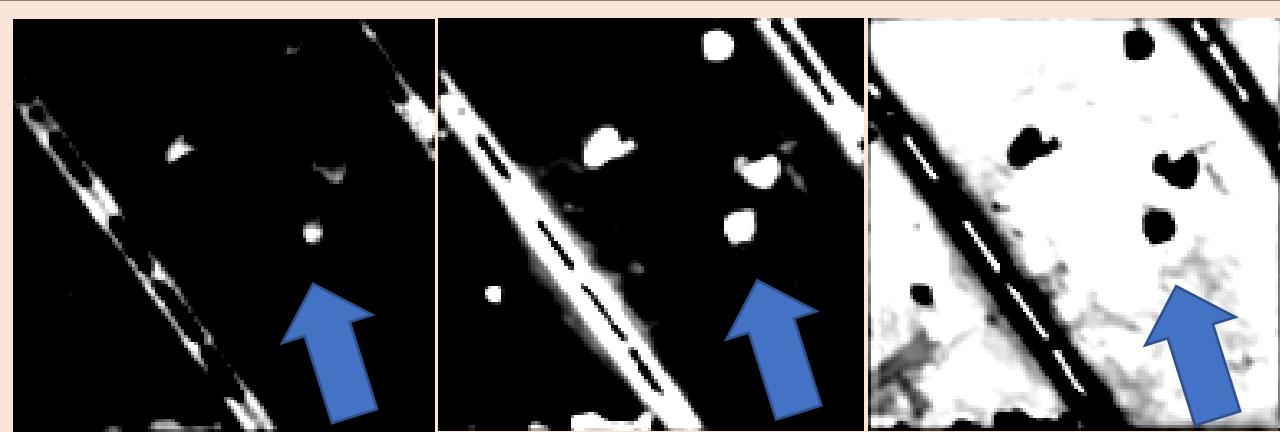
Highlight-Aware Convolution



Input Image

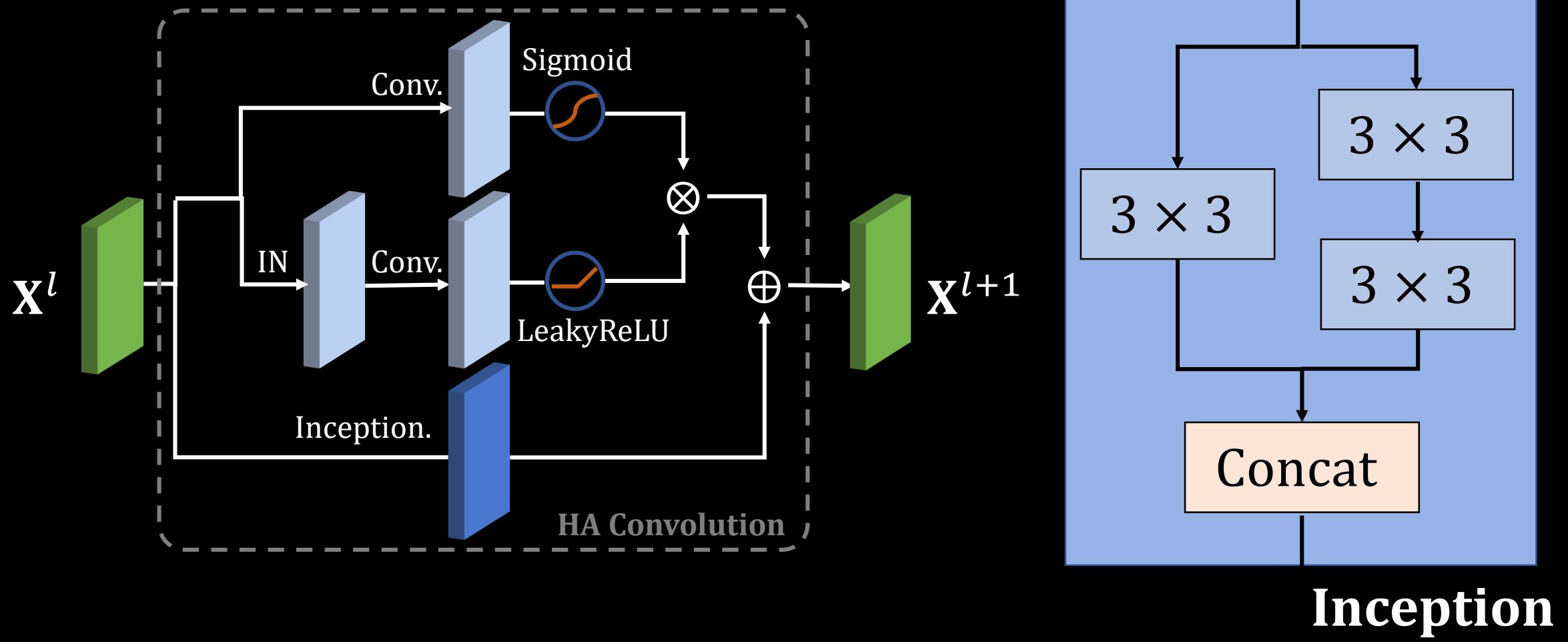


Recovered
diffuse map

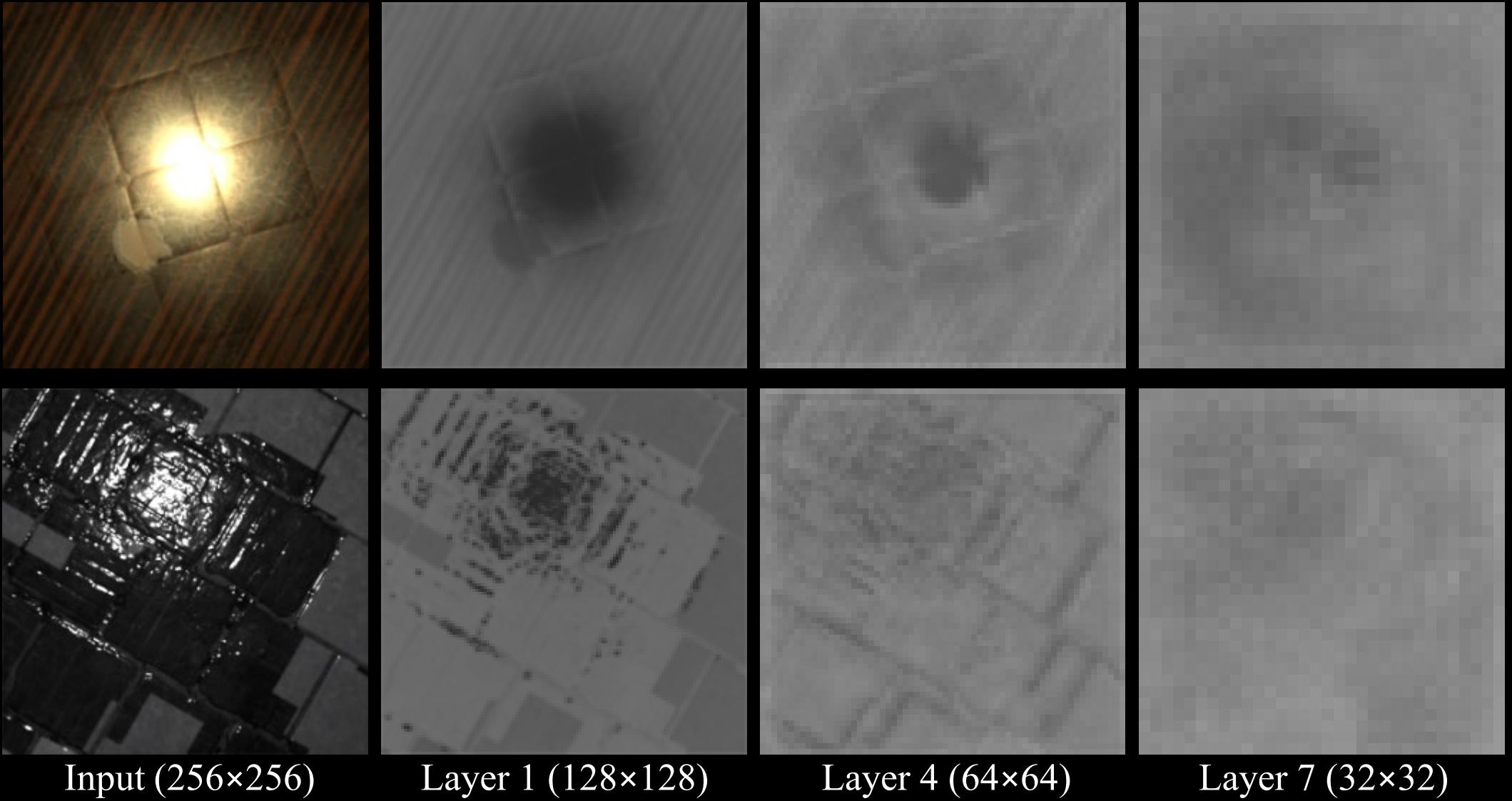


Highlight-Aware features

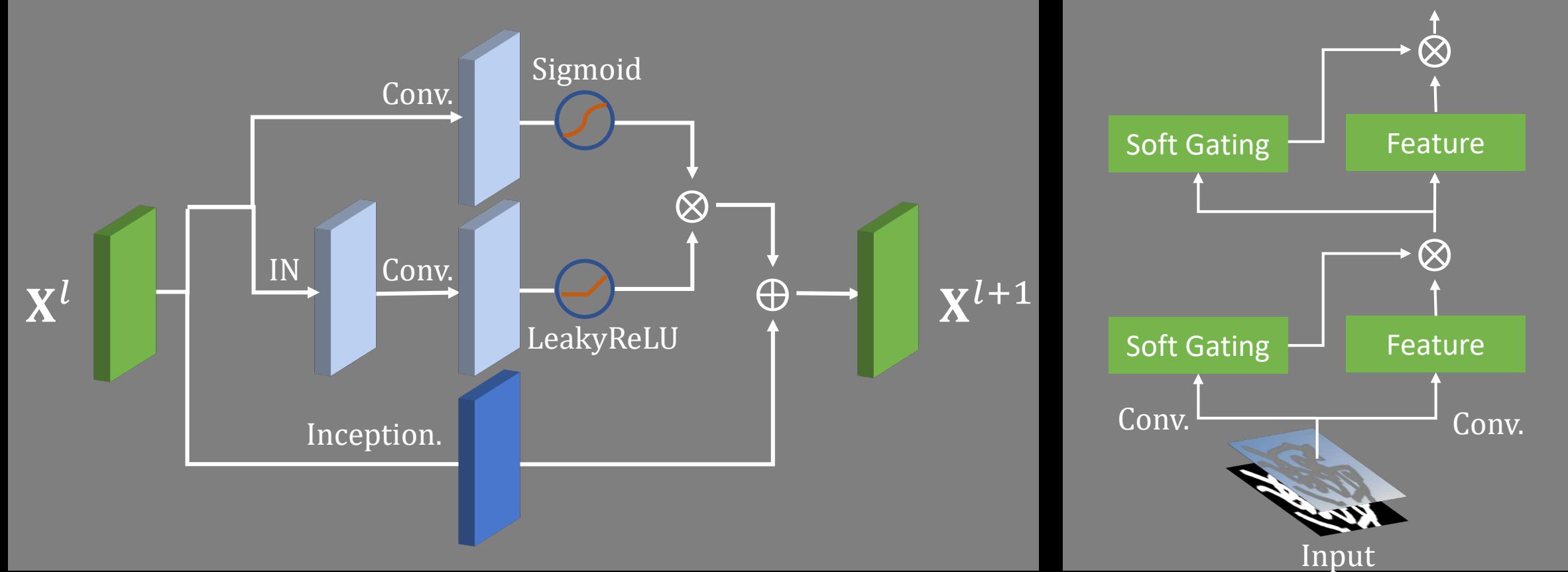
Highlight-Aware Convolution



Highlight-Aware Convolution



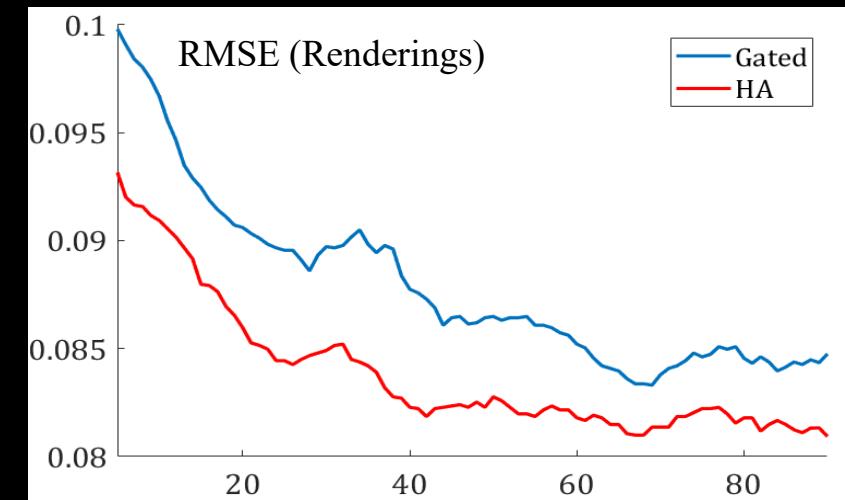
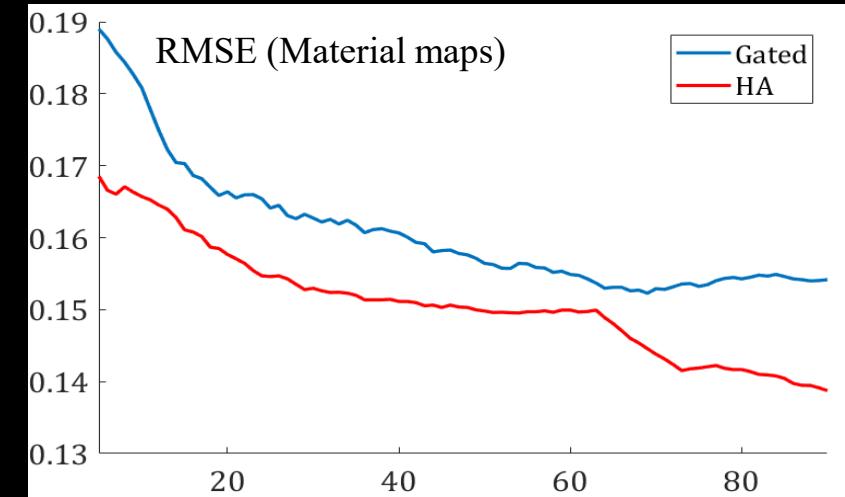
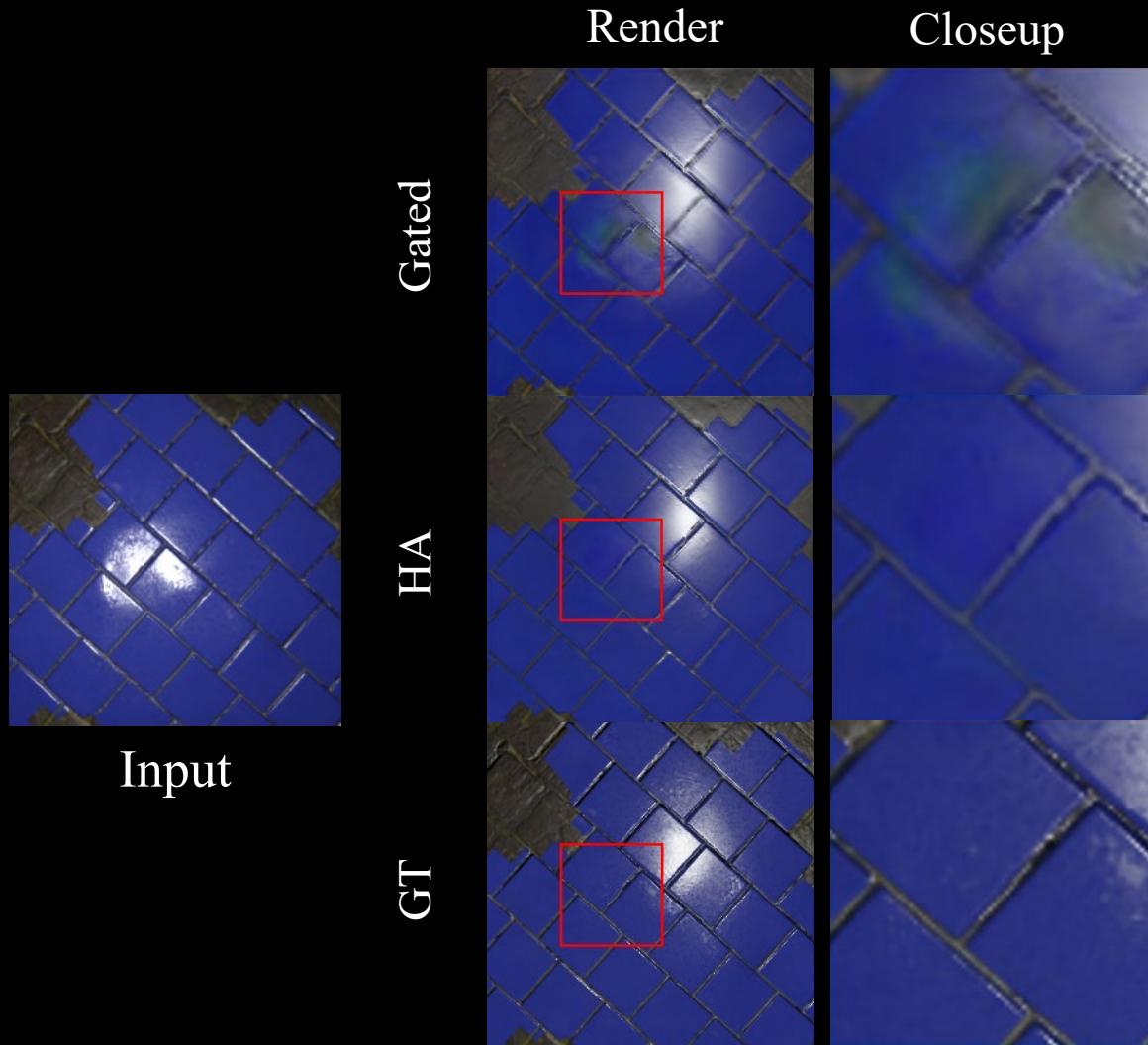
Highlight-Aware Convolution vs Gated Conv.



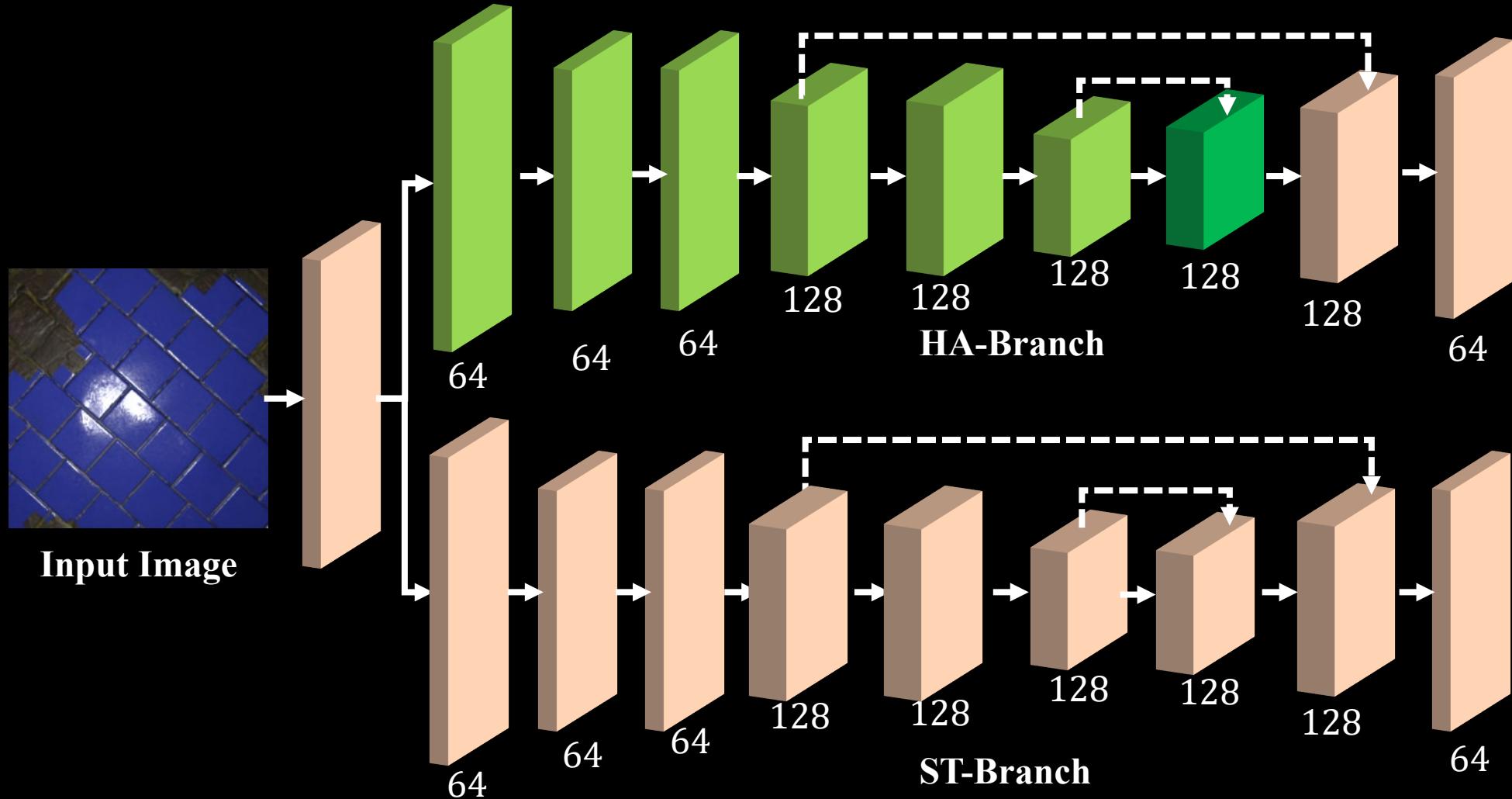
HA Convolution

Gated Convolution
[Yu et al. 2019]

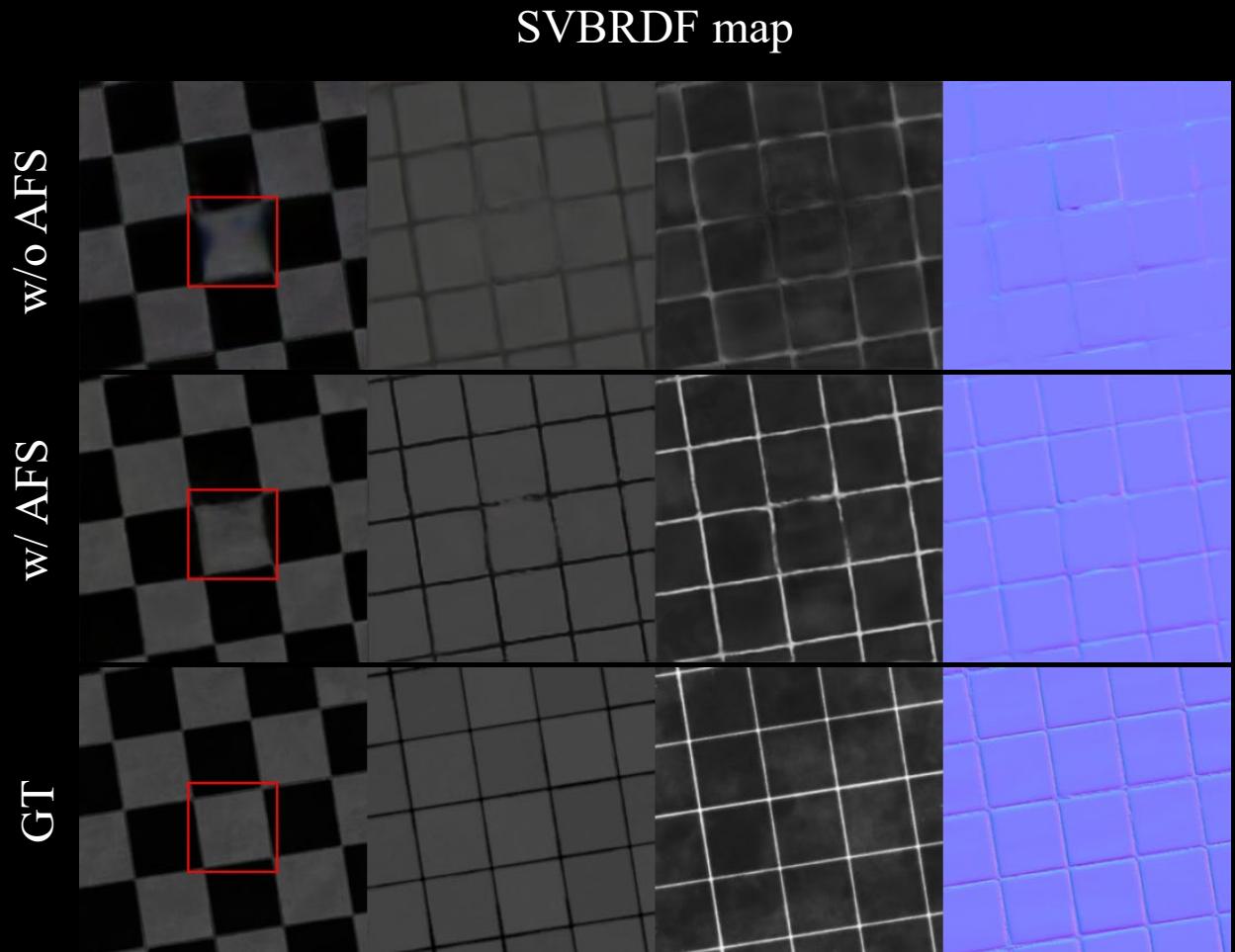
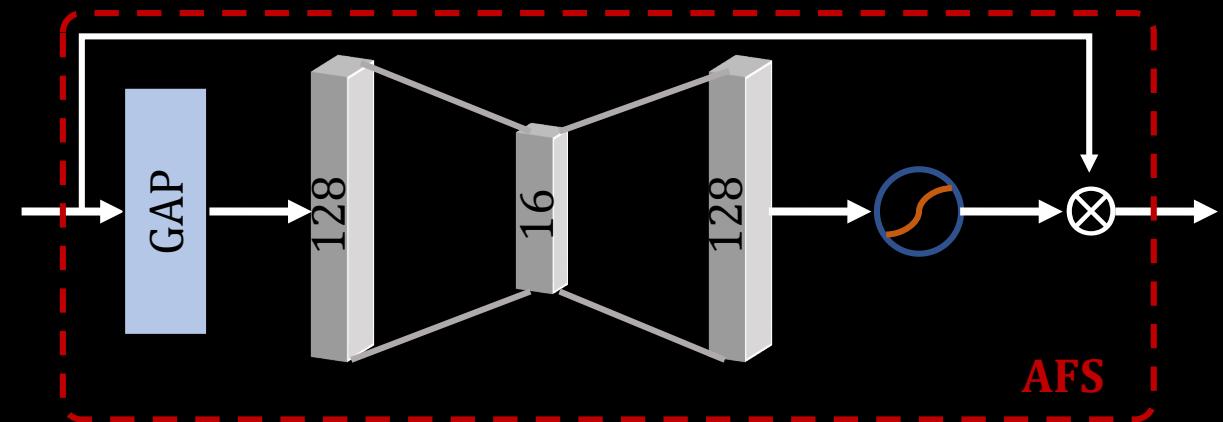
Highlight-Aware Convolution vs Gated Conv.



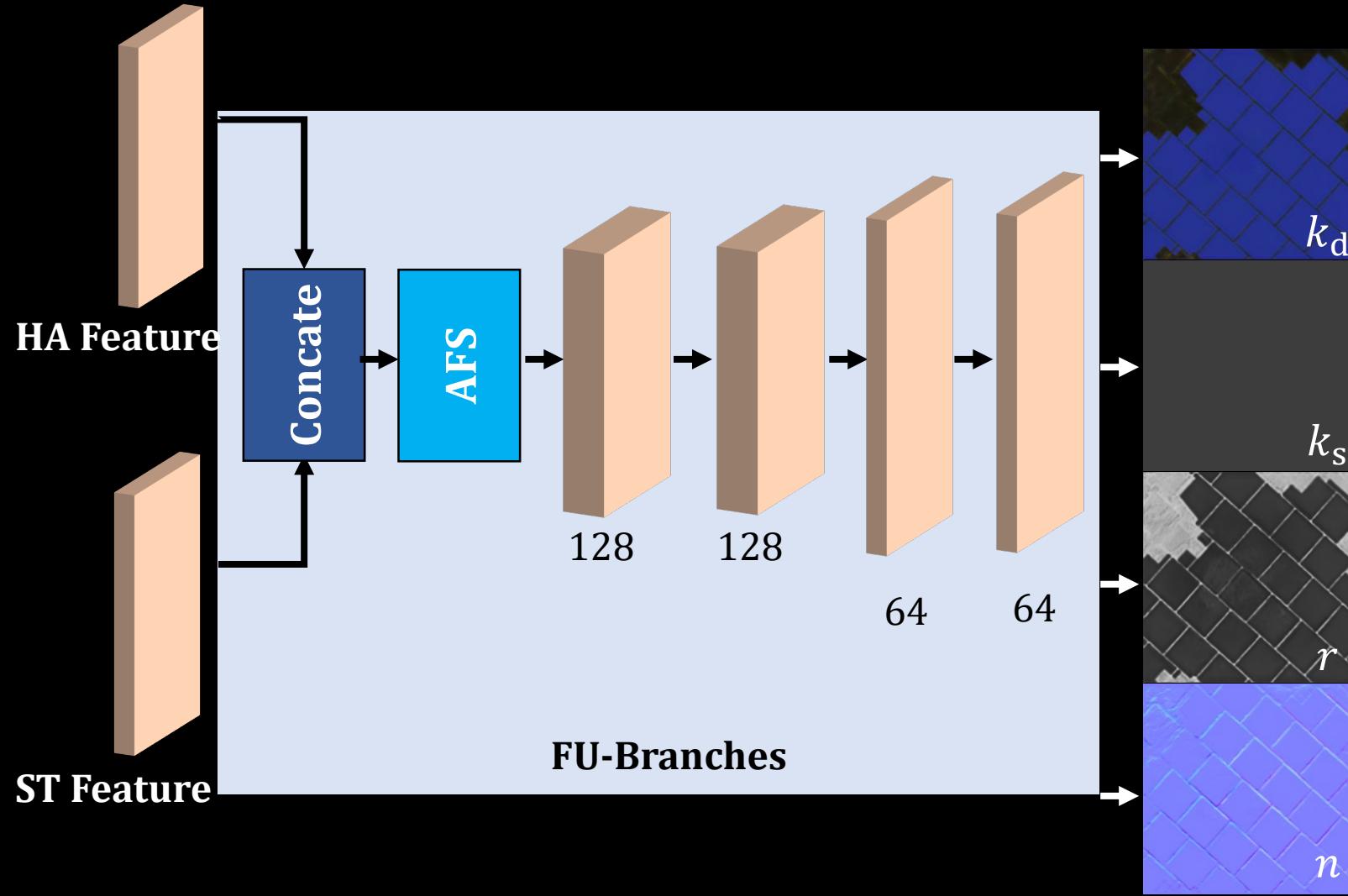
Feature Extraction with Two-Stream



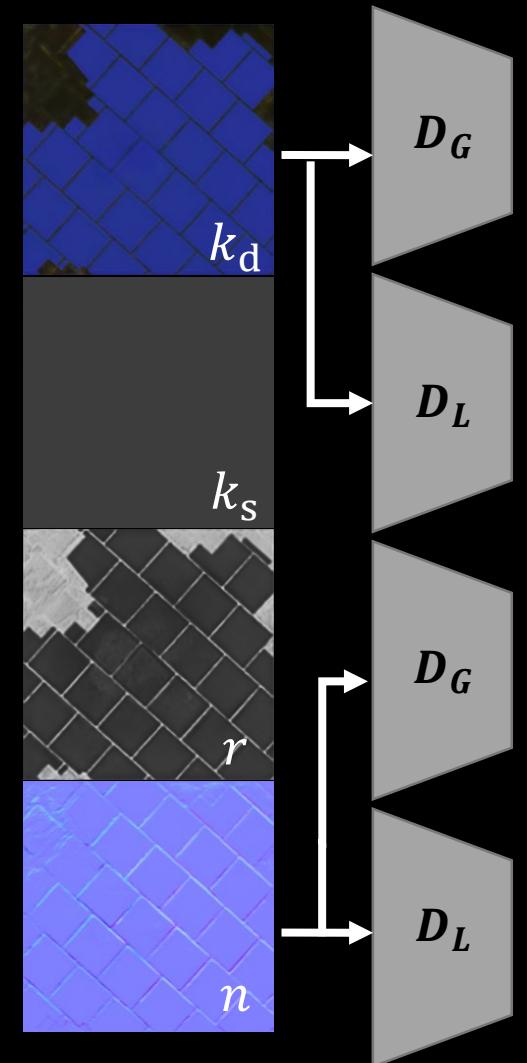
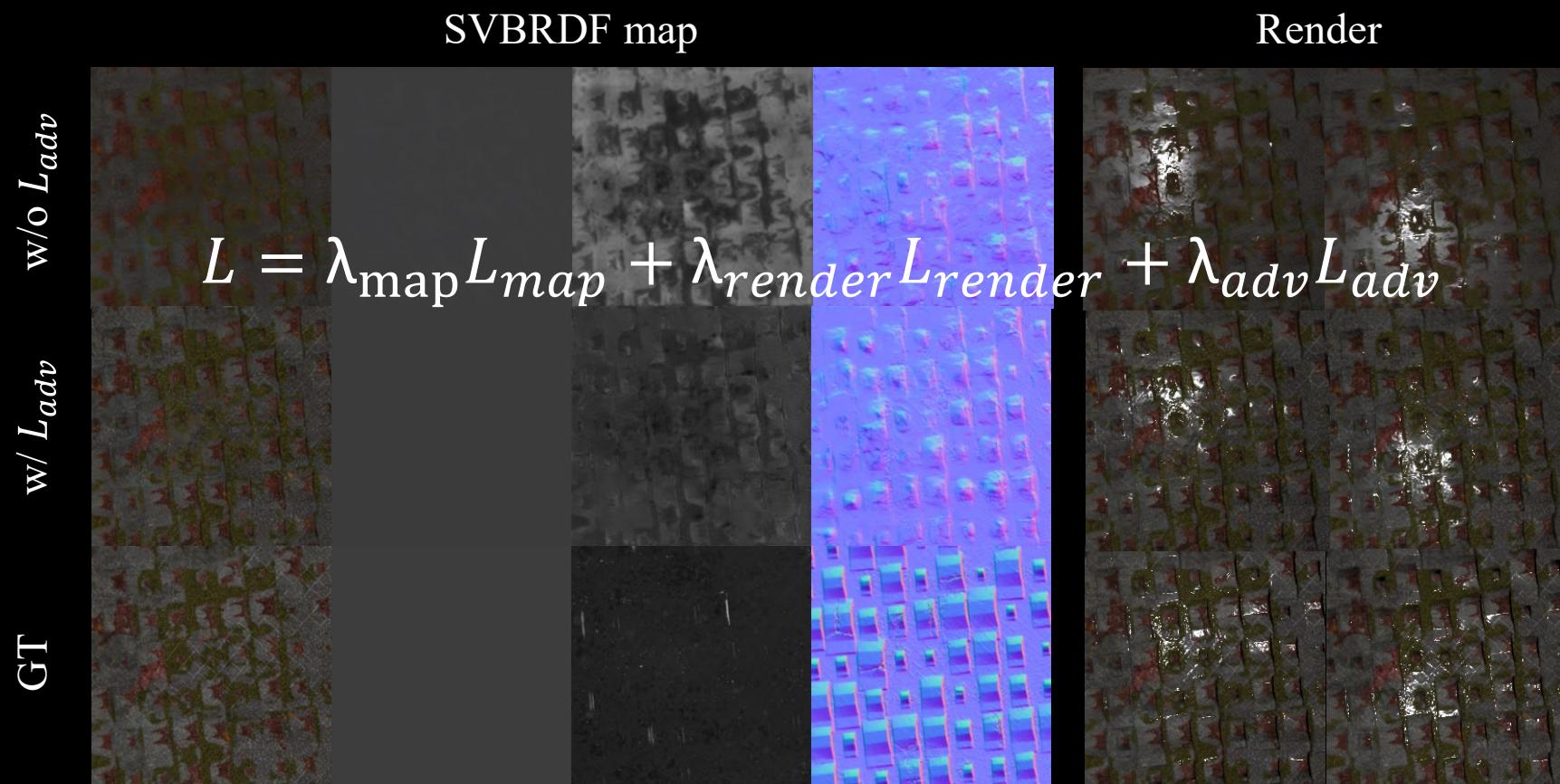
Attention-based Feature Selection Module



Feature Fusion and Selection with FU-Branch

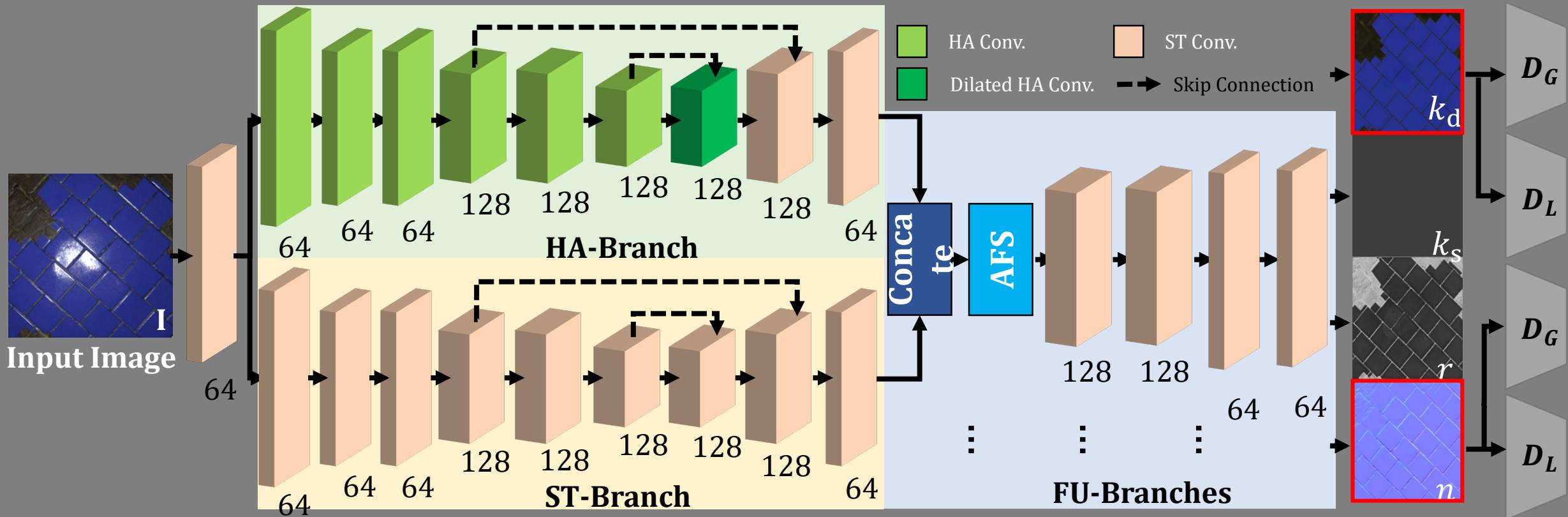


LOSS



Pipeline

Highlight-Aware Two-Stream Network

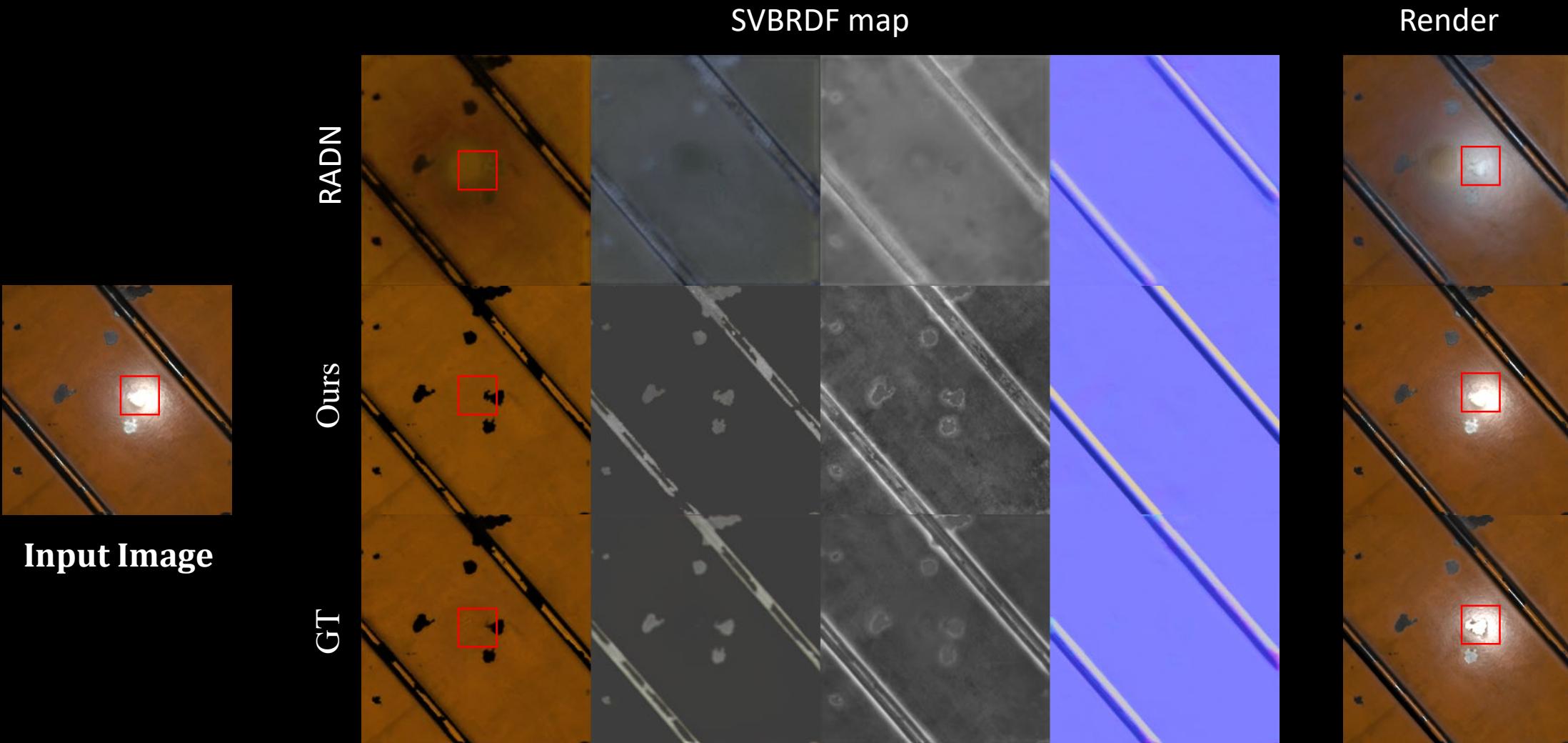


Results

We compare our method to

- Rendering-Aware Deep Network (**RADN**) [Deschaintre et al. 2018]: a **single image** SVBRDF acquisition method using classical U-Net architecture.
- Deep Inverse Rendering (**DIR**) [Gao et al. 2019]: a unified **deep inverse rendering** framework for estimating SVBRDF from an **arbitrary number of input** photographs.
- **MaterialGAN** [Guo et al. 2020]: a deep generative convolutional network based on StyleGAN2, trained to synthesize realistic SVBRDF parameter maps, needing **a number of images** as input.

Comparison on Synthetic Data



Comparison on Synthetic Data



Comparison on Real Data



Input Image

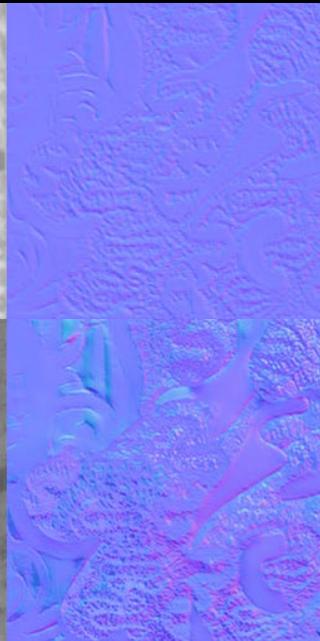
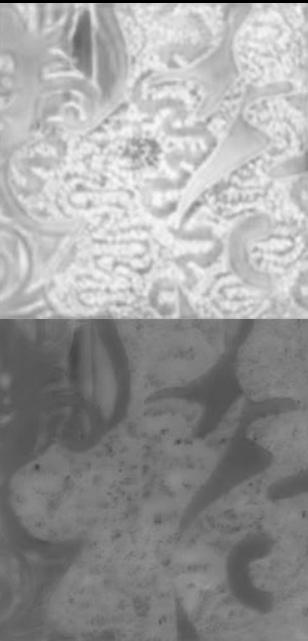
RADN



Ours



SVBRDF map



Render



Comparison on Real Data

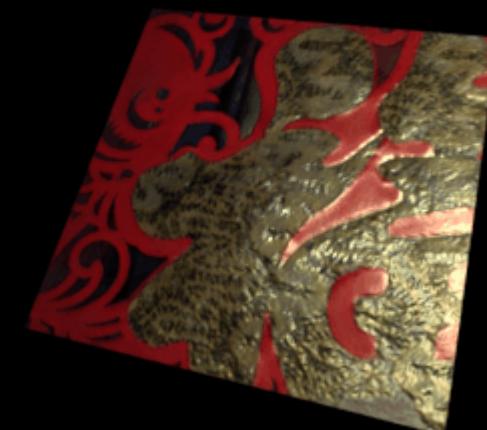
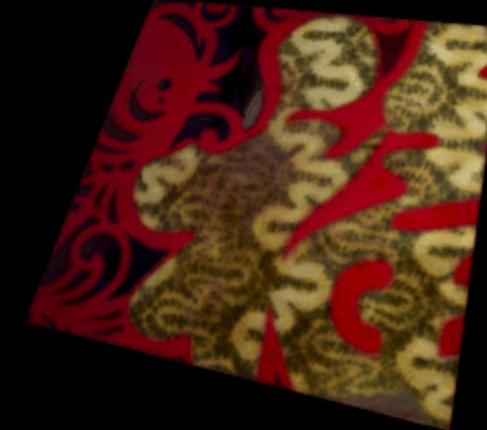


Input Image

RADN



Ours



Comparison on Real Data



Comparison on Real Data



Input Image



[Deschaintre et al.
2018]



[Gao et al. 2019]



[Guo et al. 2020]



Ours

High-resolution (1024×1024) Results



Input Image

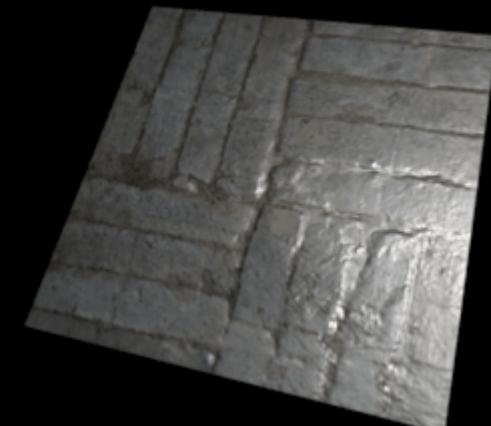
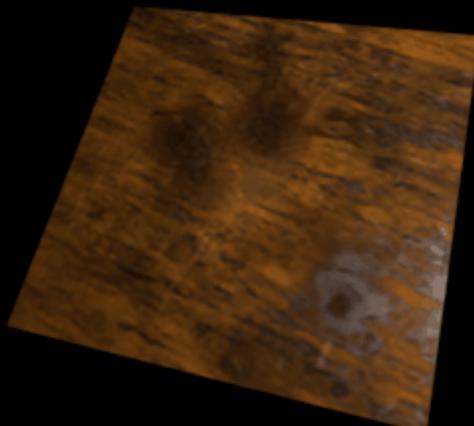


Ours render result



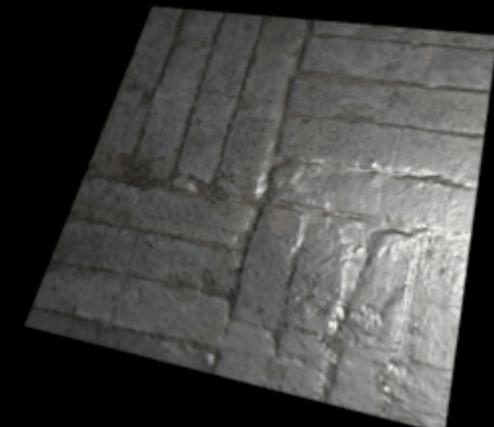
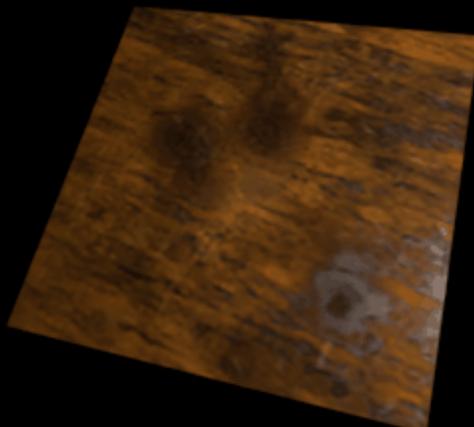
Conclusion

- A well-designed HA convolution layer for hallucinating missing contents in overexposed image regions.
- A well-designed two-stream network to fully exploit useful features from any casually captured image, facilitating disentangled learning of material properties.



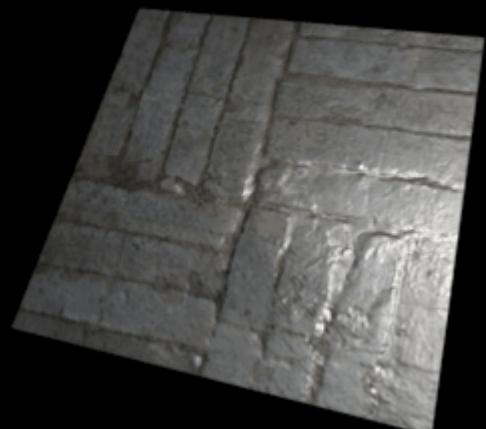
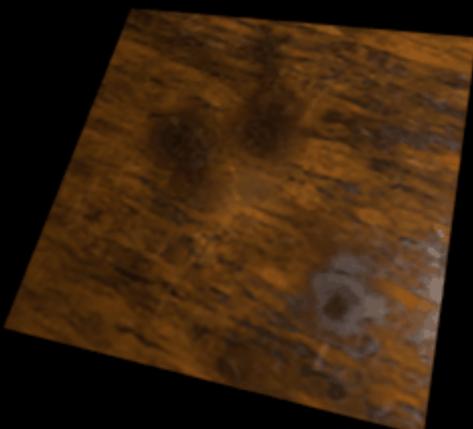
Future Work

- Use a more complex network which could infer the geometry with the help of large-scale datasets containing both geometry and material.
- Extend our method to support more than one input image.



Acknowledgements

- Anonymous reviewers
- Deschaintre et al. [2018], Gao et al. [2019] and Guo et al. [2020] for their help
- National Natural Science Foundation of China (62032011 and 61972194)



Thanks Q&A

