

SIGGRAPH 2021

**A MOMENTUM-CONSERVING IMPLICIT
MATERIAL POINT METHOD FOR SURFACE
TENSION WITH CONTACT ANGLES AND
SPATIAL GRADIENTS**

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Elias Gueidon¹, David A. B. Hyde¹, Joseph Teran²

¹ UCLA ² UC Davis

- **Backgrounds**
- Material Point Method (MPM)
- Conservative Resampling
- Spatially Varying Surface Tension
- Thermomechanical Coupling
- Summary



Water droplet on a hydrophobic surface

[Source: <https://freerangestock.com/photos/61063/milk-crown.html>]



Milk crown

[Source: <https://news.mit.edu/2013/hydrophobic-and-hydrophilic-explained-0716>]

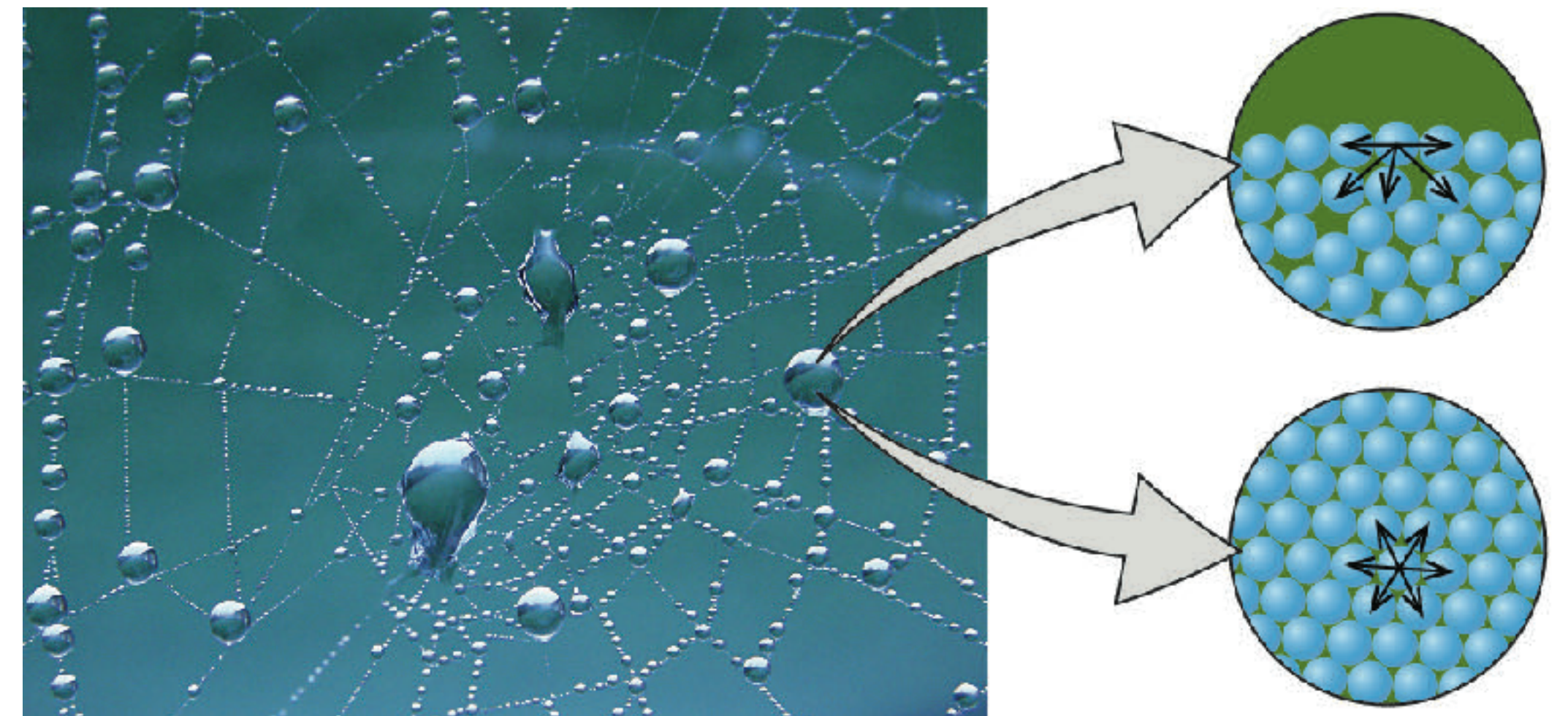


Tears of wine (Marangoni effect)

[Source: <https://www.comsol.com/blogs/tears-of-wine-and-the-marangoni-effect/>]

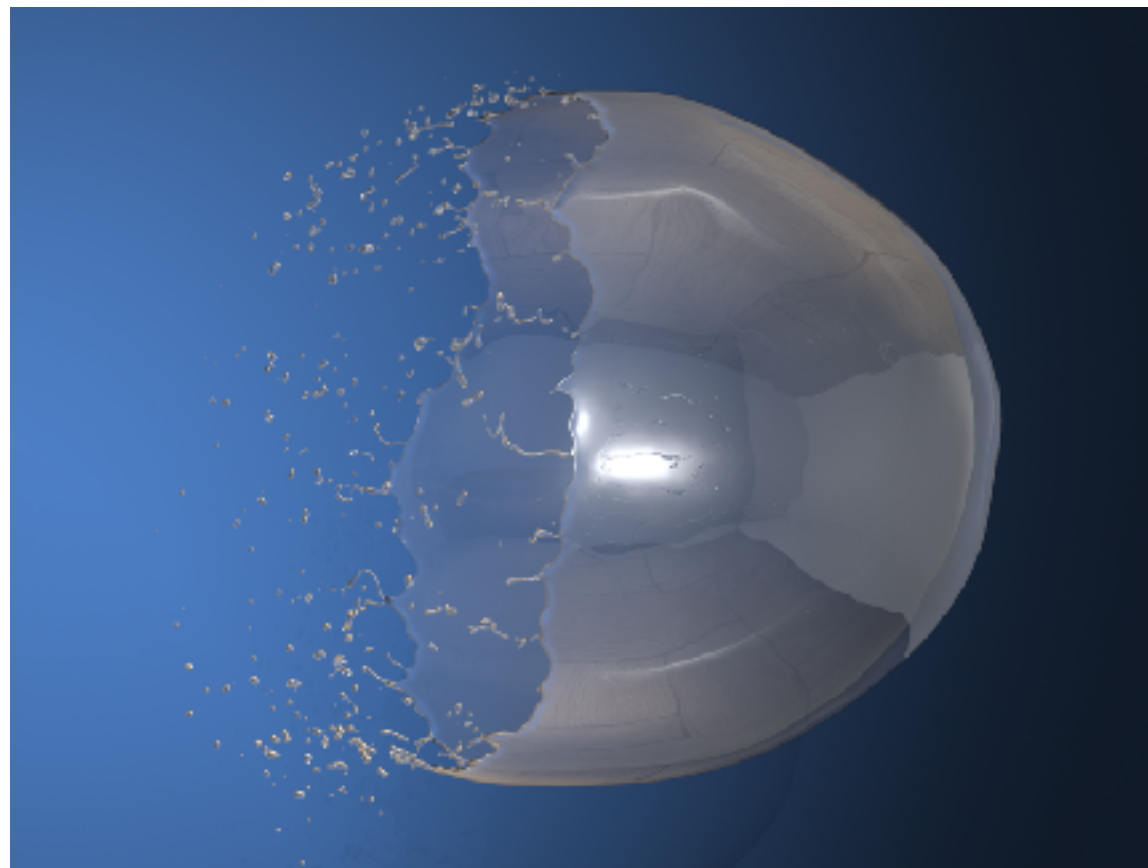
Physics of the surface tension

- Surface tension is caused by the cohesive force between water molecules.
- The liquid surface behaves like elastic membrane.
- The interface is a jump in the fluid density.

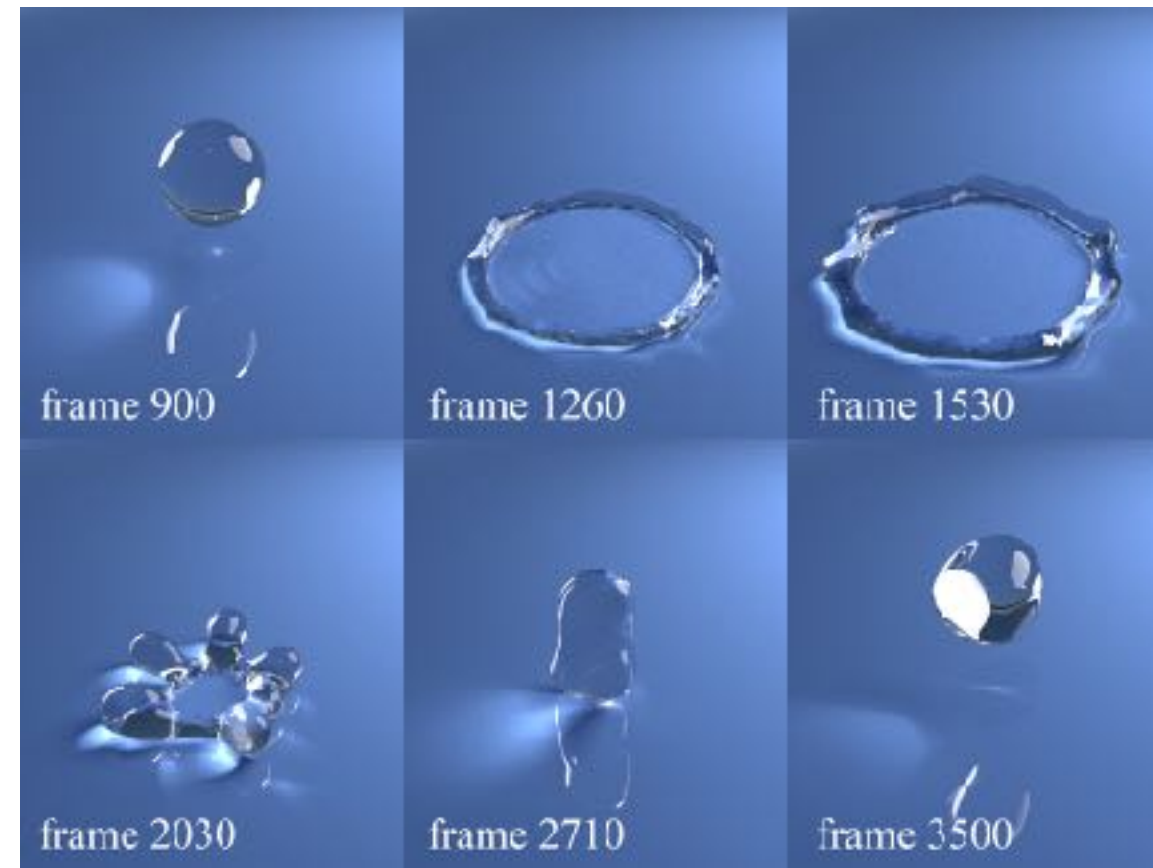


[Source: <https://cnx.org/contents/WgINhlpX@3/Properties-of-Liquids>]

→ SURFACE TENSION SIMULATIONS



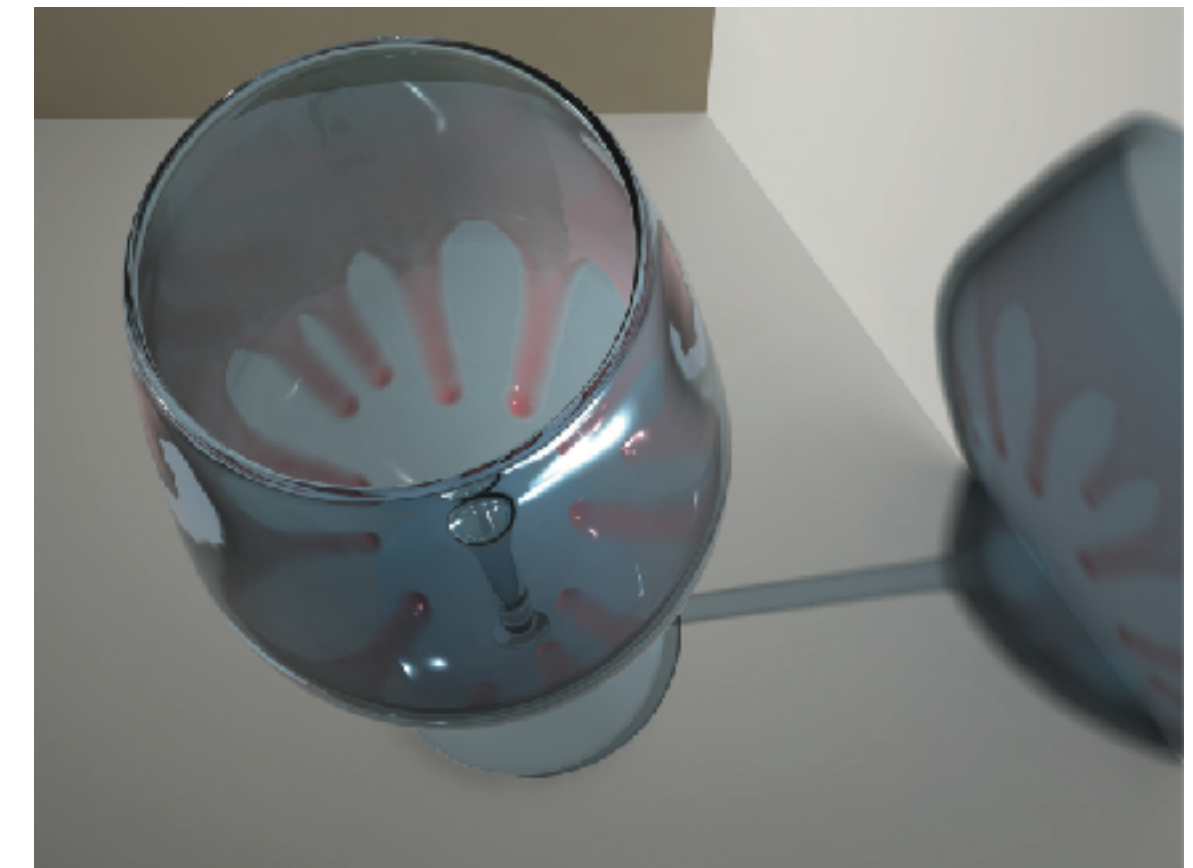
[Zhu et al. 2014]



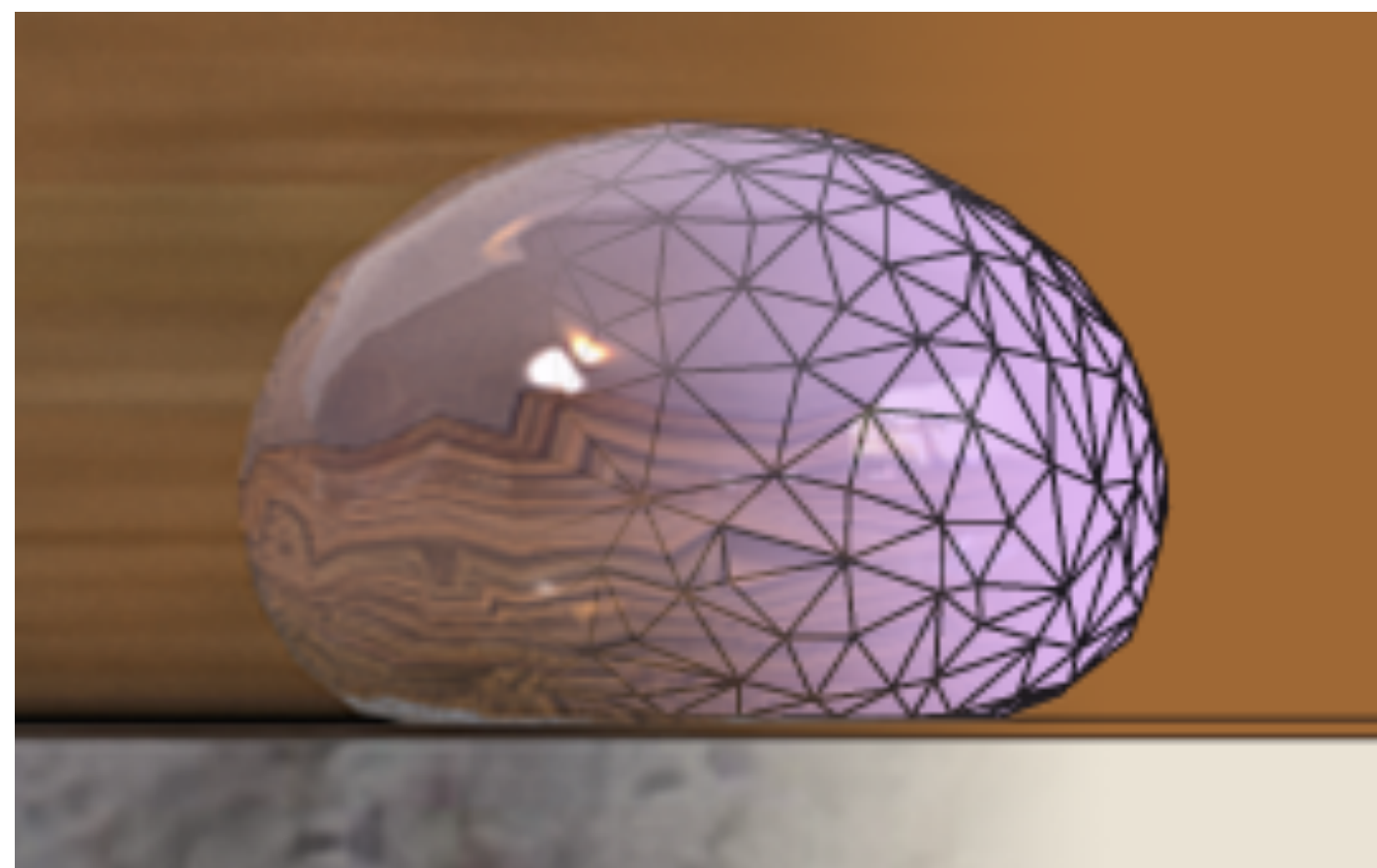
[Da et al. 2016]



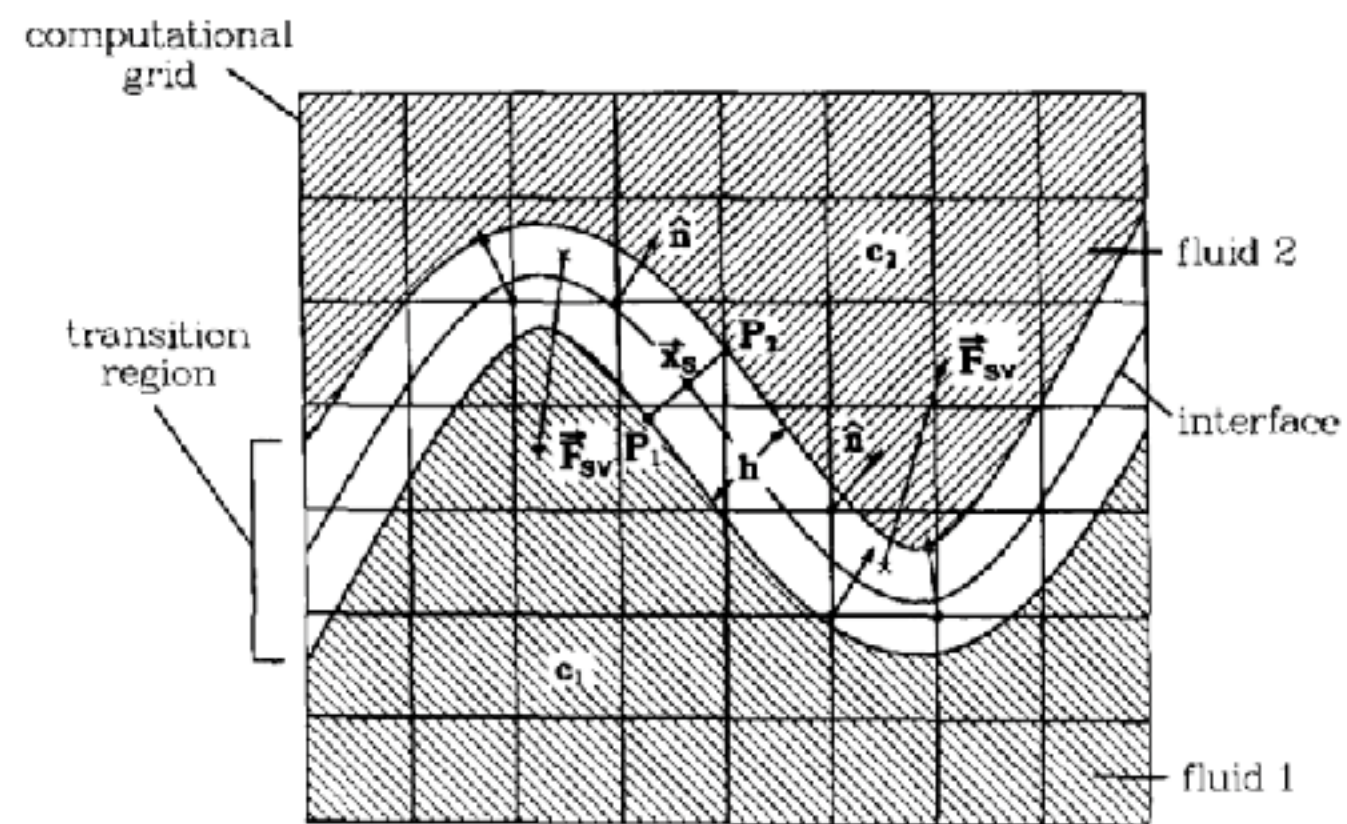
[Clausen et al. 2013]



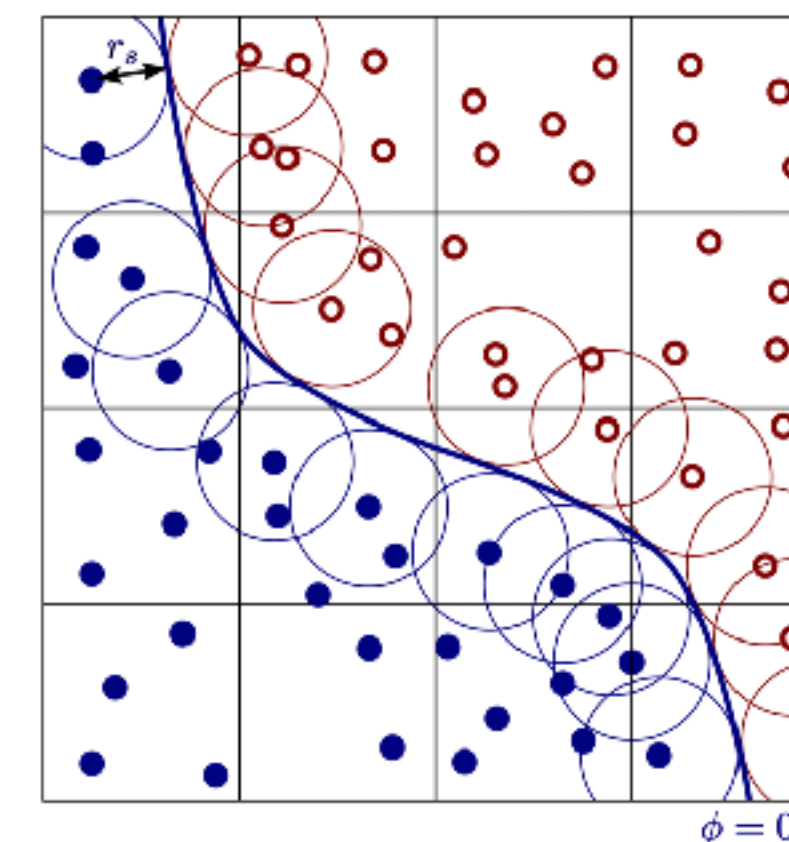
[Azencot et al. 2015]



Surface tracking with explicit mesh
[Clausen et al. 2013]



Continuum Surface Force with color function
[Brackbill et al. 1992]



Particle-derived level sets
[Boyd and Bridson 2012]

Continuum Surface Force

- Interfacial traction [Brackbill et al. 1992]

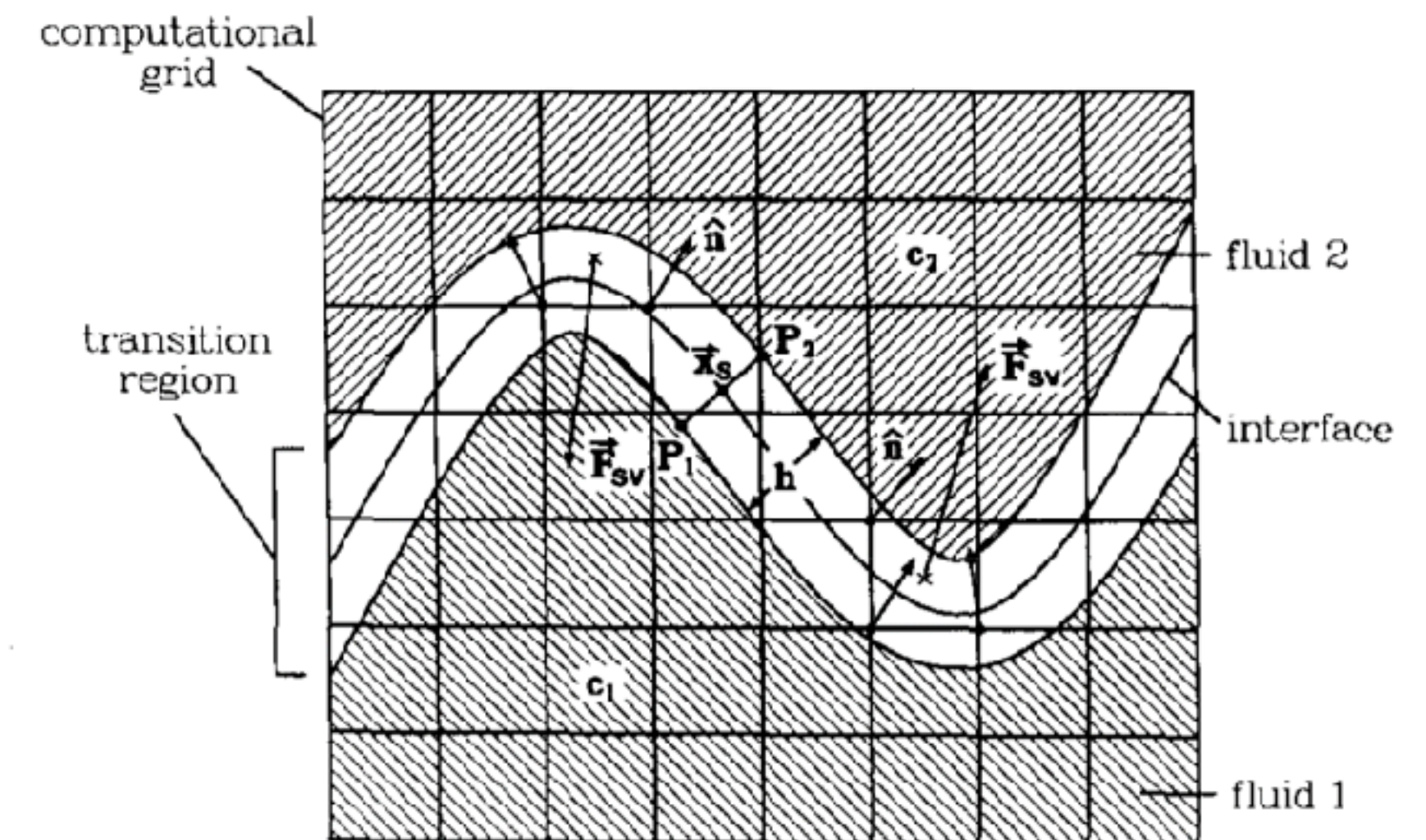
Surface tension coefficient

$$\mathbf{t} = k^\sigma \kappa \mathbf{n} + \nabla^s k^\sigma.$$

Curvature

Surface normal

- Curvature is calculated from the unit normal based on the color function.
- Challenging for implicit time marching schemes.



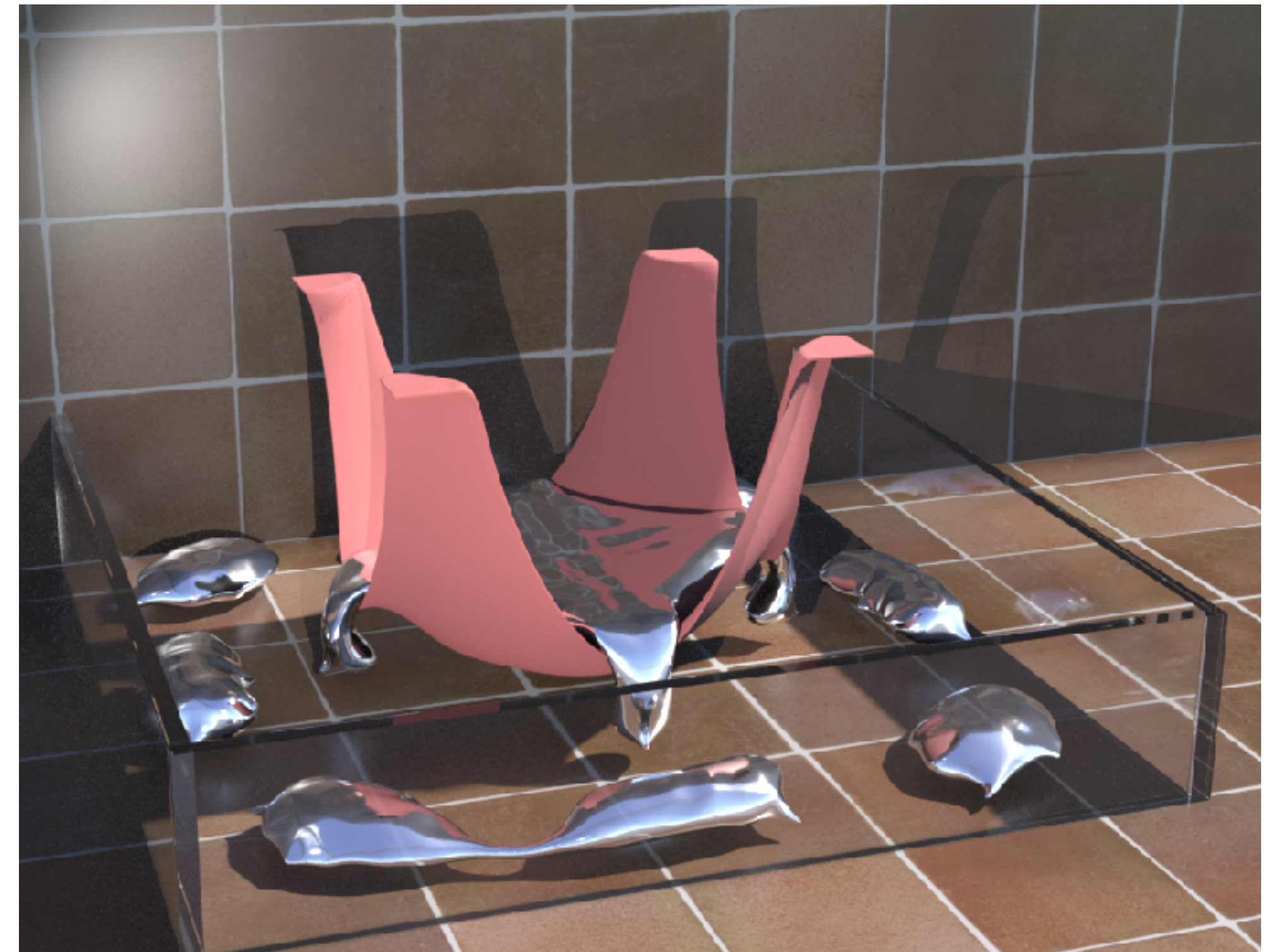
Continuum Surface Force
[Brackbill et al. 1992]

Energy-based Approach

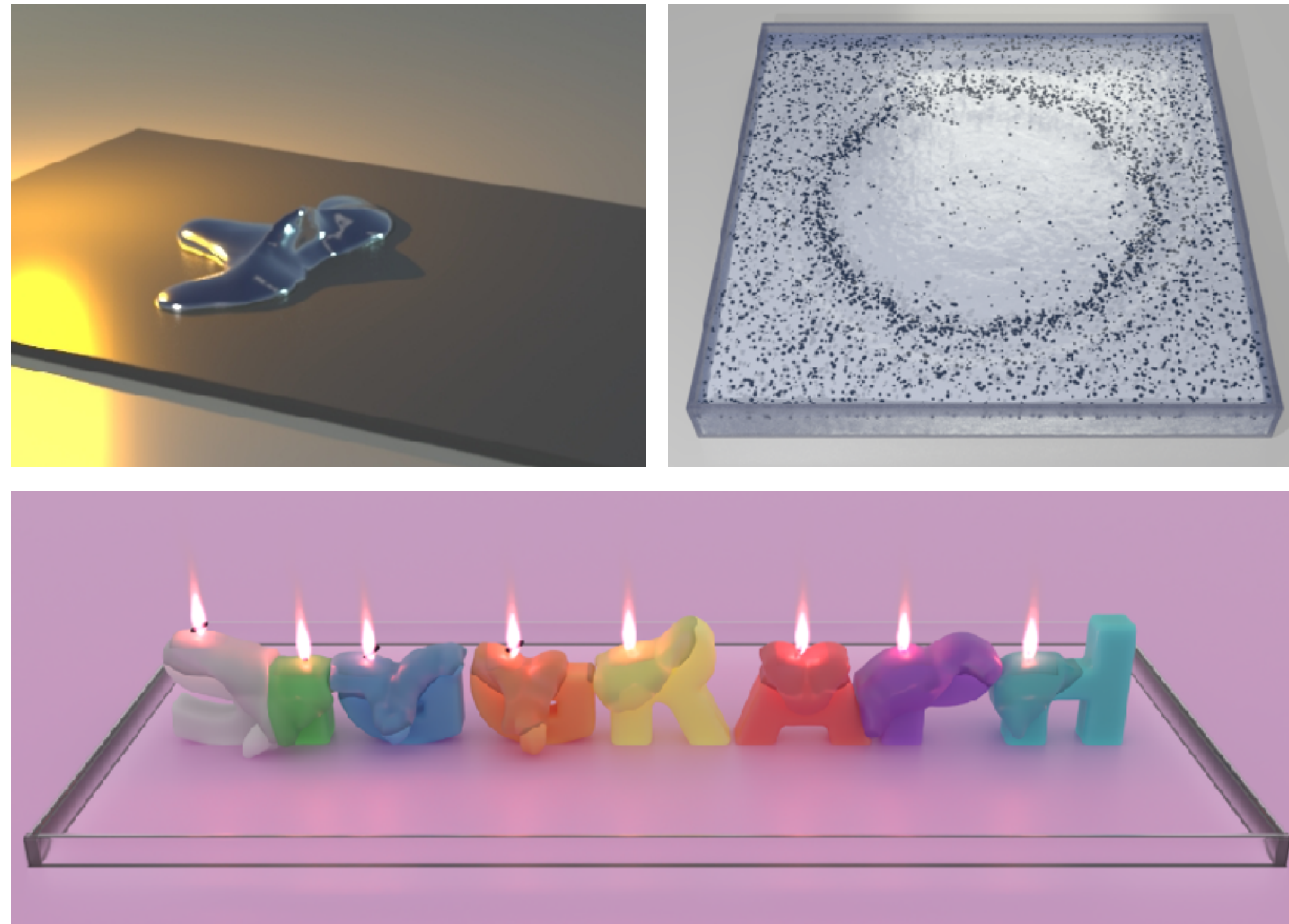
- The surface tension is modeled as a potential energy associated with the surface area [Hyde et al. 2020]

$$\Psi^\sigma(\mathbf{x}) = k^\sigma \int_{\partial\Omega^t} ds(\mathbf{x}).$$

- The surface tension force is defined as the gradient of surface energy.
- Benefits:
 - No need for mean curvature estimation.
 - Allows the implicit time stepping scheme with large Δt .



[Hyde et al. 2020]



CONTRIBUTIONS

- A novel implicit MPM discretization of spatially varying surface tension forces.
- A momentum-conserving particle resampling technique for particles near the liquid interface.
- An implicit MPM discretization of the convection/diffusion evolution of temperature/concentration coupled to the surface tension coefficient including a novel particle-based Robin boundary condition.

- Backgrounds
- **Material Point Method (MPM)**
- Conservative Resampling
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Conservation of mass

$$\frac{D\rho}{Dt} = -\rho \nabla \cdot \mathbf{v}$$

Conservation of momentum

$$\rho \frac{D\mathbf{v}}{Dt} = \nabla \cdot \boldsymbol{\sigma} + \rho \mathbf{g}$$

$\boldsymbol{\sigma}$ is the Cauchy stress. For fluid, $\boldsymbol{\sigma} = -p\mathbf{I} + \mu \left(\frac{\partial \mathbf{v}}{\partial \mathbf{x}} + \frac{\partial \mathbf{v}^T}{\partial \mathbf{x}} \right)$, $p = -\frac{\partial \psi^p}{\partial J}$.

Conservation of energy

$$\rho c_p \frac{DT}{Dt} = K \nabla^2 T + H$$
$$K \nabla T \cdot \mathbf{n} = -h(T - \bar{T}) + b$$

Conservation of mass

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↑ ↑
Convection Heat flux

- (Compressible) fluid potential energy density:

$$\psi^p(J) = \frac{\lambda^l}{2}(J - 1)^2, \quad p = -\frac{\partial\psi^p}{\partial J}.$$

- Fixed-corotated solid [Stomakhin et al. 2012]:

$$\psi^h(\mathbf{F}) = \mu^h \sum_{\alpha=0}^{d-1} (\sigma_\alpha - 1)^2 + \frac{\lambda^h}{2}(J - 1)^2.$$

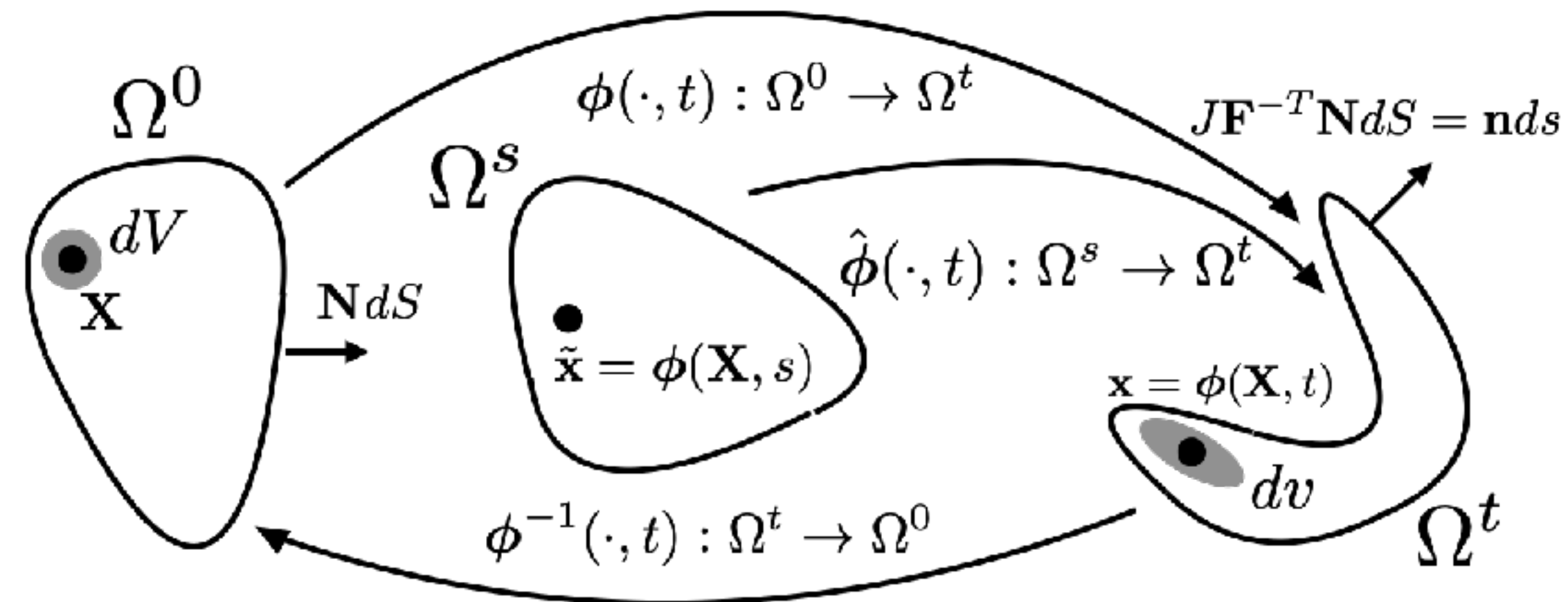
- Our surface tension potential energy:

$$\Psi^\sigma(\mathbf{x}) = \int_{\partial\Omega^t} k^\sigma(\mathbf{x}, t) ds(\mathbf{x}).$$

- $k^\sigma(\mathbf{x}, t)$ can vary in space as a function of temperature or concentration.
- No special treatment is required for the ∇^s term in $\mathbf{t} = k^\sigma \kappa \mathbf{n} + \nabla^s k^\sigma$.

- From $\partial\Omega^s$ to $\partial\Omega^t$, using Nanson's formula, the infinitesimal area is $ds(\mathbf{x}) = |\hat{J}\hat{F}^{-T}\tilde{\mathbf{n}}| ds(\tilde{\mathbf{x}})$.
- Surface tension potential energy becomes

$$\Psi^\sigma(\mathbf{x}) = \int_{\partial\Omega^t} k^\sigma(\mathbf{x}, t) ds(\mathbf{x}) = \int_{\partial\Omega^t} k^\sigma(\hat{\phi}(\tilde{x}, s, t), t) |\hat{J}\hat{F}^{-T}\tilde{\mathbf{n}}| ds(\tilde{\mathbf{x}}).$$



[Hyde et al. 2020]



MPM

- We discretized the governing equations using MPM with backward Euler scheme.
- Why MPM?
 - Based on continuum mechanics.
 - Good for fluid-solid interactions.
 - Easily handle large topological change.

UPDATE SCHEMES

- Momentum update

$$m_i^n \frac{\hat{\mathbf{v}}_i^{n+1} - \mathbf{v}_i^n}{\Delta t} = \mathbf{f}_i(\mathbf{x} + \Delta t \hat{\mathbf{q}}) + m_i^n \mathbf{g}.$$

- Temperature update

$$\begin{aligned} c_p m_i \frac{\hat{T}_i^{n+1} - T_i^n}{\Delta t} = & - \sum_p K \frac{\partial N_i}{\partial x_\alpha}(\mathbf{x}_p^n) \hat{T}_j^{n+1} \frac{\partial N_j}{\partial x_\alpha}(\mathbf{x}_p^n) V_p^n \\ & - \sum_r h N_i(\mathbf{s}_r^n) \hat{T}_j^{n+1} N_j(\mathbf{s}_r^n) |d\mathbf{A}_r^n| \\ & + \sum_r N_i(\mathbf{s}_r^n) [h \bar{T}(\mathbf{s}_r^n) + b(\mathbf{s}_r^n)] |d\mathbf{A}_r^n| \\ & + \sum_p N_i(\mathbf{x}_p^n) H(\mathbf{x}_p^n) V_p^n \end{aligned}$$

ALGORITHM 1: Time integration loop for MPM simulations using APIC transfers.

begin Particle-to-Grid Transfers

Transfer time t^n mass to grid by evaluating Equation 6,

$$m_i^n = \sum_p m_p N_i(\mathbf{x}_p^n);$$

Transfer time t^n momentum to grid by evaluating Equation 6,

$$m_i^n \mathbf{v}_i^n = \sum_p m_p N_i(\mathbf{x}_p^n) \left(\mathbf{v}_p^n + \mathbf{A}_p^n (\mathbf{x}_i - \mathbf{x}_p^n) \right);$$

end

begin Momentum Update

Update momentum on the grid from t^n to t^{n+1} by solving

Equation 8, $m_i^n \frac{\hat{\mathbf{v}}_i^{n+1} - \mathbf{v}_i^n}{\Delta t} = \mathbf{f}_i(\mathbf{x} + \Delta t \hat{\mathbf{q}}) + m_i^n \mathbf{g}$, either explicitly (set $\hat{\mathbf{q}} = 0$) or implicitly (set $\hat{\mathbf{q}} = \hat{\mathbf{v}}^{n+1}$);

end

begin Grid-to-Particle Transfers

Evaluate time t^{n+1} particle velocity via Equation 10,

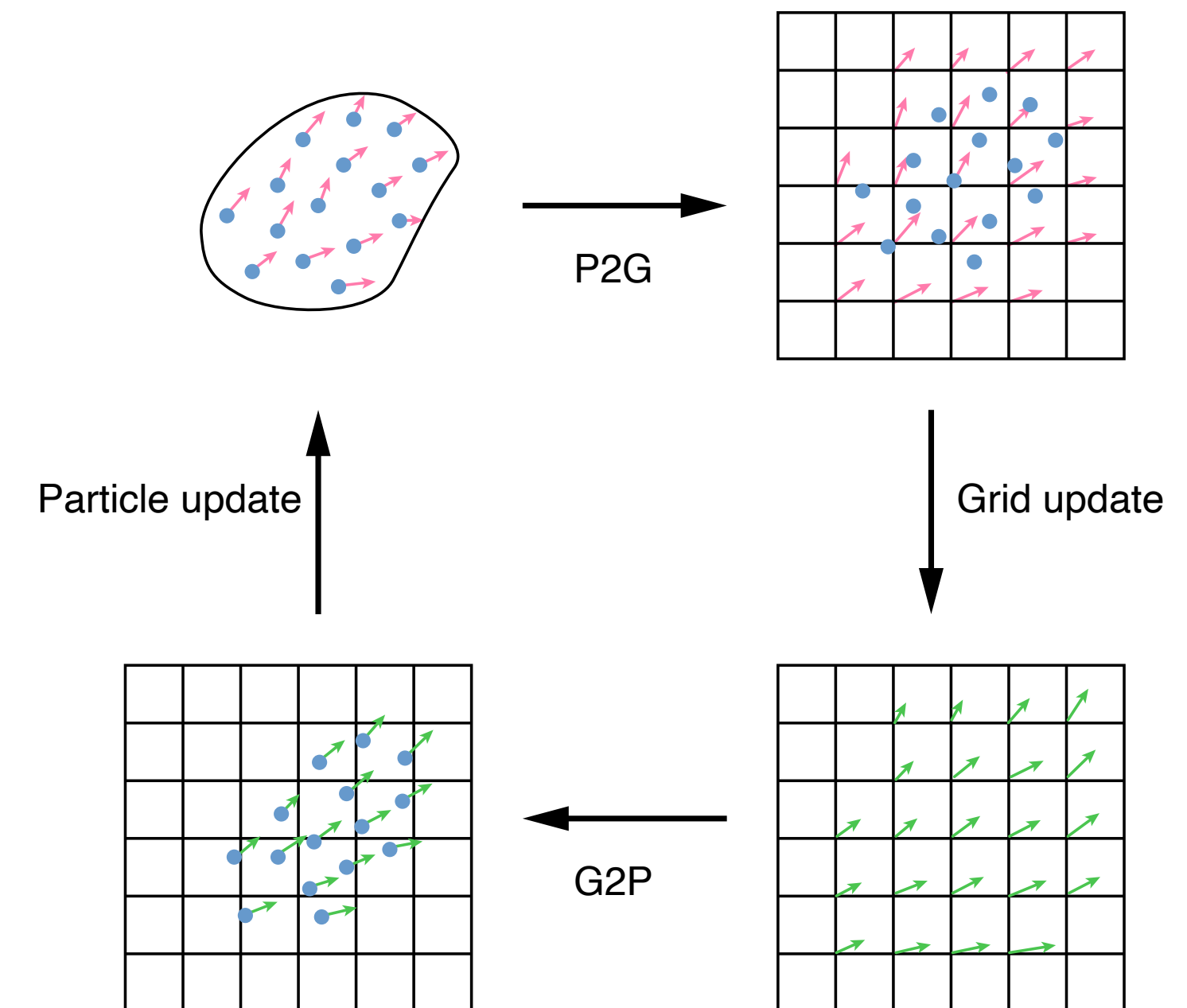
$$\mathbf{v}_p^{n+1} = \sum_i N_i(\mathbf{x}_p^{n+1}) \hat{\mathbf{v}}_i^{n+1};$$

Evaluate time t^{n+1} particle affine information via Equation 10,

$$\mathbf{A}_p^{n+1} = \frac{4}{\Delta x^2} \sum_i N_i(\mathbf{x}_p^{n+1}) \hat{\mathbf{v}}_i^{n+1} (\mathbf{x}_i - \mathbf{x}_p^{n+1})^T;$$

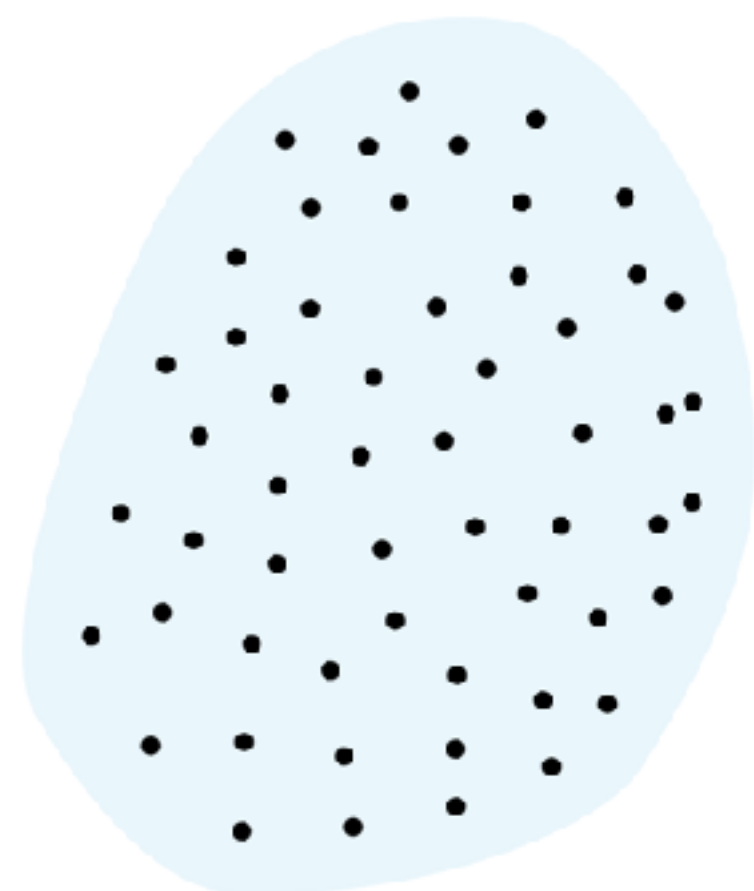
Update particle positions to t^{n+1} via $\mathbf{x}_p^{n+1} = \mathbf{x}_p^n + \Delta t \mathbf{v}_p^{n+1}$;

end



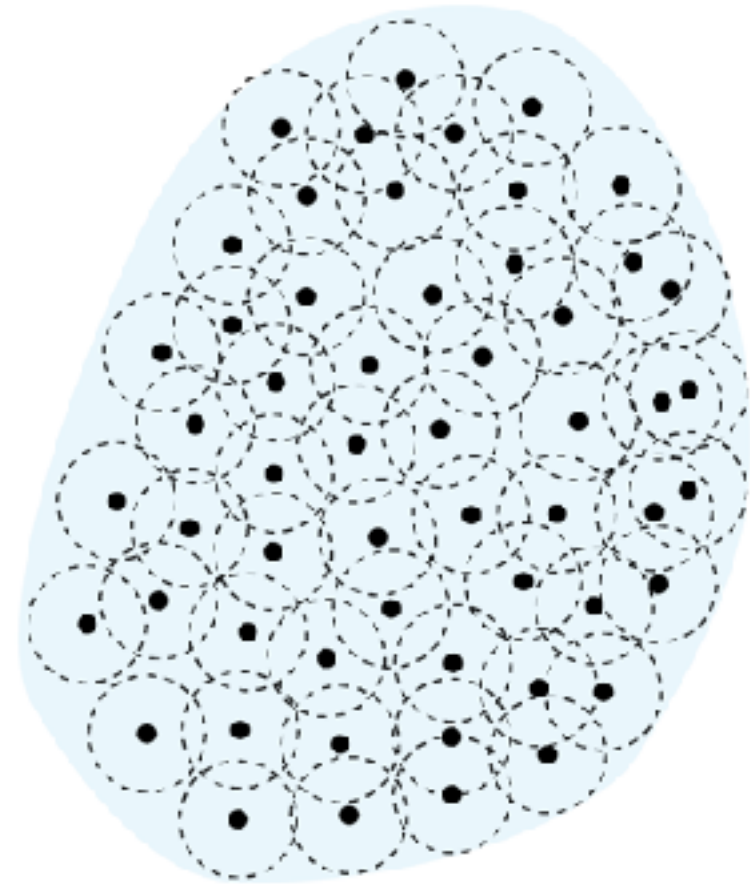
[Hyde et al. 2020]

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- Material Point Method (MPM)
- **Conservative Resampling**
- Spatially Varying Surface Tension
- Thermomechanical Coupling
- Summary



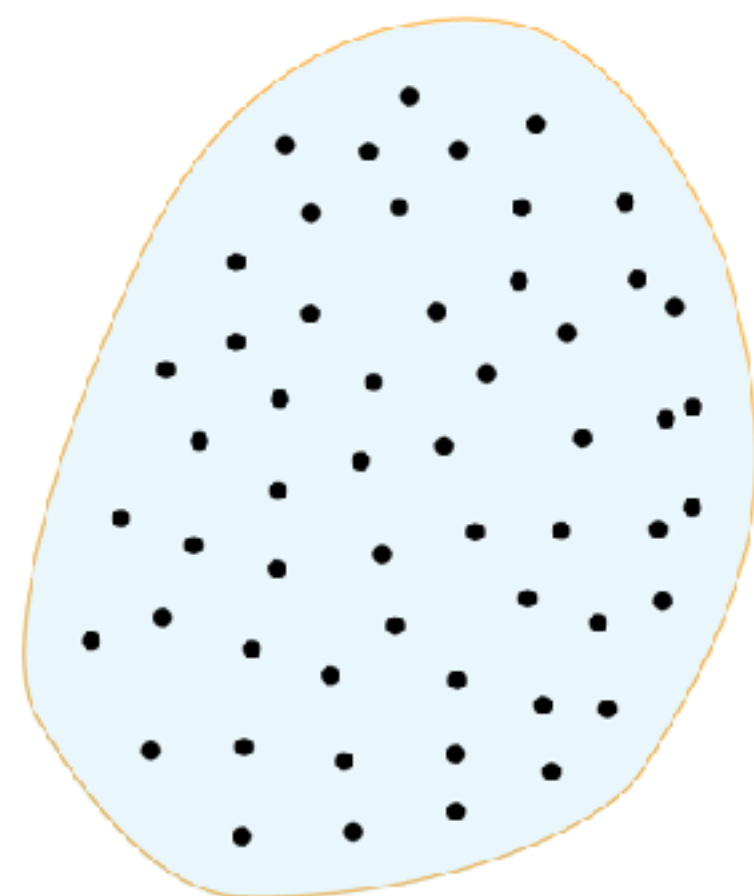
PROCEDURE

- Build particle level sets.
- Generate isocontour from particle level sets.
- Sample surface particles on the isocontour.
- Find the closest interior particles for each surface particles.
- Build balance particles $\mathbf{b}_r^n = \mathbf{s}_r^n + 2 \left(\mathbf{x}_{p(\mathbf{s}_r^n)}^n - \mathbf{s}_r^n \right)$.
- Remapping (within each particle group).
 - Assign mass, linear and affine velocity (momentum splitting).
 - Remove the temporary particles and merge the momentum.



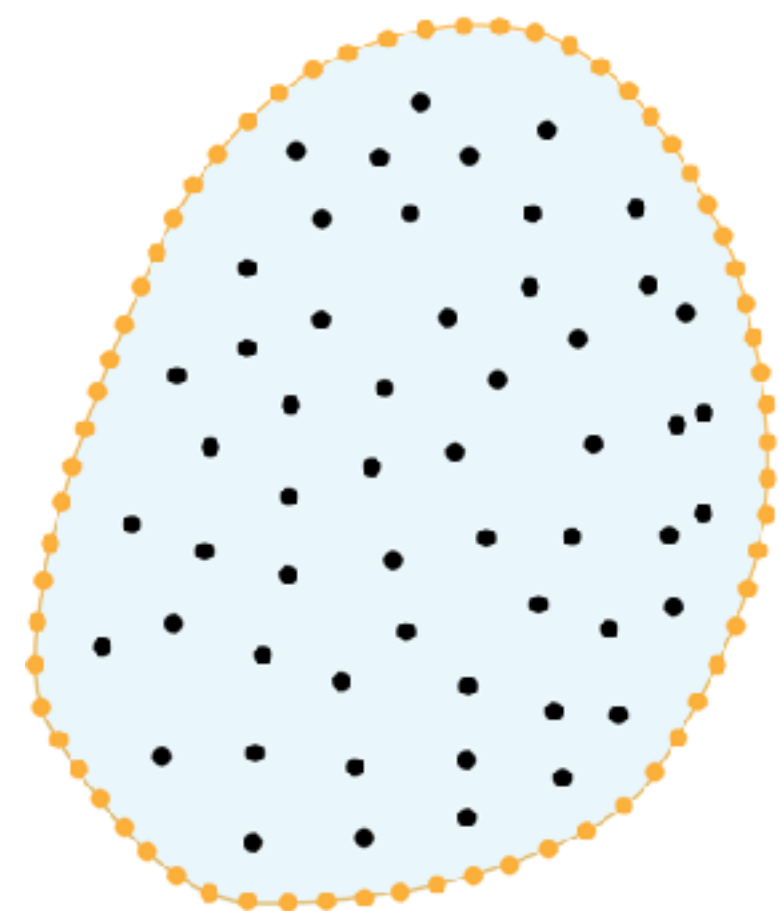
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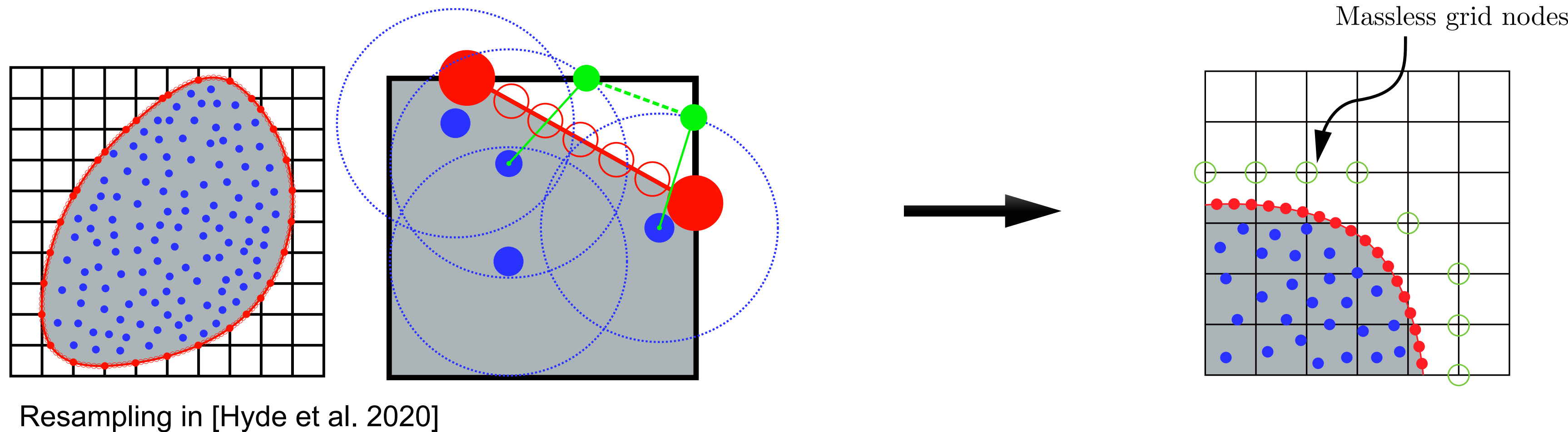
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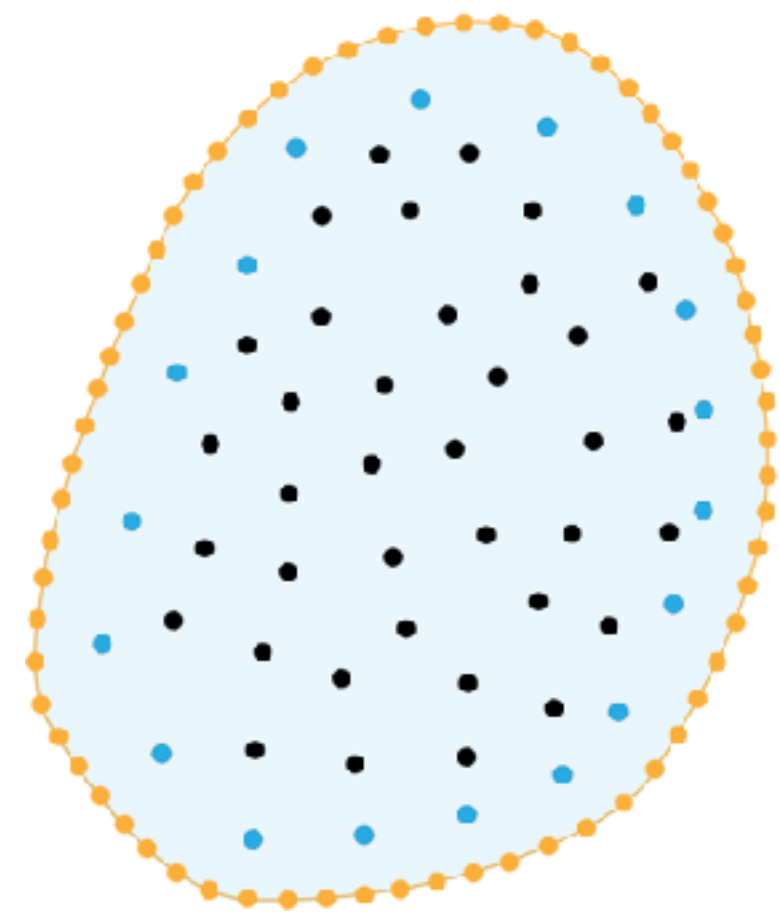


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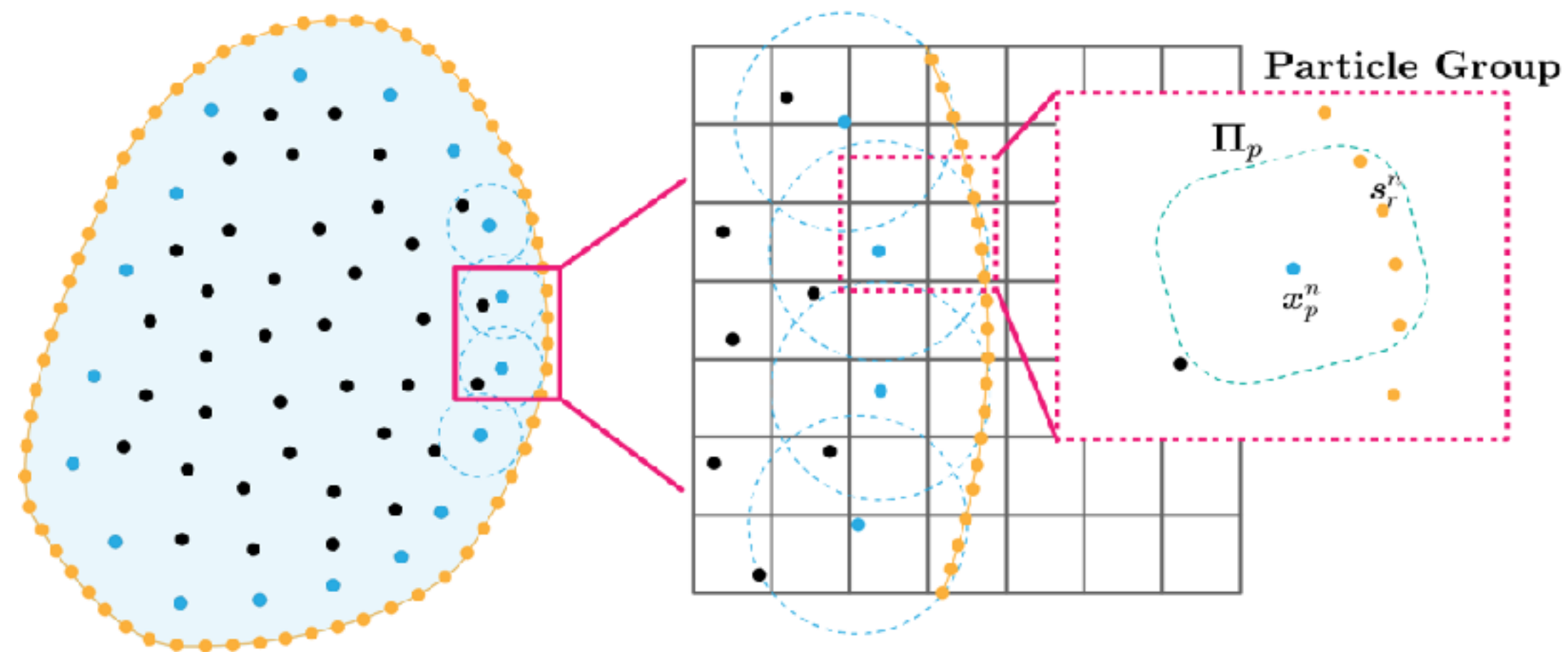
- Surface tension forces are applied through the surface particles.
- Hyde et al. [2020] proposed a method to sample the boundaries with massless surface particles.
 - Guarantee the mass conservation
 - Lose the momentum conservation





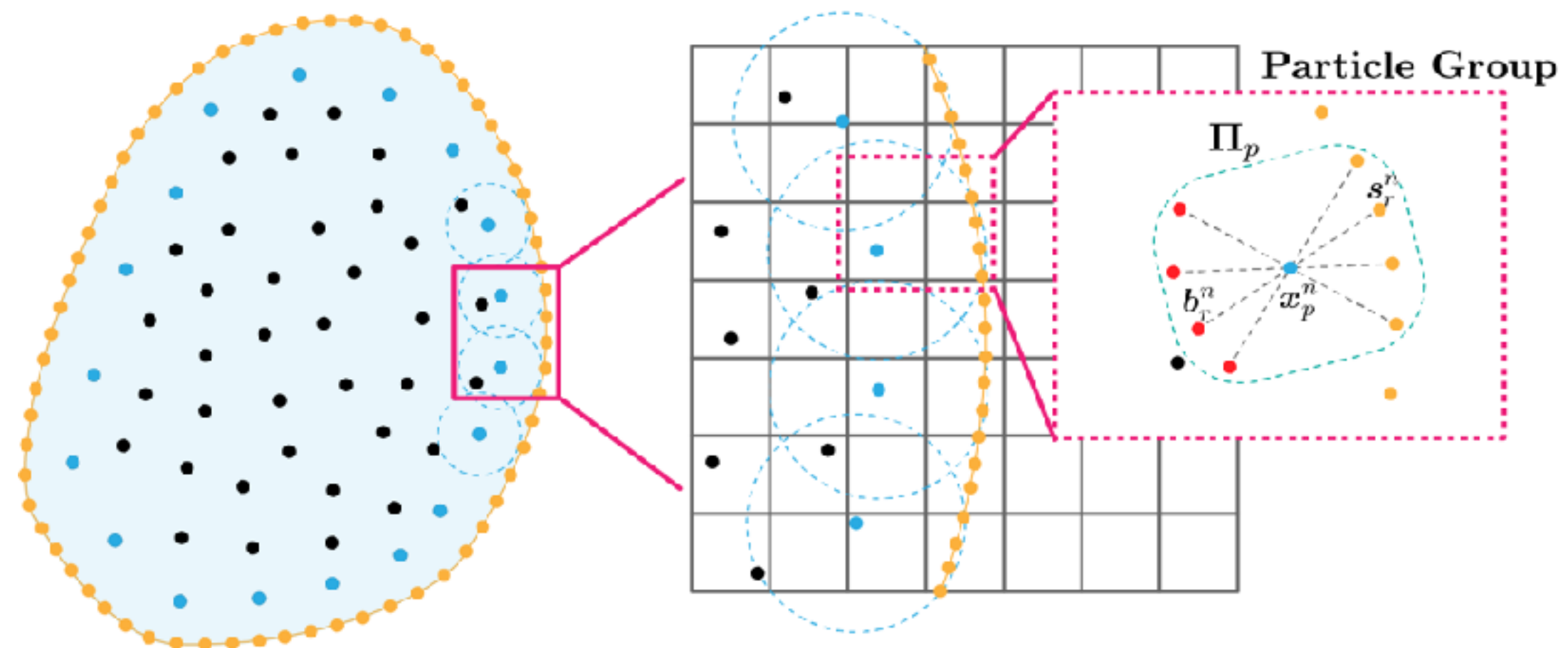
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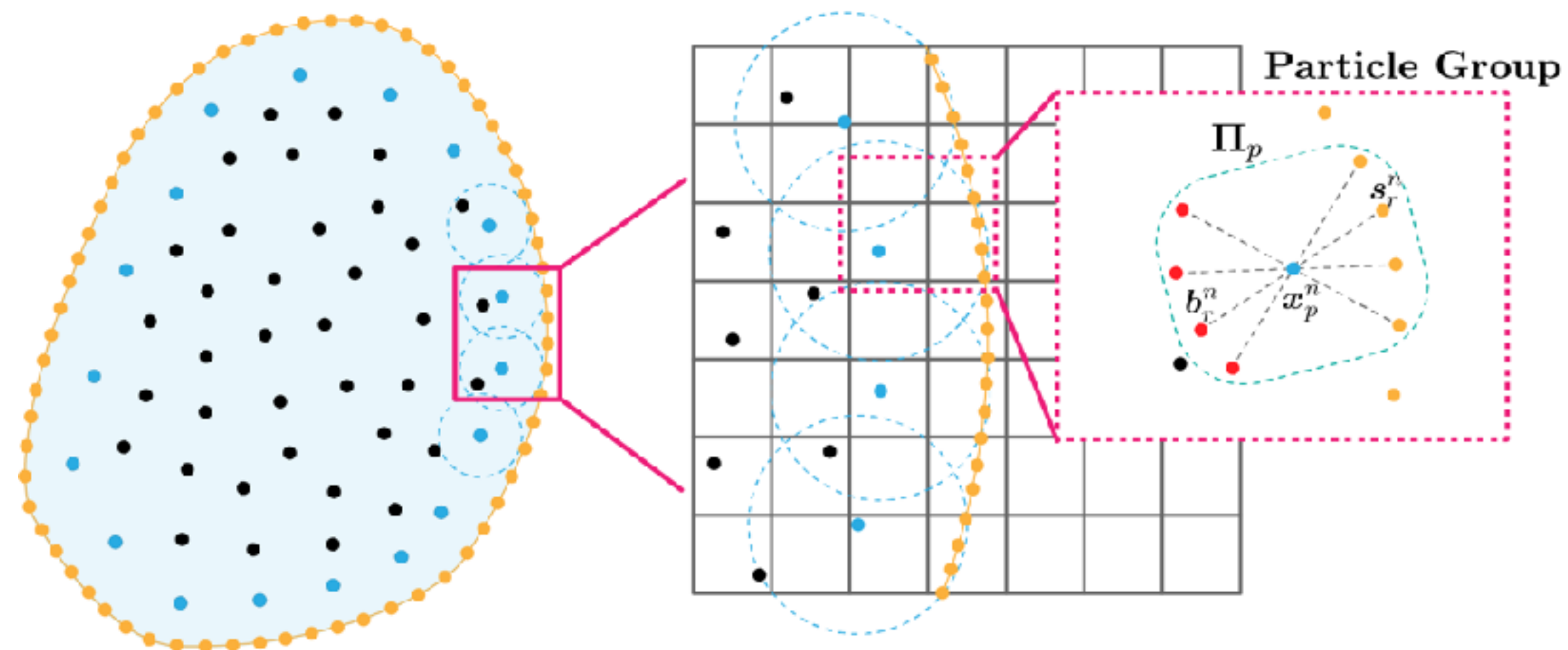
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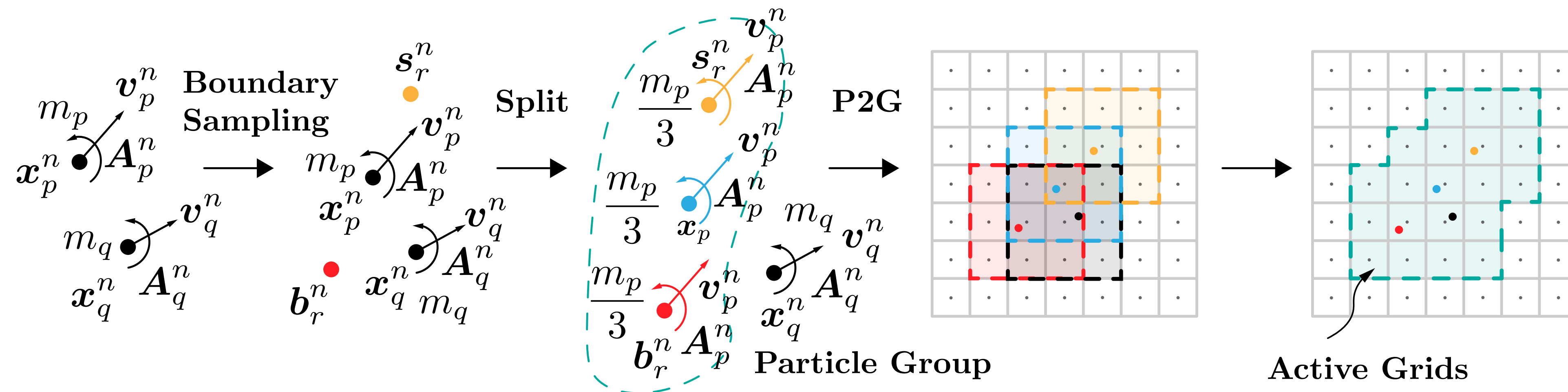
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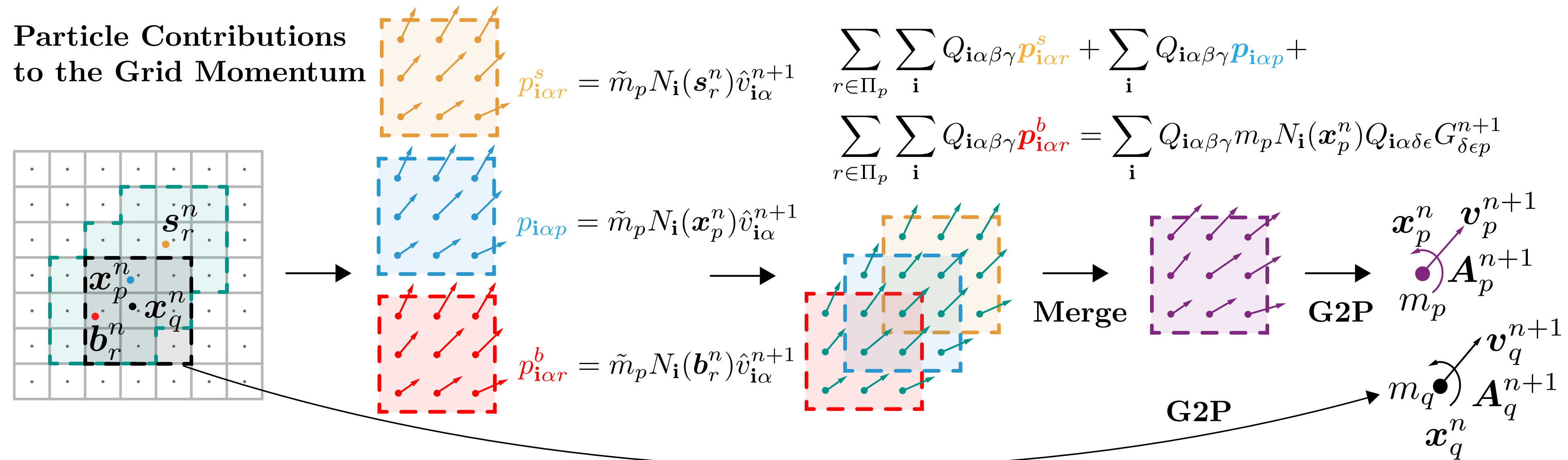
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- Split the mass m_p of the original x_p^n to surface particles s_r^n and balance particles b_r^n .
- Assign linear velocity v_p^n and affine velocity A_p^n to s_r^n and b_r^n .
- This technique avoids massless grid nodes and conserves the total linear and angular momentum.

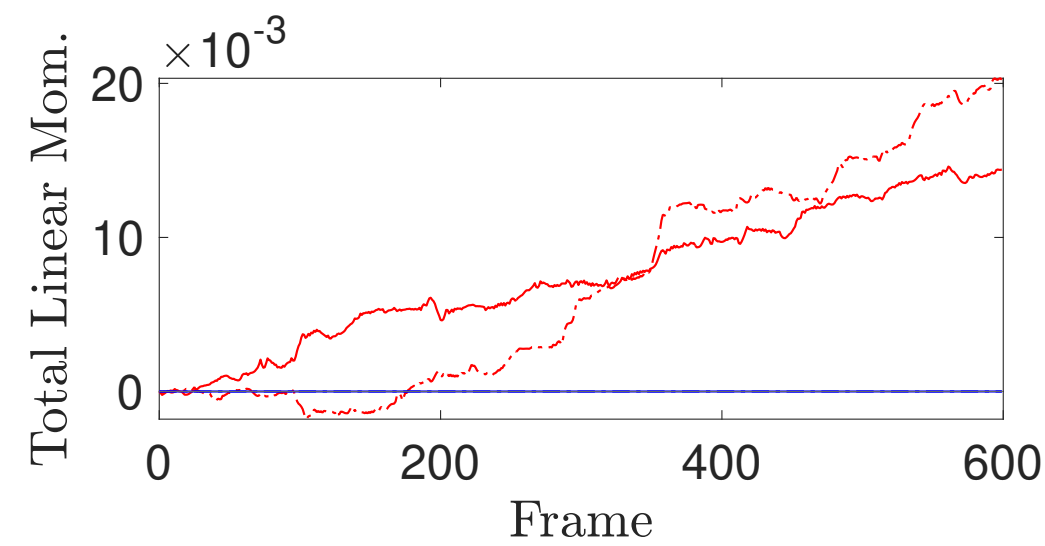


REMAPPING: MERGING

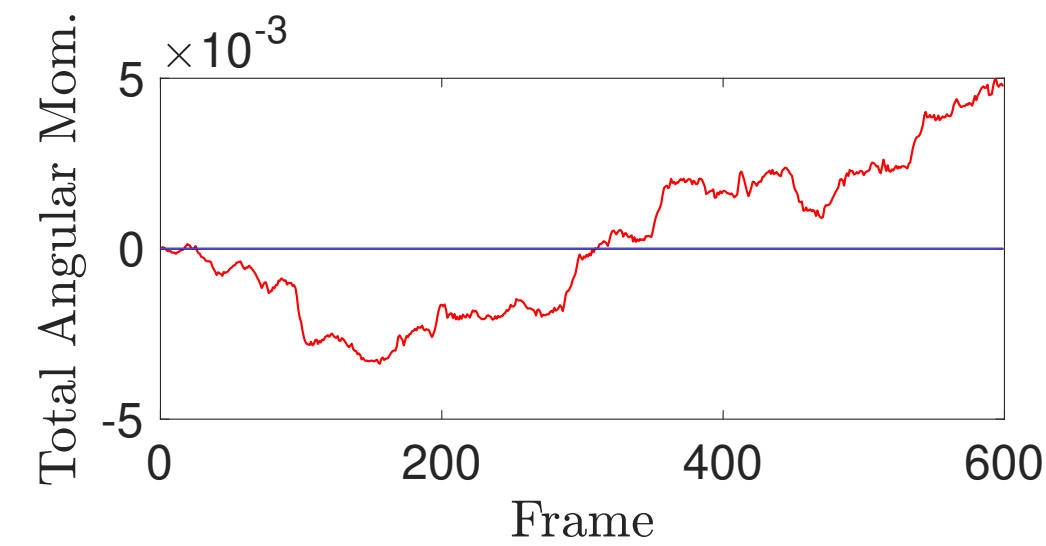


- Temporary particles are deleted before the advection.
- Mass and momentum of surface particles \mathbf{s}_r^n and balance particles \mathbf{b}_r^n are merged into the interior particles \mathbf{x}_p^n before the removal.

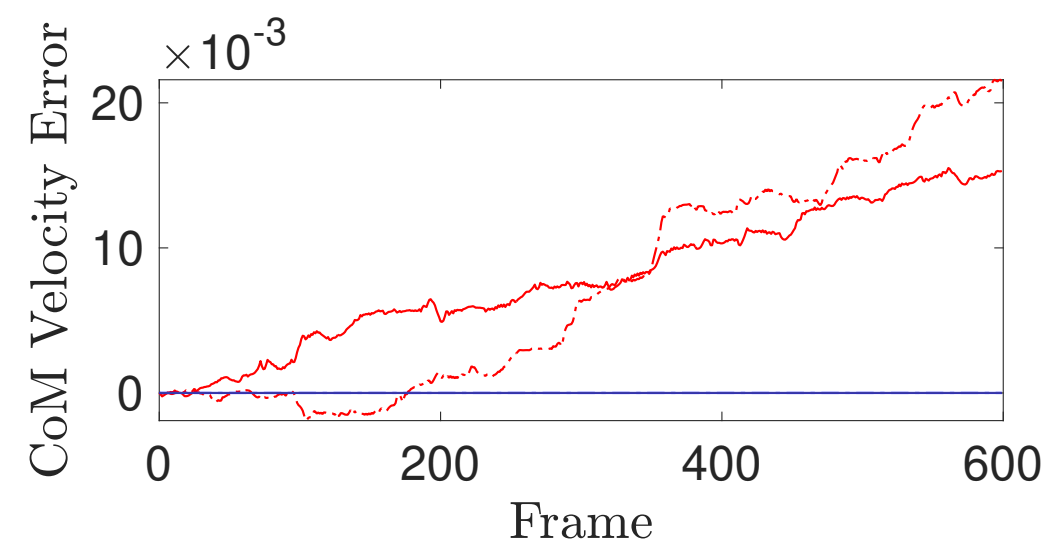
EXAMPLE: MOMENTUM CONSERVATION



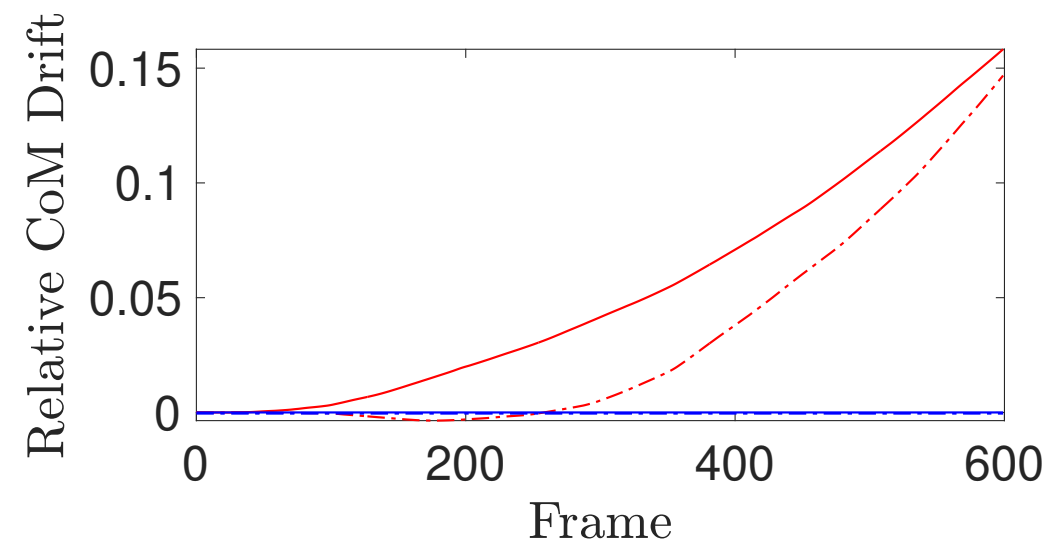
Hyde(x) Hyde(y) Ours(x) Ours(y)



Hyde Ours



Hyde(x) Hyde(y) Ours(x) Ours(y)



Hyde(x) Hyde(y) Ours(x) Ours(y)



Left: Our conservative resampling.
Right: Nonconservative resampling from Hyde et al. [2020]



$k^\sigma = 20$

$k^\sigma = 5$

$k^\sigma = 1$

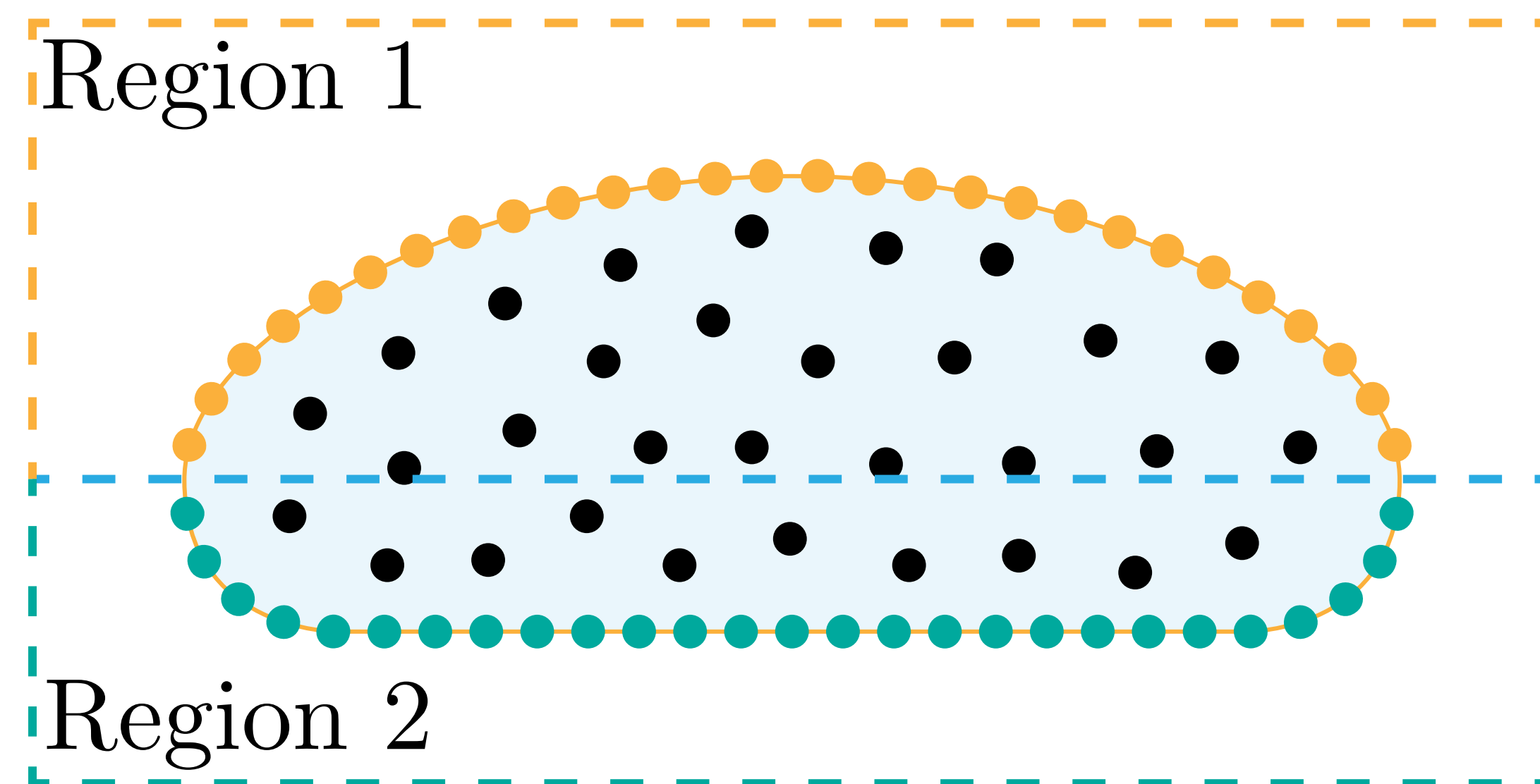
$k^\sigma = 0.1$

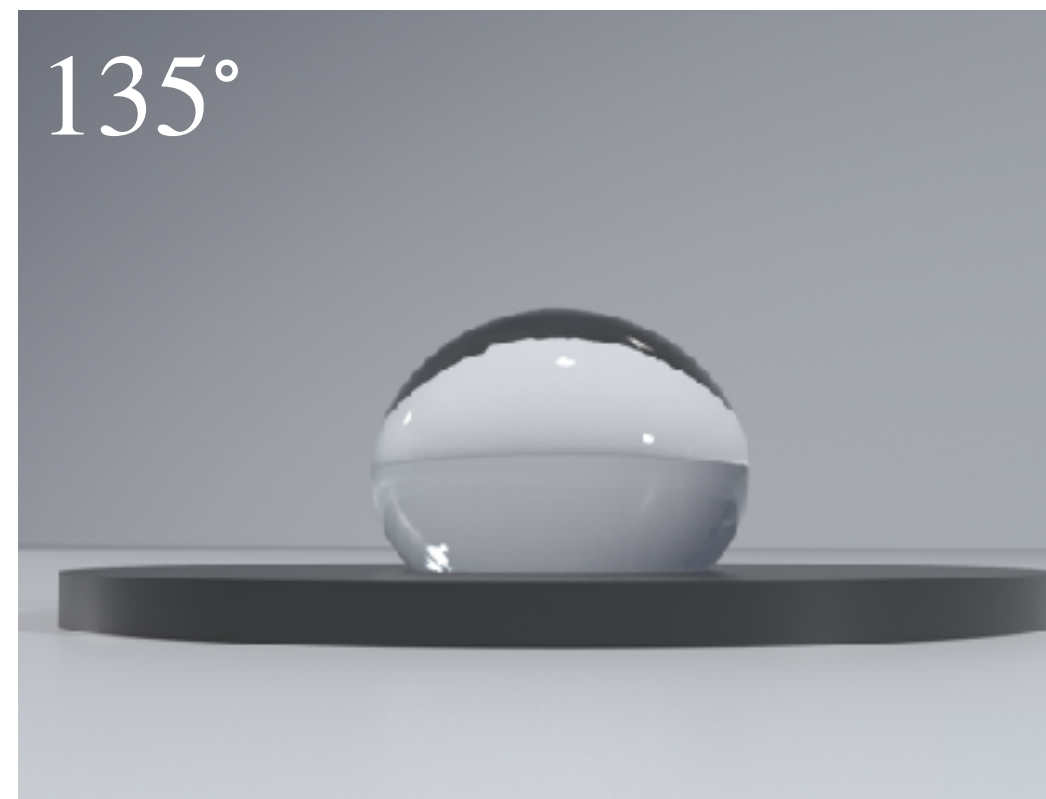
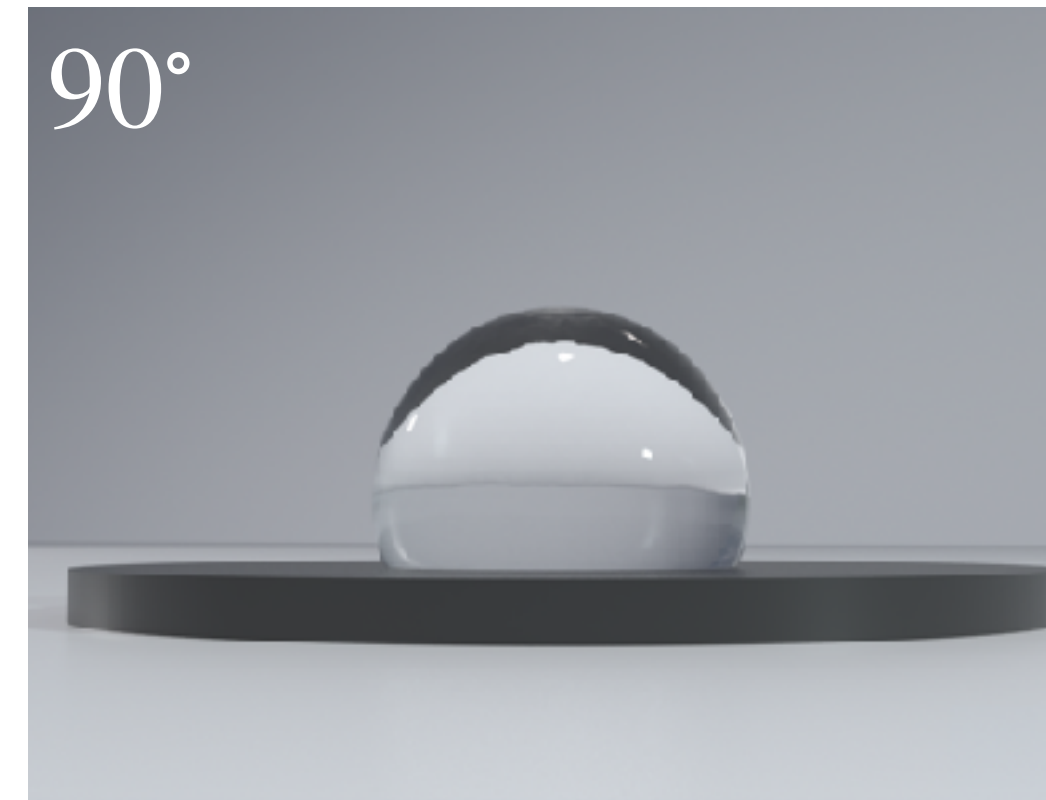
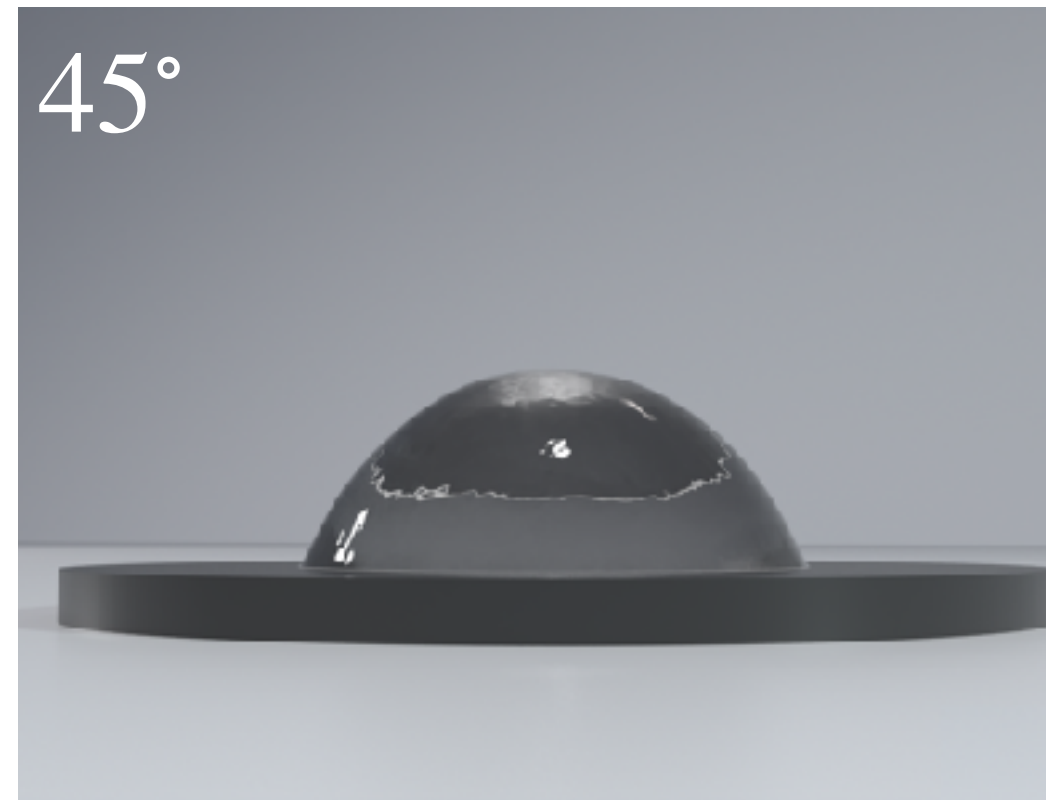
$k^\sigma = 0.05$

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SURFACE TENSION PER PARTICLE

- Each surface particles s_r^n can have different surface tension coefficient k^σ based on:
 - position
 - time
 - temperature / concentration
- Allow controlling the contact angle or dynamic spreading on the surface.
- Enable surface tension driven flow.



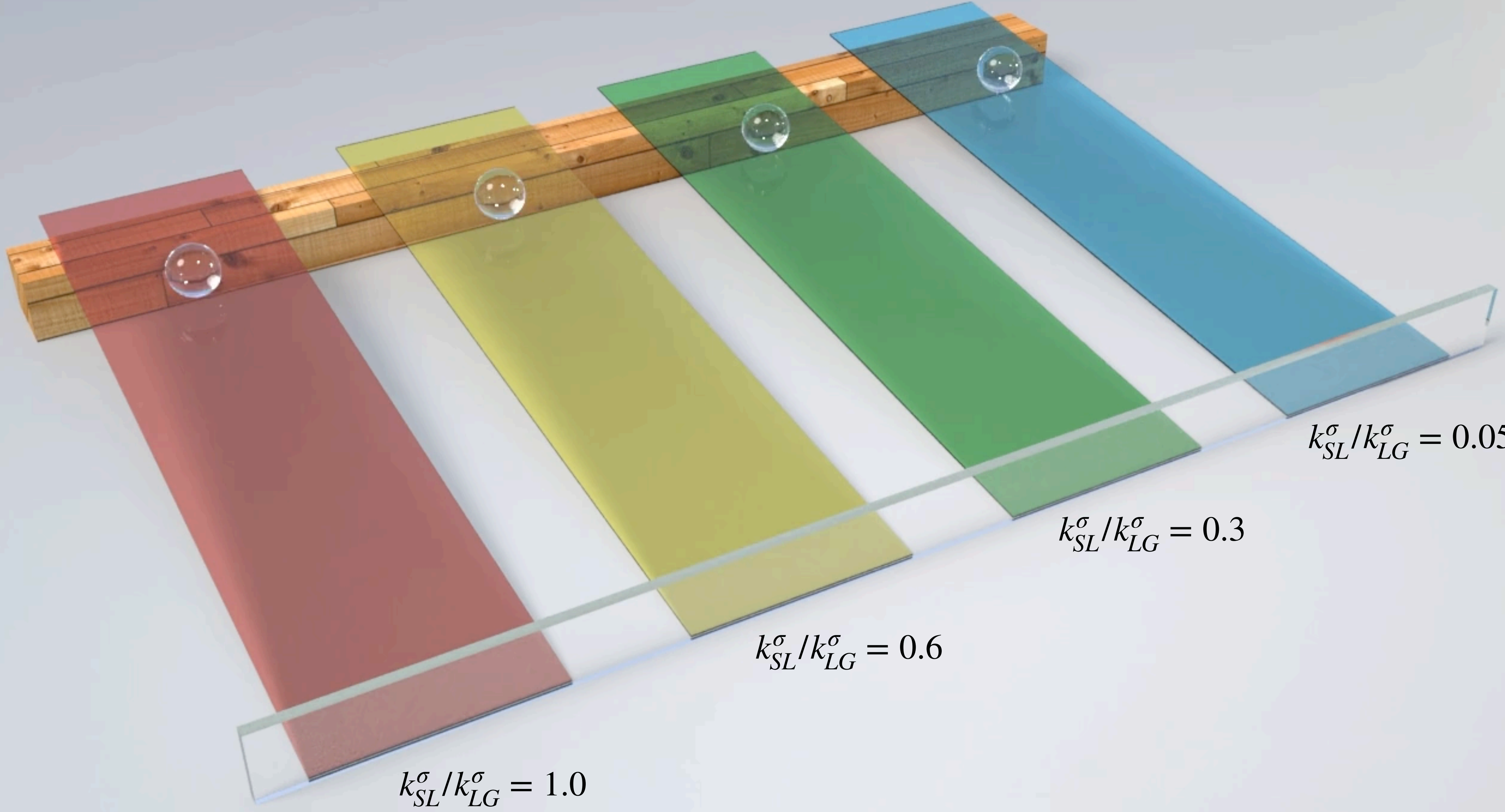


CONTACT ANGLE

- The contact angle can be determined by Young's equation

$$k_{SG}^{\sigma} = k_{SL}^{\sigma} + k_{LG}^{\sigma} \cos(\theta).$$

- Further simplify by ignoring k_{SG}^{σ} [Clausen et al. 2013].
- The desired contact angle is achieved by setting a proper surface tension ratio $k_{SL}^{\sigma} / k_{LG}^{\sigma}$.

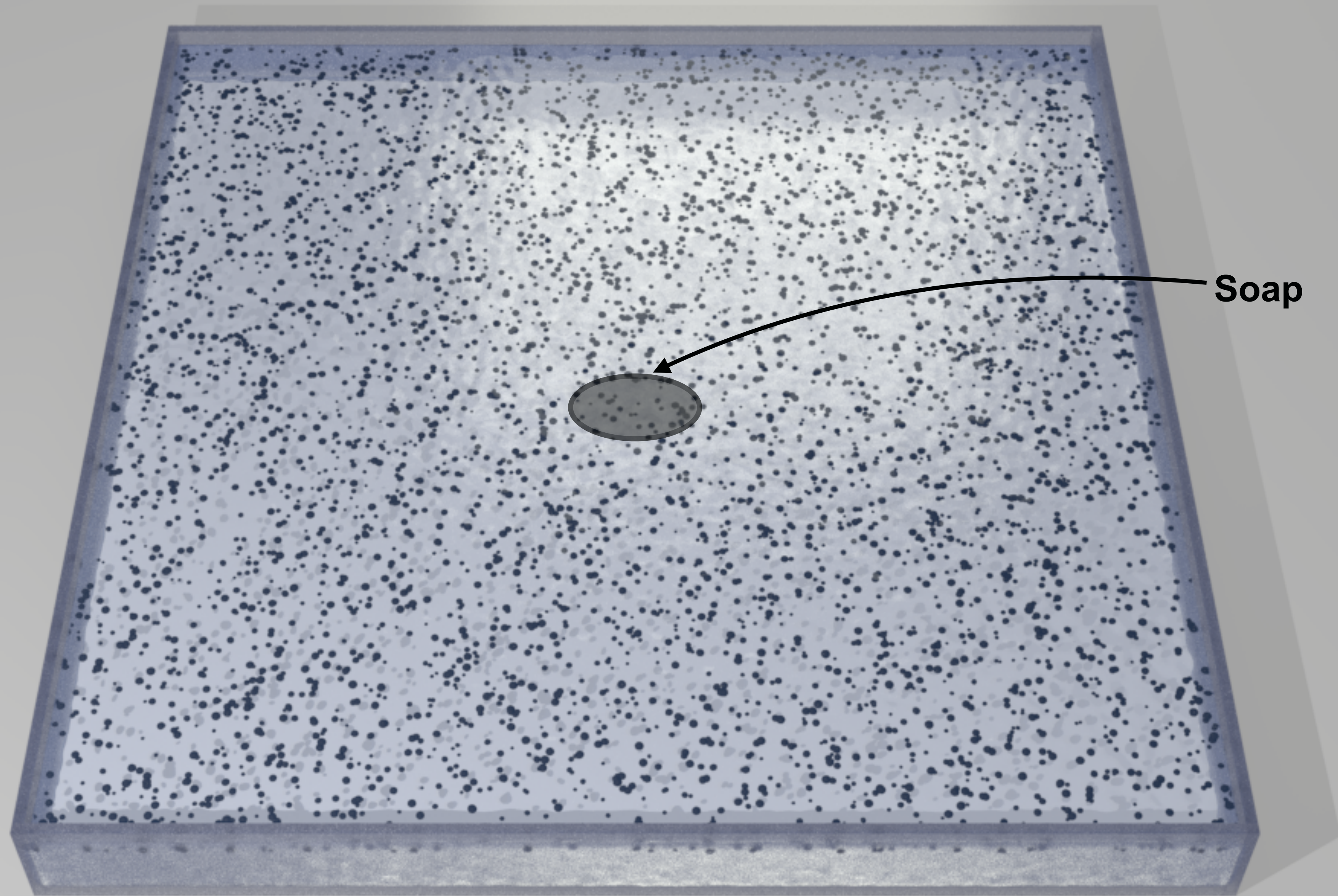


$$k_{SL}^{\sigma} / k_{LG}^{\sigma} = 1.0$$

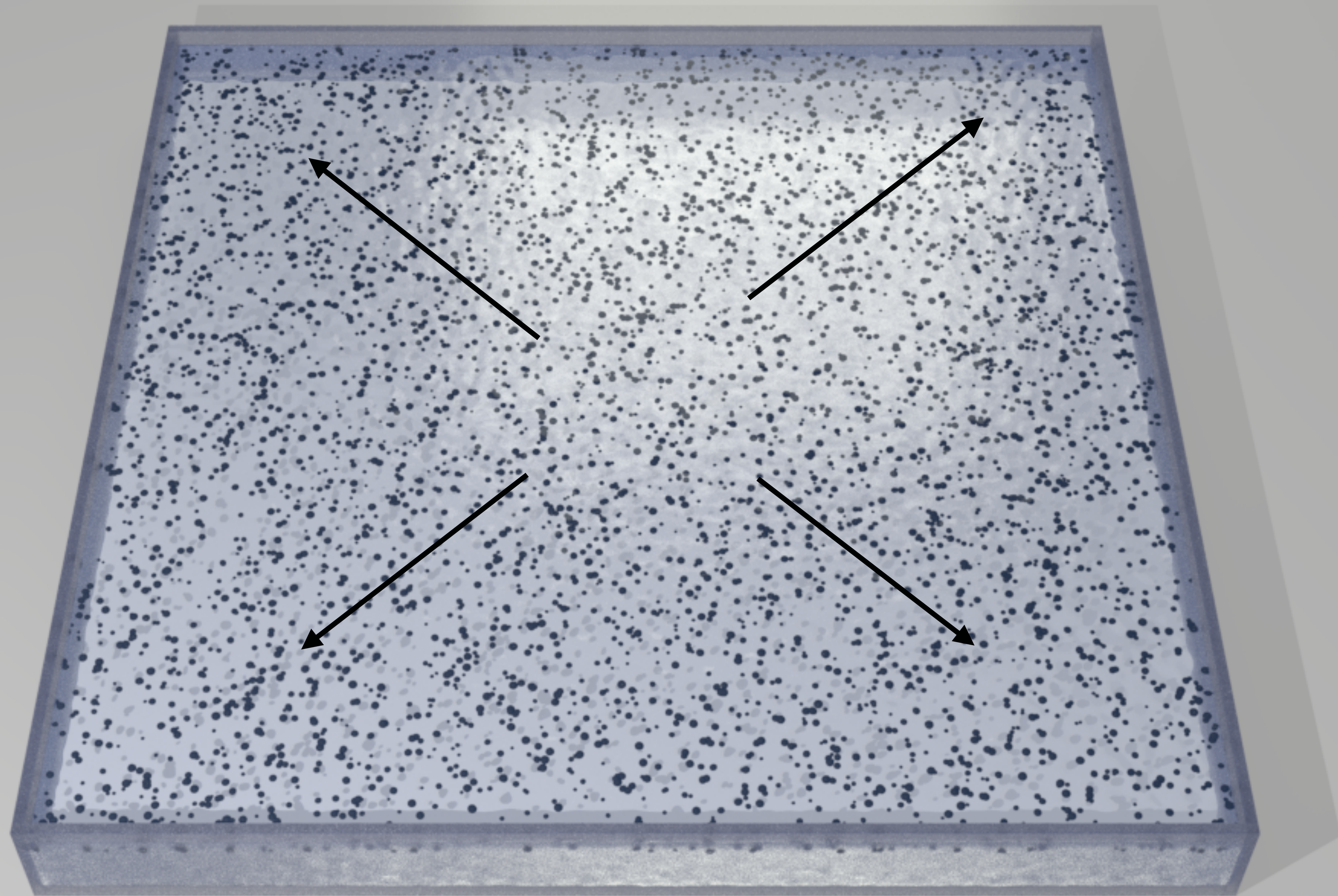
$$k_{SL}^{\sigma} / k_{LG}^{\sigma} = 0.6$$

$$k_{SL}^{\sigma} / k_{LG}^{\sigma} = 0.3$$

$$k_{SL}^{\sigma} / k_{LG}^{\sigma} = 0.05$$



Soap





- Backgrounds
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RELATED WORKS

- MPM for the thermomechanical simulations:
 - Stomakhin et al. [2014] simulated the phase change and applied the voxelized thermal boundary conditions directly on the grid.
 - Ding et al. [2019] used a temperature and porosity-dependent viscoelastoplastic model.
- Our method resolves the sub-cell boundary geometry by applying boundary conditions through particles.



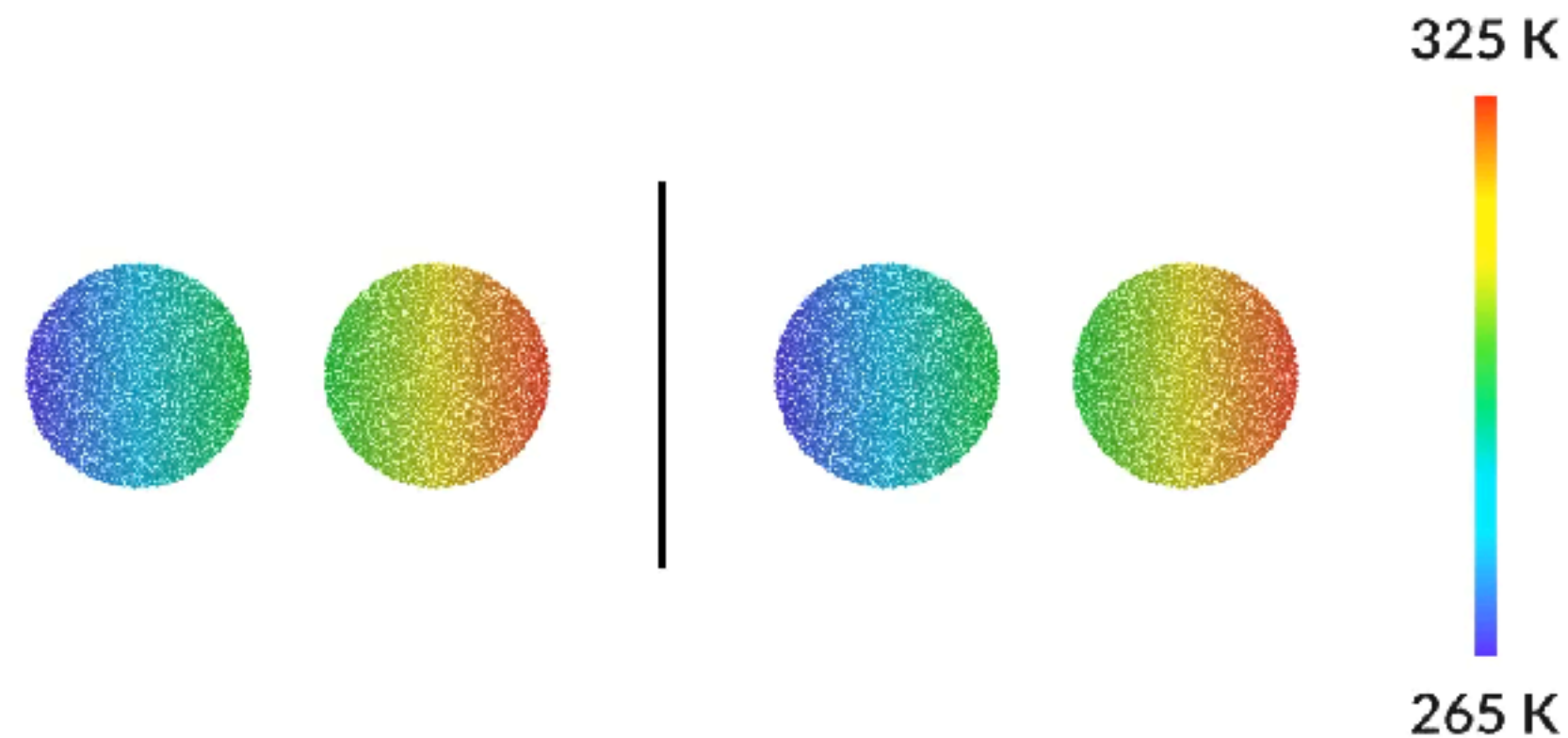
[Stomakhin et al. 2014]



[Ding et al. 2019]

ROBIN BC

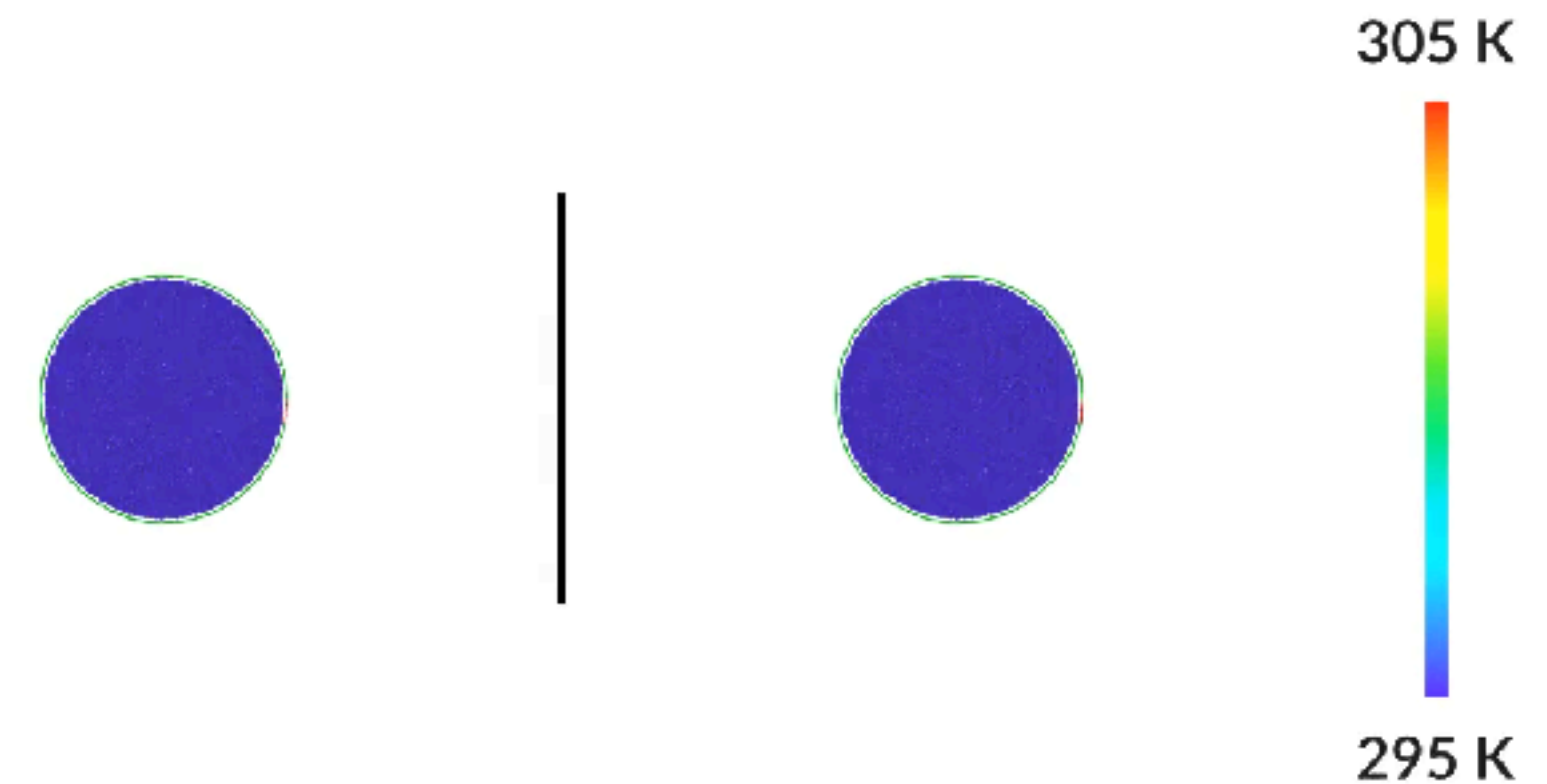
- The Robin boundary condition equilibrates material temperature to the ambient temperature.



Left: with Robin bc.
Right: without Robin bc.

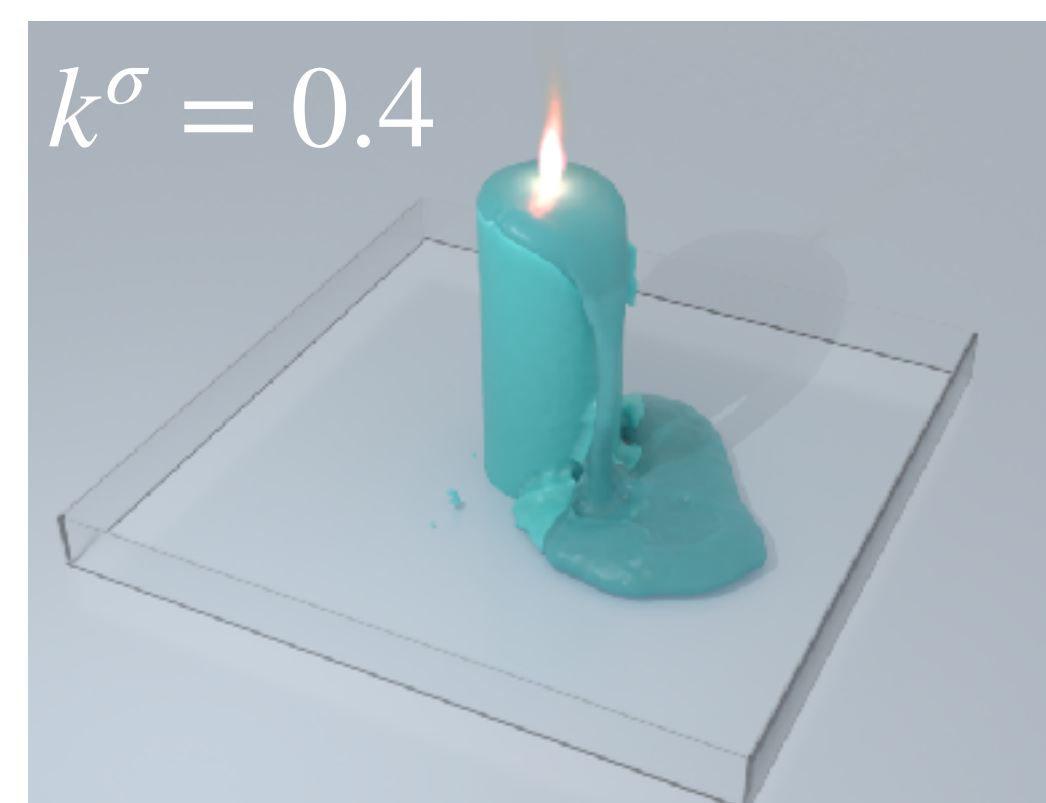
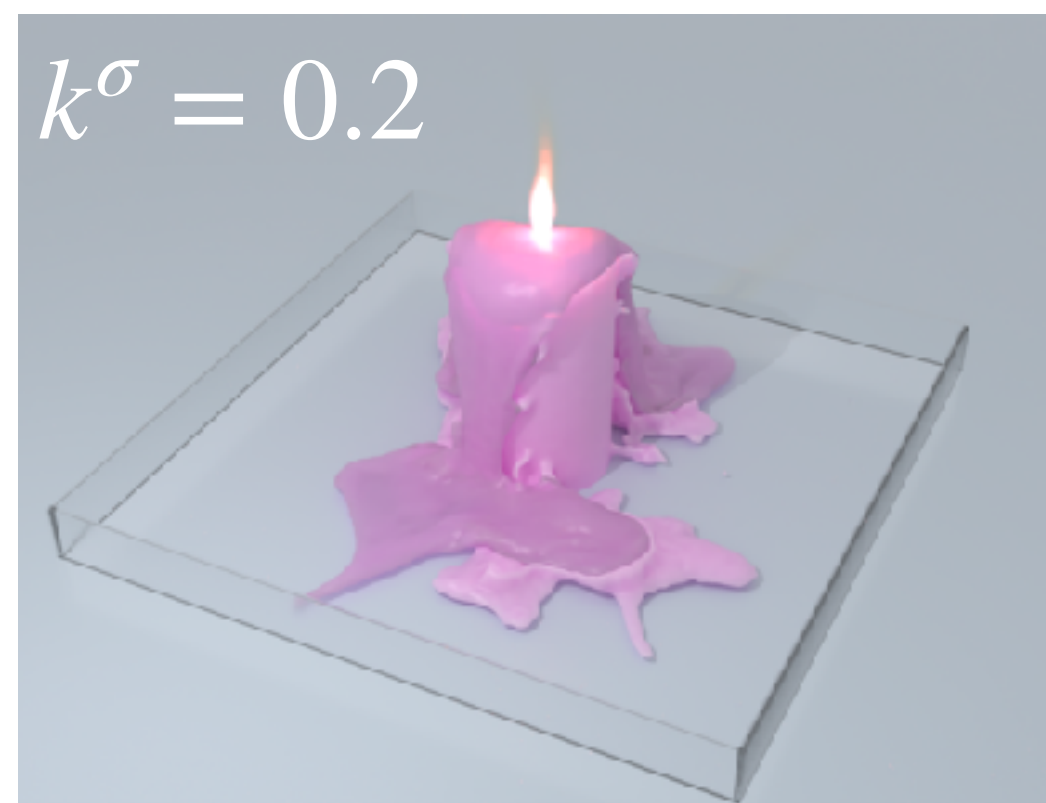
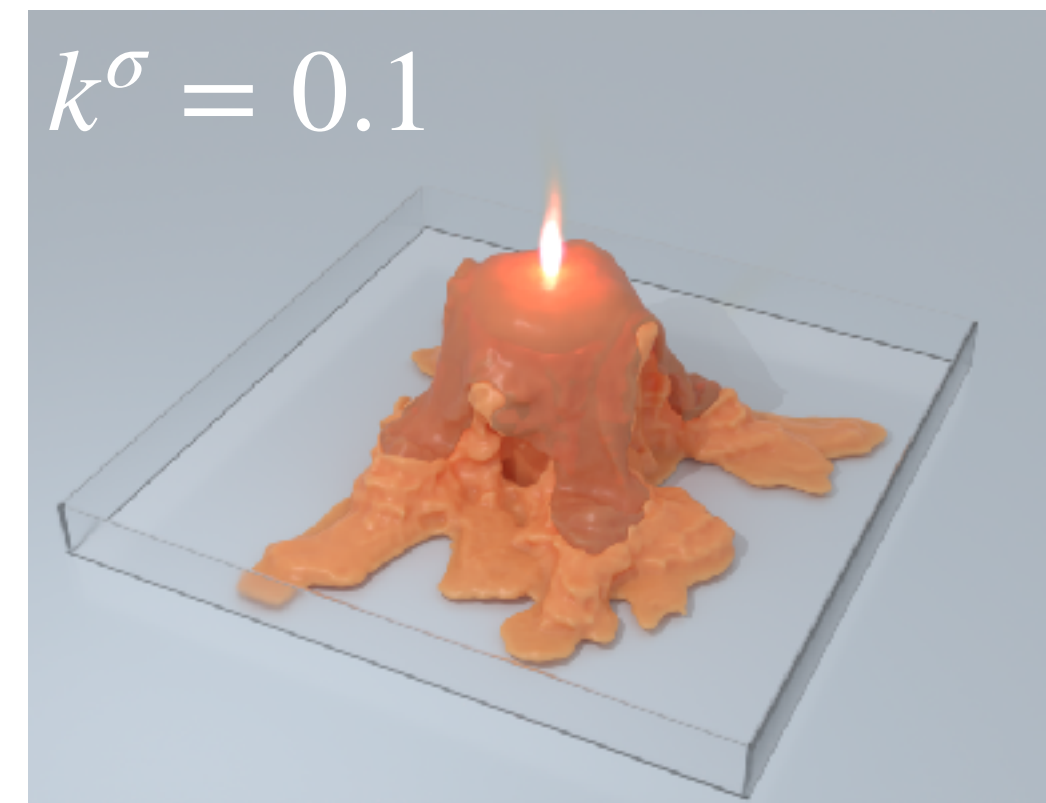
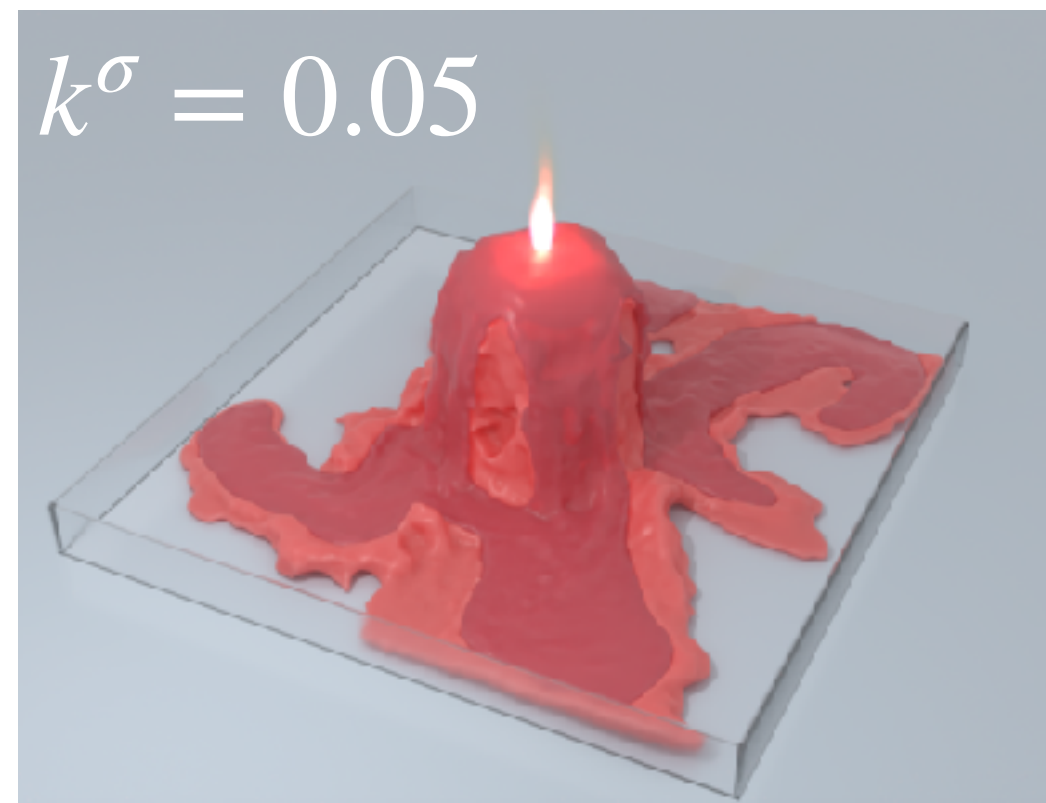
BC THROUGH PARTICLES

- Easy to apply complex boundary conditions



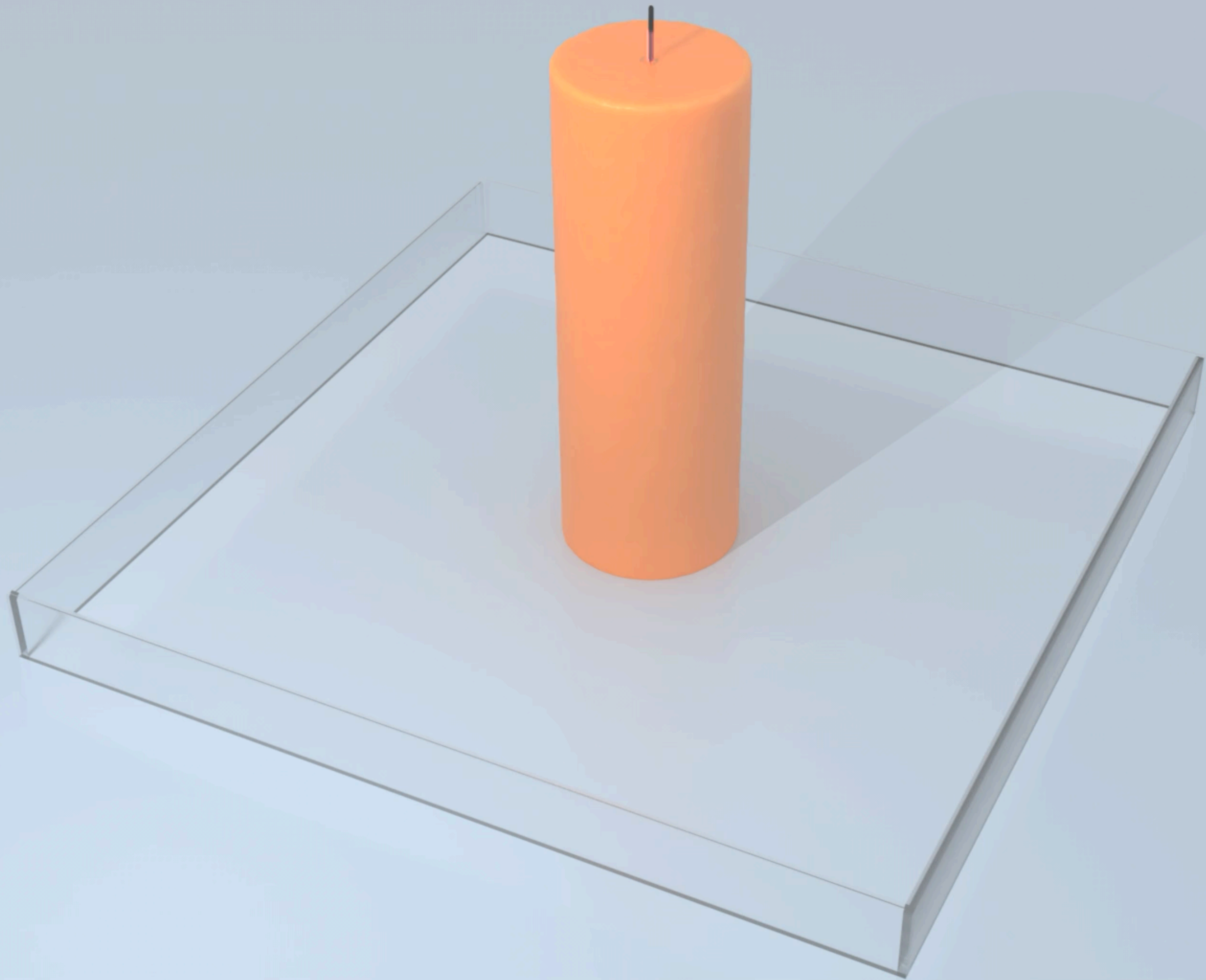
Left: heating (Neumann) + convection (Robin).
Right: heating (Neumann) only.





MELTING AND RESOLIDIFYING

- The flame is modeled as a Neumann boundary condition (heating).
- The resolidification is enabled by the Robin boundary condition (convective heat transfer).
- The wax changes phase based on its temperature:
 - melt if the temperature is above the melting point.
 - solidify if the temperature is below the melting point.



SIGGRAPH

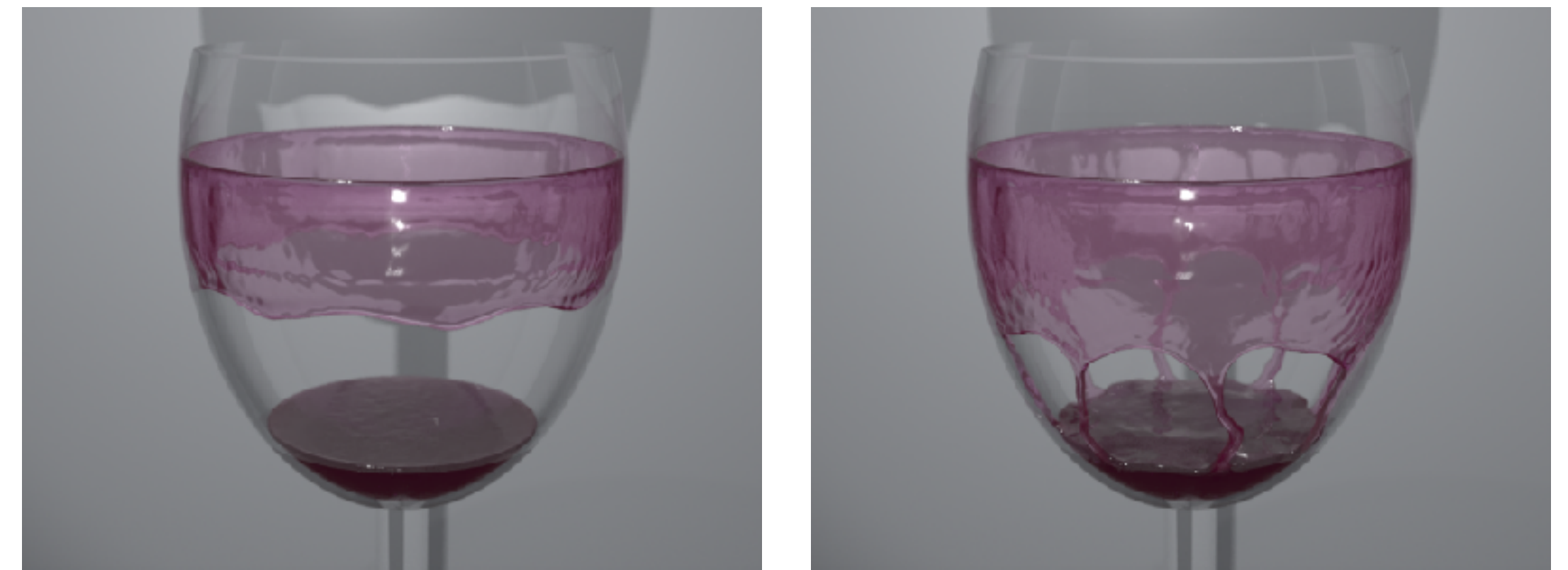
- Backgrounds
- Material Point Method (MPM)
- Conservative Resampling
- Spatially Varying Surface Tension
- Thermomechanical Coupling
- **Summary**

Contributions

- Our implicit MPM allows for simulating spatially varying surface tension.
- Our approach provides perfect conservation of the total linear and angular momentum.
- We coupled the surface tension simulation with the particle-base thermal boundary conditions.

Future directions

- Adding mixture model like [Ding et al. 2019].
- Simulating evaporation of alcohol, wax, etc.
- Generalizing our approach to SPH.



The falling wine forms tears and ridges.



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THANK YOU!

